Verification by Model Checking



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Motivation for Formal Verification

- Safety-Critical Systems
 - e.g., shutdown system of a nuclear power plant
- Mission-Critical Systems
 - e.g., mass-produced computer chips
- Formal verification of the correctness of critical systems can prevent loss of fortune or even lives.
- Formal verification consists of:
 - 1. Systems:
 - Need a **specification** language for modelling abstractions.
- 2. Properties: Need a specification language for expressing (e.g., safety, temporal) concerns.
- 3. Verification: Need a systematic method for establishing that a system satisfies the desired properties.
- The earlier errors are caught in the course of system development. the **cheaper** it is to rectify.
 - o e.g., Much cheaper to catch an error in the design phase than recalling defected products after release.

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Example of Formal Verification



Pentium FDIV bug: https://en.wikipedia.org/wiki/Pentium_FDIV_bug

The Pentium FDIV bug is a hardware bug affecting the floating-point unit (FPU) of the early Intel Pentium processors. Because of the bug, the processor would return incorrect binary floating point results when dividing certain pairs of high-precision numbers.

In December 1994, Intel recalled the defective processors ... In its 1994 annual report. Intel said it incurred "a \$475 million pre-tax charge ... to recover replacement and write-off of these microprocessors."

In the aftermath of the bug and subsequent recall, there was a marked increase in the use of formal verification of hardware floating point operations across the semiconductor industry. Prompted by the discovery of the bug, a technique ... called "word-level model checking" was developed in 1996. Intel went on to use formal verification extensively in the development of later CPU architectures. In the development of the Pentium 4, symbolic trajectory evaluation and theorem proving were used to find a number of bugs that could have led to a similar recall incident had they gone undetected.

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Classification of Verification Methods



- Degree of Automation: Automatic, Interactive, or Manual
- ModelCheck-based vs. Proof-based
 - Proof-based:
 - The system (abstractly) described as a set of formulas Γ
 - **Properties** specified as a set of formulas ϕ
 - **Prove** (automatically or interactively) that $\Gamma \vdash \phi$ [undecidable] i.e., Γ can be derived to ϕ (via *inference rules*).
 - Check-based:
 - The **system** (abstractly) described as a **finite** model M
 - Properties specified as a set of formulas φ
 - **Decide** (automatically) that $\mathbb{M} \models \phi$ [decidable, algorithmic] i.e., Traversing M's **state/reachability graph** decides if ϕ is satisfied.
- Domain of Application
 - o Hardware vs. Software
 - Seguential vs. Concurrent
 - Reactive (e.g., bridge controller) vs. Terminating (e.g., sorting alg.)
- Pre-development vs. Post-development



Verification via Model Checking

- · Automatic, Check-based
- Intended for *reactive*, *concurrent* systems
 - Reactivity:

Continuous reaction to stimuli from the environment e.g., communication protocols, operating systems, embedded systems, etc.

• Concurrency:

Simultaneous execution of (independent or inter-dependent) system units, each of which evolving its own states

- Testing of concurrent, reactive systems is hard:
 - Many scenarios are non-reproducible.
 - Hard to **systematically** cover all important interactions
 - E. W. Dijkstra: Program testing can be used to show the presence of bugs, but never to show their absence!
- Originated as a post-development method
- But should be used as *pre*-development method to save cost 5 of 58



Model Checking: Temporal Logic

System

- A system model M is a *labeled transition system (LTS)* with a (large) number of states and transitions between states.
- A model of an actual physical system abstracts away details that are irrelevant to the properties to be checked.

Properties

- *Temporal logic (TL)* incorporates the notion of *timing*.
- A TL formula ϕ is **not** statically true or false.
- \circ Instead, the truth of a TL formula ϕ depends on where the SUV **dynamically** evolves into (by following transitions).

Verification

- A computer program, called a *model checker*, takes as inputs M and ϕ , and **decides** if $\mathbb{M} \models \phi$
 - **Yes** \Rightarrow All *reachable* states of M satisfy ϕ .
 - No ⇒ An *error trace*, leading to a state satisfying ¬φ, is generated.
 This facilitates debugging through reproducing a problematic scenario.
 - Unknown ⇒ The checker runs out of memory due to state explosion.

Linear-Time Temporal Logic (LTL)



- LTL (<u>Linear-time Temoral Logic</u>) has connectives/operators which allow us to refer to the **future**.
- Two features of LTL:
 - (Computation) Path:
 Time is modelled as an infinite sequence of states.
 - Undetermined Future:
 Alternative paths exist, one of which being the "actual" path.

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LTL: Syntax in CFG (1)



```
[ true ]
\phi ::= T
                                                             false
                                      [propositional atom
         р
                                        [logical negation]
         (\neg \phi)
         (\phi \wedge \phi)
                                    [logical conjunction]
         (\phi \lor \phi)
                                     logical disjunction
         (\phi \Rightarrow \phi)
                                    [logical implication]
         (\mathbf{X}\phi)
                                                  next state
         (\mathbf{F}\phi)
                                       some Future state
          (\mathbf{G}\phi)
                     [ all future states (Globally)
         (\phi \mathbf{U} \phi)
                                                          [Until
         (\phi \mathbf{W} \phi)
                                                   Weak-until
         (\phi \mathbf{R} \phi)
                                                       [Release]
```

p denotes **atomic**, propositional statements

- e.g., Printer 1tr2 is available.
- e.g., Reading of sensor s3 exceeds some threshold.
- e.g., The sudoku board is filled out with a correct solution.



LTL: Syntax in CFG (2)

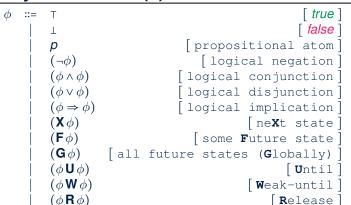
```
\phi ::= \mathsf{T}
                                                                true 1
                                                              false
                                      [propositional atom]
         (\neg \phi)
                                         [logical negation]
                                     [logical conjunction]
         (\phi \wedge \phi)
         (\phi \lor \phi)
                                      logical disjunction
         (\phi \Rightarrow \phi)
                                     [logical implication]
         (\mathbf{X}\phi)
                                                   next state
         (\mathbf{F}\phi)
                                        [some Future state]
         (\mathbf{G}\phi)
                      [all future states (Globally)
         (\phi \mathbf{U} \phi)
                                                            [Until]
         (\phi \mathbf{W} \phi)
                                                    Weak-until ≀
         (\phi \mathbf{R} \phi)
                                                         Release
```

∀ and ∃ are embedded in defining the *temporal* connectives. <u>Universe of disclosure</u>: Set of alternative (computation) *paths*

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LTL: Syntax in CFG (3)



- Temporal connectives bind <u>tighter</u> than logical ones.
- <u>Unary</u> *temporal* connectives bind <u>tighter</u> than <u>binary</u> ones.
- Use <u>parentheses</u> to force the intended order of evaluation.
- Use a parse tree, a LMD, or a RMD to verify the order of evaluation.

LTL: Symbols of Unary Temporal Operators LASSONDE



Temporal Connective	Letter	Symbol
Next	Χ	0
Future/Eventually	F	\Diamond
Global/Henceforth	G	

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Practical Knowledge about Parsing



- A context-free grammar (CFG) g
 - defines, <u>recursively</u>, all (typically an <u>infinite</u> number of) possible strings that can be <u>derived</u> from it.
 - contains both terminals/tokens (base cases) and non-terminals/variables (recursive cases)
- Given an input string s, to show that $s \in L(g)$, we can either:
 - Draw a parse tree (PT) of s, based on g, where:
 - All *internal nodes* (i.e., roots of subtrees) are ϕ (non-terminals).
 - All external nodes (a.k.a. leaves) are characters of s.
 - \circ **Perform** a *left-most derivation (LMD)*, by starting with ϕ (the *start variable*) and continuing to substitute the <u>leftmost</u> non-terminal, until **no** non-terminals remain.
 - **Perform** a *right-most derivation (RMD)*, by starting with ϕ (the *start variable*) and continuing to substitute the <u>rightmost</u> non-terminal, until **no** non-terminals remain.
- PTs, LMDs, and RMDs are legitimate, and equivalent, ways for showing interpretations of a valid LTL formula string.

LTL: Exercises on Parsing Formulas



• Draw and compare the *parse trees* of:

F
$$p \wedge \mathbf{G}$$
 $q \Rightarrow p\mathbf{U}r$
vs. F $(p \wedge \mathbf{G}$ $q \Rightarrow p\mathbf{U}r)$
vs. F $p \wedge (\mathbf{G}$ $q \Rightarrow p\mathbf{U}r)$
vs. F $p \wedge ((\mathbf{G}$ $q \Rightarrow p)\mathbf{U}r)$

- The above formulas are all *derivable* from the grammar of LTL.
 - Show using the *LMD* (<u>Left</u>-Most Derivations)
 - Show using the RMD (Right-Most Derivations)

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LTL Formulas: More Exercises



Draw the *parser trees* for:

$$(\mathbf{F}(p \Rightarrow \mathbf{G} r) \lor ((\neg q) \mathbf{U} p))$$
vs. $\mathbf{F} p \Rightarrow \mathbf{G} r \lor \neg q \mathbf{U} p$
vs. $\mathbf{F}((p \Rightarrow \mathbf{G} r) \lor (\neg q \mathbf{U} p))$

LTL Formulas: Subformulas



Given an LTL formula ϕ , its **subformulas** are all those whose **parse trees** (**rooted at** ϕ) are subtrees of ϕ 's parse tree.

e.g., Enumerate all subformula of ($\mathbf{F}(p \Rightarrow \mathbf{G} r) \vee ((\neg q) \mathbf{U} p)$).

1. p

[appearing twice in the parse tree]

- **2.** r
- 3. G r
- 4. $p \Rightarrow (\mathbf{G} r)$
- 5. $\mathbf{F}(p \Rightarrow (\mathbf{G}r))$
- **6.** q
- **7.** ¬*q*
- **8.** p
- **9.** $(\neg q) \mathbf{U} p$
- **10.** $(\mathbf{F}(p \Rightarrow \mathbf{G} r) \lor ((\neg q) \mathbf{U} p))$

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LTL Semantics: Labelled Transition Systems (LTS)



- Definition. Given that P is a set of atoms/propositions of concern, a *transition system* M is a *formal model* represented as a triple M = (S, →, L):
 - o S

A finite set of states

 $\circ \longrightarrow : S \leftrightarrow S$

A transition relation on S

 $\circ L: S \to \mathbb{P}(P)$

A labelling function mapping each state to its satisfying atoms

Assumption. No state of the system can *deadlock*:

From any state, it's always possible to make progress (by taking a transition).

$$\forall s \bullet s \in S \Rightarrow (\exists s' \bullet s' \in S \land (s, s') \in \longrightarrow)$$

Background for Self-Study



- Topics of **sets** and **relations** were covered in EECS3342.
- Slide 18 to Slide 28 contain what you should recall.

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Set of Tuples



Given n sets S_1 , S_2 , ..., S_n , a *cross/Cartesian product* of theses sets is a set of n-tuples.

Each *n*-tuple $(e_1, e_2, ..., e_n)$ contains n elements, each of which a member of the corresponding set.

$$S_1 \times S_2 \times \cdots \times S_n = \{(e_1, e_2, \dots, e_n) \mid e_i \in S_i \land 1 \le i \le n\}$$

e.g., $\{a, b\} \times \{2, 4\} \times \{\$, \&\}$ is a set of triples:

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Relations (1): Constructing a Relation



A *relation* is a set of mappings, each being an *ordered pair* that maps a member of set *S* to a member of set *T*.

e.g., Say
$$S = \{1, 2, 3\}$$
 and $T = \{a, b\}$

- ∘ Ø is the *minimum* relation (i.e., an empty relation).
- $S \times T$ is the *maximum* relation (say r_1) between S and T, mapping from each member of S to each member in T:

$$\{(1,a),(1,b),(2,a),(2,b),(3,a),(3,b)\}$$

∘ $\{(x,y) \mid (x,y) \in S \times T \land x \neq 1\}$ is a relation (say r_2) that maps only some members in S to every member in T:

$$\{(2,a),(2,b),(3,a),(3,b)\}$$

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Relations (2.1): Set of Possible Relations



 We use the power set operator to express the set of all possible relations on S and T:

$$\mathbb{P}(S \times T)$$

Each member in $\mathbb{P}(S \times T)$ is a relation.

• To declare a relation variable r, we use the colon (:) symbol to mean **set membership**:

$$r: \mathbb{P}(S \times T)$$

• Or alternatively, we write:

$$r: S \leftrightarrow T$$

where the set $S \leftrightarrow T$ is synonymous to the set $\mathbb{P}(S \times T)$

Relations (2.2): Exercise



Enumerate $\{a,b\} \leftrightarrow \{1,2,3\}$.

- Hints:
 - You may enumerate all relations in $\mathbb{P}(\{a,b\} \times \{1,2,3\})$ via their *cardinalities*: $0, 1, \ldots, |\{a,b\} \times \{1,2,3\}|$.
 - What's the *maximum* relation in $\mathbb{P}(\{a,b\} \times \{1,2,3\})$? $\{(a,1),(a,2),(a,3),(b,1),(b,2),(b,3)\}$
- The answer is a set containing **all** of the following relations:
 - ∘ Relation with cardinality 0: Ø

 - How many relations with cardinality 2? $\left[\binom{|\{a,b\}\times\{1,2,3\}|}{2}\right] = \frac{6\times5}{2!} = 15$

...

• Relation with cardinality $|\{a,b\} \times \{1,2,3\}|$: $\{(a,1),(a,2),(a,3),(b,1),(b,2),(b,3)\}$

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Relations (3.1): Domain, Range, Inverse



Given a relation

$$r = \{(a, 1), (b, 2), (c, 3), (a, 4), (b, 5), (c, 6), (d, 1), (e, 2), (f, 3)\}$$

- **domain** of r: set of first-elements from r
 - Definition: $dom(r) = \{ d \mid (d, r') \in r \}$
 - e.g., $dom(r) = \{a, b, c, d, e, f\}$
- *range* of *r* : set of second-elements from *r*
 - Definition: $ran(r) = \{ r' \mid (d, r') \in r \}$
 - \circ e.g., ran(r) = {1,2,3,4,5,6}
- *inverse* of r: a relation like r with elements swapped
 - Definition: $r^{-1} = \{ (r', d) | (d, r') \in r \}$
 - $\circ \ \ \textbf{e.g.}, \ r^{-1} = \{(1,a),(2,b),(3,c),(4,a),(5,b),(6,c),(1,d),(2,e),(3,f)\}$

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Relations (3.2): Image



Given a relation

```
r = \{(a, 1), (b, 2), (c, 3), (a, 4), (b, 5), (c, 6), (d, 1), (e, 2), (f, 3)\}

relational image of r over set s: sub-range of r mapped by s.

o Definition: r[s] = \{ r' \mid (d, r') \in r \land d \in s \}

o e.g., r[\{a, b\}] = \{1, 2, 4, 5\}
```

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Relations (3.3): Restrictions



Given a relation

```
r = \{(a, 1), (b, 2), (c, 3), (a, 4), (b, 5), (c, 6), (d, 1), (e, 2), (f, 3)\}
```

- | domain restriction of r over set ds : sub-relation of r with domain ds.
 - Definition: $ds \triangleleft r = \{ (d, r') \mid (d, r') \in r \land d \in ds \}$
- \circ e.g., $\{a,b\} \lhd r = \{(\mathbf{a},1), (\mathbf{b},2), (\mathbf{a},4), (\mathbf{b},5)\}$
- *range restriction* of *r* over set *rs*: sub-relation of *r* with range *rs*.
 - Definition: $r \triangleright rs = \{ (d, r') \mid (d, r') \in r \land r' \in rs \}$
 - e.g., $r \triangleright \{1,2\} = \{(a,1),(b,2),(d,1),(e,2)\}$

Relations (3.4): Subtractions



Given a relation

$$r = \{(a, 1), (b, 2), (c, 3), (a, 4), (b, 5), (c, 6), (d, 1), (e, 2), (f, 3)\}$$

- **domain subtraction** of *r* over set *ds*: sub-relation of *r* with domain <u>not</u> *ds*.
 - Definition: $ds \triangleleft r = \{ (d, r') \mid (d, r') \in r \land d \notin ds \}$
 - \circ e.g., $\{a,b\} \triangleleft r = \{(\mathbf{c},3), (\mathbf{c},6), (\mathbf{d},1), (\mathbf{e},2), (\mathbf{f},3)\}$
- | range subtraction of r over set rs |: sub-relation of r with range $\underline{not} rs$.
 - Definition: $r \triangleright rs = \{ (d, r') \mid (d, r') \in r \land r' \notin rs \}$
 - e.g., $r \triangleright \{1,2\} = \{(c,3),(a,4),(b,5),(c,6),(f,3)\}$

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Functions (1): Functional Property



• A *relation* r on sets S and T (i.e., $r \in S \leftrightarrow T$) is also a *function* if it satisfies the *functional property*:

isFunctional(r)

 $\forall s, t_1, t_2 \bullet (s \in S \land t_1 \in T \land t_2 \in T) \Rightarrow ((s, t_1) \in r \land (s, t_2) \in r \Rightarrow t_1 = t_2)$

- That is, in a *function*, it is <u>forbidden</u> for a member of S to map to more than one members of T.
- Equivalently, in a function, two distinct members of T cannot be mapped by the same member of S.
- e.g., Say S = {1,2,3} and T = {a,b}, which of the following relations satisfy the above functional property?
 - $\circ S \times T$ [No]
 - <u>Witness 1</u>: (1, a), (1, b); <u>Witness 2</u>: (2, a), (2, b); <u>Witness 3</u>: (3, a), (3, b). ○ $(S \times T) \setminus \{(x, y) \mid (x, y) \in S \times T \land x = 1\}$ [No]
 - Witness 1: (2,a), (2,b); Witness 2: (3,a), (3,b) $\{(1,a), (2,b), (3,a)\}$ [Yes]
 - $\{(1,a),(2,b),(3,a)\}$ [Yes] $\{(1,a),(2,b)\}$

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Functions (2.1): Total vs. Partial



Given a **relation** $r \in S \leftrightarrow T$

• r is a partial function if it satisfies the functional property:

$$r \in S \rightarrow T \iff (\text{isFunctional}(r) \land \text{dom}(r) \subseteq S)$$

Remark. $r \in S \Rightarrow T$ means there **may (or may not) be** $s \in S$ s.t. r(s) is **undefined** (i.e., $r(s) = \emptyset$).

• e.g.,
$$\{\{(\mathbf{2},a),(\mathbf{1},b)\},\{(\mathbf{2},a),(\mathbf{3},a),(\mathbf{1},b)\}\}\subseteq\{1,2,3\} \rightarrow \{a,b\}$$

• r is a *total function* if there is a mapping for each $s \in S$:

$$r \in S \to T \iff (isFunctional(r) \land dom(r) = S)$$

Remark. $r \in S \rightarrow T$ implies $r \in S \nrightarrow T$, but <u>not</u> vice versa. Why?

- ∘ e.g., $\{(\mathbf{2}, a), (\mathbf{3}, a), (\mathbf{1}, b)\} \in \{1, 2, 3\} \rightarrow \{a, b\}$
- \circ e.g., $\{(\mathbf{2}, a), (\mathbf{1}, b)\} \notin \{1, 2, 3\} \rightarrow \{a, b\}$

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Functions (2.2): Relation Image vs. Function Application



- Recall: A *function* is a *relation*, but a *relation* is not necessarily a *function*.
- Say we have a *partial function* $f \in \{1,2,3\} \Rightarrow \{a,b\}$:

$$f = \{(\mathbf{3}, a), (\mathbf{1}, b)\}$$

• With *f* wearing the *relation* hat, we can invoke *relational images*:

$$f[{3}] = {a}$$

 $f[{1}] = {b}$
 $f[{2}] = \emptyset$

Remark. $\Rightarrow |f[\{v\}]| \le 1$:

- each member in dom(f) is mapped to at most one member in ran(f)
- each input set {v} is a **singleton** set
- With f wearing the function hat, we can invoke functional applications:
 - f(3) = a
 - f(1) b
 - (2) is undefined

LTL Semantics: Example of LTS



- We may visual a transition system M using a *directed graph*:
 - Nodes/Vertices denote states.
 - Edges/Arcs denote *transitions*.
- **Exercises** Consider the system with a counter *c* with the following assumption:

$$0 \le c \le 3$$

Say c is initialized 0 and may be incremented (via a transition *inc*, enabled when c < 3) or decremented (via a transition *dec*, enabled when c > 0).

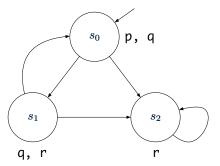
- Draw a state graph of this system.
- Formulate the state graph as an LTS (via a triple (S, \longrightarrow, L)).

 Assume: Set P of atoms is: $\{c \ge 1, c \le 1\}$

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LTL Semantics: More Example of LTS



$$\mathbb{M} = (S, \longrightarrow, L):$$

$$\circ S = \{s_0, s_1, s_2\}$$

$$\circ \longrightarrow = \{(s_0, s_1), (s_0, s_2), (s_1, s_0), (s_1, s_2), (s_2, s_2)\}$$

$$\circ L = \{(s_0, \{p, q\}), (s_1, \{q, r\}), (s_2, \{r\})\}$$
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LTL Semantics: Paths



<u>Definition</u>. A *path* in a model $\mathbb{M} = (S, \longrightarrow, L)$ is an *infinite* sequence of states $s_i \in S$, where $i \ge 1$, such that $s_i \longrightarrow s_{i+1}$.

 \circ We write the path, starting at the *initial state* s_1 , as

$$s_1 \longrightarrow s_2 \longrightarrow \dots$$

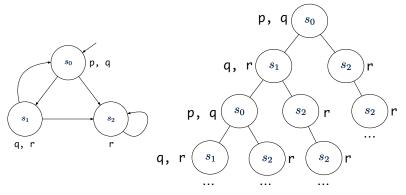
- <u>Note.</u> s₁ in the above path pattern denotes the first, initial state of the path, but in general, the actual name of the initial state may cause confusion, e.g., s₀.
- A path $\pi = s_1 \longrightarrow s_2 \longrightarrow \dots$ represents a possible future of M.
- We write π^i for the *suffix* of path π : a path starting from state s_i . e.g., $\pi^3 = s_3 \longrightarrow s_4 \longrightarrow \dots$ e.g., $\pi^1 = \pi$

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LTL Semantics: All Possible Paths



Given a state s, we represent <u>all</u> possible (computation) paths as a computation tree by unwinding the transitions. e.g.





LTL Semantics: Path Satisfaction (1)

Definition. Given a *model* $\mathbb{M} = (S, \longrightarrow, L)$ and a *path* $\pi = s_1 \longrightarrow \dots$ in M, whether or not path π satisfies an **LTL** *formula* is defined by the *satisfaction relation* ⊨ as follows:

$$\pi \models \rho \qquad \iff \rho \in L(s_1)$$

$$\pi \models T$$

$$\pi \not\models \bot$$

$$\pi \models \neg \phi \qquad \iff \neg(\pi \models \phi)$$

$$\pi \models \phi_1 \land \phi_2 \qquad \iff \pi \models \phi_1 \land \pi \models \phi_2$$

$$\pi \models \phi_1 \lor \phi_2 \qquad \iff \pi \models \phi_1 \lor \pi \models \phi_2$$

$$\pi \models \phi_1 \Rightarrow \phi_2 \qquad \iff \pi \models \phi_1 \Rightarrow \pi \models \phi_2$$

Tips. To evaluate $\pi \models \phi_1 \land \phi_2$ (and similarly for \neg , \lor , \Rightarrow):

- If ϕ_1 and ϕ_2 are sophisticated, decompose it to $\pi \vDash \phi_1$ and $\pi \vDash \phi_2$.
- Otherwise, directly evaluate $\phi_1 \wedge \phi_2$ on s_1 .

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LTL Semantics: Path Satisfaction (2.1)

Definition. Given a *model* $\mathbb{M} = (S, \longrightarrow, L)$ and a *path* $\pi = s_1 \longrightarrow \dots$ in M, whether or not path π satisfies an **LTL** *formula* is defined by the *satisfaction relation* ⊨ as follows:

$$\pi \models \mathbf{X}\phi \iff \pi^2 \models \phi
\pi \models \mathbf{G}\phi \iff (\forall i \bullet i \ge 1 \Rightarrow \pi^i \models \phi)
\pi \models \mathbf{F}\phi \iff (\exists i \bullet i \ge 1 \land \pi^i \models \phi)$$

LTL Semantics: Model Satisfaction (1)



- **Definition**. Given:
 - \circ a model $\mathbb{M} = (S, \longrightarrow, L)$
 - a state *s* ∈ *S*
 - ∘ an LTL formula *₀*

 $\mathbb{M}, s \models \phi$ if and only if for **every** path π of \mathbb{M} starting at $s, \pi \models \phi$.

$$\mathbb{M}, S \vDash \phi \iff (\forall \pi \bullet (\pi = S \longrightarrow \dots) \Rightarrow \pi \vDash \phi)$$

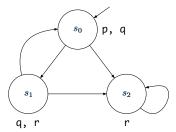
• When the model M is clear from the context, we write: $|s| = \phi$.

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LTL Semantics: Model Satisfaction (2.1)



Consider the following system model:



∘ *s*₀ ⊨ T s₀ ⊭ ⊥ \circ $S_0 \models p \land q$ \circ $s_0 \models r$

[true] [true] [true]

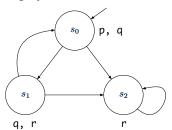
[false]



[false]

LTL Semantics: Model Satisfaction (2.2)

Consider the following system model:



∘
$$s_0 \models \mathbf{X} q$$

Witness Path: $s_0 \longrightarrow s_2 \longrightarrow s_2 \cdots \not\models \mathbf{X} q$

 \circ $s_0 \models \mathbf{X} r$ [true]

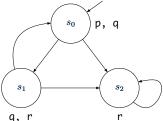
$$\circ s_0 = \mathbf{X}(q \wedge r)$$
Witness Path: $s_1 \rightarrow s_2 \rightarrow s_3 \rightarrow s_4 \rightarrow s_4 \rightarrow s_5 \rightarrow s_4 \rightarrow s_5 \rightarrow s_4 \rightarrow s_5 \rightarrow s_5$

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LTL Semantics: Model Satisfaction (2.3)



Consider the following system model:



• $s_0 \models \mathbf{G} \neg (p \land r)$ [true] $s \models \mathbf{G} \phi \iff \phi$ holds on all **reachable** states from s.

 $\circ s_0 \models \mathbf{G} r$ [false]

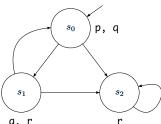
<u>Witness Path</u>: s_0 → s_2 → s_2 ··· \notin **G** r ○ $s_2 \models$ **G** r

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LTL Semantics: Model Satisfaction (2.4)



Consider the following system model:



 \circ $s_0 \models \mathbf{F} \neg (p \land r)$

•

 \circ $s_0 \models \mathbf{F} r$

[true] [true] [false]

 \circ $s_0 \models \mathbf{F}(q \land r)$

• Is is the case that $q \wedge r$ is eventually satisfied on every path?

• No. Witness Path: $s_0 \longrightarrow s_2 \longrightarrow s_2 \longrightarrow \dots$

$$\circ s_2 \models \mathbf{F} r$$
 [true]

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LTL Semantics: Nested G and F (1)



Given a model $\mathbb{M} = (S, \longrightarrow, L)$ and a state $s \in S$:

 $s \models \mathbf{F} \mathbf{G} \phi$ means that:

- <u>Each</u> path starting with s is such that <u>eventually</u>, φ holds <u>continuously</u>.
- For <u>all</u> paths π starting with s (i.e., $\pi = s \longrightarrow l \dots$):

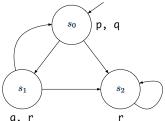
$$\exists i \bullet i \ge 1 \land (\forall j \bullet j \ge i \Rightarrow \pi^i \vDash \phi)$$

- Q. How to *prove* and *disprove* the above formula pattern?
- **Hint.** Structure of pattern: $\forall \pi \bullet \ldots \Rightarrow (\exists i \bullet \cdots \land (\forall i \bullet \ldots \Rightarrow \phi))$



LTL Semantics: Model Satisfaction (2.5.1)

Consider the following system model:



 $\circ s_0 \models \mathbf{FG} r$ [false]

 $\underline{\text{Witness}} \colon s_0 \longrightarrow s_1 \longrightarrow s_0 \longrightarrow s_1 \longrightarrow \dots$

 $\circ \ s_0 \models \mathbf{FG}(p \lor q)$ [false]

 $\underline{\text{Witness}}: s_0 \longrightarrow s_1 \longrightarrow s_2 \longrightarrow s_2 \longrightarrow \dots$

∘ $s_0 \models \mathbf{F} \mathbf{G}(p \lor r)$ [true] <u>Justification</u>: All possible paths from s_0 involve s_0 , s_1 , and s_2 , all of which satisfying $p \lor r$.

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LTL Semantics: Nested G and F (2)

Given a model $\mathbb{M} = (S, \longrightarrow, L)$ and a state $s \in S$:

 $s \models \mathbf{F}\phi_1 \Rightarrow \mathbf{F}\mathbf{G}\phi_2$ means that:

• Each path π starting with s is such that if ϕ_1 eventually holds on π , then ϕ_2 eventually holds continuously on the same π .

$$\forall \pi \bullet \pi = S \longrightarrow \dots \Rightarrow$$

$$\begin{pmatrix} (\exists i \bullet i \ge 1 \land \pi^i \models \phi_1) \\ \Rightarrow \\ (\exists i \bullet i \ge 1 \land (\forall j \bullet j \ge i \Rightarrow \pi^i \models \phi_2)) \end{pmatrix}$$

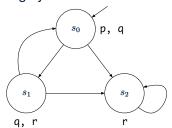
- Q. How to *disprove* the above formula pattern?
- A. Find a witness path π which makes the "inner" implication *false*.

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LTL Semantics: Model Satisfaction (2.5.2)



Consider the following system model:



∘ $s_0 \models \mathbf{F}(\neg q \land r) \Rightarrow \mathbf{FG} r$ [true] Justification:

- $s_0 \longrightarrow s_1 \longrightarrow s_0 \longrightarrow \dots$ never satisfies $\neg q \land r$.
- $s_0 \longrightarrow s_1 \longrightarrow s_2 \longrightarrow s_2 \longrightarrow \dots$ eventually satisfies $\neg q \land r$ continuously.
- $s_0 \longrightarrow s_2 \longrightarrow s_2 \longrightarrow \dots$ eventually satisfies $\neg q \land r$ continuously.
- $\circ \ \mathbf{s}_0 \vDash \mathbf{F}(\ \neg q \lor r\) \Rightarrow \mathbf{FG} \, r \qquad \qquad [false]$

<u>Witness</u>: $s_0 \longrightarrow s_1 \longrightarrow s_0 \longrightarrow \dots$ <u>eventually</u> satisfies $\neg q \lor r$, but there is no point in this path where r holds continuously.

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LTL Semantics: Nested G and F (3)



Given a model $\mathbb{M} = (S, \longrightarrow, L)$ and a state $s \in S$:

- \circ $s \models \mathbf{GF} \phi$ means that:
 - <u>Each</u> path starting with s is such that <u>continuously</u>,
 φ holds <u>eventually</u>.
 ⇒ φ holds *infinitely often*!
 - For **all** paths π starting with s (i.e., $\pi = s \longrightarrow l \dots$):

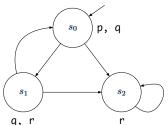
$$\forall i \bullet i \ge 1 \Rightarrow (\exists j \bullet j \ge i \land \pi^i \vDash \phi)$$

- Q. How to *prove* and *disprove* the above formula pattern?
- **Hint.** Structure of pattern: $\forall \pi \bullet ... \Rightarrow (\forall i \bullet ... \Rightarrow (\exists j \bullet ... \land \phi))$



LTL Semantics: Model Satisfaction (2.6)

Consider the following system model:



∘ $s_0 \models \mathbf{GF}p$ [false] Witness: In $s_0 \longrightarrow s_2 \longrightarrow ..., p$ is not satisfied infinitely often.

 $\circ s_0 \models \mathbf{GF}(p \lor r)$ [true] $\circ s_0 \models \mathbf{GF}p \Rightarrow \mathbf{GF}r$ [true]

s₀ ⊨ GFp ⇒ GFr
 Hint: Consider paths making the antecedent GFp true.

 $\begin{array}{ll}
\circ \ \overline{s_0} \vDash \mathbf{GF} r \Rightarrow \mathbf{GF} p \\
\underline{\text{Witness}} \colon s_0 \longrightarrow s_2 \longrightarrow \dots
\end{array} \qquad [\text{Malse}]$

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LTL Semantics: Path Satisfaction (2.2)

<u>Definition</u>. Given a *model* $\mathbb{M} = (S, \longrightarrow, L)$ and a *path* $\pi = s_1 \longrightarrow \dots$ in \mathbb{M} , whether or not path π satisfies an *LTL formula* is defined by the *satisfaction relation* \models as follows:

$$\pi \models \phi_{1} \mathbf{U} \phi_{2} \iff \left(\exists i \bullet i \ge 1 \land \begin{pmatrix} \pi^{i} \models \phi_{2} \\ \land \\ (\forall j \bullet 1 \le j \le i - 1 \Rightarrow \pi^{j} \models \phi_{1}) \end{pmatrix} \right)$$

$$\pi \models \phi_{1} \mathbf{W} \phi_{2} \iff \left(\begin{matrix} \phi_{1} \mathbf{U} \phi_{2} \\ \lor (\forall k \bullet k \ge 1 \Rightarrow \pi^{k} \models \phi_{1}) \end{pmatrix} \right)$$

$$\pi \models \phi_{1} \mathbf{R} \phi_{2} \iff \left(\begin{matrix} \exists i \bullet i \ge 1 \land \begin{pmatrix} \pi^{i} \models \phi_{1} \\ \land \\ (\forall j \bullet 1 \le j \le i \Rightarrow \pi^{j} \models \phi_{2}) \end{pmatrix} \right) \right)$$

$$\forall \forall k \bullet k \ge 1 \Rightarrow \pi^{k} \models \phi_{2}$$

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LTL Semantics: Recall Model Satisfaction



- **Definition**. Given:
 - \circ a model $\mathbb{M} = (S, \longrightarrow, L)$
 - a state *s* ∈ *S*
 - o an LTL formula ∅

 $\mathbb{M}, s \models \phi$ if and only if for **every** path π of \mathbb{M} starting at $s, \pi \models \phi$.

$$\mathbb{M}, S \vDash \phi \iff (\forall \pi \bullet (\pi = S \longrightarrow \dots) \Rightarrow \pi \vDash \phi)$$

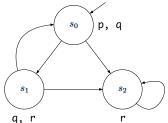
• When the model $\mathbb M$ is clear from the context, we write: $s \models \phi$.

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LTL Semantics: Model Satisfaction (3.1)



Consider the following system model:

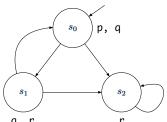


- $\circ s_0 \models p \mathbf{U} r$ [true]
- s_0 (satisfying p) branches out to s_1 or s_2 (both both satisfying r).
- $s_0 = p \mathbf{W} r$ [true] $\phi_1 \mathbf{U} \phi_2 \Rightarrow \phi_1 \mathbf{W} \phi_2$
- $\circ s_0 \models r \mathbf{R} p \qquad [false]$ Witness: Say $\pi = s_0 \longrightarrow s_1 \longrightarrow s_0 \longrightarrow s_1 \dots : \pi \not\models p \land r \text{ and } \pi \not\models \mathbf{G} p.$



LTL Semantics: Model Satisfaction (3.2)

Consider the following system model:



 $\circ \ s_0 \vDash (p \lor r) \ \mathbf{U}(p \land r)$ [false]

<u>Witness</u>: In $s_0 \longrightarrow s_1 \longrightarrow s_0 \longrightarrow s_1 \dots$, $p \land r$ never holds. • $s_0 \models (p \lor r) \mathbf{W}(p \land r)$

It is the case that: $s_0 = \mathbf{G}(p \vee r)$.

∘ $s_0 \vDash (p \land r) \mathbf{R}(p \lor r)$ [true] It is the case that: $s_0 \vDash \mathbf{G}(p \lor r)$.

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Clarification on the "Until" Connective



[true]

- $\phi_1 \mathbf{U} \phi_2$ requires that:
 - ϕ_2 must eventually become *true*.
 - Before ϕ_2 becomes *true*, ϕ_1 must hold.
- Exercise. Say:
 - Atom *t*: I was 22.
 - Atom s: I smoke.

Formulate "I had smoked until I was 22" using LTL.

- sUt [inaccurate]
- $\phi_1 \cup \phi_2$ does not insist $\neg \phi_1$ after ϕ_2 eventually becomes *true*.
- \circ "I smoked both <u>before</u> and <u>after</u> I was 22" satisfies s **U** t.
- \circ Solution? [s \boldsymbol{U} ($t \wedge (\boldsymbol{G} \neg s)$)]



Formulating English as LTL Formulas (1)



- Assume the following atomic propositions:
 busy, requested, acknowledged, enabled, floor2, floor5, directionUp, buttonPresssed5.
- It is impossible to reach a state where the system is started but not ready.
 - \circ **G** \neg (started $\land \neg$ ready) $[\neg (F(started \land \neg ready))]$
- Whenever a request is made, it will be eventually be acknowledged.
 - ∘ **G**(requested ⇒ **F** acknowledged)
- A certain process will always be enabled.
 - **G** enabled
- An upwards travelling lift at the second floor does not change its direction when it has passengers wishing to go to the fifth floor.

$$\mathbf{G} \left(\begin{array}{c} \textit{floor2} \land \textit{directionUp} \land \textit{buttonPresssed5} \\ \Rightarrow (\ \textit{directionUp} \ \mathbf{U} \ \textit{floor5} \) \end{array} \right)$$

∘ Is it ok to change from **U** to **W**?

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Formulating English as LTL Formulas (2)



Assume the following atomic propositions:

requested, waiting, granted, noOneInCS

Whenever a process makes a request, it starts waiting. As soon as no other process is in the critical section, the process is granted access to the critical section.

G (requested ⇒ (noOneInCS **R** waiting))

Q. Does the above formulation guarantee *no starvation*?Hint. Check the formal definition of R.



Formulating English as LTL Formulas (3)

Assume the following atomic propositions:

degReqFullfilled, allowedForGraduation

Until a student fullfils all their degree requirements, their academic staus remains "not allowed for graduation". The change of status, when qualified, may not be instantaneous to account for human/manual processing.

¬allowedForGraduation **W** (degReqFulfilled ∧ **G** allowedForGraduation)

Q. Does the above formulation account for situations where a student never fulfills their degree requirements?

Hint. Check the formal definition of **W**.

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Formulating English as LTL Formulas (2)

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