Introduction



EECS4315 Z: Mission-Critical Systems Winter 2025

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This module is designed to help you understand:

- Mission-Critical Systems vs. Safety-Critical Systems
- Code of Ethics for Professional Engineers
- What a Formal Method Is
- Verification vs. Validation
- Catching **Defects**: When?
- Model-Based Development: EECS3342 vs. EECS4315



What is a Safety-Critical System (SCS)?

- A safety-critical system (SCS) is a system whose failure or malfunction has one (or more) of the following consequences:
 - death or serious injury to people
 - loss or severe damage to equipment/property
 - harm to the environment
- Based on the above definition, do you know of any systems that are safety-critical?



ASSOND

Professional Engineers: Code of Ethics

- Code of Ethics is a basic guide for professional conduct and imposes duties on practitioners, with respect to society, employers, clients, colleagues (including employees and subordinates), the engineering profession and him or herself.
- It is the duty of a practitioner to act at all times with,
 - fairness and loyalty to the practitioner's associates, employers, clients, subordinates and employees;
 - 2. fidelity (i.e., dedication, faithfulness) to public needs;
 - 3. devotion to *high ideals* of personal honour and professional integrity;
 - **4. knowledge** of developments in the area of professional engineering relevant to any services that are undertaken; and
 - competence in the performance of any professional engineering services that are undertaken.
- Consequence of misconduct?
 - suspension or termination of professional licenses
 - civil law suits





Developing Safety-Critical Systems

Industrial standards in various domains list **acceptance criteria** for **mission**- or **safety**-critical systems that practitioners need to comply with: e.g.,

Aviation Domain: **RTCA DO-178C** "Software Considerations in Airborne Systems and Equipment Certification"

Nuclear Domain: **IEEE 7-4.3.2** "Criteria for Digital Computers in Safety Systems of Nuclear Power Generating Stations"

Two important criteria are:

- System requirements are precise and complete
- **2.** System *implementation* conforms to the requirements But how do we accomplish these criteria?





• Critical:

A task whose successful completion ensures the success of a larger, more complex operation.

e.g., Success of a pacemaker ⇒ Regulated heartbeats of a patient

Safety:

Being free from danger/injury to or loss of human lives.

• Mission:

An operation or task assigned by a higher authority.

Q. Formally relate being *safety*-critical and *mission*-critical.

Α.

- safety-critical ⇒ mission-critical
- mission-critical
 ⇒ safety-critical
- Relevant industrial standard: RTCA DO-178C (replacing RTCA DO-178B in 2012) "Software Considerations in Airborne Systems and Equipment Certification"



Using Formal Methods for Certification

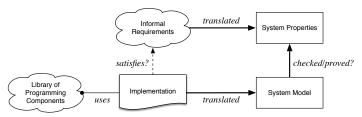
- A formal method (FM) is a mathematically rigorous technique for the specification, development, and verification of software and hardware systems.
- **DO-333** "Formal methods supplement to DO-178C and DO-278A" advocates the use of formal methods:

The use of **formal methods** is motivated by the expectation that, as in other engineering disciplines, performing appropriate **mathematical analyses** can contribute to establishing the **correctness** and **robustness** of a design.

- FMs, because of their mathematical basis, are capable of:
 - Unambiguously describing software system requirements.
 - Enabling precise communication between engineers.
 - Providing verification (towards certification) evidence of:
 - A formal representation of the system being healthy.
 - A *formal* representation of the system *satisfying* safety properties.

Verification: Building the Product Right?

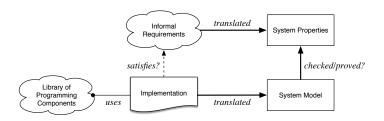




- Implementation built via reusable programming components.
- Goal : Implementation Satisfies Intended Requirements
- To verify this, we *formalize* them as a *system model* and a set of (e.g., safety) *properties*, using the specification language of a theorem prover (EECS3342) or a <u>model checker</u> (EECS4315).
- Two Verification Issues:
 - 1. Library components may not behave as intended.
 - 2. Successful checks/proofs ensure that we *built the product right*, with respect to the informal requirements. **But**...

Validation: Building the Right Product?





- Successful checks/proofs
 ⇒ We built the right product.
- The target of our checks/proofs may <u>not</u> be valid:
 The requirements may be <u>ambiguous</u>, <u>incomplete</u>, or <u>contradictory</u>.
- Solution: Precise Documentation [EECS4312]





Catching Defects – When?

- To minimize *development costs*, minimize *software defects*.
- Software Development Cycle:

Requirements → *Design* → *Implementation* → Release

Q. Design or Implementation Phase?

Catch defects as early as possible.

Design and architecture	Implementation	Integration testing	Customer beta test	Postproduct release	
1X*	5X	10X	15X	30X	

- .. The cost of fixing defects *increases exponentially* as software progresses through the development lifecycle.
- Discovering <u>defects</u> after <u>release</u> costs up to <u>30 times more</u> than catching them in the <u>design</u> phase.
- Choice of a design language, amendable to formal verification, is therefore critical for your project.

Source: IBM Report

LASSONDE

Model-Based Development in EECS3342

- Modelling and formal reasoning should be performed <u>before</u> implementing/coding a system.
 - A system's *model* is its *abstraction*, filtering irrelevant details.
 A system *model* means as much to a software engineer as a *blueprint* means to an architect.
 - A system may have a list of models, "sorted" by accuracy:

$$\langle m_0, m_1, \ldots, m_i \rangle$$
, $m_j, \ldots, m_n \rangle$

- The list starts by the most abstract model with least details.
- A more abstract model m_i is said to be refined by its subsequent, more concrete model m_j.
- The list ends with the most concrete/refined model with most details.
- It is far easier to reason about:
 - a system's *abstract* models (rather than its full *implementation*)
 - **refinement steps** between subsequent models
- The final product is **correct by construction**.





- Modelling and formal reasoning should be performed <u>before</u> implementing/coding a system.
 - A system's *model* is its *abstraction*, filtering irrelevant details.
 - A system *model* means as much to a software engineer as a *blueprint* means to an architect.
- A design model m specified at the "right" level of abstraction:
 State space not causing a state explosion.
 - m is checked against invariant and temporal properties.
 - m may be added with more details (e.g., variables) to result in a more "refined" model m'.
 - m' is consistent with (or "refines") m as long as:
 - No combinatorial explosion from variable ranges
 - All properties that m passes also pass in m'.



TLA+: An Industrial Strength Toolbox

From https://lamport.azurewebsites.net/tla/tla.html

TLA + (Temporal Logic of Actions) is a high-level language for modeling programs and systems—especially concurrent and distributed ones. It's based on the idea that the best way to describe things precisely is with simple mathematics.

TLA+ and its tools are useful for eliminating fundamental design errors, which are hard to find and expensive to correct in code.

TLA+ is a language for modeling **software** above the code level and **hardware** above the circuit level.

It has an *IDE* (Integrated Development Environment) for writing models and running tools to check them. The tool most commonly used by engineers is the *TLC model checker*, but there is also a proof checker.

TLA+ is based on mathematics and does not resemble any programming language. Most engineers will find *PlusCal*, described below, to be the easiest way to start using TLA+.



Beyond this lecture ...

• The *TLA+ toolbox* has been report about its use in industry:

https://lamport.azurewebsites.net/tla/
industrial-use.html

- Two papers have been made available on eClass:
 - Newcombe, C. Why Amazon Chose TLA+. In Abstract State Machines, Alloy, B, TLA, VDM, and Z, pp 25 – 39. Springer (2014).
 - Newcombe, C., Rath, T., Zhang, F., Munteanu, B., Brooker, M., Deardeuff, M. How Amazon Web Services Uses Formal Methods. In Communications of the ACM, 58(4), pp 66 – 73. ACM (2015).
- You're encouraged to read them first: we will guide you through some highlights later in the course (after you've gained experience on the TLA+ toolbox).





Learning Outcomes

What is a Safety-Critical System (SCS)?

Professional Engineers: Code of Ethics

Developing Safety-Critical Systems

Safety-Critical vs. Mission-Critical?

Using Formal Methods to for Certification

Verification: Building the Product Right?

Validation: Building the Right Product?

Catching Defects – When?

Model-Based Development in EECS3342

Model-Based Development in EECS4315

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TLA+: An Industrial Strength Toolbox

Beyond this lecture ...

Review of Math



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Learning Outcomes of this Lecture

This module is designed to help you **review**:

- Propositional Logic
- Predicate Logic





- A proposition is a statement of claim that must be of either true or false, but not both.
- Basic logical operands are of type Boolean: true and false.
- We use logical operators to construct compound statements.
 - Unary logical operator: negation (¬)

р	$\neg p$	
true	false	
false	true	

 Binary logical operators: conjunction (∧), disjunction (∨), implication (⇒), equivalence (≡), and if-and-only-if (⇐⇒).

р	q	$p \wedge q$	$p \lor q$	$p \Rightarrow q$	$p \iff q$	$p \equiv q$
true	true	true	true	true	true	true
true	false	false	true	false	false	false
false	true	false	true	true	false	false
false	false	false	false	true	true	true



Propositional Logic: Implication (1)

- Written as $p \Rightarrow q$ [pronounced as "p implies q"]
 - We call *p* the antecedent, assumption, or premise.
 - We call q the consequence or conclusion.
- Compare the *truth* of $p \Rightarrow q$ to whether a contract is *honoured*:
 - ∘ antecedent/assumption/premise $p \approx$ promised terms [e.g., salary]
 - \circ consequence/conclusion $q \approx$ obligations [e.g., duties]
- When the promised terms are met, then the contract is:
 - \circ honoured if the obligations fulfilled. [(true \Rightarrow true) \iff true]
 - \circ breached if the obligations violated. [(true \Rightarrow false) \iff false]
- When the promised terms are not met, then:
 - Fulfilling the obligation (q) or not (¬q) does not breach the contract.

р	q	$p \Rightarrow q$
false	true	true
false	false	true



Propositional Logic: Implication (2)

There are alternative, equivalent ways to expressing $p \Rightarrow q$:

- \circ q if p
 - g is true if p is true
- \circ p only if q

If p is true, then for $p \Rightarrow q$ to be true, it can only be that q is also true. Otherwise, if p is true but q is false, then $(true \Rightarrow false) \equiv false$.

Note. To prove $p \equiv q$, prove $p \iff q$ (pronounced: "p if and only if q"):

p if q

 $[p \leftarrow q \equiv q \Rightarrow p]$

• p only if q

[$p \Rightarrow q$] similar to q if p]

p is sufficient for q

true

For *q* to be *true*, it is sufficient to have *p* being *true*.

q is necessary for p

[similar to p only if q]

If *p* is *true*, then it is necessarily the case that *q* is also *true*. Otherwise, if *p* is *true* but *q* is *false*, then ($true \Rightarrow false$) $\equiv false$.

q unless ¬p

[When is $p \Rightarrow q \text{ true?}$]

If q is true, then $p \Rightarrow q$ true regardless of p.

If q is false, then $p \Rightarrow q$ cannot be true unless p is false.





Propositional Logic: Implication (3)

Given an implication $p \Rightarrow q$, we may construct its:

- **Inverse**: $\neg p \Rightarrow \neg q$ [negate antecedent and consequence]
- Converse: $q \Rightarrow p$ [swap antecedent and consequence]
- **Contrapositive**: $\neg q \Rightarrow \neg p$ [inverse of converse]



Propositional Logic (2)



• **Axiom**: Definition of ⇒

$$p \Rightarrow q \equiv \neg p \lor q$$

• **Theorem**: Identity of ⇒

$$true \Rightarrow p \equiv p$$

• **Theorem**: Zero of ⇒

$$false \Rightarrow p \equiv true$$

• Axiom: De Morgan

$$\neg(p \land q) \equiv \neg p \lor \neg q$$
$$\neg(p \lor q) \equiv \neg p \land \neg q$$

Axiom: Double Negation

$$p \equiv \neg (\neg p)$$

• Theorem: Contrapositive

$$p \Rightarrow q \equiv \neg q \Rightarrow \neg p$$

Predicate Logic (1)



- A predicate is a universal or existential statement about objects in some universe of disclosure.
- Unlike propositions, predicates are typically specified using variables, each of which declared with some range of values.
- We use the following symbols for common numerical ranges:
 - \circ \mathbb{Z} : the set of integers $[-\infty, ..., -1, 0, 1, ..., +\infty]$ \circ \mathbb{N} : the set of natural numbers $[0, 1, ..., +\infty]$
- Variable(s) in a predicate may be quantified:
 - Universal quantification:
 All values that a variable may take satisfy certain property.
 e.g., Given that i is a natural number, i is always non-negative.
 - Existential quantification:
 Some value that a variable may take satisfies certain property.
 e.g., Given that i is an integer, i can be negative.



Predicate Logic (2.1): Universal Q. (∀)

- A *universal quantification* has the form $(\forall X \bullet R \Rightarrow P)$
 - X is a comma-separated list of variable names
 - R is a constraint on types/ranges of the listed variables
 - P is a property to be satisfied
- For all (combinations of) values of variables listed in X that satisfies R, it is the case that P is satisfied.

```
\circ \forall i \bullet i \in \mathbb{N} \Rightarrow i > 0
\circ \forall i \bullet i \in \mathbb{Z} \Rightarrow i > 0
\circ \forall i, j \bullet i \in \mathbb{Z} \land j \in \mathbb{Z} \Rightarrow i < j \lor i > j
```

[true] [false]

[false]

- Proof Strategies
 - **1.** How to prove $(\forall X \bullet R \Rightarrow P)$ *true*?

```
• Hint. When is R \Rightarrow P true?
```

[true \Rightarrow true, false \Rightarrow _]

- Show that for all instances of $x \in X$ s.t. R(x), P(x) holds.
- Show that for all instances of $x \in X$ it is the case $\neg R(x)$.
- **2.** How to prove $(\forall X \bullet R \Rightarrow P)$ **false**?
 - **Hint.** When is $R \Rightarrow P$ **false**?

[$true \Rightarrow false$]

• Give a *witness/counterexample* of $x \in X$ s.t. R(x), $\neg P(x)$ holds.



Predicate Logic (2.2): Existential Q. (∃)

- An existential quantification has the form $(\exists X \bullet R \land P)$
 - X is a comma-separated list of variable names
 - R is a constraint on types/ranges of the listed variables
 - P is a property to be satisfied
- There exist (a combination of) values of variables listed in X that satisfy both R and P.

```
\circ \exists i \bullet i \in \mathbb{N} \land i > 0
\circ \exists i \bullet i \in \mathbb{Z} \land i > 0
\circ \exists i, j \bullet i \in \mathbb{Z} \land j \in \mathbb{Z} \land (i < j \lor i > j)
```

[true] [true]

[true]

- Proof Strategies
 - **1.** How to prove $(\exists X \bullet R \land P)$ *true*?
 - Hint. When is B ∧ P true?

[true \(\) true \(\)

- Give a **witness** of $x \in X$ s.t. R(x), P(x) holds.
- **2.** How to prove $(\exists X \bullet R \land P)$ *false*?
 - Hint. When is R ∧ P false?

[true \land false, false \land _]

- Show that for all instances of $x \in X$ s.t. R(x), $\neg P(x)$ holds.
- Show that for all instances of $x \in X$ it is the case $\neg R(x)$.





- Prove or disprove: $\forall x \bullet (x \in \mathbb{Z} \land 1 \le x \le 10) \Rightarrow x > 0$. All 10 integers between 1 and 10 are greater than 0.
- Prove or disprove: $\forall x \bullet (x \in \mathbb{Z} \land 1 \le x \le 10) \Rightarrow x > 1$. Integer 1 (a witness/counterexample) in the range between 1 and 10 is *not* greater than 1.
- Prove or disprove: ∃x (x ∈ Z ∧ 1 ≤ x ≤ 10) ∧ x > 1.
 Integer 2 (a witness) in the range between 1 and 10 is greater than 1.
- Prove or disprove that ∃x (x ∈ Z ∧ 1 ≤ x ≤ 10) ∧ x > 10?
 All integers in the range between 1 and 10 are not greater than 10.

Conversions between ∀ and ∃:

$$(\forall X \bullet R \Rightarrow P) \iff \neg(\exists X \bullet R \land \neg P)$$
$$(\exists X \bullet R \land P) \iff \neg(\forall X \bullet R \Rightarrow \neg P)$$



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Verification by Model Checking



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Motivation for Formal Verification

- Safety-Critical Systems

 e.g., shutdown system of a nuclear power plant
- Mission-Critical Systems

 e.g., mass-produced computer chips
- Formal verification of the correctness of critical systems can prevent loss of fortune or even lives.
- · Formal verification consists of:
 - 1. Systems:

Need a **specification** language for modelling <u>abstractions</u>.

- Properties: Need a specification language for expressing (e.g., safety, temporal) concerns.
- Verification: Need a systematic method for establishing that a system satisfies the desired properties.
- The earlier errors are caught in the course of system development, the cheaper it is to rectify.
 - e.g., Much cheaper to catch an error in the <u>design</u> phase than recalling defected products after <u>release</u>.

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Example of Formal Verification



Pentium FDIV bug: https://en.wikipedia.org/wiki/Pentium_FDIV_bug

The Pentium FDIV bug is a hardware bug affecting the **floating-point unit (FPU)** of the early Intel Pentium processors. Because of the bug, the processor would return incorrect binary floating point results when dividing certain pairs of high-precision numbers.

In December 1994, Intel recalled the defective processors ... In its 1994 annual report, Intel said it incurred "a \$475 million pre-tax charge ... to recover replacement and write-off of these microprocessors."

In the aftermath of the bug and subsequent recall, there was a marked increase in the use of formal verification of hardware floating point operations across the semiconductor industry. Prompted by the discovery of the bug, a technique ... called "word-level model checking" was developed in 1996. Intel went on to use formal verification extensively in the development of later CPU architectures. In the development of the Pentium 4, symbolic trajectory evaluation and theorem proving were used to find a number of bugs that could have led to a similar recall incident had they gone undetected.



Classification of Verification Methods

- Degree of Automation: Automatic, Interactive, or Manual
- ModelCheck-based vs. Proof-based
 - Proof-based:
 - The system (abstractly) described as a set of formulas Γ
 - **Properties** specified as a set of formulas ϕ
 - **Prove** (automatically or interactively) that $\Gamma \vdash \phi$ [undecidable] i.e., Γ can be derived to ϕ (via inference rules).
 - Check-based:
 - The system (abstractly) described as a finite model M
 - **Properties** specified as a set of formulas ϕ
 - **Decide** (automatically) that $\mathbb{M} \models \phi$ [decidable, algorithmic] i.e., Traversing \mathbb{M} 's **state/reachability graph** decides if ϕ is satisfied.
- Domain of Application
 - Hardware vs. Software
 - Sequential vs. Concurrent
 - Reactive (e.g., bridge controller) vs. Terminating (e.g., sorting alg.)
- · Pre-development vs. Post-development



Verification via Model Checking

- · Automatic, Check-based
- Intended for *reactive*, *concurrent* systems
 - Reactivity:
 - **Continuous** reaction to stimuli from the environment e.g., communication protocols, operating systems, embedded systems, etc.
 - Concurrency:
 Simultaneous execution of (independent or inter-dependent)
 system units, each of which evolving its own states
- Testing of concurrent, reactive systems is <u>hard</u>:
 - Many scenarios are non-reproducible.
 - Hard to systematically cover all important interactions
 - E. W. Dijkstra: Program testing can be used to show the presence of bugs, but never to show their <u>absence!</u>
- Originated as a post-development method
- But should be used as pre-development method to save cost





System

- A system model M is a *labeled transition system (LTS)* with a (large) number of states and transitions between states.
- A model of an actual physical system abstracts away details that are <u>irrelevant</u> to the properties to be checked.

Properties

- Temporal logic (TL) incorporates the notion of timing.
- A TL formula ϕ is **not** statically true or false.
- Instead, the truth of a TL formula ϕ depends on where the SUV **dynamically** evolves into (by following transitions).

Verification

- A computer program, called a *model checker*, takes as inputs M and ϕ , and <u>decides</u> if $\mathbb{M} \models \phi$
 - **Yes** \Rightarrow All *reachable* states of M satisfy ϕ .
 - No ⇒ An error trace, leading to a state satisfying ¬φ, is generated.
 This facilitates debugging through reproducing a problematic scenario.
 - **Unknown** ⇒ The checker runs out of memory due to **state explosion**.





- LTL (<u>Linear-time Temoral Logic</u>) has connectives/operators which allow us to refer to the *future*.
- Two features of *LTL*:
 - (Computation) Path:
 Time is modelled as an infinite sequence of states.
 - Undetermined Future:
 Alternative paths exist, one of which being the "actual" path.



LTL: Syntax in CFG (1)

```
[ true ]
                                              [ false ]
                         propositional atom
                            [logical negation
                        [logical conjunction]
                         logical disjunction
                         logical implication
(\mathbf{X}\phi)
                                     [neXt state]
(\mathbf{F}\phi)
                           some Future state
(\mathbf{G}\phi)
          [all future states (Globally)
(\phi \mathbf{U} \phi)
                                            [Until
(\phi \mathbf{W} \phi)
                                     Weak-until
(\phi \mathbf{R} \phi)
                                         [Release]
```

p denotes **atomic**, propositional statements

- e.g., Printer 1tr2 is available.
- e.g., Reading of sensor s3 exceeds some threshold.
- e.g., The sudoku board is filled out with a correct solution.



LTL: Syntax in CFG (2)

```
[ true ]
                                               false
                          [propositional atom
                            [logical negation]
                        [logical conjunction]
                         logical disjunction
(\phi \Rightarrow \phi)
                         logical implication
(\mathbf{X}\phi)
                                     [neXt state]
(\mathbf{F}\phi)
                           [some Future state]
          [ all future states (Globally)
(\phi \mathbf{U} \phi)
                                             [Until]
(\phi \mathbf{W} \phi)
                                      [Weak-until]
(\phi \mathbf{R} \phi)
                                          [Release]
```

∀ and ∃ are embedded in defining the *temporal* connectives.

<u>Universe of disclosure</u>: Set of alternative (computation) *paths*



LTL: Syntax in CFG (3)

```
[ true ]
                                             [ false ]
                        propositional atom
                           [logical negation]
                       [logical conjunction]
                        logical disjunction
                        logical implication
(\mathbf{X}\phi)
                                    [neXt state]
(\mathbf{F}\phi)
                          some Future state
          [all future states (Globally)
(\phi \mathbf{U} \phi)
                                           [Until]
(\phi \mathbf{W} \phi)
                                    Weak-until
(\phi \mathbf{R} \phi)
                                        [Release]
```

- Temporal connectives bind <u>tighter</u> than logical ones.
- <u>Unary</u> *temporal* connectives bind <u>tighter</u> than <u>binary</u> ones.
 - Use <u>parentheses</u> to force the intended order of evaluation.
- Use a parse tree, a LMD, or a RMD to verify the order of evaluation.



LTL: Symbols of Unary Temporal Operators LASSONDE

Temporal Connective	Letter	Symbol
Next	X	0
Future/Eventually	F	\Diamond
Global/Henceforth	G	



Practical Knowledge about Parsing

- A context-free grammar (CFG) g
 - defines, <u>recursively</u>, all (typically an <u>infinite</u> number of) possible strings that can be <u>derived</u> from it.
 - contains both terminals/tokens (base cases) and non-terminals/variables (recursive cases)
- Given an input string s, to show that $s \in L(g)$, we can either:
 - **<u>Draw</u>** a *parse tree (PT)* of *s*, based on *g*, where:
 - All *internal nodes* (i.e., roots of subtrees) are ϕ (non-terminals).
 - All *external nodes* (a.k.a. leaves) are characters of s.
 - <u>Perform</u> a *left-most derivation (LMD)*, by starting with φ (the *start variable*) and continuing to substitute the <u>leftmost</u> non-terminal, until **no** non-terminals remain.
 - **Perform** a *right-most derivation (RMD)*, by starting with ϕ (the *start variable*) and continuing to substitute the <u>rightmost</u> non-terminal, until **no** non-terminals remain.
- PTs, LMDs, and RMDs are legitimate, and equivalent, ways for showing interpretations of a valid LTL formula string.



LTL: Exercises on Parsing Formulas

Draw and compare the parse trees of:

F
$$p \wedge \mathbf{G}$$
 $q \Rightarrow p\mathbf{U}r$
vs. F $(p \wedge \mathbf{G}$ $q \Rightarrow p\mathbf{U}r)$
vs. F $p \wedge (\mathbf{G}$ $q \Rightarrow p\mathbf{U}r)$
vs. F $p \wedge ((\mathbf{G}$ $q \Rightarrow p)\mathbf{U}r)$

- The above formulas are all derivable from the grammar of LTL.
 - Show using the LMD (<u>Left</u>-Most Derivations)
 - Show using the RMD (Right-Most Derivations)



LTL Formulas: More Exercises

Draw the *parser trees* for:

$$(\mathbf{F}(p \Rightarrow \mathbf{G} r) \lor ((\neg q) \mathbf{U} p))$$

vs.
$$\mathbf{F}p \Rightarrow \mathbf{G}r \vee \neg q\mathbf{U}p$$

vs.
$$\mathbf{F}(\ (p \Rightarrow \mathbf{G} \, r) \lor (\neg q \, \mathbf{U} \, p)\)$$

LTL Formulas: Subformulas



Given an LTL formula ϕ , its **subformulas** are all those whose **parse trees** (**rooted at** ϕ) are subtrees of ϕ 's parse tree.

```
e.g., Enumerate all subformula of (\mathbf{F}(p \Rightarrow \mathbf{G} r) \lor ((\neg q) \mathbf{U} p)).
```

1. p

[appearing twice in the parse tree]

- **2.** r
- 3. G r
- 4. $p \Rightarrow (\mathbf{G} r)$
- 5. $F(p \Rightarrow (Gr))$
- **6.** q
- **7.** ¬*a*
- **8.** *p*
- **9.** $(\neg q) \, \mathbf{U} \, p$
- **10.** $(F(p \Rightarrow Gr) \lor ((\neg q)Up))$



LTL Semantics: Labelled Transition Systems (LTS)

- Definition. Given that P is a set of atoms/propositions of concern, a transition system M is a formal model represented as a triple M = (S, →, L):
 - S

A finite set of states

$$\circ \longrightarrow : S \leftrightarrow S$$

A transition relation on S

$$\circ$$
 $L: S \to \mathbb{P}(P)$

A *labelling function* mapping each <u>state</u> to its <u>satisfying atoms</u>

Assumption. No state of the system can *deadlock*:

From any state, it's always possible to make progress (by taking a transition).

$$\forall s \bullet s \in S \Rightarrow (\exists s' \bullet s' \in S \land (s, s') \in \longrightarrow)$$

Background for Self-Study



- Topics of sets and relations were covered in EECS3342.
- Slide 18 to Slide 28 contain what you should recall.

Set of Tuples



Given n sets S_1 , S_2 , ..., S_n , a *cross/Cartesian product* of theses sets is a set of n-tuples.

Each n-tuple $(e_1, e_2, ..., e_n)$ contains n elements, each of which a member of the corresponding set.

$$S_1 \times S_2 \times \cdots \times S_n = \{ \left(e_1, e_2, \dots, e_n \right) \mid e_i \in S_i \land 1 \leq i \leq n \}$$

e.g., $\{a,b\} \times \{2,4\} \times \{\$,\&\}$ is a set of triples:



Relations (1): Constructing a Relation

A <u>relation</u> is a set of mappings, each being an **ordered pair** that maps a member of set S to a member of set T.

e.g., Say
$$S = \{1, 2, 3\}$$
 and $T = \{a, b\}$

- $\circ \varnothing$ is the *minimum* relation (i.e., an empty relation).
- $S \times T$ is the *maximum* relation (say r_1) between S and T, mapping from each member of S to each member in T:

$$\{(1,a),(1,b),(2,a),(2,b),(3,a),(3,b)\}$$

∘ $\{(x,y) \mid (x,y) \in S \times T \land x \neq 1\}$ is a relation (say r_2) that maps only some members in S to every member in T:

$$\{(2,a),(2,b),(3,a),(3,b)\}$$



Relations (2.1): Set of Possible Relations

We use the *power set* operator to express the set of *all possible relations* on S and T:

$$\mathbb{P}(S \times T)$$

Each member in $\mathbb{P}(S \times T)$ is a relation.

 To declare a relation variable r, we use the colon (:) symbol to mean set membership:

$$r: \mathbb{P}(S \times T)$$

Or alternatively, we write:

$$r: S \leftrightarrow T$$

where the set $S \leftrightarrow T$ is synonymous to the set $\mathbb{P}(S \times T)$

Relations (2.2): Exercise



Enumerate $\{a,b\} \leftrightarrow \{1,2,3\}$.

- Hints:
 - You may enumerate all relations in $\mathbb{P}(\{a,b\} \times \{1,2,3\})$ via their cardinalities: $0, 1, \ldots, |\{a,b\} \times \{1,2,3\}|$.
 - What's the *maximum* relation in $\mathbb{P}(\{a,b\} \times \{1,2,3\})$? $\{(a,1),(a,2),(a,3),(b,1),(b,2),(b,3)\}$
- The answer is a set containing <u>all</u> of the following relations:
 - Relation with cardinality 0: Ø
 - How many relations with cardinality 1? $[(|\{a,b\} \times \{1,2,3\}|) = 6]$
 - How many relations with cardinality 2? $\left[{|\{a,b\} \times \{1,2,3\}| \choose 2} = \frac{6 \times 5}{2!} = 15 \right]$

. . .

• Relation with cardinality $|\{a,b\} \times \{1,2,3\}|$:

$$\{(a,1),(a,2),(a,3),(b,1),(b,2),(b,3)\}$$



Relations (3.1): Domain, Range, Inverse

Given a relation

$$r = \{(a, 1), (b, 2), (c, 3), (a, 4), (b, 5), (c, 6), (d, 1), (e, 2), (f, 3)\}$$

- domain of r : set of first-elements from r
 - Definition: $dom(r) = \{ d \mid (d, r') \in r \}$
 - e.g., $dom(r) = \{a, b, c, d, e, f\}$
- range of r : set of second-elements from r
 - Definition: $ran(r) = \{ r' \mid (d, r') \in r \}$
 - \circ e.g., ran(r) = {1,2,3,4,5,6}
- *inverse* of r: a relation like r with elements swapped
 - Definition: $r^{-1} = \{ (r', d) \mid (d, r') \in r \}$
 - e.g., $r^{-1} = \{(1,a), (2,b), (3,c), (4,a), (5,b), (6,c), (1,d), (2,e), (3,f)\}$

Relations (3.2): Image

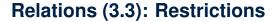


Given a relation

$$r = \{(a, 1), (b, 2), (c, 3), (a, 4), (b, 5), (c, 6), (d, 1), (e, 2), (f, 3)\}$$

relational image of r over set s: sub-range of r mapped by s.

- Definition: $r[s] = \{ r' \mid (d, r') \in r \land d \in s \}$
- e.g., $r[{a,b}] = {1,2,4,5}$

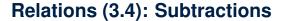




Given a relation

$$r = \{(a, 1), (b, 2), (c, 3), (a, 4), (b, 5), (c, 6), (d, 1), (e, 2), (f, 3)\}$$

- domain restriction of r over set ds: sub-relation of r with domain ds.
 - Definition: $ds \triangleleft r = \{ (d, r') \mid (d, r') \in r \land d \in ds \}$
 - e.g., $\{a,b\} \triangleleft r = \{(\mathbf{a},1), (\mathbf{b},2), (\mathbf{a},4), (\mathbf{b},5)\}$
- range restriction of r over set rs: sub-relation of r with range rs.
 - Definition: $r \triangleright rs = \{ (d, r') \mid (d, r') \in r \land r' \in rs \}$
 - e.g., $r \rhd \{1,2\} = \{(a,1),(b,2),(d,1),(e,2)\}$





Given a relation

$$r = \{(a, 1), (b, 2), (c, 3), (a, 4), (b, 5), (c, 6), (d, 1), (e, 2), (f, 3)\}$$

- **domain subtraction** of r over set ds: sub-relation of r with domain <u>not</u> ds.
 - Definition: $ds \triangleleft r = \{ (d, r') \mid (d, r') \in r \land d \notin ds \}$
 - e.g., $\{a,b\} \le r = \{(\mathbf{c},3), (\mathbf{c},6), (\mathbf{d},1), (\mathbf{e},2), (\mathbf{f},3)\}$
- range subtraction of r over set rs: sub-relation of r with range not rs.
 - Definition: $r \triangleright rs = \{ (d, r') \mid (d, r') \in r \land r' \notin rs \}$
 - e.g., $r \triangleright \{1,2\} = \{(c,3),(a,4),(b,5),(c,6),(f,3)\}$



Functions (1): Functional Property

• A *relation* r on sets S and T (i.e., $r \in S \leftrightarrow T$) is also a *function* if it satisfies the *functional property*:

```
isFunctional(r) \iff \forall s, t_1, t_2 \bullet (s \in S \land t_1 \in T \land t_2 \in T) \Rightarrow ((s, t_1) \in r \land (s, t_2) \in r \Rightarrow t_1 = t_2)
```

- That is, in a *function*, it is <u>forbidden</u> for a member of S to map to <u>more than one</u> members of T.
- Equivalently, in a *function*, two <u>distinct</u> members of *T* <u>cannot</u> be mapped by the <u>same</u> member of *S*.
- e.g., Say S = {1,2,3} and T = {a,b}, which of the following relations satisfy the above functional property?
 - $\begin{array}{ll} \circ & S \times T & [\text{No}\,] \\ & \underline{\textit{Witness}}\, 1 \colon (1,a), (1,b); \, \underline{\textit{Witness}}\, 2 \colon (2,a), (2,b); \, \underline{\textit{Witness}}\, 3 \colon (3,a), (3,b). \\ \circ & (S \times T) \setminus \{(x,y) \mid (x,y) \in S \times T \land x = 1\} & [\text{No}\,] \\ & \underline{\textit{Witness}}\, 1 \colon (2,a), (2,b); \, \underline{\textit{Witness}}\, 2 \colon (3,a), (3,b) \\ \circ & \{(1,a), (2,b), (3,a)\} & [\text{Yes}\,] \\ \circ & \{(1,a), (2,b)\} & [\text{Yes}\,] \end{array}$



Functions (2.1): Total vs. Partial

Given a **relation** $r \in S \leftrightarrow T$

• r is a partial function if it satisfies the functional property:

$$r \in S \nrightarrow T \iff (isFunctional(r) \land dom(r) \subseteq S)$$

Remark. $r \in S \Rightarrow T$ means there **may (or may not) be** $s \in S$ s.t. r(s) is **undefined** (i.e., $r(s) = \emptyset$).

∘ e.g.,
$$\{\{(\mathbf{2},a),(\mathbf{1},b)\},\{(\mathbf{2},a),(\mathbf{3},a),(\mathbf{1},b)\}\}$$
 ⊆ $\{1,2,3\}$ \Rightarrow $\{a,b\}$

r is a total function if there is a mapping for each s ∈ S:

$$r \in S \rightarrow T \iff (isFunctional(r) \land dom(r) = S)$$

Remark. $r \in S \rightarrow T$ implies $r \in S \rightarrow T$, but <u>not</u> vice versa. Why?

∘ e.g.,
$$\{(\mathbf{2}, a), (\mathbf{3}, a), (\mathbf{1}, b)\} \in \{1, 2, 3\} \rightarrow \{a, b\}$$

∘ e.g.,
$$\{(\mathbf{2}, a), (\mathbf{1}, b)\} \notin \{1, 2, 3\} \rightarrow \{a, b\}$$



Functions (2.2):

Relation Image vs. Function Application

- Recall: A function is a relation, but a relation is not necessarily a function.
- Say we have a *partial function* $f \in \{1,2,3\} \Rightarrow \{a,b\}$:

$$f = \{(\mathbf{3}, a), (\mathbf{1}, b)\}$$

With f wearing the relation hat, we can invoke relational images:

$$f[{3}] = {a}$$

 $f[{1}] = {b}$
 $f[{2}] = \emptyset$

Remark. $\Rightarrow |f[\{v\}]| \le 1$:

- each member in dom(f) is mapped to <u>at most one</u> member in ran(f)
- each input set {v} is a <u>singleton</u> set
- With f wearing the function hat, we can invoke functional applications:

$$f(3) = a$$

 $f(1) = b$
 $f(2)$ is undefined

LTL Semantics: Example of LTS



- We may visual a transition system M using a directed graph:
 - Nodes/Vertices denote states.
 - Edges/Arcs denote *transitions*.
- **Exercises** Consider the system with a counter *c* with the following assumption:

$$0 \le c \le 3$$

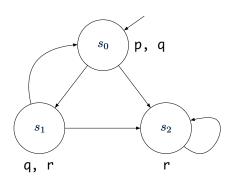
Say c is initialized 0 and may be incremented (via a transition *inc*, enabled when c < 3) or decremented (via a transition *dec*, enabled when c > 0).

- <u>Draw</u> a state graph of this system.
- **Formulate** the state graph as an *LTS* (via a triple (S, \longrightarrow, L)).

```
Assume: Set P of atoms is: \{c \ge 1, c \le 1\}
```



LTL Semantics: More Example of LTS



$$\mathbb{M} = (S, \longrightarrow, L):
\circ S = \{s_0, s_1, s_2\}
\circ \longrightarrow = \{(s_0, s_1), (s_0, s_2), (s_1, s_0), (s_1, s_2), (s_2, s_2)\}
\circ L = \{(s_0, \{p, q\}), (s_1, \{q, r\}), (s_2, \{r\})\}$$

LTL Semantics: Paths



<u>Definition</u>. A *path* in a model $\mathbb{M} = (S, \longrightarrow, L)$ is an <u>infinite</u> sequence of states $s_i \in S$, where $i \ge 1$, such that $s_i \longrightarrow s_{i+1}$.

• We write the path, starting at the *initial state* s_1 , as

$$s_1 \longrightarrow s_2 \longrightarrow \dots$$

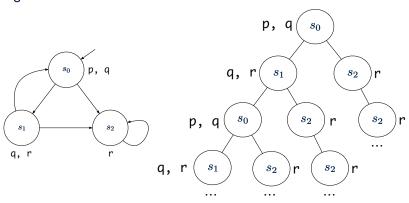
- <u>Note.</u> s₁ in the above path pattern denotes the first, initial state of the path, but in general, the actual name of the initial state may cause confusion, e.g., s₀.
- A path $\pi = s_1 \longrightarrow s_2 \longrightarrow \dots$ represents a possible future of M.
- We write π^i for the **suffix** of path π : a path starting from state s_i . e.g., $\pi^3 = s_3 \longrightarrow s_4 \longrightarrow \dots$

e.g.,
$$\pi^1 = \pi$$



LTL Semantics: All Possible Paths

Given a state *s*, we represent <u>all</u> possible *(computation)*paths as a computation tree by unwinding the transitions.
e.g.





LTL Semantics: Path Satisfaction (1)

<u>Definition</u>. Given a *model* $\mathbb{M} = (S, \longrightarrow, L)$ and a *path* $\pi = s_1 \longrightarrow \ldots$ in \mathbb{M} , whether or not path π satisfies an *LTL formula* is defined by the *satisfaction relation* \models as follows:

$$\pi \models p \iff p \in L(s_1)$$

$$\pi \models T$$

$$\pi \not\models \bot$$

$$\pi \models \neg \phi \iff \neg(\pi \models \phi)$$

$$\pi \models \phi_1 \land \phi_2 \iff \pi \models \phi_1 \land \pi \models \phi_2$$

$$\pi \models \phi_1 \lor \phi_2 \iff \pi \models \phi_1 \lor \pi \models \phi_2$$

$$\pi \models \phi_1 \Rightarrow \phi_2 \iff \pi \models \phi_1 \Rightarrow \pi \models \phi_2$$

<u>Tips.</u> To evaluate $\pi \models \phi_1 \land \phi_2$ (and similarly for \neg , \lor , \Rightarrow):

- If ϕ_1 and ϕ_2 are sophisticated, decompose it to $\pi \vDash \phi_1$ and $\pi \vDash \phi_2$.
- Otherwise, directly evaluate $\phi_1 \wedge \phi_2$ on s_1 .



LTL Semantics: Path Satisfaction (2.1)

<u>Definition.</u> Given a *model* $\mathbb{M} = (S, \longrightarrow, L)$ and a *path* $\pi = s_1 \longrightarrow \dots$ in \mathbb{M} , whether or not path π satisfies an *LTL formula* is defined by the *satisfaction relation* \models as follows:

$$\pi \models \mathbf{X}\phi \iff \pi^2 \models \phi
\pi \models \mathbf{G}\phi \iff (\forall i \bullet i \ge 1 \Rightarrow \pi^i \models \phi)
\pi \models \mathbf{F}\phi \iff (\exists i \bullet i \ge 1 \land \pi^i \models \phi)$$



LTL Semantics: Model Satisfaction (1)

- Definition. Given:
 - \circ a model $\mathbb{M} = (S, \longrightarrow, L)$
 - a state s ∈ S
 - o an LTL formula

 $\mathbb{M}, s \models \phi \mid \underline{\text{if and only if}} \text{ for every path } \pi \text{ of } \mathbb{M} \text{ starting at } s, \pi \models \phi.$

$$\mathbb{M}, S \vDash \phi \iff (\forall \pi \bullet (\pi = S \longrightarrow \dots) \Rightarrow \pi \vDash \phi)$$

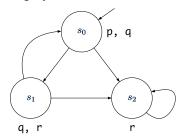
• When the model M is clear from the context, we write: $|s| = \phi$.



LASSONDE

LTL Semantics: Model Satisfaction (2.1)

Consider the following system model:



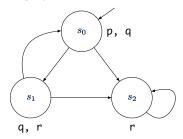
- \circ $s_0 \models T$
- *s*₀ ⊭ ⊥
- ∘ $s_0 \models p \land q$
- \circ $s_0 \models r$

[true] [true] [true] [false]



LTL Semantics: Model Satisfaction (2.2)

Consider the following system model:



$$\circ$$
 $s_0 \models \mathbf{X} r$

$$\circ$$
 $s_0 \models \mathbf{X}(q \land r)$

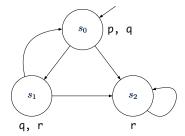
Witness Path:
$$s_0 \longrightarrow s_2 \cdots \not\models \mathbf{X}(q \land r)$$

$$\circ$$
 $s_0 \models \mathbf{X}(q \Rightarrow r)$

LASSONDE

LTL Semantics: Model Satisfaction (2.3)

Consider the following system model:



•
$$s_0 \models \mathbf{G} \neg (p \land r)$$

 $s \models \mathbf{G} \phi \iff \phi \text{ holds on all } \mathbf{reachable} \text{ states from } s.$

• $s_0 \models \mathbf{G} r$

$$\underline{\text{Witness Path}}: \boxed{s_0} \longrightarrow s_2 \longrightarrow s_2 \cdots \notin \mathbf{G} r$$

$$\circ$$
 $s_2 \models \mathbf{G} r$

[true]

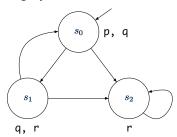
[false]

[true]



LTL Semantics: Model Satisfaction (2.4)

Consider the following system model:



$$\circ \ \mathbf{s}_0 \models \mathbf{F} \neg (p \land r)$$

[true]

$$\circ$$
 $s_0 \models \mathbf{F} r$

[true]

$$\circ$$
 $s_0 \models \mathbf{F}(q \land r)$

[false]

- Is is the case that $q \wedge r$ is eventually satisfied on every path?
- No. Witness Path: $s_0 \longrightarrow s_2 \longrightarrow s_2 \longrightarrow \dots$

$$\circ$$
 $s_2 \models \mathbf{F} r$

[true]



LTL Semantics: Nested G and F (1)

Given a model $\mathbb{M} = (S, \longrightarrow, L)$ and a state $s \in S$:

 $s \models \mathbf{F} \mathbf{G} \phi$ means that:

- <u>Each</u> path starting with s is such that <u>eventually</u>, φ holds <u>continuously</u>.
- For <u>all</u> paths π starting with s (i.e., $\pi = s \longrightarrow 1 \dots$):

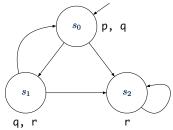
$$\exists i \bullet i \ge 1 \land (\forall j \bullet j \ge i \Rightarrow \pi^i \vDash \phi)$$

- Q. How to prove and disprove the above formula pattern?
- **Hint.** Structure of pattern: $\forall \pi \bullet ... \Rightarrow (\exists i \bullet \cdots \land (\forall j \bullet ... \Rightarrow \phi))$



LTL Semantics: Model Satisfaction (2.5.1)

Consider the following system model:



$$\circ s_0 \models \mathbf{FG} r$$
 [false]

$$\underline{\text{Witness}} : s_0 \longrightarrow s_1 \longrightarrow s_0 \longrightarrow s_1 \longrightarrow \dots$$

$$\circ \ s_0 \models \mathbf{FG}(p \lor q)$$

Witness:
$$s_0 \longrightarrow s_1 \longrightarrow s_2 \longrightarrow s_2 \longrightarrow \dots$$

• $s_0 \models \mathbf{FG}(p \lor r)$ [

<u>Justification</u>: All possible paths from s_0 involve s_0 , s_1 , and s_2 , all of which satisfying $p \lor r$.



LTL Semantics: Nested G and F (2)

Given a model $\mathbb{M} = (S, \longrightarrow, L)$ and a state $s \in S$:

 $s \models \mathbf{F}\phi_1 \Rightarrow \mathbf{F}\mathbf{G}\phi_2$ means that:

Each path π starting with s is such that
if φ₁ eventually holds on π, then φ₂ eventually holds continuously
on the same π.

$$\forall \pi \bullet \pi = S \longrightarrow \dots \Rightarrow$$

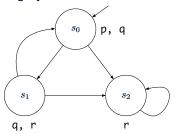
$$\begin{pmatrix} (\exists i \bullet i \ge 1 \land \pi^i \models \phi_1) \\ \Rightarrow \\ (\exists i \bullet i \ge 1 \land (\forall j \bullet j \ge i \Rightarrow \pi^i \models \phi_2)) \end{pmatrix}$$

- Q. How to *disprove* the above formula pattern?
- A. Find a <u>witness</u> path π which makes the "inner" implication *false*.



LTL Semantics: Model Satisfaction (2.5.2)

Consider the following system model:



∘
$$s_0 \models \mathbf{F}(\neg q \land r) \Rightarrow \mathbf{F} \mathbf{G} r$$

Justification:

[true]

- $s_0 \longrightarrow s_1 \longrightarrow s_0 \longrightarrow \dots$ never satisfies $\neg q \land r$.
- $s_0 \longrightarrow s_1 \longrightarrow s_2 \longrightarrow s_2 \longrightarrow \dots$ <u>eventually</u> satisfies $\neg q \land r$ <u>continuously</u>.
- $s_0 \longrightarrow s_2 \longrightarrow s_2 \longrightarrow \dots$ eventually satisfies $\neg q \land r$ continuously.

∘
$$s_0 \models \mathbf{F}(\neg q \lor r) \Rightarrow \mathbf{FG} r$$
 [*false*]
 Witness: $s_0 \longrightarrow s_1 \longrightarrow s_0 \longrightarrow \dots$ eventually satisfies $\neg q \lor r$, but there is no point in this path where r holds continuously.



LTL Semantics: Nested G and F (3)

Given a model $\mathbb{M} = (S, \longrightarrow, L)$ and a state $s \in S$:

- $s = GF\phi$ means that:
 - Each path starting with s is such that continuously, φ holds eventually.
 - $\Rightarrow \phi$ holds *infinitely often*!
 - For <u>all</u> paths π starting with s (i.e., $\pi = s \longrightarrow 1 \dots$):

$$\forall i \bullet i \ge 1 \Rightarrow \left(\exists j \bullet j \ge i \land \pi^i \vDash \phi\right)$$

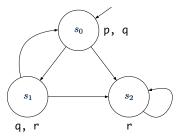
- Q. How to prove and disprove the above formula pattern?
- **Hint.** Structure of pattern: $\forall \pi \bullet ... \Rightarrow (\forall i \bullet ... \Rightarrow (\exists j \bullet ... \land \phi))$



[true]

LTL Semantics: Model Satisfaction (2.6)

Consider the following system model:



○
$$s_0 \models \mathbf{GF}p$$
 [false]
Witness: In $s_0 \longrightarrow s_2 \longrightarrow ..., p$ is not satisfied **infinitely often**.
○ $s_0 \models \mathbf{GF}(p \lor r)$ [true]

∘ $s_0 \models \mathbf{GF}p \Rightarrow \mathbf{GF}r$ Hint: Consider paths making the antecedent $\mathbf{GF}p$ *true*.

•
$$s_0 \models \mathbf{GF} p$$
 [false] Witness: $s_0 \rightarrow s_2 \rightarrow \dots$



LTL Semantics: Path Satisfaction (2.2)

<u>Definition</u>. Given a *model* $\mathbb{M} = (S, \longrightarrow, L)$ and a *path* $\pi = s_1 \longrightarrow \dots$ in \mathbb{M} , whether or not path π satisfies an *LTL formula* is defined by the *satisfaction relation* \models as follows:

$$\begin{array}{lll} \pi & \vDash & \phi_1 \, \mathbf{U} \, \phi_2 & \iff & \left(\begin{array}{c} \exists i \bullet i \geq 1 \, \wedge \left(\begin{array}{c} \pi^i \vDash \phi_2 \\ \wedge \\ (\forall j \bullet 1 \leq j \leq i-1 \ \Rightarrow \ \pi^j \vDash \phi_1) \end{array} \right) \right) \\ \\ \pi & \vDash & \phi_1 \, \mathbf{W} \, \phi_2 & \iff & \left(\begin{array}{c} \phi_1 \, \mathbf{U} \, \phi_2 \\ \vee & (\forall k \bullet k \geq 1 \Rightarrow \pi^k \vDash \phi_1) \end{array} \right) \\ \\ \pi & \vDash & \phi_1 \, \mathbf{R} \, \phi_2 & \iff & \left(\begin{array}{c} \left(\begin{array}{c} \pi^i \vDash \phi_1 \\ \wedge \\ (\forall j \bullet 1 \leq j \leq i \ \Rightarrow \ \pi^j \vDash \phi_2) \end{array} \right) \right) \right) \\ \\ \vee & \left(\forall k \bullet k \geq 1 \Rightarrow \pi^k \vDash \phi_2 \right) \end{array} \right) \end{array} \right)$$



LTL Semantics: Recall Model Satisfaction

- **Definition**. Given:
 - \circ a model $\mathbb{M} = (S, \longrightarrow, L)$
 - a state *s* ∈ *S*
 - ∘ an LTL formula *ϕ*

 $\mathbb{M}, s \models \phi$ if and only if for **every** path π of \mathbb{M} starting at $s, \pi \models \phi$.

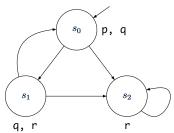
$$\mathbb{M}, S \vDash \phi \iff (\forall \pi \bullet (\pi = S \longrightarrow \dots) \Rightarrow \pi \vDash \phi)$$

• When the model \mathbb{M} is clear from the context, we write: $s \models \phi$.

LASSONDE

LTL Semantics: Model Satisfaction (3.1)

Consider the following system model:

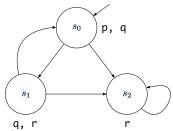


- $s_0 = p \mathbf{U} r$ [true] s_0 (satisfying p) branches out to s_1 or s_2 (both both satisfying r).
- $\circ s_0 = p \mathbf{W} r$ [true] $\phi_1 \mathbf{U} \phi_2 \Rightarrow \phi_1 \mathbf{W} \phi_2$
- $s_0 \models r \mathbf{R} p$ [false] Witness: Say $\pi = s_0 \longrightarrow s_1 \longrightarrow s_0 \longrightarrow s_1 \dots : \pi \not\models p \land r \text{ and } \pi \not\models \mathbf{G} p.$



LTL Semantics: Model Satisfaction (3.2)

Consider the following system model:



- $\circ \ s_0 \vDash (p \lor r) \ \mathbf{U}(p \land r)$
 - Witness: In $s_0 \longrightarrow s_1 \longrightarrow s_0 \longrightarrow s_1 \dots, p \land r$ never holds.
- $\circ \ \mathbf{s}_0 \vDash (p \lor r) \mathbf{W}(p \land r)$

[true]

[false]

It is the case that: $s_0 \models \mathbf{G}(p \lor r)$.

[true]

∘ $s_0 \vDash (p \land r) \mathbf{R}(p \lor r)$ It is the case that: $s_0 \vDash \mathbf{G}(p \lor r)$.

Clarification on the "Until" Connective



- $\phi_1 \mathbf{U} \phi_2$ requires that:
 - ϕ_2 must eventually become *true*.
 - Before ϕ_2 becomes **true**, ϕ_1 must hold.
- Exercise. Say:
 - Atom t: I was 22.
 - Atom s: I smoke.

Formulate "I had smoked until I was 22" using LTL.

o sUt

[inaccurate]

- $\phi_1 \cup \phi_2$ does not insist $\neg \phi_1$ after ϕ_2 eventually becomes *true*.
- "I smoked both before and after I was 22" satisfies s U t.
- Solution?

 $[s U(t \wedge (G \neg s))]$



Formulating English as LTL Formulas (1)

- Assume the following atomic propositions:
 busy, requested, acknowledged, enabled, floor2, floor5,
 directionUp, buttonPresssed5.
- It is impossible to reach a state where the system is started but not ready.
 - \circ **G** \neg (started $\land \neg$ ready) [\neg (**F**(started $\land \neg$ ready))]
- Whenever a request is made, it will be eventually be acknowledged.
 - G(requested ⇒ F acknowledged)
- A certain process will always be enabled.
 - G enabled
- An upwards travelling lift at the second floor does not change its direction when it has passengers wishing to go to the fifth floor.

$$\mathbf{G} \left(\begin{array}{c} \textit{floor2} \land \textit{directionUp} \land \textit{buttonPresssed5} \\ \Rightarrow (\ \textit{directionUp} \ \mathbf{U} \ \textit{floor5} \) \end{array} \right)$$

• Is it ok to change from U to W?



Formulating English as LTL Formulas (2)

Assume the following atomic propositions:

requested, waiting, granted, noOneInCS

Whenever a process makes a request, it starts waiting. As soon as no other process is in the critical section, the process is granted access to the critical section.

G (requested ⇒ (noOneInCS **R** waiting))

Q. Does the above formulation guarantee *no starvation*? **Hint.** Check the formal definition of **R**.



Formulating English as LTL Formulas (3)

Assume the following atomic propositions:

degReqFullfilled, allowedForGraduation

Until a student fullfils all their degree requirements, their academic staus remains "not allowed for graduation". The change of status, when qualified, may not be instantaneous to account for human/manual processing.

¬allowedForGraduation W (degReqFulfilled ∧ G allowedForGraduation)

Q. Does the above formulation account for situations where a student never fulfills their degree requirements?

Hint. Check the formal definition of W.

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Motivation for Formal Verification

Example of Formal Verification

Classification of Verification Methods

Verification via Model Checking

Model Checking: Temporal Logic

Linear-Time Temporal Logic (LTL)

LTL: Syntax in CFG (1)

LTL: Syntax in CFG (2)

LTL: Syntax in CFG (3)

LTL: Symbols of Unary Temporal Operators

Practical Knowledge about Parsing

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LTL: Exercises on Parsing Formulas

LTL Formulas: More Exercises

LTL Formulas: Subformulas

LTL Semantics:

Labelled Transition Systems (LTS)

Background for Self-Study

Set of Tuples

Relations (1): Constructing a Relation

Relations (2.1): Set of Possible Relations

Relations (2.2): Exercise

Relations (3.1): Domain, Range, Inverse

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Relations (3.2): Image

Relations (3.3): Restrictions

Relations (3.4): Subtractions

Functions (1): Functional Property

Functions (2.1): Total vs. Partial

Functions (2.2):

Relation Image vs. Function Application

LTL Semantics: Example of LTS

LTL Semantics: More Example of LTS

LTL Semantics: Paths

LTL Semantics: All Possible Paths



- LTL Semantics: Path Satisfaction (1)
- LTL Semantics: Path Satisfaction (2.1)
- LTL Semantics: Model Satisfaction (1)
- LTL Semantics: Model Satisfaction (2.1)
- LTL Semantics: Model Satisfaction (2.2)
- LTL Semantics: Model Satisfaction (2.3)
- LTL Semantics: Model Satisfaction (2.4)
- LTL Semantics: Nested G and F (1)
- LTL Semantics: Model Satisfaction (2.5.1)
- LTL Semantics: Nested G and F (2)
- LTL Semantics: Model Satisfaction (2.5.2)



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LTL Semantics: Nested G and F (3)

LTL Semantics: Model Satisfaction (2.6)

LTL Semantics: Path Satisfaction (2.2)

LTL Semantics: Recall Model Satisfaction

LTL Semantics: Model Satisfaction (3.1)

LTL Semantics: Model Satisfaction (3.2)

Clarification on the "Until" Connective

Formulating English as LTL Formulas (1)

Formulating English as LTL Formulas (2)

Formulating English as LTL Formulas (3)

Program Verification

Readings: Chapter 4 of LICS2



EECS4315 Z: Mission-Critical Systems Winter 2025

CHEN-WEI WANG

Learning Objectives



- 1. Motivating Examples: *Program Correctness*
- 2. Hoare Triple
- 3. Weakest Precondition (wp)
- 4. Rules of wp Calculus
- **5.** Contract of Loops (*invariant* vs. *variant*)
- 6. **Correctness Proofs** of Loops

LASSONDE

Assertions: Weak vs. Strong

- Describe each assertion as a set of satisfying value.
 - x > 3 has satisfying values $\{ x \mid x > 3 \} = \{ 4, 5, 6, 7, ... \}$ x > 4 has satisfying values $\{ x \mid x > 4 \} = \{ 5, 6, 7, ... \}$
- An assertion p is stronger than an assertion q if p's set of satisfying values is a subset of q's set of satisfying values.
 - Logically speaking, p being stronger than q (or, q being weaker than p) means $p \Rightarrow q$.
 - \circ e.g., $x > 4 \Rightarrow x > 3$
- What's the weakest assertion?

[TRUE]

What's the strongest assertion?

[FALSE]

- In System Specification:
 - A <u>weaker</u> invariant has more acceptable object states
 e.g., balance > 0 vs. balance > 100 as an invariant for ACCOUNT
 - A weaker precondition has more acceptable input values
 - A <u>weaker</u> postcondition has more acceptable output values

Assertions: Preconditions



Given preconditions P_1 and P_2 , we say that

 P_2 requires less than P_1 if

 P_2 is *less strict* on (thus *allowing more*) inputs than P_1 does.

$$\{ x \mid P_1(x) \} \subseteq \{ x \mid P_2(x) \}$$

More concisely:

$$P_1 \Rightarrow P_2$$

e.g., For command withdraw (amount: INTEGER),

 P_2 : amount ≥ 0 requires less than P_1 : amount > 0

What is the *precondition* that *requires the least*?

[true]

Assertions: Postconditions



Given postconditions or invariants Q_1 and Q_2 , we say that

 Q_2 ensures more than Q_1 if

 Q_2 is **stricter** on (thus **allowing less**) outputs than Q_1 does.

$$\{ x \mid Q_2(x) \} \subseteq \{ x \mid Q_1(x) \}$$

More concisely:

$$Q_2 \Rightarrow Q_1$$

e.g., For query q(i: INTEGER): BOOLEAN,

$$Q_2$$
: Result = $(i > 0) \land (i \mod 2 = 0)$ ensures more than

$$Q_1 : \mathbf{Result} = (i > 0) \lor (i \bmod 2 = 0)$$

What is the postcondition that ensures the most?

[false]





Is this algorithm correct?

```
--algorithm increment_by_9 {
 variable i;
   (* precondition *)
   assert | i > 3
   (* implementation *)
   i := i + 9;
   (* postcondition *)
   assert | i > 13
```

Q: Is i > 3 is too weak or too strong?

A: Too weak

 \therefore assertion i > 3 allows value 4 which would fail postcondition.





Is this algorithm correct?

```
--algorithm increment_by_9 {
 variable i;
   (* precondition *)
   assert | i > 5
   (* implementation *)
   i := i + 9:
   (* postcondition *)
   assert | i > 13
```

Q: Is i > 5 too weak or too strong?

A: Maybe too strong

 \therefore assertion i > 5 disallows 5 which would not fail postcondition.

Whether 5 should be allowed depends on the requirements.

Software Correctness



- Correctness is a *relative* notion: consistency of implementation with respect to specification.
 - ⇒ This assumes there is a specification!
- We introduce a formal and systematic way for formalizing a program **S** and its *specification* (pre-condition **Q** and post-condition R) as a Boolean predicate: $\{Q\}$ $\{R\}$
 - \circ e.g., $\{i > 3\}$ i := i + 9 $\{i > 13\}$
 - e.g., $\{i > 5\}$ i := i + 9 $\{i > 13\}$
 - If \(\big| \ \mathbb{Q} \) \(\mathbb{S} \) \(\big| \ \mathbb{Can} \) be proved TRUE, then the S is correct.
 - $e.\overline{g.}, \{i > 5\}$ $i := i + 9 \{i > 13\}$ can be proved TRUE.
 - If | {Q} s {R} | cannot be proved TRUE, then the S is incorrect. e.g., $\{i > 3\}$ i := i + 9 $\{i > 13\}$ cannot be proved TRUE.

Hoare Logic



- Consider a program S with precondition Q and postcondition R.
 - ∘ {Q} S {R} is a correctness predicate for program S
 - {Q} S {R} is TRUE if program S starts executing in a state satisfying the precondition Q, and then:
 - (a) The program S terminates.
 - **(b)** Given that program **S** terminates, then it terminates in a state satisfying the postcondition R.
- Separation of concerns
 - (a) requires a proof of *termination*.
 - **(b)** requires a proof of **partial** correctness.
 - Proofs of (a) + (b) imply **total** correctness.



Hoare Logic and Software Correctness

Consider the contract/specification view of an algorithm f (whose body of implementation is S) as a Hoare Triple:

```
\{Q\} S \{R\}
Q is the precondition of f.
S is the implementation of f.
R is the postcondition of f.

    {true} s {R}

      All input values are valid
                                                        [ Most-user friendly ]

    {false} S {R}

      All input values are invalid
                                                   [ Most useless for clients ]
• {Q} s {true}
      All output values are valid [ Most risky for clients; Easiest for suppliers ]

    {Q} s {false}

      All output values are invalid
                                             [ Most challenging coding task ]
{true} s {true}
      All inputs/outputs are valid (No specification) [Least informative]
```

Proof of Hoare Triple using wp



$$\{Q\} S \{R\} \equiv Q \Rightarrow wp(S,R)$$

- wp(S, R) is the weakest precondition for S to establish R.
 - If $Q \Rightarrow wp(S, \mathbb{R})$, then <u>any</u> execution started in a state satisfying Q will terminate in a state <u>satisfying</u> \mathbb{R} .
 - If $Q \neq wp(S, \mathbb{R})$, then <u>some</u> execution started in a state satisfying Q will terminate in a state violating \mathbb{R} .
- *S* can be:
- We will learn how to calculate the wp for the above programming constructs.



Denoting Pre- and Post-State Values

- In the *postcondition*, for a program variable *x*:
 - We write x_0 to denote its **pre-state** (old) value.
 - We write x to denote its post-state (new) value.
 Implicitly, in the precondition, all program variables have their pre-state values.

e.g.,
$$\{b_0 > a\}$$
 b := b - a $\{b = b_0 - a\}$

- · Notice that:
 - We may choose to write "b" rather than "b₀" in preconditions
 ∴ All variables are pre-state values in preconditions
 - We don't write "b₀" in program
 - : there might be <u>multiple</u> intermediate values of a variable due to **sequential** composition





$$wp(x := e, R) = R[x := e]$$

R[x := e] means to substitute all *free occurrences* of variable x in postcondition R by expression e.

wp Rule: Assignments (2)



Recall:

$$\{Q\} S \{R\} \equiv Q \Rightarrow wp(S,R)$$

How do we prove $\{Q\} \times = e\{R\}$?

$$\{Q\} \times := e \{R\} \iff Q \Rightarrow \underbrace{R[X := e]}_{wp(x := e, R)}$$



wp Rule: Assignments (3) Exercise

What is the weakest precondition for a program x := x + 1 to establish the postcondition $x > x_0$?

$$\{??\} \times := \times + 1 \{x > x_0\}$$

For the above Hoare triple to be **TRUE**, it must be that $?? \Rightarrow wp(x := x + 1, x > x_0)$.

$$wp(x := x + 1, x > x_0)$$
= { Rule of wp: Assignments }
 $x > x_0[x := x_0 + 1]$
= { Replacing x by $x_0 + 1$ }
 $x_0 + 1 > x_0$
= { 1 > 0 always true }
True

Any precondition is OK.

False is valid but not useful.



wp Rule: Assignments (4) Exercise

What is the weakest precondition for a program x := x + 1 to establish the postcondition x = 23?

$$\{??\} \times := \times + 1 \{x = 23\}$$

For the above Hoare triple to be *TRUE*, it must be that $?? \Rightarrow wp(x := x + 1, x = 23)$.

$$wp(x := x + 1, x = 23)$$
= { Rule of wp: Assignments }
 $x = 23[x := x_0 + 1]$
= { Replacing x by $x_0 + 1$ }
 $x_0 + 1 = 23$
= { arithmetic }
 $x_0 = 22$

Any precondition weaker than x = 22 is not OK.



wp Rule: Assignments (4) Revisit

Given
$$\{??\}n := n + 9\{n > 13\}$$
:

- n > 4 is the weakest precondition (wp) for the given implementation (n := n + 9) to start and establish the postcondition (n > 13).
- Any precondition that is equal to or stronger than the wp (n > 4) will result in a correct program.

e.g.,
$$\{n > 5\}n := n + 9\{n > 13\}$$
 can be proved **TRUE**.

 Any precondition that is weaker than the wp (n > 4) will result in an incorrect program.

e.g.,
$$\{n > 3\}n := n + 9\{n > 13\}$$
 cannot be proved **TRUE**.

Counterexample: n = 4 satisfies precondition n > 3 but the output n = 13 fails postcondition n > 13.





$$wp(if B then S_1 else S_2 end, R) = \begin{pmatrix} B \Rightarrow wp(S_1, R) \\ \land \\ \neg B \Rightarrow wp(S_2, R) \end{pmatrix}$$

The *wp* of an alternation is such that *all branches* are able to establish the postcondition *R*.



wp Rule: Alternations (2)

```
Recall: \{Q\} S \{R\} \equiv Q \Rightarrow wp(S, R)
```

How do we prove that $\{Q\}$ if B then S_1 else S_2 end $\{R\}$?

```
 \begin{cases} \mathcal{Q} \\ \text{if } & \mathsf{B} \text{ then} \\ & \left\{ \mathcal{Q} \wedge & \mathsf{B} \right\} \ S_1 \ \left\{ \mathsf{R} \right\} \\ & \text{else} \\ & \left\{ \mathcal{Q} \wedge \neg & \mathsf{B} \right\} \ S_2 \ \left\{ \mathsf{R} \right\} \\ & \text{end} \\ & \left\{ \mathsf{R} \right\}
```



wp Rule: Alternations (3) Exercise

Is this program correct?

```
{x > 0 ∧ y > 0}
if x > y then
bigger := x ; smaller := y
else
bigger := y ; smaller := x
end
{bigger ≥ smaller}
```

```
\begin{cases} \{(x > 0 \land y > 0) \land (x > y)\} \\ \text{bigger} := x ; \text{smaller} := y \\ \{bigger \ge smaller\} \\ \land \\ \{(x > 0 \land y > 0) \land \neg (x > y)\} \\ \text{bigger} := y ; \text{smaller} := x \\ \{bigger \ge smaller\} \end{cases}
```



wp Rule: Sequential Composition (1)

$$wp(S_1 ; S_2, \mathbb{R}) = wp(S_1, wp(S_2, \mathbb{R}))$$

The wp of a sequential composition is such that the first phase establishes the wp for the second phase to establish the postcondition R.



wp Rule: Sequential Composition (2)

Recall:

$$\{Q\} S \{R\} \equiv Q \Rightarrow wp(S,R)$$

How do we prove $\{Q\}$ S_1 ; S_2 $\{R\}$?

$$\{Q\}$$
 S_1 ; S_2 $\{R\}$ \iff $Q \Rightarrow \underbrace{wp(S_1, wp(S_2, R))}_{wp(S_1; S_2, R)}$

wp Rule: Sequential Composition (3) Exercises SONDE

```
Is \{ True \}  tmp := x; x := y; y := tmp \{ x > y \}  correct?
If and only if True \Rightarrow wp(tmp := x ; x := y ; y := tmp, x > y)
         wp(tmp := x ; | x := y ; y := tmp |, x > y)
      = { wp rule for seq. comp. }
         wp(tmp := x, wp(x := y ; y := tmp, x > y))
      = { wp rule for seq. comp. }
         wp(tmp := x, wp(x := y, wp(y := tmp, x > |y|)))
      = { wp rule for assignment }
         wp(tmp := x, wp(x := y, x > tmp))
      = { wp rule for assignment }
         wp(tmp := x, y > |tmp|)
      = { wp rule for assignment }
         V > X
```

- : *True* \Rightarrow y > x does not hold in general.
- : The above program is not correct.

Loops



- A loop is a way to compute a certain result by successive approximations.
 - e.g. computing the maximum value of an array of integers
- Loops are needed and powerful
- But loops very hard to get right:
 - "off-by-one" error
 - Not establishing the desired condition
 - Improper handling of borderline cases
 - Infinite loops

[partial correctness]

[partial correctness]

[partial correctness]

[termination]





How do we prove that the following loop is correct?

```
 \begin{cases} Q \\ S_{init} \\ \textbf{while} (B) \end{cases}   \begin{cases} S_{body} \\ \}
```

In case of C/Java/PlusCal, B denotes the *stay condition*.

- In TLA+ toolbox, there is <u>not</u> native, syntactic support for model-checking the <u>total correctness</u> of loops.
- Instead, we have to <u>manually</u> add assertions to encode:
 - LOOP INVARIANT
 - LOOP VARIANT

[for establishing *partial correctness*]

[for ensuring termination]

Specifying Loops



- Use of loop invariant (LI) and loop variant (LV).
 - LI: <u>Boolean</u> expression for measuring/proving partial correctness
 - Typically a special case of the postcondition.
 e.g., Given postcondition "Result is maximum of the array":
 LI can be "Result is maximum of the part of array scanned so far".
 - *Established* before the very first iteration.
 - Maintained TRUE after each iteration.
 - LV: <u>Integer</u> expression for measuring/proving <u>termination</u>
 - Denotes the "number of iterations remaining"
 - Decreased at the end of each subsequent iteration
 - Maintained *non-negative* at the end of each iteration.
 - As soon as value of LV reaches zero, meaning that no more iterations remaining, the loop must exit.
- Remember:

total correctness = partial correctness + termination

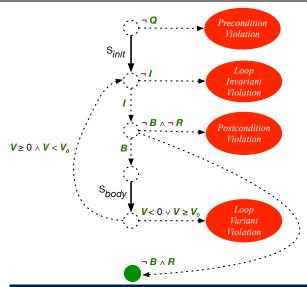


Specifying Loops: Syntax

```
CONSTANT ... (* input list *)
I(var \ list) == ...
\mathbf{V}(var\ list) == \dots
--algorithm MYALGORITHM {
 variables ..., variant_pre = 0, variant_post = 0;
   assert O; (* Precondition *)
   Sinit
   assert I(...): (* Ts LT established? *)
   while (B)
     variant_pre := V(...);
    S_{bodv}
     variant_post := V(...);
    assert variant_post >= 0;
    assert variant_post < variant_pre;</pre>
     assert I(...); (* Is LI preserved? *)
   assert R: (* Postcondition *)
```



Specifying Loops: Runtime Checks (1)





Specifying Loops: Runtime Checks (2)

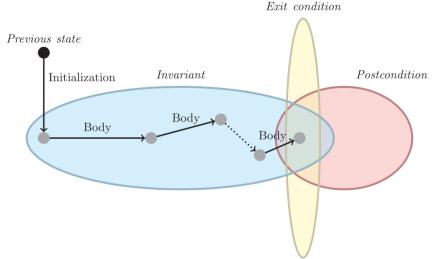
```
I(i) == (1 <= i) / (i <= 6)
    V(i) == 6 - i
    --algorithm loop_invariant_test
     variables i = 1, variant pre = 0, variant post = 0;
6
      assert I(i);
      while (i \le 5) {
8
        variant pre := V(i):
        i := i + 1;
10
        variant post := V(i);
11
        assert variant_post >= 0;
12
        assert variant post < variant pre;
13
        assert I(i):
14
15
```

- **L1**: Change to $1 \le i / i \le 5$ for a *Loop Invariant Violation*.
- **L2**: Change to 5 i for a *Loop Variant Violation*.

Specifying Loops: Visualization

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Digram Source: page 5 in Loop Invariants: Analysis, Classification, and Examples



Proving Correctness of Loops (1)

```
{Q}
{Q}
Sinit
assert I(...);
while(B) {
  variant_pre := V(...);
  Sbody
  variant_post := V(...);
  assert variant_post >= 0;
  assert variant_post < variant_pre;
  assert I(...);
}
{R}</pre>
```

- A loop is partially correct if:
 - Given precondition Q, the initialization step S_{init} establishes LI I.
 - At the end of S_{body} , if not yet to exit, LII is maintained.
 - If ready to exit and *LI I* maintained, postcondition *R* is established.
- A loop terminates if:
 - Given LI I, and not yet to exit, S_{body} maintains LV V as non-negative.
 - Given LI I, and not yet to exit, S_{body} decrements LV V.

Proving Correctness of Loops (2)



- A loop is *partially correct* if:
 - \circ Given precondition Q, the initialization step S_{init} establishes LII.

$$\{Q\}$$
 S_{init} $\{I\}$

• At the end of S_{body} , if not yet to exit, **LI** I is maintained.

$$\{I \land B\} \ S_{body} \ \{I\}$$

If ready to exit and LI I maintained, postcondition R is established.

$$I \wedge \neg B \Rightarrow R$$

- A loop terminates if:
 - Given LII, and not yet to exit, S_{body} maintains LVV as non-negative.

$$\{I \wedge B\} \ S_{body} \ \{V \geq 0\}$$

Given LI I, and not yet to exit, S_{body} decrements LV V.

$$\left\{\textit{I} \land \textit{B}\right\} \; \textit{S}_{\textit{body}} \; \left\{\textit{V} < \textit{V}_{0}\right\}$$

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Learning Objectives

Assertions: Weak vs. Strong

Assertions: Preconditions

Assertions: Postconditions

Motivating Examples (1)

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Software Correctness

Hoare Logic

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Loops

Correctness of Loops

Specifying Loops

Specifying Loops: Syntax

Specifying Loops: Runtime Checks (1)

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Proving Correctness of Loops (1)

Proving Correctness of Loops (2)