

# Introduction

MEB: Prologue, Chapter 1



EECS3342 E: System  
Specification and Refinement  
Fall 2024

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## Learning Outcomes



This module is designed to help you understand:

- What a **safety-critical** system is
- **Code of Ethics** for Professional Engineers
- What a **Formal Method** is
- **Verification** vs. **Validation**
- **Model**-Based System Development

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## What is a Safety-Critical System (SCS)?



- A **safety-critical system (SCS)** is a system whose **failure** or **malfunction** has one (or more) of the following consequences:
  - death or serious injury to **people**
  - loss or severe damage to **equipment/property**
  - harm to the **environment**
- Based on the above definition, do you know of any systems that are **safety-critical**?

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## Professional Engineers: Code of Ethics



- **Code of Ethics** is a basic guide for **professional conduct** and imposes duties on practitioners, with respect to **society**, **employers**, **clients**, **colleagues** (including employees and subordinates), the **engineering profession** and him or herself.
- It is the duty of a practitioner to act at all times with,
  1. **fairness** and **loyalty** to the practitioner's associates, employers, clients, subordinates and employees;
  2. **fidelity** (i.e., dedication, faithfulness) to public needs;
  3. devotion to **high ideals** of personal honour and professional integrity;
  4. **knowledge** of developments in the area of professional engineering relevant to any services that are undertaken; and
  5. **competence** in the performance of any professional engineering services that are undertaken.
- Consequence of misconduct?
  - **suspension** or **termination** of professional licenses
  - civil **law suits**

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Source: PEO's Code of Ethics

## Developing Safety-Critical Systems



**Industrial standards** in various domains list **acceptance criteria** for **mission-** or **safety-**critical systems that practitioners need to comply with: e.g.,

**Aviation** Domain: **RTCA DO-178C** "Software Considerations in Airborne Systems and Equipment Certification"

**Nuclear** Domain: **IEEE 7-4.3.2** "Criteria for Digital Computers in Safety Systems of Nuclear Power Generating Stations"

Two important criteria are:

1. System **requirements** are precise and complete
2. System **implementation** conforms to the requirements

But how do we accomplish these criteria?

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## Safety-Critical vs. Mission-Critical?



- **Critical:**  
A task whose successful completion ensures the success of a larger, more complex operation.  
e.g., Success of a pacemaker  $\Rightarrow$  Regulated heartbeats of a patient
- **Safety:**  
Being free from danger/injury to or loss of human lives.
- **Mission:**  
An operation or task assigned by a higher authority.  
Q. Formally relate being **safety-**critical and **mission-**critical.  
A.
  - **safety-**critical  $\Rightarrow$  **mission-**critical
  - **mission-**critical  $\nRightarrow$  **safety-**critical
- Relevant industrial standard: **RTCA DO-178C** (replacing RTCA DO-178B in 2012) "Software Considerations in Airborne Systems and Equipment Certification"

Source: [Article from OpenSystems](#)

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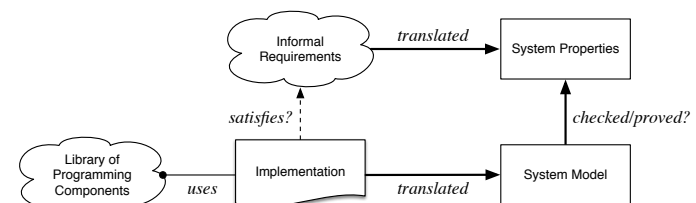
## Using Formal Methods for Certification



- A **formal method (FM)** is a **mathematically rigorous** technique for the specification, development, and verification of software and hardware systems.
- **DO-333** "Formal methods supplement to DO-178C and DO-278A" advocates the use of formal methods:  
The use of **formal methods** is motivated by the expectation that, as in other engineering disciplines, performing appropriate **mathematical analyses** can contribute to establishing the **correctness** and **robustness** of a design.
- FMs, because of their mathematical basis, are capable of:
  - **Unambiguously** describing software system requirements.
  - Enabling **precise** communication between engineers.
  - Providing **verification (towards certification) evidence** of:
    - A **formal** representation of the system being **healthy**.
    - A **formal** representation of the system **satisfying safety properties**.

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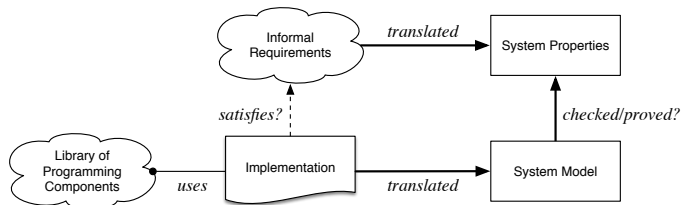
## Verification: Building the Product Right?



- **Implementation** built via **reusable programming components**.
- **Goal:** **Implementation Satisfies Intended Requirements**
- To verify this, we **formalize** them as a **system model** and a set of (e.g., safety) **properties**, using the specification language of a theorem prover (EECS3342) or a model checker (EECS4315).
- Two Verification Issues:
  1. Library components may **not behave as intended**.
  2. Successful checks/proofs ensure that we **built the product right**, with respect to the informal requirements. **But...**

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## Validation: Building the Right Product?



- Successful checks/proofs  $\nRightarrow$  We **built the right product**.
- The target of our checks/proofs may not be valid:  
The requirements may be **ambiguous**, **incomplete**, or **contradictory**.
- Solution: **Precise Documentation** [EECS4312]

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## Model-Based System Development



- Modelling** and **formal reasoning** should be performed **before** implementing/coding a system.
  - A system's **model** is its **abstraction**, filtering irrelevant details.  
A system **model** means as much to a software engineer as a **blueprint** means to an architect.
  - A system may have a list of **models**, "sorted" by **accuracy**:  

$$\langle m_0, m_1, \dots, m_i, m_j, \dots, m_n \rangle$$
    - The list starts by the most **abstract** model with least details.
    - A more **abstract** model  $m_i$  is said to be **refined by** its subsequent, more **concrete** model  $m_j$ .
    - The list ends with the most **concrete/refined** model with most details.
  - It is far easier to reason about:
    - a system's **abstract** models (rather than its full **implementation**)
    - refinement steps** between subsequent models
- The final product is **correct by construction**.

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## Catching Defects – When?



- To minimize **development costs**, minimize **software defects**.
- Software Development Cycle:  
Requirements  $\rightarrow$  **Design**  $\rightarrow$  **Implementation**  $\rightarrow$  Release
- Q.** Design or Implementation Phase?  
Catch defects **as early as possible**.

Design and architecture	Implementation	Integration testing	Customer beta test	Postproduct release
1X*	5X	10X	15X	30X

- $\therefore$  The cost of fixing defects **increases exponentially** as software progresses through the development lifecycle.
- Discovering **defects** after **release** costs up to 30 times more than catching them in the **design** phase.
- Choice of a **design language**, amendable to **formal verification**, is therefore critical for your project.

Source: IBM Report

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## Learning through Case Studies



- We will study example **models of programs/codes**, as well as **proofs** on them, drawn from various application domains:
  - REACTIVE** Systems [sensors vs. actuators]
  - DISTRIBUTED** Systems [(geographically) distributed parties]
- What you learn in this course will allow you to explore example in other application domains:
  - SEQUENTIAL** Programs [single thread of control]
  - CONCURRENT** Programs [interleaving processes]
- The **Rodin Platform** will be used to:
  - Construct system **models** using the Even-B notation.
  - Prove **properties** and **refinements** using **classical logic** (propositional and predicate calculus) and **set theory**.

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## Index (1)

### Learning Outcomes

What is a Safety-Critical System (SCS)?

Professional Engineers: Code of Ethics

Developing Safety-Critical Systems

Safety-Critical vs. Mission-Critical?

Using Formal Methods to for Certification

Verification: Building the Product Right?

Validation: Building the Right Product?

Catching Defects – When?

Model-Based System Development

Learning through Case Studies

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## Review of Math

MEB: Chapter 9



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## Learning Outcomes of this Lecture

This module is designed to help you **review**:

- Propositional Logic
- Predicate Logic
- Sets, Relations, and Functions

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## Propositional Logic (1)

- A **proposition** is a statement of claim that must be of either **true** or **false**, but not both.
- Basic logical operands are of type Boolean: **true** and **false**.
- We use logical operators to construct compound statements.
  - Unary logical operator: negation ( $\neg$ )

$p$	$\neg p$
true	false
false	true

- Binary logical operators: conjunction ( $\wedge$ ), disjunction ( $\vee$ ), implication ( $\Rightarrow$ ), equivalence ( $\equiv$ ), and if-and-only-if ( $\Leftrightarrow$ ).

$p$	$q$	$p \wedge q$	$p \vee q$	$p \Rightarrow q$	$p \Leftrightarrow q$	$p \equiv q$
true	true	true	true	true	true	true
true	false	false	true	false	false	false
false	true	false	true	true	false	false
false	false	false	false	true	true	true

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## Propositional Logic: Implication (1)



- Written as  $p \Rightarrow q$  [pronounced as "p implies q"]
  - We call  $p$  the antecedent, assumption, or premise.
  - We call  $q$  the consequence or conclusion.
- Compare the *truth* of  $p \Rightarrow q$  to whether a contract is *honoured*:
  - antecedent/assumption/premise  $p \approx$  promised terms [e.g., salary]
  - consequence/conclusion  $q \approx$  obligations [e.g., duties]
- When the promised terms are met, then the contract is:
  - honoured* if the obligations fulfilled. [  $(true \Rightarrow true) \Longleftrightarrow true$  ]
  - breached* if the obligations violated. [  $(true \Rightarrow false) \Longleftrightarrow false$  ]
- When the promised terms are not met, then:
  - Fulfilling the obligation ( $q$ ) or not ( $\neg q$ ) does *not breach* the contract.

$p$	$q$	$p \Rightarrow q$
false	true	true
false	false	true

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## Propositional Logic: Implication (3)



Given an implication  $p \Rightarrow q$ , we may construct its:

- Inverse:**  $\neg p \Rightarrow \neg q$  [negate antecedent and consequence]
- Converse:**  $q \Rightarrow p$  [swap antecedent and consequence]
- Contrapositive:**  $\neg q \Rightarrow \neg p$  [inverse of converse]

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## Propositional Logic: Implication (2)



There are alternative, equivalent ways to expressing  $p \Rightarrow q$ :

- $q$  **if**  $p$ 
  - $q$  is *true* if  $p$  is *true*
- $p$  **only if**  $q$ 
  - If  $p$  is *true*, then for  $p \Rightarrow q$  to be *true*, it can only be that  $q$  is also *true*. Otherwise, if  $p$  is *true* but  $q$  is *false*, then  $(true \Rightarrow false) \equiv false$ .
- Note.** To prove  $p \equiv q$ , prove  $p \Longleftrightarrow q$  (pronounced: "p if and only if q"):
  - $p$  **if**  $q$  [  $q \Rightarrow p$  ]
  - $p$  **only if**  $q$  [  $p \Rightarrow q$  ]
- $p$  is **sufficient** for  $q$ 
  - For  $q$  to be *true*, it is sufficient to have  $p$  being *true*.
- $q$  is **necessary** for  $p$  [similar to  $p$  only if  $q$ ]
  - If  $p$  is *true*, then it is necessarily the case that  $q$  is also *true*. Otherwise, if  $p$  is *true* but  $q$  is *false*, then  $(true \Rightarrow false) \equiv false$ .
- $q$  **unless**  $\neg p$  [When is  $p \Rightarrow q$  *true*?]
  - If  $q$  is *true*, then  $p \Rightarrow q$  *true* regardless of  $p$ .
  - If  $q$  is *false*, then  $p \Rightarrow q$  cannot be *true* unless  $p$  is *false*.

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## Propositional Logic (2)



- Axiom:** Definition of  $\Rightarrow$

$$p \Rightarrow q \equiv \neg p \vee q$$

- Theorem:** Identity of  $\Rightarrow$

$$true \Rightarrow p \equiv p$$

- Theorem:** Zero of  $\Rightarrow$

$$false \Rightarrow p \equiv true$$

- Axiom:** De Morgan

$$\neg(p \wedge q) \equiv \neg p \vee \neg q$$

$$\neg(p \vee q) \equiv \neg p \wedge \neg q$$

- Axiom:** Double Negation

$$p \equiv \neg(\neg p)$$

- Theorem:** Contrapositive

$$p \Rightarrow q \equiv \neg q \Rightarrow \neg p$$

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## Predicate Logic (1)

- A **predicate** is a **universal** or **existential** statement about objects in some universe of discourse.
- Unlike propositions, predicates are typically specified using **variables**, each of which declared with some **range** of values.
- We use the following symbols for common numerical ranges:
  - $\mathbb{Z}$ : the set of integers  $[-\infty, \dots, -1, 0, 1, \dots, +\infty]$
  - $\mathbb{N}$ : the set of natural numbers  $[0, 1, \dots, +\infty]$
- Variable(s) in a predicate may be **quantified**:
  - Universal quantification**:  
All values that a variable may take satisfy certain property.  
e.g., Given that  $i$  is a natural number,  $i$  is **always** non-negative.
  - Existential quantification**:  
Some value that a variable may take satisfies certain property.  
e.g., Given that  $i$  is an integer,  $i$  **can be** negative.

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## Predicate Logic (2.2): Existential Q. ( $\exists$ )

- An **existential quantification** has the form  $(\exists X \bullet R \wedge P)$ 
  - $X$  is a comma-separated list of variable names
  - $R$  is a **constraint on types/ranges** of the listed variables
  - $P$  is a **property** to be satisfied
- There exist** (a combination of) values of variables listed in  $X$  that satisfy both  $R$  and  $P$ .
  - $\exists i \bullet i \in \mathbb{N} \wedge i \geq 0$  [true]
  - $\exists i \bullet i \in \mathbb{Z} \wedge i \geq 0$  [true]
  - $\exists i, j \bullet i \in \mathbb{Z} \wedge j \in \mathbb{Z} \wedge (i < j \vee i > j)$  [true]
- Proof Strategies**
  - How to prove  $(\exists X \bullet R \wedge P)$  **true**?
    - Hint.** When is  $R \wedge P$  **true**? [true  $\wedge$  true]
    - Give a **witness** of  $x \in X$  s.t.  $R(x), P(x)$  holds.
  - How to prove  $(\exists X \bullet R \wedge P)$  **false**?
    - Hint.** When is  $R \wedge P$  **false**? [true  $\wedge$  false, false  $\wedge$  -]
    - Show that for all instances of  $x \in X$  s.t.  $R(x), \neg P(x)$  holds.
    - Show that for all instances of  $x \in X$  it is the case  $\neg R(x)$ .

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## Predicate Logic (2.1): Universal Q. ( $\forall$ )

- A **universal quantification** has the form  $(\forall X \bullet R \Rightarrow P)$ 
  - $X$  is a comma-separated list of variable names
  - $R$  is a **constraint on types/ranges** of the listed variables
  - $P$  is a **property** to be satisfied
- For all** (combinations of) values of variables listed in  $X$  that satisfies  $R$ , it is the case that  $P$  is satisfied.
  - $\forall i \bullet i \in \mathbb{N} \Rightarrow i \geq 0$  [true]
  - $\forall i \bullet i \in \mathbb{Z} \Rightarrow i \geq 0$  [false]
  - $\forall i, j \bullet i \in \mathbb{Z} \wedge j \in \mathbb{Z} \Rightarrow i < j \vee i > j$  [false]
- Proof Strategies**
  - How to prove  $(\forall X \bullet R \Rightarrow P)$  **true**?
    - Hint.** When is  $R \Rightarrow P$  **true**? [true  $\Rightarrow$  true, false  $\Rightarrow$  -]
    - Show that for all instances of  $x \in X$  s.t.  $R(x), P(x)$  holds.
    - Show that for all instances of  $x \in X$  it is the case  $\neg R(x)$ .
  - How to prove  $(\forall X \bullet R \Rightarrow P)$  **false**?
    - Hint.** When is  $R \Rightarrow P$  **false**? [true  $\Rightarrow$  false]
    - Give a **witness/counterexample** of  $x \in X$  s.t.  $R(x), \neg P(x)$  holds.

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## Predicate Logic (3): Exercises

- Prove or disprove:  $\forall x \bullet (x \in \mathbb{Z} \wedge 1 \leq x \leq 10) \Rightarrow x > 0$ .  
All 10 integers between 1 and 10 are greater than 0.
- Prove or disprove:  $\forall x \bullet (x \in \mathbb{Z} \wedge 1 \leq x \leq 10) \Rightarrow x > 1$ .  
Integer 1 (a witness/counterexample) in the range between 1 and 10 is **not** greater than 1.
- Prove or disprove:  $\exists x \bullet (x \in \mathbb{Z} \wedge 1 \leq x \leq 10) \wedge x > 1$ .  
Integer 2 (a witness) in the range between 1 and 10 is greater than 1.
- Prove or disprove that  $\exists x \bullet (x \in \mathbb{Z} \wedge 1 \leq x \leq 10) \wedge x > 10$ ?  
All integers in the range between 1 and 10 are **not** greater than 10.

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## Predicate Logic (4): Switching Quantifications



Conversions between  $\forall$  and  $\exists$ :

$$(\forall X \bullet R \Rightarrow P) \iff \neg(\exists X \bullet R \wedge \neg P)$$

$$(\exists X \bullet R \wedge P) \iff \neg(\forall X \bullet R \Rightarrow \neg P)$$

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## Sets: Definitions and Membership



- A **set** is a collection of objects.
  - Objects in a set are called its *elements* or *members*.
  - Order* in which elements are arranged does not matter.
  - An element can appear *at most once* in the set.
- We may define a set using:
  - Set Enumeration**: Explicitly list all members in a set.  
e.g.,  $\{1, 3, 5, 7, 9\}$
  - Set Comprehension**: Implicitly specify the condition that all members satisfy.  
e.g.,  $\{x \mid 1 \leq x \leq 10 \wedge x \text{ is an odd number}\}$
- An empty set (denoted as  $\{\}$  or  $\emptyset$ ) has no members.
- We may check if an element is a *member* of a set:
  - e.g.,  $5 \in \{1, 3, 5, 7, 9\}$  [ true ]
  - e.g.,  $4 \notin \{x \mid x \leq 1 \leq 10, x \text{ is an odd number}\}$  [ true ]
- The number of elements in a set is called its *cardinality*.  
e.g.,  $|\emptyset| = 0$ ,  $|\{x \mid x \leq 1 \leq 10, x \text{ is an odd number}\}| = 5$

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## Set Relations



Given two sets  $S_1$  and  $S_2$ :

- $S_1$  is a **subset** of  $S_2$  if every member of  $S_1$  is a member of  $S_2$ .

$$S_1 \subseteq S_2 \iff (\forall x \bullet x \in S_1 \Rightarrow x \in S_2)$$

- $S_1$  and  $S_2$  are **equal** iff they are the subset of each other.

$$S_1 = S_2 \iff S_1 \subseteq S_2 \wedge S_2 \subseteq S_1$$

- $S_1$  is a **proper subset** of  $S_2$  if it is a strictly smaller subset.

$$S_1 \subset S_2 \iff S_1 \subseteq S_2 \wedge |S_1| < |S_2|$$

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## Set Relations: Exercises



$\emptyset \subseteq S$ always holds	[ $\emptyset$ and $S$ ]
$\emptyset \subset S$ always fails	[ $S$ ]
$\emptyset \subset S$ holds for some $S$ and fails for some $S$	[ $\emptyset$ ]
$S_1 = S_2 \Rightarrow S_1 \subseteq S_2$ ?	[ Yes ]
$S_1 \subseteq S_2 \Rightarrow S_1 = S_2$ ?	[ No ]

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## Set Operations

Given two sets  $S_1$  and  $S_2$ :

- **Union** of  $S_1$  and  $S_2$  is a set whose members are in either.

$$S_1 \cup S_2 = \{x \mid x \in S_1 \vee x \in S_2\}$$

- **Intersection** of  $S_1$  and  $S_2$  is a set whose members are in both.

$$S_1 \cap S_2 = \{x \mid x \in S_1 \wedge x \in S_2\}$$

- **Difference** of  $S_1$  and  $S_2$  is a set whose members are in  $S_1$  but not  $S_2$ .

$$S_1 \setminus S_2 = \{x \mid x \in S_1 \wedge x \notin S_2\}$$

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## Power Sets

The **power set** of a set  $S$  is a **set** of all  $S$ 's **subsets**.

$$\mathbb{P}(S) = \{s \mid s \subseteq S\}$$

The power set contains subsets of **cardinalities** 0, 1, 2, ...,  $|S|$ .  
e.g.,  $\mathbb{P}(\{1, 2, 3\})$  is a set of sets, where each member set  $s$  has cardinality 0, 1, 2, or 3:

$$\left\{ \begin{array}{l} \emptyset, \\ \{1\}, \{2\}, \{3\}, \\ \{1, 2\}, \{2, 3\}, \{3, 1\}, \\ \{1, 2, 3\} \end{array} \right\}$$

**Exercise:** What is  $\mathbb{P}(\{1, 2, 3, 4, 5\}) \setminus \mathbb{P}(\{1, 2, 3\})$ ?

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## Set of Tuples

Given  $n$  sets  $S_1, S_2, \dots, S_n$ , a **cross/Cartesian product** of these sets is a set of  $n$ -tuples.

Each  **$n$ -tuple**  $(e_1, e_2, \dots, e_n)$  contains  $n$  elements, each of which a member of the corresponding set.

$$S_1 \times S_2 \times \dots \times S_n = \{(e_1, e_2, \dots, e_n) \mid e_i \in S_i \wedge 1 \leq i \leq n\}$$

e.g.,  $\{a, b\} \times \{2, 4\} \times \{\$, \&\}$  is a set of triples:

$$\begin{aligned} & \{a, b\} \times \{2, 4\} \times \{\$, \&\} \\ = & \{(e_1, e_2, e_3) \mid e_1 \in \{a, b\} \wedge e_2 \in \{2, 4\} \wedge e_3 \in \{\$, \&\}\} \\ = & \left\{ \begin{array}{l} (a, 2, \$), (a, 2, \&), (a, 4, \$), (a, 4, \&), \\ (b, 2, \$), (b, 2, \&), (b, 4, \$), (b, 4, \&) \end{array} \right\} \end{aligned}$$

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## Relations (1): Constructing a Relation

A **relation** is a set of mappings, each being an **ordered pair** that maps a member of set  $S$  to a member of set  $T$ .

e.g., Say  $S = \{1, 2, 3\}$  and  $T = \{a, b\}$

- $\emptyset$  is the **minimum** relation (i.e., an empty relation).
- $S \times T$  is the **maximum** relation (say  $r_1$ ) between  $S$  and  $T$ , mapping from each member of  $S$  to each member in  $T$ :

$$\{(1, a), (1, b), (2, a), (2, b), (3, a), (3, b)\}$$

- $\{(x, y) \mid (x, y) \in S \times T \wedge x \neq 1\}$  is a relation (say  $r_2$ ) that maps only some members in  $S$  to every member in  $T$ :

$$\{(2, a), (2, b), (3, a), (3, b)\}$$

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## Relations (2.1): Set of Possible Relations



- We use the **power set** operator to express the set of **all possible relations** on  $S$  and  $T$ :

$$\mathbb{P}(S \times T)$$

Each member in  $\mathbb{P}(S \times T)$  is a relation.

- To declare a relation variable  $r$ , we use the colon ( $:$ ) symbol to mean **set membership**:

$$r : \mathbb{P}(S \times T)$$

- Or alternatively, we write:

$$r : S \leftrightarrow T$$

where the set  $S \leftrightarrow T$  is synonymous to the set  $\mathbb{P}(S \times T)$

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## Relations (2.2): Exercise



Enumerate  $\{a, b\} \leftrightarrow \{1, 2, 3\}$ .

### Hints:

- You may enumerate all relations in  $\mathbb{P}(\{a, b\} \times \{1, 2, 3\})$  via their **cardinalities**:  $0, 1, \dots, |\{a, b\} \times \{1, 2, 3\}|$ .
- What's the **maximum** relation in  $\mathbb{P}(\{a, b\} \times \{1, 2, 3\})$ ?

$$\{(a, 1), (a, 2), (a, 3), (b, 1), (b, 2), (b, 3)\}$$

- The answer is a set containing **all** of the following relations:

- Relation with cardinality 0:  $\emptyset$
- How many relations with cardinality 1?  $\left[ \binom{|\{a, b\} \times \{1, 2, 3\}|}{1} \right] = 6$
- How many relations with cardinality 2?  $\left[ \binom{|\{a, b\} \times \{1, 2, 3\}|}{2} \right] = \frac{6 \times 5}{2!} = 15$

...

- Relation with cardinality  $|\{a, b\} \times \{1, 2, 3\}|$ :

$$\{(a, 1), (a, 2), (a, 3), (b, 1), (b, 2), (b, 3)\}$$

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## Relations (3.1): Domain, Range, Inverse



Given a relation

$$r = \{(a, 1), (b, 2), (c, 3), (a, 4), (b, 5), (c, 6), (d, 1), (e, 2), (f, 3)\}$$

- domain** of  $r$ : set of first-elements from  $r$ 
  - Definition:  $\text{dom}(r) = \{d \mid (d, r') \in r\}$
  - e.g.,  $\text{dom}(r) = \{a, b, c, d, e, f\}$
  - ASCII syntax: `dom(r)`
- range** of  $r$ : set of second-elements from  $r$ 
  - Definition:  $\text{ran}(r) = \{r' \mid (d, r') \in r\}$
  - e.g.,  $\text{ran}(r) = \{1, 2, 3, 4, 5, 6\}$
  - ASCII syntax: `ran(r)`
- inverse** of  $r$ : a relation like  $r$  with elements swapped
  - Definition:  $r^{-1} = \{(r', d) \mid (d, r') \in r\}$
  - e.g.,  $r^{-1} = \{(1, a), (2, b), (3, c), (4, a), (5, b), (6, c), (1, d), (2, e), (3, f)\}$
  - ASCII syntax: `r~`

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## Relations (3.2): Image



Given a relation

$$r = \{(a, 1), (b, 2), (c, 3), (a, 4), (b, 5), (c, 6), (d, 1), (e, 2), (f, 3)\}$$

**relational image** of  $r$  over set  $s$ : sub-range of  $r$  mapped by  $s$ .

- Definition:  $r[s] = \{r' \mid (d, r') \in r \wedge d \in s\}$
- e.g.,  $r[\{a, b\}] = \{1, 2, 4, 5\}$
- ASCII syntax: `r[s]`

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## Relations (3.3): Restrictions



Given a relation

$$r = \{(a, 1), (b, 2), (c, 3), (a, 4), (b, 5), (c, 6), (d, 1), (e, 2), (f, 3)\}$$

- **domain restriction** of  $r$  over set  $ds$ : sub-relation of  $r$  with domain  $ds$ .
  - Definition:  $ds \triangleleft r = \{(d, r') \mid (d, r') \in r \wedge d \in ds\}$
  - e.g.,  $\{a, b\} \triangleleft r = \{(a, 1), (b, 2), (a, 4), (b, 5)\}$
  - ASCII syntax:  $ds <| r$
- **range restriction** of  $r$  over set  $rs$ : sub-relation of  $r$  with range  $rs$ .
  - Definition:  $r \triangleright rs = \{(d, r') \mid (d, r') \in r \wedge r' \in rs\}$
  - e.g.,  $r \triangleright \{1, 2\} = \{(a, 1), (b, 2), (d, 1), (e, 2)\}$
  - ASCII syntax:  $r |> rs$

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## Relations (3.5): Overriding



Given a relation

$$r = \{(a, 1), (b, 2), (c, 3), (a, 4), (b, 5), (c, 6), (d, 1), (e, 2), (f, 3)\}$$

**overriding** of  $r$  with relation  $t$ : a relation which agrees with  $t$  within  $\text{dom}(t)$ , and agrees with  $r$  outside  $\text{dom}(t)$

- Definition:  $r \triangleleft t = \{(d, r') \mid (d, r') \in t \vee ((d, r') \in r \wedge d \notin \text{dom}(t))\}$
- e.g.,

$$\begin{aligned} r \triangleleft t &= \{(a, 3), (c, 4)\} \\ &= \underbrace{\{(a, 3), (c, 4)\}}_{\{(d, r') \mid (d, r') \in t\}} \cup \underbrace{\{(b, 2), (b, 5), (d, 1), (e, 2), (f, 3)\}}_{\{(d, r') \mid (d, r') \in r \wedge d \notin \text{dom}(t)\}} \\ &= \{(a, 3), (c, 4), (b, 2), (b, 5), (d, 1), (e, 2), (f, 3)\} \end{aligned}$$

- ASCII syntax:  $r <+ t$

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## Relations (3.4): Subtractions



Given a relation

$$r = \{(a, 1), (b, 2), (c, 3), (a, 4), (b, 5), (c, 6), (d, 1), (e, 2), (f, 3)\}$$

- **domain subtraction** of  $r$  over set  $ds$ : sub-relation of  $r$  with domain not  $ds$ .
  - Definition:  $ds \triangleleft r = \{(d, r') \mid (d, r') \in r \wedge d \notin ds\}$
  - e.g.,  $\{a, b\} \triangleleft r = \{(c, 3), (c, 6), (d, 1), (e, 2), (f, 3)\}$
  - ASCII syntax:  $ds <<| r$
- **range subtraction** of  $r$  over set  $rs$ : sub-relation of  $r$  with range not  $rs$ .
  - Definition:  $r \triangleright rs = \{(d, r') \mid (d, r') \in r \wedge r' \notin rs\}$
  - e.g.,  $r \triangleright \{1, 2\} = \{(c, 3), (a, 4), (b, 5), (c, 6), (f, 3)\}$
  - ASCII syntax:  $r |>> rs$

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## Relations (4): Exercises



1. Define  $r[s]$  in terms of other relational operations.

**Answer:**  $r[s] = \text{ran}(s \triangleleft r)$

e.g.,

$$r[\underbrace{\{a, b\}}_s] = \text{ran}(\underbrace{\{(a, 1), (b, 2), (a, 4), (b, 5)\}}_{\{a, b\} \triangleleft r}) = \{1, 2, 4, 5\}$$

2. Define  $r \triangleleft t$  in terms of other relational operators.

**Answer:**  $r \triangleleft t = t \cup (\text{dom}(t) \triangleleft r)$

e.g.,

$$\begin{aligned} r \triangleleft t &= \{(a, 3), (c, 4)\} \\ &= \underbrace{\{(a, 3), (c, 4)\}}_t \cup \underbrace{\{(b, 2), (b, 5), (d, 1), (e, 2), (f, 3)\}}_{\text{dom}(t) \triangleleft r} \\ &= \{(a, 3), (c, 4), (b, 2), (b, 5), (d, 1), (e, 2), (f, 3)\} \end{aligned}$$

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## Functions (1): Functional Property

- A **relation**  $r$  on sets  $S$  and  $T$  (i.e.,  $r \in S \leftrightarrow T$ ) is also a **function** if it satisfies the **functional property**:  

$$\text{isFunctional}(r) \iff \forall s, t_1, t_2 \bullet (s \in S \wedge t_1 \in T \wedge t_2 \in T) \Rightarrow ((s, t_1) \in r \wedge (s, t_2) \in r \Rightarrow t_1 = t_2)$$
  - That is, in a **function**, it is forbidden for a member of  $S$  to map to more than one members of  $T$ .
  - Equivalently, in a **function**, two distinct members of  $T$  cannot be mapped by the same member of  $S$ .
- e.g., Say  $S = \{1, 2, 3\}$  and  $T = \{a, b\}$ , which of the following **relations** satisfy the above **functional property**?
  - $S \times T$  [ No ]  
**Witness 1:**  $(1, a), (1, b)$ ; **Witness 2:**  $(2, a), (2, b)$ ; **Witness 3:**  $(3, a), (3, b)$ .
  - $(S \times T) \setminus \{(x, y) \mid (x, y) \in S \times T \wedge x = 1\}$  [ No ]  
**Witness 1:**  $(2, a), (2, b)$ ; **Witness 2:**  $(3, a), (3, b)$
  - $\{(1, a), (2, b), (3, a)\}$  [ Yes ]
  - $\{(1, a), (2, b)\}$  [ Yes ]

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## Functions (2.2): Relation Image vs. Function Application

- Recall: A **function** is a **relation**, but a **relation** is not necessarily a **function**.
- Say we have a **partial function**  $f \in \{1, 2, 3\} \nrightarrow \{a, b\}$ :  

$$f = \{(3, a), (1, b)\}$$
  - With  $f$  wearing the **relation** hat, we can invoke **relational images**:

$$\begin{aligned} f[\{3\}] &= \{a\} \\ f[\{1\}] &= \{b\} \\ f[\{2\}] &= \emptyset \end{aligned}$$

**Remark.**  $\Rightarrow |f[\{v\}]| \leq 1 \therefore$

- each member in  $\text{dom}(f)$  is mapped to at most one member in  $\text{ran}(f)$
- each input set  $\{v\}$  is a **singleton** set
- With  $f$  wearing the **function** hat, we can invoke **functional applications**:

$$\begin{aligned} f(3) &= a \\ f(1) &= b \\ f(2) &\text{ is } \textbf{undefined} \end{aligned}$$

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## Functions (2.1): Total vs. Partial

Given a **relation**  $r \in S \leftrightarrow T$

- $r$  is a **partial function** if it satisfies the **functional property**:  

$$r \in S \nrightarrow T \iff (\text{isFunctional}(r) \wedge \text{dom}(r) \subseteq S)$$

**Remark.**  $r \in S \nrightarrow T$  means there may (or may not) be  $s \in S$  s.t.  $r(s)$  is **undefined** (i.e.,  $r[\{s\}] = \emptyset$ ).

  - e.g.,  $\{(2, a), (1, b)\}, \{(2, a), (3, a), (1, b)\} \subseteq \{1, 2, 3\} \nrightarrow \{a, b\}$
  - ASCII syntax:  $r : + \rightarrow$
- $r$  is a **total function** if there is a mapping for each  $s \in S$ :  

$$r \in S \rightarrow T \iff (\text{isFunctional}(r) \wedge \text{dom}(r) = S)$$

**Remark.**  $r \in S \rightarrow T$  implies  $r \in S \nrightarrow T$ , but not vice versa. Why?

  - e.g.,  $\{(2, a), (3, a), (1, b)\} \in \{1, 2, 3\} \rightarrow \{a, b\}$
  - e.g.,  $\{(2, a), (1, b)\} \notin \{1, 2, 3\} \rightarrow \{a, b\}$
  - ASCII syntax:  $r : -- \rightarrow$

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## Functions (2.3): Modelling Decision

An organization has a system for keeping **track** of its employees as to where they are on the premises (e.g., ``Zone A, Floor 23``). To achieve this, each employee is issued with an active badge which, when scanned, synchronizes their current positions to a central database.

Assume the following two sets:

- Employee** denotes the **set** of all employees working for the organization.
- Location** denotes the **set** of all valid locations in the organization.

- Is it appropriate to **model/formalize** such a **track** functionality as a **relation** (i.e., **where.is**  $\in$  **Employee**  $\leftrightarrow$  **Location**)?  
**Answer.** No – an employee cannot be at distinct locations simultaneously.  
 e.g.,  $\text{where.is}[\text{Alan}] = \{\text{``Zone A, Floor 23``}, \text{``Zone C, Floor 46``}\}$
- How about a **total function** (i.e., **where.is**  $\in$  **Employee**  $\rightarrow$  **Location**)?  
**Answer.** No – in reality, not necessarily all employees show up.  
 e.g.,  $\text{where.is}(\text{Mark})$  should be **undefined** if Mark happens to be on vacation.
- How about a **partial function** (i.e., **where.is**  $\in$  **Employee**  $\nrightarrow$  **Location**)?  
**Answer.** Yes – this addresses the inflexibility of the total function.

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## Functions (3.1): Injective Functions



Given a **function**  $f$  (either partial or total):

- $f$  is **injective/one-to-one/an injection** if  $f$  does **not** map more than one members of  $S$  to a single member of  $T$ .

$isInjective(f)$

$\iff$

$$\forall s_1, s_2, t \bullet (s_1 \in S \wedge s_2 \in S \wedge t \in T) \Rightarrow ((s_1, t) \in f \wedge (s_2, t) \in f \Rightarrow s_1 = s_2)$$

- If  $f$  is a **partial injection**, we write:  $f \in S \rightsquigarrow T$ 
  - e.g.,  $\{\emptyset, \{(1, a)\}, \{(2, a), (3, b)\}\} \subseteq \{1, 2, 3\} \rightsquigarrow \{a, b\}$
  - e.g.,  $\{(1, b), (2, a), (3, b)\} \notin \{1, 2, 3\} \rightsquigarrow \{a, b\}$  [total, not inj.]
  - e.g.,  $\{(1, b), (3, b)\} \notin \{1, 2, 3\} \rightsquigarrow \{a, b\}$  [partial, not inj.]
  - ASCII syntax:  $f : >+>$
- If  $f$  is a **total injection**, we write:  $f \in S \rightarrow T$ 
  - e.g.,  $\{1, 2, 3\} \rightarrow \{a, b\} = \emptyset$
  - e.g.,  $\{(2, d), (1, a), (3, c)\} \in \{1, 2, 3\} \rightarrow \{a, b, c, d\}$
  - e.g.,  $\{(2, d), (1, c)\} \notin \{1, 2, 3\} \rightarrow \{a, b, c, d\}$  [not total, inj.]
  - e.g.,  $\{(2, d), (1, c), (3, d)\} \notin \{1, 2, 3\} \rightarrow \{a, b, c, d\}$  [total, not inj.]
  - ASCII syntax:  $f : >->$

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## Functions (3.3): Bijective Functions



Given a function  $f$ :

$f$  is **bijective/a bijection/one-to-one correspondence** if  $f$  is **total**, **injective**, and **surjective**.

- e.g.,  $\{1, 2, 3\} \rightsquigarrow \{a, b\} = \emptyset$
- e.g.,  $\{\{(1, a), (2, b), (3, c)\}, \{(2, a), (3, b), (1, c)\}\} \subseteq \{1, 2, 3\} \rightsquigarrow \{a, b, c\}$
- e.g.,  $\{(2, b), (3, c), (4, a)\} \notin \{1, 2, 3, 4\} \rightsquigarrow \{a, b, c\}$
- e.g.,  $\{(1, a), (2, b), (3, c), (4, a)\} \notin \{1, 2, 3, 4\} \rightsquigarrow \{a, b, c\}$  [not total, inj., sur.]
- e.g.,  $\{(1, a), (2, c)\} \notin \{1, 2\} \rightsquigarrow \{a, b, c\}$  [total, not inj., sur.]
- ASCII syntax:  $f : >->>$
- e.g.,  $\{(1, a), (2, c)\} \notin \{1, 2\} \rightsquigarrow \{a, b, c\}$  [total, inj., not sur.]

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## Functions (3.2): Surjective Functions



Given a **function**  $f$  (either partial or total):

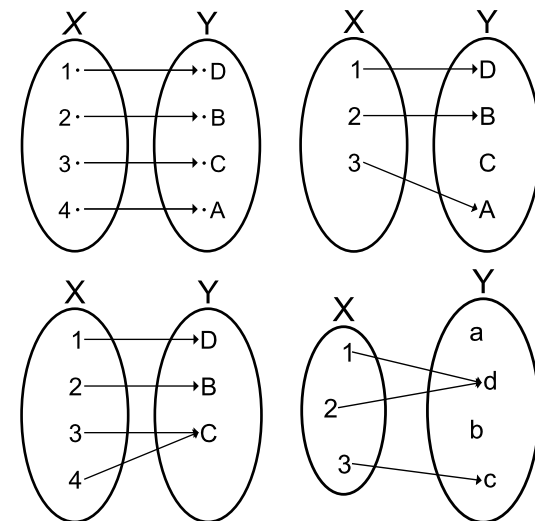
- $f$  is **surjective/onto/a surjection** if  $f$  maps to all members of  $T$ .

$$isSurjective(f) \iff \text{ran}(f) = T$$

- If  $f$  is a **partial surjection**, we write:  $f \in S \rightsquigarrow T$ 
  - e.g.,  $\{\{(1, b), (2, a)\}, \{(1, b), (2, a), (3, b)\}\} \subseteq \{1, 2, 3\} \rightsquigarrow \{a, b\}$
  - e.g.,  $\{(2, a), (1, a), (3, a)\} \notin \{1, 2, 3\} \rightsquigarrow \{a, b\}$  [total, not sur.]
  - e.g.,  $\{(2, b), (1, b)\} \notin \{1, 2, 3\} \rightsquigarrow \{a, b\}$  [partial, not sur.]
  - ASCII syntax:  $f : +->>$
- If  $f$  is a **total surjection**, we write:  $f \in S \rightarrow T$ 
  - e.g.,  $\{\{(2, a), (1, b), (3, a)\}, \{(2, b), (1, a), (3, b)\}\} \subseteq \{1, 2, 3\} \rightarrow \{a, b\}$
  - e.g.,  $\{(2, a), (3, b)\} \notin \{1, 2, 3\} \rightarrow \{a, b\}$  [not total, sur.]
  - e.g.,  $\{(2, a), (3, a), (1, a)\} \notin \{1, 2, 3\} \rightarrow \{a, b\}$  [total., not sur.]
  - ASCII syntax:  $f : -->>$

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## Functions (4.1): Exercises



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## Functions (4.2): Modelling Decisions

1. Should an array `a` declared as `"String[] a"` be **modelled/formalized** as a **partial** function (i.e.,  $a \in \mathbb{Z} \rightarrow \text{String}$ ) or a **total** function (i.e.,  $a \in \mathbb{Z} \rightarrow \text{String}$ )?

**Answer.**  $a \in \mathbb{Z} \rightarrow \text{String}$  is not appropriate as:

- Indices are **non-negative** (i.e.,  $a(i)$ , where  $i < 0$ , is **undefined**).
- Each array size is **finite**: not all positive integers are valid indices.

2. What does it mean if an **array** is **modelled/formalized** as a **partial injection** (i.e.,  $a \in \mathbb{Z} \rightarrow \text{String}$ )?

**Answer.** It means that the array does **not** contain any duplicates.

3. Can an integer array `"int[] a"` be **modelled/formalized** as a **partial surjection** (i.e.,  $a \in \mathbb{Z} \rightarrow \mathbb{Z}$ )?

**Answer.** Yes, if `a` stores all  $2^{32}$  integers (i.e.,  $[-2^{31}, 2^{31} - 1]$ ).

4. Can a string array `"String[] a"` be **modelled/formalized** as a **partial surjection** (i.e.,  $a \in \mathbb{Z} \rightarrow \text{String}$ )?

**Answer.** No  $\because$  # possible strings is  $\infty$ .

5. Can an integer array `"int[]"` storing all  $2^{32}$  values be **modelled/formalized** as a **bijection** (i.e.,  $a \in \mathbb{Z} \rightarrow \mathbb{Z}$ )?

**Answer.** No, because it cannot be **total** (as discussed earlier).

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## Beyond this lecture ...

- For the **where\_is**  $\in$  **Employee**  $\rightarrow$  **Location** model, what does it mean when it is:
  - **Injective**  $[ \text{where\_is} \in \text{Employee} \rightarrow \text{Location} ]$
  - **Surjective**  $[ \text{where\_is} \in \text{Employee} \rightarrow \text{Location} ]$
  - **Bijjective**  $[ \text{where\_is} \in \text{Employee} \rightarrow \text{Location} ]$
- Review examples discussed in your earlier math courses on **logic** and **set theory**.

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## Index (1)

### Learning Outcomes of this Lecture

#### Propositional Logic (1)

#### Propositional Logic: Implication (1)

#### Propositional Logic: Implication (2)

#### Propositional Logic: Implication (3)

#### Propositional Logic (2)

#### Predicate Logic (1)

#### Predicate Logic (2.1): Universal Q. ( $\forall$ )

#### Predicate Logic (2.2): Existential Q. ( $\exists$ )

#### Predicate Logic (3): Exercises

#### Predicate Logic (4): Switching Quantifications

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## Index (2)

### Sets: Definitions and Membership

#### Set Relations

#### Set Relations: Exercises

#### Set Operations

#### Power Sets

#### Set of Tuples

#### Relations (1): Constructing a Relation

#### Relations (2.1): Set of Possible Relations

#### Relations (2.2): Exercise

#### Relations (3.1): Domain, Range, Inverse

#### Relations (3.2): Image

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## Index (3)



Relations (3.3): Restrictions

Relations (3.4): Subtractions

Relations (3.5): Overriding

Relations (4): Exercises

Functions (1): Functional Property

Functions (2.1): Total vs. Partial

Functions (2.2):

Relation Image vs. Function Application

Functions (2.3): Modelling Decision

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## Index (4)



Functions (3.3): Bijective Functions

Functions (4.1): Exercises

Functions (4.2): Modelling Decisions

Beyond this lecture ...

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## Specifying & Refining a Bridge Controller

MEB: Chapter 2



EECS3342 E: System  
Specification and Refinement  
Fall 2024

CHEN-WEI WANG

## Learning Outcomes



This module is designed to help you understand:

- What a **Requirement Document (RD)** is
- What a **refinement** is
- Writing **formal specifications**
  - (Static) **contexts**: constants, axioms, theorems
  - (Dynamic) **machines**: variables, invariants, events, guards, actions
- **Proof Obligations (POs)** associated with proving:
  - **refinements**
  - system **properties**
- Applying **inference rules** of the **sequent calculus**

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## Recall: Correct by Construction

- Directly reasoning about **source code** (written in a programming language) is too complicated to be feasible.
- Instead, given a **requirements document**, prior to **implementation**, we develop **models** through a series of **refinement** steps:
  - Each model formalizes an **external observer**'s perception of the system.
  - Models are "sorted" with **increasing levels of accuracy** w.r.t. the system.
  - The **first model**, though the most **abstract**, can already be proved satisfying some requirements.
  - Starting from the **second model**, each model is analyzed and proved **correct** relative to two criteria:
    1. **Some requirements** (i.e., R-descriptions)
    2. **Proof Obligations (POs)** related to the **preceding model** being **refined by** the **current model** (via "extra" **state** variables and **events**).
  - The **last model** (which is **correct by construction**) should be **sufficiently close** to be transformed into a **working program** (e.g., in C).

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## State Space of a Model

- A model's **state space** is the set of **all** configurations:
  - Each **configuration** assigns values to **constants** & **variables**, subject to:
    - **axiom** (e.g., typing constraints, assumptions)
    - **invariant** properties/theorems
  - Say an initial model of a bank system with two **constants** and a **variable**:
 
$$c \in \mathbb{N}1 \wedge L \in \mathbb{N}1 \wedge \text{accounts} \in \text{String} \rightarrow \mathbb{Z} \quad /* \text{typing constraint} */$$

$$\forall id \bullet id \in \text{dom}(\text{accounts}) \Rightarrow -c \leq \text{accounts}(id) \leq L \quad /* \text{desired property} */$$
  - Q. What is the **state space** of this initial model?
    - A. All valid combinations of  $c$ ,  $L$ , and  $\text{accounts}$ .
      - Configuration 1:  $(c = 1,000, L = 500,000, b = \emptyset)$
      - Configuration 2:  $(c = 2,375, L = 700,000, b = \{("id1", 500), ("id2", 1,250)\})$
      - ...
    - [ Challenge: **Combinatorial Explosion** ]
  - Model Concreteness  $\uparrow \Rightarrow$  (State Space  $\uparrow \wedge$  Verification Difficulty  $\uparrow$ )
- A model's **complexity** should be guided by those properties intended to be verified against that model.
  - $\Rightarrow$  **Infeasible** to prove **all** desired properties on a model.
  - $\Rightarrow$  **Feasible** to distribute desired properties over a list of **refinements**.

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## Roadmap of this Module

- We will walk through the **development process** of constructing **models** of a control system regulating cars on a bridge.
  - Such controllers exemplify a **reactive system**.  
(with **sensors** and **actuators**)
- Always stay on top of the following roadmap:
  1. A **Requirements Document (RD)** of the bridge controller
  2. A brief overview of the **refinement strategy**
  3. An initial, the most **abstract** model
  4. A subsequent **model** representing the **1st refinement**
  5. A subsequent **model** representing the **2nd refinement**
  6. A subsequent **model** representing the **3rd refinement**

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## Requirements Document: Mainland, Island

Imagine you are asked to build a bridge (as an alternative to ferry) connecting the downtown and Toronto Island.



Page Source: <https://soldbyshane.com/area/toronto-islands/>

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## Requirements Document: E-Descriptions

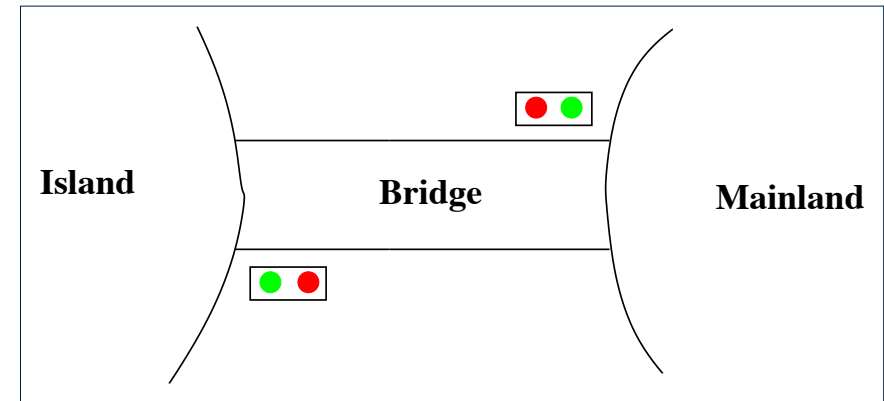


Each **E-Description** is an **atomic specification** of a **constraint** or an **assumption** of the system's working environment.

ENV1	The system is equipped with two traffic lights with two colors: green and red.
ENV2	The traffic lights control the entrance to the bridge at both ends of it.
ENV3	Cars are not supposed to pass on a red traffic light, only on a green one.
ENV4	The system is equipped with four sensors with two states: on or off.
ENV5	The sensors are used to detect the presence of a car entering or leaving the bridge: "on" means that a car is willing to enter the bridge or to leave it.

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## Requirements Document: Visual Summary of Equipment Pieces



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## Requirements Document: R-Descriptions



Each **R-Description** is an **atomic specification** of an intended **functionality** or a desired **property** of the working system.

REQ1	The system is controlling cars on a bridge connecting the mainland to an island.
REQ2	The number of cars on bridge and island is limited.
REQ3	The bridge is one-way or the other, not both at the same time.

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## Refinement Strategy



- Before diving into details of the **models**, we first clarify the adopted **design strategy of progressive refinements**.
  - The **initial model** ( $m_0$ ) will address the intended functionality of a **limited** number of cars on the island and bridge. [ REQ2 ]
  - A **1st refinement** ( $m_1$  which **refines**  $m_0$ ) will address the intended functionality of the **bridge being one-way**. [ REQ1, REQ3 ]
  - A **2nd refinement** ( $m_2$  which **refines**  $m_1$ ) will address the environment constraints imposed by **traffic lights**. [ ENV1, ENV2, ENV3 ]
  - A **final, 3rd refinement** ( $m_3$  which **refines**  $m_2$ ) will address the environment constraints imposed by **sensors** and the **architecture**: controller, environment, communication channels. [ ENV4, ENV5 ]
- Recall **Correct by Construction** :

From each **model** to its **refinement**, only a **manageable** amount of details are added, making it **feasible** to conduct **analysis** and **proofs**.

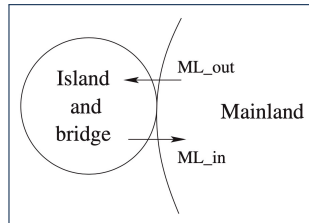
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## Model $m_0$ : Abstraction

- In this most abstract perception of the bridge controller, we do not even consider the bridge, traffic lights, and sensors!
- Instead, we focus on this single requirement:

REQ2	The number of cars on bridge and island is limited.
------	---

- Analogies:**
  - Observe the system from the sky: island and bridge appear only as a compound.



- “**Zoom in**” on the system as refinements are introduced.

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## Model $m_0$ : State Transitions via Events

- The system acts as an **ABSTRACT STATE MACHINE (ASM)**: it evolves as actions of enabled events change values of variables, subject to invariants.
- At any given state (a valid configuration of constants/variables):
  - An event is said to be enabled if its guard evaluates to true.
  - An event is said to be disabled if its guard evaluates to false.
  - An enabled event makes a state transition if it occurs and its actions take effect.
- 1st event:** A car exits mainland (and enters the island-bridge compound).

```
ML_out
begin
  n := n + 1
end
```

Correct Specification? Say  $d = 2$ .

**Witness:** Event Trace  $\langle \text{init}, \text{ML\_out}, \text{ML\_out}, \text{ML\_out} \rangle$

- 2nd event:** A car enters mainland (and exits the island-bridge compound).

```
ML_in
begin
  n := n - 1
end
```

Correct Specification? Say  $d = 2$ .

**Witness:** Event Trace  $\langle \text{init}, \text{ML\_in} \rangle$

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## Model $m_0$ : State Space

- The static part is fixed and may be seen/imported.  
A constant  $d$  denotes the maximum number of cars allowed to be on the island-bridge compound at any time.  
(whereas cars on the mainland is unbounded)

constants:  $d$

axioms:  
 $\text{axm0\_1} : d \in \mathbb{N}$

**Remark.** Axioms are assumed true and may be used to prove theorems.

- The dynamic part changes as the system evolves.  
A variable  $n$  denotes the actual number of cars, at a given moment, in the island-bridge compound.

variables:  $n$

invariants:  
 $\text{inv0\_1} : n \in \mathbb{N}$   
 $\text{inv0\_2} : n \leq d$

**Remark.** Invariants should be (subject to proofs):

- Established** when the system is first initialized
- Preserved/Maintained** after any enabled event's actions take effect

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## Model $m_0$ : Actions vs. Before-After Predicates

- When an enabled event  $e$  occurs there are two notions of state:
  - Before-/Pre-State:** Configuration just before  $e$ 's actions take effect
  - After-/Post-State:** Configuration just after  $e$ 's actions take effect
- Remark.** When an enabled event occurs, its action(s) cause a transition from the pre-state to the post-state.

- As examples, consider actions of  $m_0$ 's two events:

Events

ML\_out  
 $n := n + 1$

ML\_in  
 $n := n - 1$

before-after predicates

$n' = n + 1$

$n' = n - 1$

- An event action “ $n := n + 1$ ” is not a variable assignment; instead, it is a specification: “ $n$  becomes  $n + 1$  (when the state transition completes)”.
- The before-after predicate (BAP) “ $n' = n + 1$ ” expresses that  $n'$  (the post-state value of  $n$ ) is one more than  $n$  (the pre-state value of  $n$ ).

- When we express proof obligations (POs) associated with events, we use BAP.

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## Design of Events: Invariant Preservation



- Our design of the two events



only specifies how the **variable**  $n$  should be updated.

- Remember, **invariants** are conditions that should never be **violated**!

invariants:  
inv0.1 :  $n \in \mathbb{N}$   
inv0.2 :  $n \leq d$

- By simulating the system as an **ASM**, we discover **witnesses** (i.e., event traces) of the **invariants** not being preserved all the time.  
 $\exists s \bullet s \in \text{STATE SPACE} \Rightarrow \neg \text{invariants}(s)$
- We formulate such a commitment to preserving **invariants** as a **proof obligation (PO)** rule (a.k.a. a **verification condition (VC)** rule).

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## PO of Invariant Preservation: Sketch



- Here is a sketch of the PO/VC rule for **invariant preservation**:

Axioms  
Invariants Satisfied at **Pre-State**  
Guards of the Event  
 $\vdash$   
Invariants Satisfied at **Post-State**

INV

- Informally, this is what the above PO/VC **requires to prove**:  
Assuming **all** axioms, invariants, and the event's guards hold at the **pre-state**, after the **state transition** is made by the event, **all invariants** hold at the **post-state**.

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## Sequents: Syntax and Semantics



- We formulate each **PO/VC** rule as a (horizontal or vertical) **sequent**:



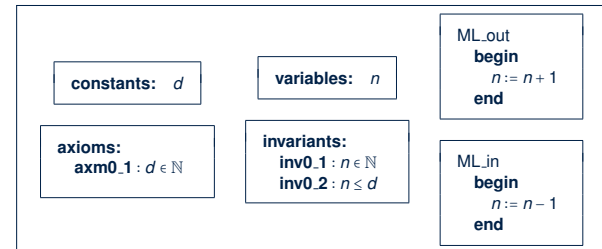
- The symbol  $\vdash$  is called the **turnstile**.
- $H$  is a set of predicates forming the **hypotheses/assumptions**.  
[ assumed as **true** ]
- $G$  is a set of predicates forming the **goal/conclusion**.  
[ claimed to be **provable** from  $H$  ]
- Informally:
  - $H \vdash G$  is **true** if  $G$  can be proved by assuming  $H$ .  
[ i.e., We say " $H$  **entails**  $G$ " or " $H$  **yields**  $G$ " ]
  - $H \vdash G$  is **false** if  $G$  cannot be proved by assuming  $H$ .
- Formally:  $H \vdash G \iff (H \Rightarrow G)$

Q. What does it mean when  $H$  is empty (i.e., no hypotheses)?

A.  $\vdash G \equiv \text{true} \vdash G$  [ Why not  $\vdash G \equiv \text{false} \vdash G$  ? ]

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## PO of Invariant Preservation: Components



- $c$ : list of **constants**  $\langle d \rangle$
- $A(c)$ : list of **axioms**  $\langle \text{axm0.1} \rangle$
- $v$  and  $v'$ : list of **variables** in **pre-** and **post-**states  $v \equiv \langle n \rangle, v' \equiv \langle n' \rangle$
- $I(c, v)$ : list of **invariants**  $\langle \text{inv0.1}, \text{inv0.2} \rangle$
- $G(c, v)$ : the **event's** list of guards  
 $G(\langle d \rangle, \langle n \rangle)$  of ML\_out  $\equiv \langle \text{true} \rangle$ ,  $G(\langle d \rangle, \langle n \rangle)$  of ML\_in  $\equiv \langle \text{true} \rangle$
- $E(c, v)$ : effect of the **event's** actions i.t.o. what variable values **become**  
 $E(\langle d \rangle, \langle n \rangle)$  of ML\_out  $\equiv \langle n + 1 \rangle$ ,  $E(\langle d \rangle, \langle n \rangle)$  of ML\_in  $\equiv \langle n - 1 \rangle$
- $v' = E(c, v)$ : **before-after predicate** formalizing  $E$ 's actions  
 BAP of ML\_out:  $\langle n' \rangle = \langle n + 1 \rangle$ , BAP of ML\_in:  $\langle n' \rangle = \langle n - 1 \rangle$

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## Rule of Invariant Preservation: Sequents



- Based on the components  $(c, A(c), v, I(c, v), E(c, v))$ , we are able to formally state the **PO/VC Rule of Invariant Preservation**:

$$\boxed{\begin{array}{l} A(c) \\ I(c, v) \\ G(c, v) \\ \vdash \\ I_i(c, E(c, v)) \end{array}} \quad \text{INV} \quad \text{where } I_i \text{ denotes a single invariant condition}$$

- Accordingly, how many **sequents** to be proved? [ # events  $\times$  # invariants ]
- We have two **sequents** generated for **event**  $ML\_out$  of model  $m_0$ :

$$\boxed{\begin{array}{l} d \in \mathbb{N} \\ n \in \mathbb{N} \\ n \leq d \\ \vdash \\ n + 1 \in \mathbb{N} \end{array}} \quad \text{ML\_out/inv0\_1/INV} \quad \boxed{\begin{array}{l} d \in \mathbb{N} \\ n \in \mathbb{N} \\ n \leq d \\ \vdash \\ n + 1 \leq d \end{array}} \quad \text{ML\_out/inv0\_2/INV}$$

**Exercise.** Write the **POs of invariant preservation** for event  $ML\_in$ .

- Before claiming that a **model** is **correct**, outstanding **sequents** associated with all **POs** must be proved/discharged.

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## Proof of Sequent: Steps and Structure



- To prove the following sequent (related to **invariant preservation**):

$$\boxed{\begin{array}{l} d \in \mathbb{N} \\ n \in \mathbb{N} \\ n \leq d \\ \vdash \\ n + 1 \in \mathbb{N} \end{array}} \quad \text{ML\_out/inv0\_1/INV}$$

- Apply a **inference rule**, which **transforms** some “outstanding” **sequent** to **one** or **more** other **sequents** to be proved instead.
  - Keep applying **inference rules** until **all transformed sequents** are **axioms** that do **not** require any further justifications.
- Here is a **formal proof** of  $ML\_out/inv0\_1/INV$ , by applying IRs **MON** and **P2**:

$$\boxed{\begin{array}{l} d \in \mathbb{N} \\ n \in \mathbb{N} \\ n \leq d \\ \vdash \\ n + 1 \in \mathbb{N} \end{array}} \quad \text{MON} \quad \boxed{\begin{array}{l} n \in \mathbb{N} \\ \vdash \\ n + 1 \in \mathbb{N} \end{array}} \quad \text{P2}$$

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## Inference Rules: Syntax and Semantics



- An **inference rule (IR)** has the following form:

$$\boxed{\begin{array}{l} A \\ \vdash \\ C \end{array}} \quad \text{L} \quad \begin{array}{l} \text{Formally: } A \Rightarrow C \text{ is an axiom.} \\ \text{Informally: To prove } C, \text{ it is sufficient to prove } A \text{ instead.} \\ \text{Informally: } C \text{ is the case, assuming that } A \text{ is the case.} \end{array}$$

- $L$  is a **name** label for referencing the **inference rule** in proofs.
- $A$  is a **set** of sequents known as **antecedents** of rule  $L$ .
- $C$  is a **single** sequent known as **consequent** of rule  $L$ .
- Let's consider **inference rules (IRs)** with two different flavours:

$$\boxed{\begin{array}{l} H1 \vdash G \\ \vdash \\ H1, H2 \vdash G \end{array}} \quad \text{MON} \quad \boxed{\begin{array}{l} \vdash \\ n \in \mathbb{N} \vdash n + 1 \in \mathbb{N} \end{array}} \quad \text{P2}$$

- IR **MON**: To prove  $H1, H2 \vdash G$ , it suffices to prove  $H1 \vdash G$  instead.
- IR **P2**:  $n \in \mathbb{N} \vdash n + 1 \in \mathbb{N}$  is an **axiom**.

[ proved automatically without further justifications ]

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## Example Inference Rules (1)



$$\boxed{\vdash 0 \in \mathbb{N}} \quad \text{P1} \quad \text{1st Peano axiom: 0 is a natural number.}$$

$$\boxed{\begin{array}{l} n \in \mathbb{N} \vdash n + 1 \in \mathbb{N} \end{array}} \quad \text{P2} \quad \text{2nd Peano axiom: } n + 1 \text{ is a natural number, assuming that } n \text{ is a natural number.}$$

$$\boxed{\begin{array}{l} 0 < n \vdash n - 1 \in \mathbb{N} \end{array}} \quad \text{P2'} \quad \text{ } n - 1 \text{ is a natural number, assuming that } n \text{ is positive.}$$

$$\boxed{\begin{array}{l} n \in \mathbb{N} \vdash 0 \leq n \end{array}} \quad \text{P3} \quad \text{3rd Peano axiom: } n \text{ is non-negative, assuming that } n \text{ is a natural number.}$$

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## Example Inference Rules (2)



$$\frac{}{n < m \vdash n + 1 \leq m} \text{ INC}$$

$n + 1$  is less than or equal to  $m$ ,  
assuming that  $n$  is strictly less than  $m$ .

$$\frac{}{n \leq m \vdash n - 1 < m} \text{ DEC}$$

$n - 1$  is strictly less than  $m$ ,  
assuming that  $n$  is less than or equal to  $m$ .

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## Example Inference Rules (3)



$$\frac{H1 \vdash G}{H1, H2 \vdash G} \text{ MON}$$

To prove a goal under certain hypotheses,  
it suffices to prove it under less hypotheses.

$$\frac{H, P \vdash R \quad H, Q \vdash R}{H, P \vee Q \vdash R} \text{ OR.L}$$

Proof by Cases:  
To prove a goal under a disjunctive assumption,  
it suffices to prove **independently**  
the same goal, twice, under each disjunct.

$$\frac{H \vdash P}{H \vdash P \vee Q} \text{ OR.R1}$$

To prove a disjunction,  
it suffices to prove the left disjunct.

$$\frac{H \vdash Q}{H \vdash P \vee Q} \text{ OR.R2}$$

To prove a disjunction,  
it suffices to prove the right disjunct.

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## Revisiting Design of Events: $ML\_out$



- Recall that we already proved **PO**  $ML\_out/inv0\_1/INV$ :

$$\begin{array}{c} d \in \mathbb{N} \\ n \in \mathbb{N} \\ n \leq d \\ \vdash \\ n + 1 \in \mathbb{N} \end{array} \text{ MON} \quad \begin{array}{c} n \in \mathbb{N} \\ \vdash \\ n + 1 \in \mathbb{N} \end{array} \text{ P2}$$

$\therefore ML\_out/inv0\_1/INV$  succeeds in being discharged.

- How about the other **PO**  $ML\_out/inv0\_2/INV$  for the same event?

$$\begin{array}{c} d \in \mathbb{N} \\ n \in \mathbb{N} \\ n \leq d \\ \vdash \\ n + 1 \leq d \end{array} \text{ MON} \quad \begin{array}{c} n \leq d \\ \vdash \\ n + 1 \leq d \end{array} ?$$

$\therefore ML\_out/inv0\_2/INV$  fails to be discharged.

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## Revisiting Design of Events: $ML\_in$



- How about the **PO**  $ML\_in/inv0\_1/INV$  for  $ML\_in$ :

$$\begin{array}{c} d \in \mathbb{N} \\ n \in \mathbb{N} \\ n \leq d \\ \vdash \\ n - 1 \in \mathbb{N} \end{array} \text{ MON} \quad \begin{array}{c} n \in \mathbb{N} \\ \vdash \\ n - 1 \in \mathbb{N} \end{array} ?$$

$\therefore ML\_in/inv0\_1/INV$  fails to be discharged.

- How about the other **PO**  $ML\_in/inv0\_2/INV$  for the same event?

$$\begin{array}{c} d \in \mathbb{N} \\ n \in \mathbb{N} \\ n \leq d \\ \vdash \\ n - 1 \leq d \end{array} \text{ MON} \quad \begin{array}{c} n \leq d \\ \vdash \\ n - 1 < d \vee n - 1 = d \end{array} \text{ OR.1} \quad \begin{array}{c} n \leq d \\ \vdash \\ n - 1 < d \end{array} \text{ DEC}$$

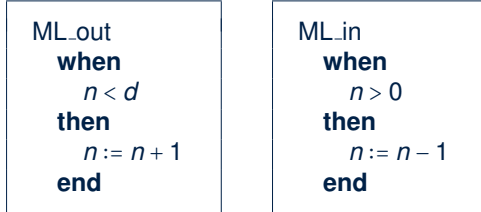
$\therefore ML\_in/inv0\_2/INV$  succeeds in being discharged.

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## Fixing the Design of Events



- Proofs of **ML\_out/inv0.2/INV** and **ML\_in/inv0.1/INV** fail due to the two events being **enabled when they should not**.
- Having this feedback, we add proper **guards** to **ML\_out** and **ML\_in**:



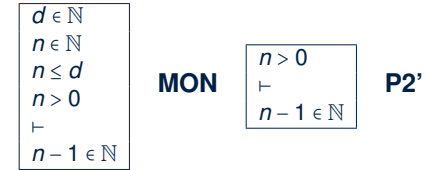
- Having changed both events, updated **sequents** will be generated for the PO/VC rule of **invariant preservation**.
- All **sequents** ( $\{ML\_out, ML\_in\} \times \{inv0.1, inv0.2\}$ ) now **provable**?

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## Revisiting Fixed Design of Events: **ML\_in**

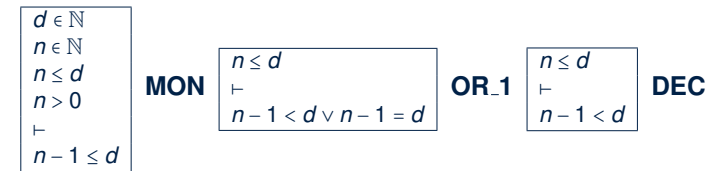


- How about the **PO** **ML\_in/inv0.1/INV** for **ML\_in**:



∴ **ML\_in/inv0.1/INV** now **succeeds** in being discharged!

- How about the other **PO** **ML\_in/inv0.2/INV** for the same event?



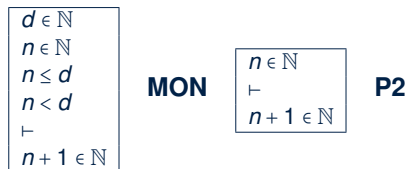
∴ **ML\_in/inv0.2/INV** still **succeeds** in being discharged!

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## Revisiting Fixed Design of Events: **ML\_out**

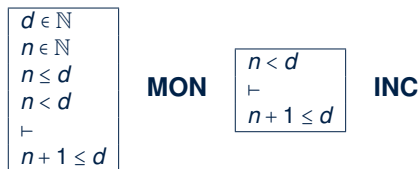


- How about the **PO** **ML\_out/inv0.1/INV** for **ML\_out**:



∴ **ML\_out/inv0.1/INV** still **succeeds** in being discharged!

- How about the other **PO** **ML\_out/inv0.2/INV** for the same event?



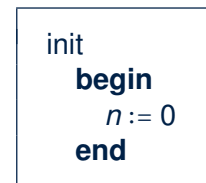
∴ **ML\_out/inv0.2/INV** now **succeeds** in being discharged!

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## Initializing the Abstract System $m_0$



- Discharging the four **sequents** proved that both **invariant** conditions are **preserved** between occurrences/interleavings of **events** **ML\_out** and **ML\_in**.
- But how are the **invariants established** in the first place?  
**Analogy.** Proving  $P$  via **mathematical induction**, two cases to prove:
  - $P(1), P(2), \dots$  [ **base** cases  $\approx$  **establishing** inv. ]
  - $P(n) \Rightarrow P(n+1)$  [ **inductive** cases  $\approx$  **preserving** inv. ]
- Therefore, we specify how the **ASM**'s **initial state** looks like:



- ✓ The IB compound, once **initialized**, has **no** cars.
- ✓ Initialization always possible: guard is **true**.
- ✓ There is no **pre-state** for **init**.  
 ∴ The **RHS** of  $:=$  must **not** involve variables.  
 ∴ The **RHS** of  $:=$  may **only** involve constants.
- ✓ There is only the **post-state** for **init**.  
 ∴ Before-**After Predicate**:  $n' = 0$

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## PO of Invariant Establishment



```
init
begin
  n := 0
end
```

- ✓ An **reactive system**, once **initialized**, should **never** terminate.
- ✓ Event *init* cannot "preserve" the **invariants**.  
 $\therefore$  State before its occurrence (**pre-state**) does **not** exist.
- ✓ Event *init* only required to **establish** invariants for the first time

- A new formal component is needed:
  - $K(c)$ : effect of *init*'s actions i.t.o. what variable values **become**  
 e.g.,  $K(\langle d \rangle)$  of *init*  $\equiv \langle 0 \rangle$
  - $v' = K(c)$ : **before-after predicate** formalizing *init*'s actions  
 e.g., BAP of *init*:  $\langle n' \rangle = \langle 0 \rangle$
- Accordingly, PO of **invariant establishment** is formulated as a **sequent**:

Axioms $\vdash$ <b>Invariants</b> Satisfied at <b>Post-State</b>	INV	$A(c)$ $\vdash$ $I_i(c, K(c))$	INV
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## System Property: Deadlock Freedom



- So far we have proved that our initial model  $m_0$  is s.t. **all invariant conditions** are:
  - Established when system is first initialized via *init*
  - Preserved whenever there is a **state transition**  
 (via an enabled event: *ML\_out* or *ML\_in*)
- However, whenever **event occurrences** are **conditional** (i.e., **guards** stronger than **true**), there is a possibility of **deadlock**:
  - A state where **guards** of **all** events evaluate to **false**
  - When a **deadlock** happens, **none** of the **events** is **enabled**.  
 $\Rightarrow$  The system is blocked and **not** reactive anymore!
- We express this **non-blocking** property as a new requirement:

REQ4	Once started, the system should work for ever.
------	--

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## Discharging PO of Invariant Establishment



- How many **sequents** to be proved? [ # invariants ]
- We have **two sequents** generated for **event** *init* of model  $m_0$ :

$d \in \mathbb{N}$ $\vdash$ $0 \in \mathbb{N}$	init/inv0_1/INV	$d \in \mathbb{N}$ $\vdash$ $0 \leq d$	init/inv0_2/INV
--	-----------------	--	-----------------

- Can we discharge the **PO** *init/inv0\_1/INV*?

$d \in \mathbb{N}$ $\vdash$ $0 \in \mathbb{N}$	MON	$\vdash$ $0 \in \mathbb{N}$	P1	$\therefore$ <i>init/inv0_1/INV</i> <u>succeeds</u> in being discharged.
--	-----	--------------------------------	----	---

- Can we discharge the **PO** *init/inv0\_2/INV*?

$d \in \mathbb{N}$ $\vdash$ $0 \leq d$	P3	$\therefore$ <i>init/inv0_2/INV</i> <u>succeeds</u> in being discharged.
--	----	---

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## PO of Deadlock Freedom (1)



- Recall some of the formal components we discussed:
  - $c$ : list of **constants**
  - $A(c)$ : list of **axioms**
  - $v$  and  $v'$ : list of **variables** in **pre-** and **post-**states
  - $I(c, v)$ : list of **invariants**
  - $G(c, v)$ : the event's list of **guards**
- A system is **deadlock-free** if **at least one** of its **events** is **enabled**:

Axioms <b>Invariants</b> Satisfied at <b>Pre-State</b> $\vdash$ Disjunction of the guards satisfied at <b>Pre-State</b>	DLF	$A(c)$ $I(c, v)$ $\vdash$ $G_1(c, v) \vee \dots \vee G_m(c, v)$	DLF
--	-----	--	-----

To prove about deadlock freedom

- An event's effect of state transition is **not** relevant.
- Instead, the evaluation of **all** events' **guards** at the **pre-state** is relevant.

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## PO of Deadlock Freedom (2)



- Deadlock freedom** is not necessarily a desired property.  
 $\Rightarrow$  When it is (like  $m_0$ ), then the generated **sequents** must be discharged.
- Applying the PO of **deadlock freedom** to the initial model  $m_0$ :

$$\begin{array}{c}
 \boxed{
 \begin{array}{l}
 A(c) \\
 I(c, v) \\
 \vdash \\
 G_1(c, v) \vee \dots \vee G_m(c, v)
 \end{array}
 } \quad \text{DLF} \quad \boxed{
 \begin{array}{l}
 d \in \mathbb{N} \\
 n \in \mathbb{N} \\
 n \leq d \\
 \vdash \\
 n < d \vee n > 0
 \end{array}
 } \quad \text{DLF}
 \end{array}$$

Our bridge controller being **deadlock-free** means that cars can **always** enter (via *ML\_out*) or leave (via *ML\_in*) the island-bridge compound.

- Can we formally discharge this **PO** for our **initial model**  $m_0$ ?

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## Example Inference Rules (5)



$$\frac{H(F), E = F \vdash P(F)}{H(E), E = F \vdash P(E)} \quad \text{EQ\_LR}$$

To prove a goal  $P(E)$  assuming  $H(E)$ , where both  $P$  and  $H$  depend on expression  $E$ , it suffices to prove  $P(F)$  assuming  $H(F)$ , where both  $P$  and  $H$  depend on expression  $F$ , given that  $E$  is equal to  $F$ .

$$\frac{H(E), E = F \vdash P(E)}{H(F), E = F \vdash P(F)} \quad \text{EQ\_RL}$$

To prove a goal  $P(F)$  assuming  $H(F)$ , where both  $P$  and  $H$  depend on expression  $F$ , it suffices to prove  $P(E)$  assuming  $H(E)$ , where both  $P$  and  $H$  depend on expression  $E$ , given that  $E$  is equal to  $F$ .

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## Example Inference Rules (4)



$$\frac{}{H, P \vdash P} \quad \text{HYP}$$

A goal is proved if it can be assumed.

$$\frac{}{\perp \vdash P} \quad \text{FALSE\_I}$$

Assuming **false** ( $\perp$ ), anything can be proved.

$$\frac{}{P \vdash \top} \quad \text{TRUE\_R}$$

**true** ( $\top$ ) is proved, regardless of the assumption.

$$\frac{}{P \vdash E = E} \quad \text{EQ}$$

An expression being equal to itself is proved, regardless of the assumption.

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## Discharging PO of DLF: Exercise



$$\begin{array}{c}
 \boxed{
 \begin{array}{l}
 A(c) \\
 I(c, v) \\
 \vdash \\
 G_1(c, v) \vee \dots \vee G_m(c, v)
 \end{array}
 } \quad \text{DLF} \quad \boxed{
 \begin{array}{l}
 d \in \mathbb{N} \\
 n \in \mathbb{N} \\
 n \leq d \\
 \vdash \\
 n < d \vee n > 0
 \end{array}
 } \quad ??
 \end{array}$$

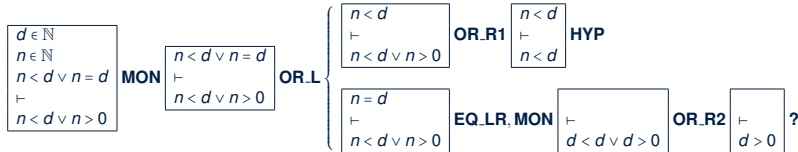
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## Discharging PO of DLF: First Attempt



$$\begin{array}{l} d \in \mathbb{N} \\ n \in \mathbb{N} \\ n \leq d \\ \vdash \\ n < d \vee n > 0 \end{array}$$

=



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## Fixing the Context of Initial Model



- Having understood the failed proof, we add a proper **axiom** to  $m_0$ :

**axioms:**  
**axm0\_2 :  $d > 0$**

- We have effectively elaborated on **REQ2**:

REQ2	The number of cars on bridge and island is limited but positive.
------	--

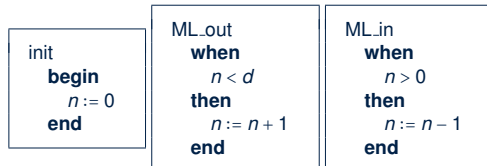
- Having changed the context, an updated **sequent** will be generated for the PO/VC rule of **deadlock freedom**.
- Is this new sequent now **provable**?

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## Why Did the DLF PO Fail to Discharge?



- In our first attempt, proof of the 2nd case failed:  $\vdash d > 0$
- This **unprovable** sequent gave us a good hint:
  - For the model under consideration ( $m_0$ ) to be **deadlock-free**, it is required that  $d > 0$ . [  $\geq 1$  car allowed in the IB compound ]
  - But current **specification** of  $m_0$  **not** strong enough to entail this:
    - $\neg(d > 0) \equiv d \leq 0$  is possible for the current model
    - Given **axm0.1** :  $d \in \mathbb{N}$   
 $\Rightarrow d = 0$  is allowed by  $m_0$  which causes a **deadlock**.
- Recall the *init* event and the two **guarded** events:



When  $d = 0$ , the disjunction of guards evaluates to **false**:  $0 < 0 \vee 0 > 0$   
 $\Rightarrow$  As soon as the system is initialized, it **deadlocks immediately**  
 as no car can either enter or leave the IR compound!!

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## Discharging PO of DLF: Second Attempt



$$\begin{array}{l} d \in \mathbb{N} \\ d > 0 \\ n \in \mathbb{N} \\ n \leq d \\ \vdash \\ n < d \vee n > 0 \end{array}$$

=

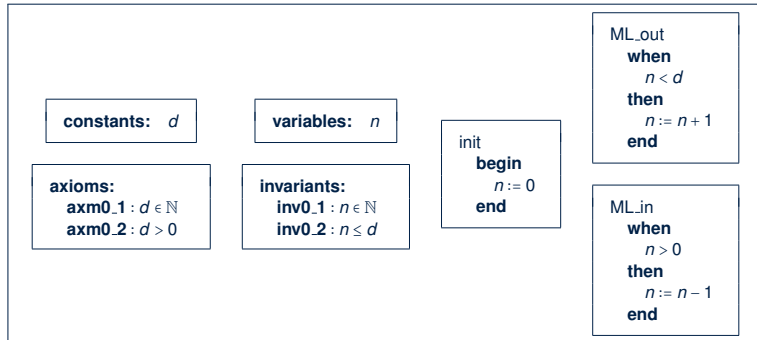


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## Initial Model: Summary



- The final version of our *initial model*  $m_0$  is **provably correct** w.r.t.:
  - Establishment of *Invariants*
  - Preservation of *Invariants*
  - Deadlock* Freedom
- Here is the final specification of  $m_0$ :



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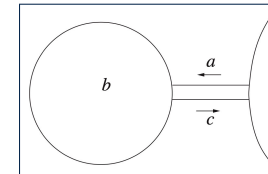
## Model $m_1$ : Refined State Space



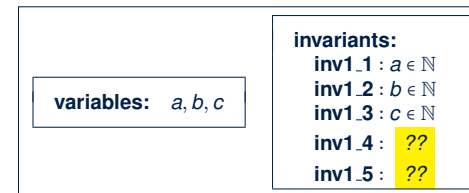
- The static part is the same as  $m_0$ 's:

constants:  $d$   
axioms:  
axm0.1 :  $d \in \mathbb{N}$   
axm0.2 :  $d > 0$

- The dynamic part of the *concrete state* consists of three *variables*:



- $a$ : number of cars on the bridge, heading to the island
- $b$ : number of cars on the island
- $c$ : number of cars on the bridge, heading to the mainland



- ✓ inv1.1, inv1.2, inv1.3 are *typing* constraints.
- ✓ inv1.4 *links/glues* the *abstract* and *concrete* states.
- ✓ inv1.5 specifies that the bridge is one-way.

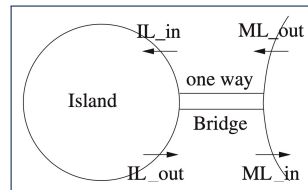
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## Model $m_1$ : “More Concrete” Abstraction



- First *refinement* has a *more concrete* perception of the bridge controller:
  - We “*zoom in*” by observing the system from closer to the ground, so that the island-bridge compound is split into:

- the island
- the (one-way) bridge



- Nonetheless, traffic lights and sensors remain *abstracted* away!
- That is, we focus on these two *requirement*:

REQ1	The system is controlling cars on a bridge connecting the mainland to an island.
REQ3	The bridge is one-way or the other, not both at the same time.

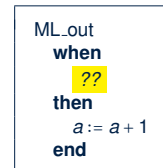
- We are *obliged to prove* this *added concreteness* is *consistent* with  $m_0$ .

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## Model $m_1$ : State Transitions via Events

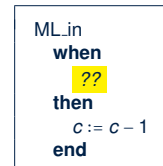


- The system acts as an **ABSTRACT STATE MACHINE (ASM)**: it *evolves* as *actions of enabled events* change values of variables, subject to *invariants*.
- We first consider the “old” *events* already existing in  $m_0$ .
- Concrete/Refined* version of *event* ML.out:



- Meaning of *ML.out* is *refined*: a car exits mainland (getting on the bridge).
- ML.out* *enabled* only when:
  - the bridge's current traffic flows to the island
  - number of cars on both the bridge and the island is limited

- Concrete/Refined* version of *event* ML.in:



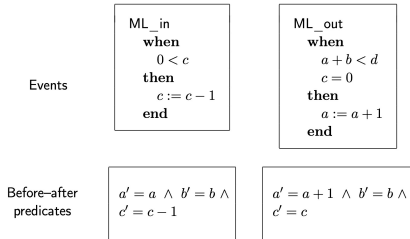
- Meaning of *ML.in* is *refined*: a car enters mainland (getting off the bridge).
- ML.in* *enabled* only when: there is some car on the bridge heading to the mainland.

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## Model $m_1$ : Actions vs. Before-After Predicates

- Consider the **concrete/refined** version of **actions** of  $m_0$ 's two events:



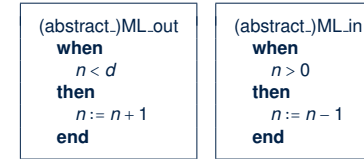
- An event's **actions** are a **specification**: "c becomes c - 1 after the transition".
- The **before-after predicate (BAP)** " $c' = c - 1$ " expresses that  $c'$  (the **post-state** value of c) is one less than c (the **pre-state** value of c).
- Given that the **concrete state** consists of three variables:
  - An event's **actions** only specify those changing from **pre-state** to **post-state**. [e.g.,  $c' = c - 1$ ]
  - Other unmentioned variables have their **post-state** values remain unchanged. [e.g.,  $a' = a \wedge b' = b$ ]

- When we express **proof obligations (POs)** associated with **events**, we use **BAP**.

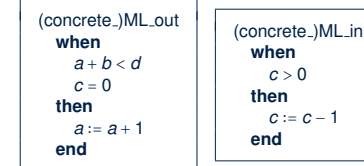
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## Events: Abstract vs. Concrete

- When an **event** exists in both models  $m_0$  and  $m_1$ , there are two versions of it:
  - The **abstract** version modifies the **abstract** state.



- The **concrete** version modifies the **concrete** state.



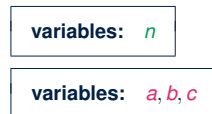
- A **new event** may only exist in  $m_1$  (the **concrete** model): we will deal with this kind of events later, separately from "redefined/overridden" events.

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## States & Invariants: Abstract vs. Concrete

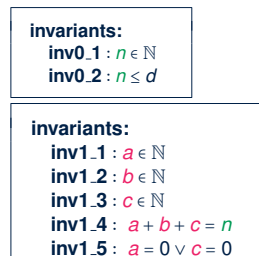
- $m_1$  refines  $m_0$  by introducing more **variables**:

- Abstract** State (of  $m_0$  being refined):
- Concrete** State (of the refinement model  $m_1$ ):



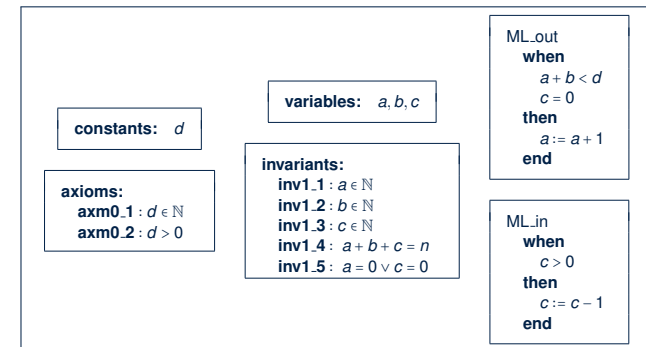
- Accordingly, **invariants** may involve different **states**:

- Abstract** Invariants (involving the **abstract** state only):
- Concrete** Invariants (involving at least the **concrete** state):



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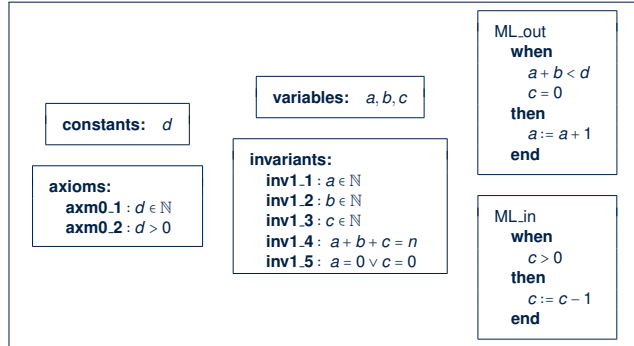
## PO of Refinement: Components (1)



- c: list of **constants**  $\langle d \rangle$
- A(c): list of **axioms**  $\langle \text{axm0.1} \rangle$
- v and v': **abstract variables** in pre- & post-states  $v \triangleq \langle n \rangle, v' \triangleq \langle n \rangle$
- w and w': **concrete variables** in pre- & post-states  $w \triangleq \langle a, b, c \rangle, w' \triangleq \langle a', b', c' \rangle$
- I(c, v): list of **abstract invariants**  $\langle \text{inv0.1}, \text{inv0.2} \rangle$
- J(c, v, w): list of **concrete invariants**  $\langle \text{inv1.1}, \text{inv1.2}, \text{inv1.3}, \text{inv1.4}, \text{inv1.5} \rangle$

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## PO of Refinement: Components (2)



- $G(c, v)$ : list of guards of the **abstract event**  
 $G(\langle d \rangle, \langle n \rangle) \text{ of } ML.out \hat{=} \langle n < d \rangle, G(c, v) \text{ of } ML.in \hat{=} \langle n > 0 \rangle$
- $H(c, w)$ : list of guards of the **concrete event**  
 $H(\langle d \rangle, \langle a, b, c \rangle) \text{ of } ML.out \hat{=} \langle a + b < d, c = 0 \rangle, H(c, w) \text{ of } ML.in \hat{=} \langle c > 0 \rangle$

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## Sketching PO of Refinement



The PO/VC rule for a **proper refinement** consists of two parts:

### 1. Guard Strengthening

Axioms  
 $\text{Abstract Invariants Satisfied at Pre-State}$   
 $\text{Concrete Invariants Satisfied at Pre-State}$   
 $\text{Guards of the Concrete Event}$   
 $\vdash$   
 $\text{Guards of the Abstract Event}$

GRD

- A **concrete** transition always has an **abstract** counterpart.
- A **concrete** event is enabled only if its **abstract** counterpart is enabled.

### 2. Invariant Preservation

Axioms  
 $\text{Abstract Invariants Satisfied at Pre-State}$   
 $\text{Concrete Invariants Satisfied at Pre-State}$   
 $\text{Guards of the Concrete Event}$   
 $\vdash$   
 $\text{Concrete Invariants Satisfied at Post-State}$

INV

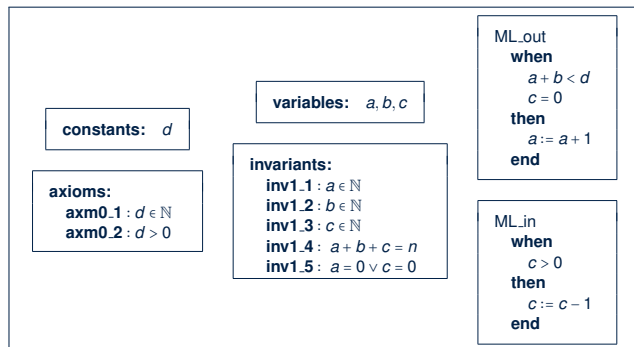
- A **concrete** event performs a **transition** on **concrete** states.
- This **concrete** state **transition** must be consistent with how its **abstract** counterpart performs a corresponding **abstract transition**.

**Note.** **Guard strengthening** and **invariant preservation** are only applicable to events that might be **enabled** after the system is launched.

The special, non-guarded **init** event will be discussed separately later.

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## PO of Refinement: Components (3)



- $E(c, v)$ : effect of the **abstract event**'s actions i.t.o. what variable values **become**  
 $E(\langle d \rangle, \langle n \rangle) \text{ of } ML.out \hat{=} \langle n + 1 \rangle, E(\langle d \rangle, \langle n \rangle) \text{ of } ML.in \hat{=} \langle n - 1 \rangle$
- $F(c, w)$ : effect of the **concrete event**'s actions i.t.o. what variable values **become**  
 $F(c, w) \text{ of } ML.out \hat{=} \langle a + 1, b, c \rangle, F(c, w) \text{ of } ML.in \hat{=} \langle a, b, c - 1 \rangle$

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## Refinement Rule: Guard Strengthening



- Based on the components, we are able to formally state the **PO/VC Rule of Guard Strengthening for Refinement**:

$A(c)$   
 $I(c, v)$   
 $J(c, v, w)$   
 $H(c, w)$   
 $\vdash$   
 $G_i(c, v)$

GRD

where  $G_i$  denotes a single **guard** condition of the **abstract** event

- How many **sequents** to be proved? [ # **abstract** guards ]
- For **ML.out**, only one **abstract** guard, so one **sequent** is generated :

$d \in \mathbb{N} \quad d > 0$   
 $n \in \mathbb{N} \quad n \leq d$   
 $a \in \mathbb{N} \quad b \in \mathbb{N} \quad c \in \mathbb{N} \quad a + b + c = n \quad a = 0 \vee c = 0$   
 $a + b < d \quad c = 0$   
 $\vdash$   
 $n < d$

ML.out/GRD

- Exercise.** Write **ML.in**'s **PO of Guard Strengthening for Refinement**.

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## PO Rule: Guard Strengthening of $ML\_out$

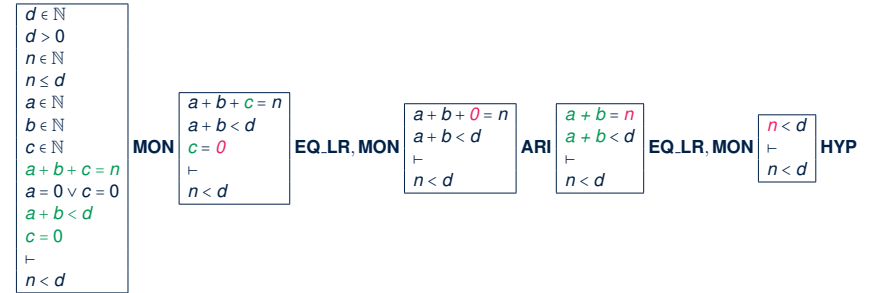


axm0_1	$d \in \mathbb{N}$
axm0_2	$d > 0$
inv0_1	$n \in \mathbb{N}$
inv0_2	$n \leq d$
inv1_1	$a \in \mathbb{N}$
inv1_2	$b \in \mathbb{N}$
inv1_3	$c \in \mathbb{N}$
inv1_4	$a + b + c = n$
inv1_5	$a = 0 \vee c = 0$
<b>Concrete</b> guards of $ML\_out$	$\begin{cases} a + b < d \\ c = 0 \end{cases}$
<b>Abstract</b> guards of $ML\_out$	$\begin{cases} n < d \end{cases}$

**ML\_out/GRD**

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## Proving Refinement: $ML\_out/GRD$



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## PO Rule: Guard Strengthening of $ML\_in$

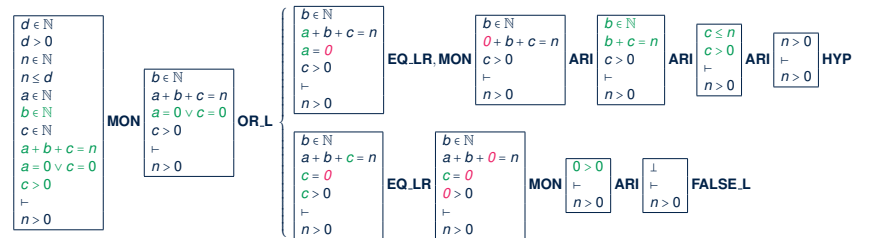


axm0_1	$d \in \mathbb{N}$
axm0_2	$d > 0$
inv0_1	$n \in \mathbb{N}$
inv0_2	$n \leq d$
inv1_1	$a \in \mathbb{N}$
inv1_2	$b \in \mathbb{N}$
inv1_3	$c \in \mathbb{N}$
inv1_4	$a + b + c = n$
inv1_5	$a = 0 \vee c = 0$
<b>Concrete</b> guards of $ML\_in$	$\begin{cases} c > 0 \end{cases}$
<b>Abstract</b> guards of $ML\_in$	$\begin{cases} n > 0 \end{cases}$

**ML\_in/GRD**

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## Proving Refinement: $ML\_in/GRD$



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## Refinement Rule: Invariant Preservation



- Based on the components, we are able to formally state the **PO/VC Rule of Invariant Preservation for Refinement**:

$$\begin{array}{l} A(c) \\ I(c, v) \\ J(c, v, w) \\ H(c, w) \\ \vdash \\ J_i(c, E(c, v), F(c, w)) \end{array}$$

INV where  $J_i$  denotes a single **concrete invariant**

- # **sequents** to be proved? [ # **concrete**, old evts  $\times$  # **concrete** invariants ]
- Here are two (of the ten) **sequents** generated:

$$\begin{array}{l} d \in \mathbb{N} \\ d > 0 \\ n \in \mathbb{N} \\ n \leq d \\ a \in \mathbb{N} \\ b \in \mathbb{N} \\ c \in \mathbb{N} \\ a + b + c = n \\ a = 0 \vee c = 0 \\ a + b < d \\ c = 0 \\ \vdash \\ (a + 1) + b + c = (n + 1) \end{array}$$

ML\_out/inv1\_4/INV

$$\begin{array}{l} d \in \mathbb{N} \\ d > 0 \\ n \in \mathbb{N} \\ n \leq d \\ a \in \mathbb{N} \\ b \in \mathbb{N} \\ c \in \mathbb{N} \\ a + b + c = n \\ a = 0 \vee c = 0 \\ c > 0 \\ \vdash \\ a = 0 \vee (c - 1) = 0 \end{array}$$

ML\_in/inv1\_5/INV

- Exercises.** Specify and prove other **eight** **POs of Invariant Preservation**.

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## INV PO of $m_1$ : ML\_out/inv1\_4/INV



$$\begin{array}{l} \text{axm0.1} \{ d \in \mathbb{N} \\ \text{axm0.2} \{ d > 0 \\ \text{inv0.1} \{ n \in \mathbb{N} \\ \text{inv0.2} \{ n \leq d \\ \text{inv1.1} \{ a \in \mathbb{N} \\ \text{inv1.2} \{ b \in \mathbb{N} \\ \text{inv1.3} \{ c \in \mathbb{N} \\ \text{inv1.4} \{ a + b + c = n \\ \text{inv1.5} \{ a = 0 \vee c = 0 \\ \quad \{ a + b < d \\ \quad \{ c = 0 \\ \vdash \\ \text{Concrete guards of ML\_out} \\ \text{Concrete invariant inv1.4} \\ \text{with ML\_out's effect in the post-state} \end{array}$$

ML\_out/inv1\_4/INV

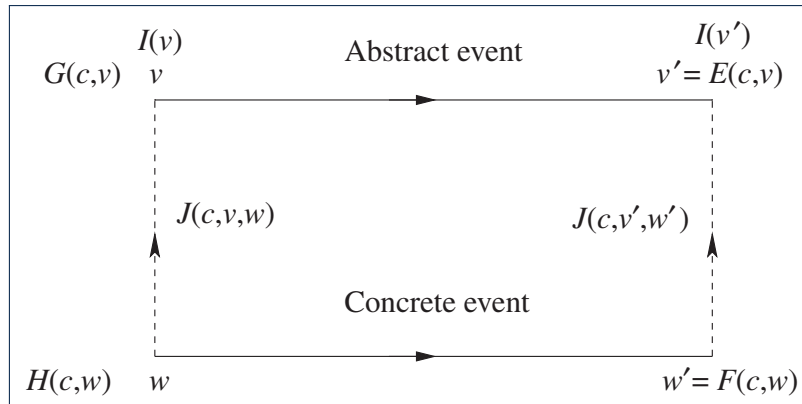
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## Visualizing Inv. Preservation in Refinement



Each **concrete** event ( $w$  to  $w'$ ) is **simulated by** an **abstract** event ( $v$  to  $v'$ ):

- abstract** & **concrete** pre-states related by **concrete** invariants  $J(c, v, w)$
- abstract** & **concrete** post-states related by **concrete** invariants  $J(c, v', w')$



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## INV PO of $m_1$ : ML\_in/inv1\_5/INV

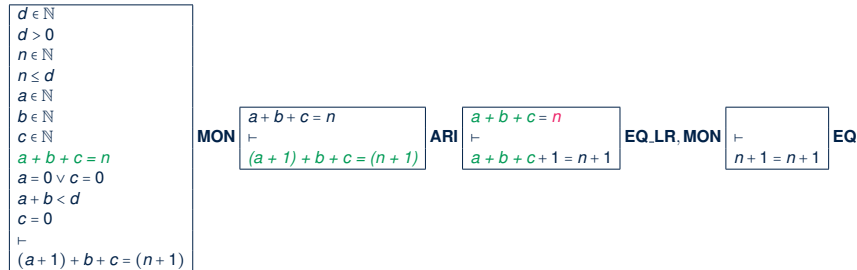


$$\begin{array}{l} \text{axm0.1} \{ d \in \mathbb{N} \\ \text{axm0.2} \{ d > 0 \\ \text{inv0.1} \{ n \in \mathbb{N} \\ \text{inv0.2} \{ n \leq d \\ \text{inv1.1} \{ a \in \mathbb{N} \\ \text{inv1.2} \{ b \in \mathbb{N} \\ \text{inv1.3} \{ c \in \mathbb{N} \\ \text{inv1.4} \{ a + b + c = n \\ \text{inv1.5} \{ a = 0 \vee c = 0 \\ \quad \{ a + b < d \\ \quad \{ c > 0 \\ \vdash \\ \text{Concrete guards of ML\_in} \\ \text{Concrete invariant inv1.5} \\ \text{with ML\_in's effect in the post-state} \end{array}$$

ML\_in/inv1\_5/INV

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## Proving Refinement: ML\_out/inv1\_4/INV



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## Initializing the Refined System $m_1$



- Discharging the **twelve sequents** proved that:
  - concrete invariants** preserved by  $ML\_out$  &  $ML\_in$
  - concrete guards** of  $ML\_out$  &  $ML\_in$  entail their **abstract** counterparts
- What's left is the specification of how the **ASM's initial state** looks like:

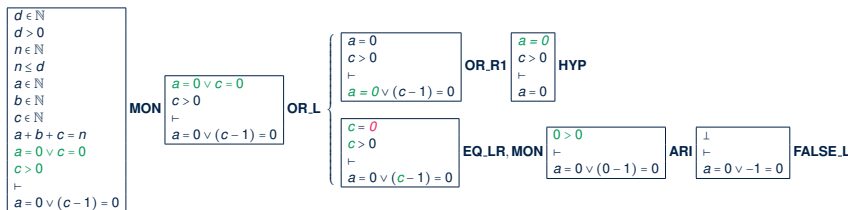
```

init
begin
  a := 0
  b := 0
  c := 0
end
    
```

- ✓ No cars on bridge (heading either way) and island
- ✓ Initialization always possible: guard is **true**.
- ✓ There is no **pre-state** for *init*.
  - $\therefore$  The **RHS** of  $:=$  must **not** involve variables.
  - $\therefore$  The **RHS** of  $:=$  may **only** involve constants.
- ✓ There is only the **post-state** for *init*.
  - $\therefore$  Before-**After Predicate**:  $a' = 0 \wedge b' = 0 \wedge c' = 0$

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## Proving Refinement: ML\_in/inv1\_5/INV



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## PO of $m_1$ Concrete Invariant Establishment



- Some (new) formal components are needed:
  - $K(c)$ : effect of **abstract init's** actions:
    - e.g.,  $K(\langle d \rangle)$  of *init*  $\equiv \langle 0 \rangle$
  - $v' = K(c)$ : **before-after predicate** formalizing **abstract init's** actions
    - e.g., BAP of *init*:  $\langle n' \rangle = \langle 0 \rangle$
  - $L(c)$ : effect of **concrete init's** actions:
    - e.g.,  $K(\langle d \rangle)$  of *init*  $\equiv \langle 0, 0, 0 \rangle$
  - $w' = L(c)$ : **before-after predicate** formalizing **concrete init's** actions
    - e.g., BAP of *init*:  $\langle a', b', c' \rangle = \langle 0, 0, 0 \rangle$
- Accordingly, PO of **invariant establishment** is formulated as a **sequent**:

Axioms $\vdash$ <b>Concrete Invariants</b> Satisfied at <u>Post-State</u>	INV	$A(c)$ $\vdash$ $J_i(c, K(c), L(c))$	INV
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## Discharging PO of $m_1$ Concrete Invariant Establishment

- How many **sequents** to be proved? [ # **concrete** invariants ]
- Two (of the **five**) sequents generated for **concrete** *init* of  $m_1$ :

$$\begin{array}{c} d \in \mathbb{N} \\ d > 0 \\ \vdash \\ 0 + 0 + 0 = 0 \end{array} \quad \text{init/inv1.4/INV} \quad \begin{array}{c} d \in \mathbb{N} \\ d > 0 \\ \vdash \\ 0 = 0 \vee 0 = 0 \end{array} \quad \text{init/inv1.5/INV}$$

- Can we discharge the **PO**  $\text{init/inv1.4/INV}$ ?

$$\begin{array}{c} d \in \mathbb{N} \\ d > 0 \\ \vdash \\ 0 + 0 + 0 = 0 \end{array} \quad \text{ARI, MON} \quad \vdash \top \quad \text{TRUE\_R} \quad \therefore \text{init/inv1.4/INV} \text{ succeeds in being discharged.}$$

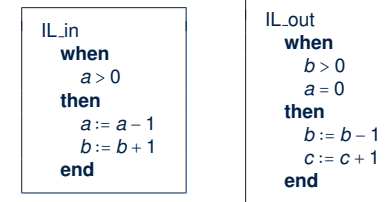
- Can we discharge the **PO**  $\text{init/inv1.5/INV}$ ?

$$\begin{array}{c} d \in \mathbb{N} \\ d > 0 \\ \vdash \\ 0 = 0 \vee 0 = 0 \end{array} \quad \text{ARI, MON} \quad \vdash \top \quad \text{TRUE\_R} \quad \therefore \text{init/inv1.5/INV} \text{ succeeds in being discharged.}$$

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## Model $m_1$ : BA Predicates of Multiple Actions

Consider **actions** of  $m_1$ 's two **new** events:



- What is the **BAP** of  $\text{ML\_in}$ 's **actions**?

$$a' = a - 1 \wedge b' = b + 1 \wedge c' = c$$

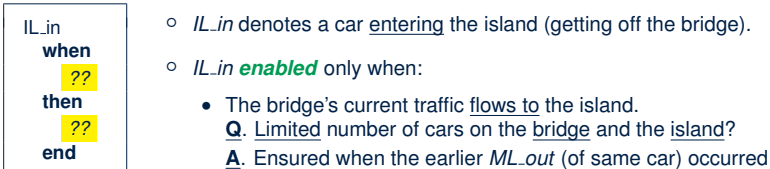
- What is the **BAP** of  $\text{ML\_in}$ 's **actions**?

$$a' = a \wedge b' = b - 1 \wedge c' = c + 1$$

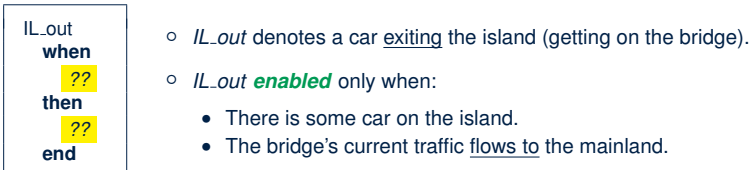
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## Model $m_1$ : New, Concrete Events

- The system acts as an **ABSTRACT STATE MACHINE (ASM)**: it **evolves** as **actions of enabled events** change values of variables, subject to **invariants**.
- Considered **concrete/refined events** already existing in  $m_0$ :  $\text{ML\_out}$  &  $\text{ML\_in}$
- New event**  $\text{IL\_in}$ :



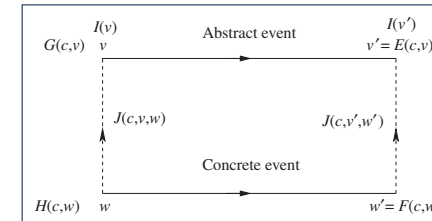
- New event**  $\text{IL\_out}$ :



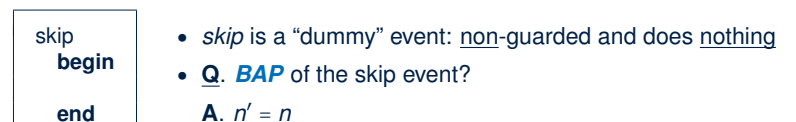
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## Visualizing Inv. Preservation in Refinement

- Recall how a **concrete** event is **simulated** by its **abstract** counterpart:



- For each **new** event:
  - Strictly speaking, it does **not** have an **abstract** counterpart.
  - It is **simulated by** a special **abstract** event (transforming  $v$  to  $v'$ ):



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## Refinement Rule: Invariant Preservation



- The new events  $IL\_in$  and  $IL\_out$  do not exist in  $m_0$ , but:
  - They **exist** in  $m_1$  and may impact upon the **concrete** state space.
  - They **preserve** the **concrete invariants**, just as  $ML\_out$  &  $ML\_in$  do.
- Recall the **PO/VC Rule of Invariant Preservation for Refinement**:

$$\frac{A(c) \quad I(c, v) \quad J(c, v, w) \quad H(c, w) \quad \vdash \quad J_i(c, E(c, v), F(c, w))}{INV} \text{ where } J_i \text{ denotes a single concrete invariant}$$

- How many **sequents** to be proved? [ # **new** evts  $\times$  # **concrete** invariants ]
- Here are two (of the ten) **sequents** generated:

$$\frac{d \in \mathbb{N} \quad d > 0 \quad n \in \mathbb{N} \quad n \leq d \quad a \in \mathbb{N} \quad b \in \mathbb{N} \quad c \in \mathbb{N} \quad a + b + c = n \quad a = 0 \vee c = 0 \quad a > 0 \quad \vdash \quad (a-1) + (b+1) + c = n}{IL\_in/inv1\_4/INV}$$

$$\frac{d \in \mathbb{N} \quad d > 0 \quad n \in \mathbb{N} \quad n \leq d \quad a \in \mathbb{N} \quad b \in \mathbb{N} \quad c \in \mathbb{N} \quad a + b + c = n \quad a = 0 \vee c = 0 \quad a > 0 \quad \vdash \quad (a-1) = 0 \vee c = 0}{IL\_in/inv1\_5/INV}$$

- Exercises.** Specify and prove other **eight** **POs of Invariant Preservation**.

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## INV PO of $m_1$ : $IL\_in/inv1\_5/INV$



$$\frac{\begin{array}{l} axm0\_1 \quad \{ d \in \mathbb{N} \\ axm0\_2 \quad \{ d > 0 \\ inv0\_1 \quad \{ n \in \mathbb{N} \\ inv0\_2 \quad \{ n \leq d \\ inv1\_1 \quad \{ a \in \mathbb{N} \\ inv1\_2 \quad \{ b \in \mathbb{N} \\ inv1\_3 \quad \{ c \in \mathbb{N} \\ inv1\_4 \quad \{ a + b + c = n \\ inv1\_5 \quad \{ a = 0 \vee c = 0 \\ \quad \{ a > 0 \end{array}}{\vdash \quad (a-1) = 0 \vee c = 0}$$

$IL\_in/inv1\_5/INV$

**Concrete** invariant **inv1.5**  
with  $IL\_in$ 's effect in the post-state

*Guards of  $IL\_in$*

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## INV PO of $m_1$ : $IL\_in/inv1\_4/INV$



$$\frac{\begin{array}{l} axm0\_1 \quad \{ d \in \mathbb{N} \\ axm0\_2 \quad \{ d > 0 \\ inv0\_1 \quad \{ n \in \mathbb{N} \\ inv0\_2 \quad \{ n \leq d \\ inv1\_1 \quad \{ a \in \mathbb{N} \\ inv1\_2 \quad \{ b \in \mathbb{N} \\ inv1\_3 \quad \{ c \in \mathbb{N} \\ inv1\_4 \quad \{ a + b + c = n \\ inv1\_5 \quad \{ a = 0 \vee c = 0 \\ \quad \{ a > 0 \end{array}}{\vdash \quad (a-1) + (b+1) + c = n}$$

$IL\_in/inv1\_4/INV$

**Concrete** invariant **inv1.4**  
with  $IL\_in$ 's effect in the post-state

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## Proving Refinement: $IL\_in/inv1\_4/INV$



$$\frac{d \in \mathbb{N} \quad d > 0 \quad n \in \mathbb{N} \quad n \leq d \quad a \in \mathbb{N} \quad b \in \mathbb{N} \quad c \in \mathbb{N} \quad a + b + c = n \quad a = 0 \vee c = 0 \quad a > 0 \quad \vdash \quad (a-1) + (b+1) + c = n}{MON}$$

**MON**

$$\frac{a + b + c = n \quad \vdash \quad (a-1) + (b+1) + c = n}{ARI}$$

**ARI**

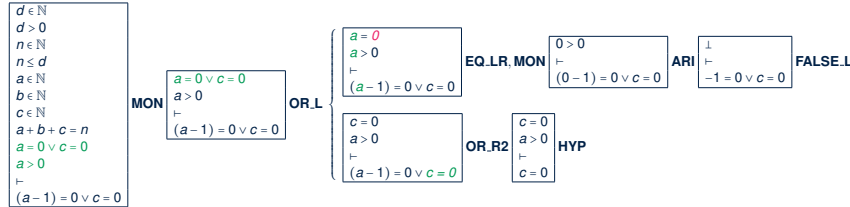
$$\frac{a + b + c = n \quad \vdash \quad a + b + c = n}{HYP}$$

**HYP**

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## Proving Refinement: IL\_in/inv1\_5/INV

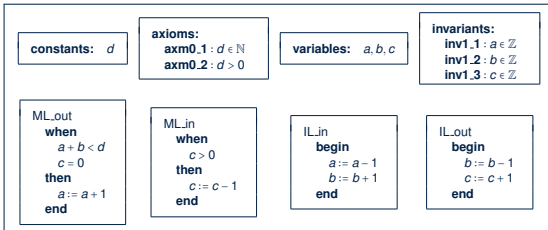


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## Livelock Caused by New Events Diverging



- An alternative  $m_1$  (with **inv1\_4**, **inv1\_5**, and **guards** of **new** events removed):



**Concrete invariants** are **under-specified**: only typing constraints.

**Exercises**: Show that **Invariant Preservation** is provable, but **Guard Strengthening** is not.

- Say this alternative  $m_1$  is implemented as is: **IL.in** and **IL.out** **always enabled** and may occur **indefinitely**, preventing other "old" events (**ML.out** and **ML.in**) from ever happening:

$\langle \text{init}, \text{ML.out}, \text{IL.in}, \text{IL.out}, \text{IL.in}, \text{IL.out}, \dots \rangle$

**Q**: What are the corresponding **abstract** transitions?

**A**:  $\langle \text{init}, \text{ML.out}, \text{skip}, \text{skip}, \text{skip}, \text{skip}, \dots \rangle$  [  $\approx$  executing `while(true);` ]

- We say that these two **new** events **diverge**, creating a **livelock**:
  - Different from a **deadlock**: **always** an event occurring (**IL.in** or **IL.out**).
  - But their **indefinite** occurrences contribute **nothing** useful.

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## PO of Convergence of New Events



The PO/VC rule for **non-divergence/livelock freedom** consists of two parts:

- Interleaving of **new** events characterized as an integer expr.: **variant**.
- A variant  $V(c, w)$  may refer to constants and/or **concrete** variables.
- In the original  $m_1$ , let's try **variants**:  $2 \cdot a + b$

### 1. Variant Stays Non-Negative

$A(c)$   
 $I(c, v)$   
 $J(c, v, w)$   
 $H(c, w)$   
 $\vdash$   
 $V(c, w) \in \mathbb{N}$

- Variant  $V(c, w)$  measures how many more times the **new** events can occur.

- If a **new** event is **enabled**, then  $V(c, w) > 0$ .

- When  $V(c, w)$  reaches 0, some "old" events must happen s.t.  $V(c, w)$  goes back above 0.

### 2. A New Event Occurrence Decreases Variant

$A(c)$   
 $I(c, v)$   
 $J(c, v, w)$   
 $H(c, w)$   
 $\vdash$   
 $V(c, F(c, w)) < V(c, w)$

**NAT**

- If a **new** event is **enabled** and occurs, the value of  $V(c, w) \downarrow$ .

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## PO of Convergence of New Events: NAT



- Recall: PO related to **Variant Stays Non-Negative**:

$A(c)$   
 $I(c, v)$   
 $J(c, v, w)$   
 $H(c, w)$   
 $\vdash$   
 $V(c, w) \in \mathbb{N}$

**NAT**

How many **sequents** to be proved?

[ # **new** events ]

- For the **new** event **IL.in**:

$d \in \mathbb{N} \quad d > 0$   
 $n \in \mathbb{N} \quad n \leq d$   
 $a \in \mathbb{N} \quad b \in \mathbb{N} \quad c \in \mathbb{N}$   
 $a+b+c=n \quad a=0 \vee c=0$   
 $a > 0$   
 $\vdash$   
 $2 \cdot a + b \in \mathbb{N}$

**IL.in/NAT**

**Exercises**: Prove **IL.in/NAT** and Formulate/Prove **IL.out/NAT**.

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## PO of Convergence of New Events: VAR



- Recall: PO related to **A New Event Occurrence Decreases Variant**

$$\begin{array}{l}
 A(c) \\
 I(c, v) \\
 J(c, v, w) \\
 H(c, w) \\
 \vdash \\
 V(c, F(c, w)) < V(c, w)
 \end{array}
 \quad \text{VAR} \quad \text{How many **sequents** to be proved?} \quad [ \# \text{ new events } ]$$

- For the **new** event **IL.in**:

$$\begin{array}{l}
 d \in \mathbb{N} \quad d > 0 \\
 n \in \mathbb{N} \quad n \leq d \\
 a \in \mathbb{N} \quad b \in \mathbb{N} \quad c \in \mathbb{N} \\
 a + b + c = n \quad a = 0 \vee c = 0 \\
 a > 0 \\
 \vdash \\
 2 \cdot (a - 1) + (b + 1) < 2 \cdot a + b
 \end{array}
 \quad \text{IL.in/VAR}$$

**Exercises:** Prove **IL.in/VAR** and Formulate/Prove **IL.out/VAR**.

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## Convergence of New Events: Exercise



Given the original **m<sub>1</sub>**, what if the following **variant** expression is used:

**variants** :  $a + b$

Are the formulated sequents still **provable**?

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## PO of Refinement: Deadlock Freedom



- Recall:
  - We proved that the initial model  $m_0$  is deadlock free (see **DLF**).
  - We proved, according to **guard strengthening**, that if a **concrete** event is **enabled**, then its **abstract** counterpart is **enabled**.
- PO of **relative deadlock freedom** for a **refinement** model:

$$\begin{array}{l}
 A(c) \\
 I(c, v) \\
 J(c, v, w) \\
 G_1(c, v) \vee \dots \vee G_m(c, v) \\
 \vdash \\
 H_1(c, w) \vee \dots \vee H_n(c, w)
 \end{array}
 \quad \text{DLF} \quad \begin{array}{l}
 \text{If an **abstract** state does not **deadlock** (i.e., } G_1(c, v) \vee \dots \vee G_m(c, v) \text{), then its **concrete** counterpart does not **deadlock** (i.e., } H_1(c, w) \vee \dots \vee H_n(c, w) \text{).}
 \end{array}$$

- Another way to think of the above PO:  
The **refinement** does **not** introduce, in the **concrete**, any “new” **deadlock** scenarios **not** existing in the **abstract** state.

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## PO Rule: Relative Deadlock Freedom $m_1$



$$\begin{array}{l}
 \text{axm0.1} \quad \left\{ \begin{array}{l} d \in \mathbb{N} \\ d > 0 \end{array} \right. \\
 \text{axm0.2} \quad \left\{ \begin{array}{l} n \in \mathbb{N} \\ n \leq d \end{array} \right. \\
 \text{inv0.1} \quad \left\{ \begin{array}{l} a \in \mathbb{N} \\ b \in \mathbb{N} \\ c \in \mathbb{N} \\ a + b + c = n \\ a = 0 \vee c = 0 \end{array} \right. \\
 \text{inv1.1} \quad \left\{ \begin{array}{l} n < d \\ n > 0 \end{array} \right. \\
 \text{inv1.2} \quad \left\{ \begin{array}{l} a + b < d \wedge c = 0 \\ c > 0 \\ a > 0 \\ b > 0 \wedge a = 0 \end{array} \right. \\
 \text{inv1.3} \quad \left\{ \begin{array}{l} \text{guards of } ML.out \text{ in } m_0 \\ \text{guards of } ML.in \text{ in } m_0 \end{array} \right. \\
 \text{inv1.4} \quad \left\{ \begin{array}{l} \text{guards of } ML.out \text{ in } m_1 \\ \text{guards of } ML.in \text{ in } m_1 \\ \text{guards of } IL.in \text{ in } m_1 \\ \text{guards of } IL.out \text{ in } m_1 \end{array} \right. \\
 \text{inv1.5} \quad \left\{ \begin{array}{l} \text{guards of } ML.out \text{ in } m_0 \\ \text{guards of } ML.in \text{ in } m_0 \end{array} \right. \\
 \text{Disjunction of **abstract** guards} \quad \left\{ \begin{array}{l} \vee \\ \vee \end{array} \right. \\
 \text{Disjunction of **concrete** guards} \quad \left\{ \begin{array}{l} \vee \\ \vee \\ \vee \\ \vee \end{array} \right.
 \end{array}
 \quad \text{DLF}$$

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## Example Inference Rules (6)



$$\frac{H, \neg P \vdash Q}{H \vdash P \vee Q} \text{ OR\_R}$$

To prove a **disjunctive goal**, it suffices to prove one of the disjuncts, with the the negation of the the other disjunct serving as an additional hypothesis.

$$\frac{H, P, Q \vdash R}{H, P \wedge Q \vdash R} \text{ AND\_L}$$

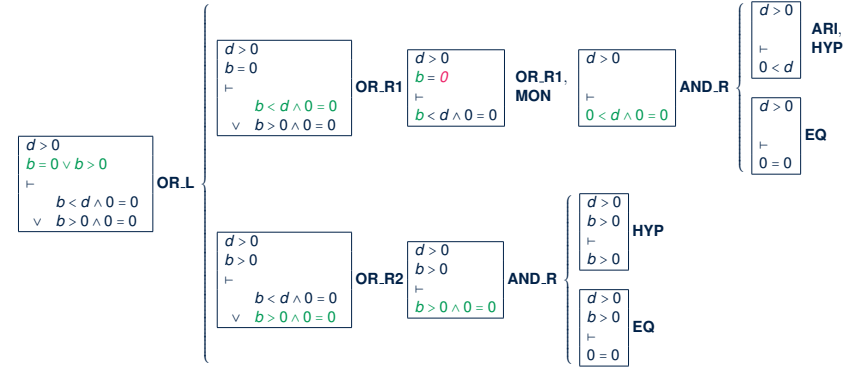
To prove a goal with a **conjunctive hypothesis**, it suffices to prove the same goal, with the the two conjuncts serving as two separate hypotheses.

$$\frac{H \vdash P \quad H \vdash Q}{H \vdash P \wedge Q} \text{ AND\_R}$$

To prove a goal with a **conjunctive goal**, it suffices to prove each conjunct as a separate goal.

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## Proving Refinement: DLF of $m_1$ (continued)



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## Proving Refinement: DLF of $m_1$



$$\frac{d \in \mathbb{N} \quad a \in \mathbb{N} \quad n \in \mathbb{N} \quad n \leq d \quad a \in \mathbb{N} \quad b \in \mathbb{N} \quad c \in \mathbb{N} \quad a+b+c=n \quad a=0 \vee c=0 \quad n < d \vee n > 0}{\vdash a+b < d \wedge c=0 \vee c > 0 \vee a > 0 \vee b > 0 \wedge a=0} \text{ MON}$$

$$\frac{d > 0 \quad a \in \mathbb{N} \quad b \in \mathbb{N} \quad c = 0}{\vdash a+b < d \wedge c=0 \vee c > 0 \vee a > 0 \vee b > 0 \wedge a=0} \text{ OR\_R, ARI}$$

$$\frac{d > 0 \quad a \in \mathbb{N} \quad b \in \mathbb{N} \quad c = 0}{\vdash a+b < d \wedge c=0 \vee c > 0 \vee a > 0 \vee b > 0 \wedge a=0} \text{ EQ\_LR, MON}$$

$$\frac{d > 0 \quad a \in \mathbb{N} \quad b \in \mathbb{N} \quad c = 0}{\vdash a+b < d \wedge c=0 \vee c > 0 \vee a > 0 \vee b > 0 \wedge a=0} \text{ OR\_R, ARI}$$

$$\frac{d > 0 \quad a \in \mathbb{N} \quad b \in \mathbb{N} \quad c = 0}{\vdash a+b < d \wedge c=0 \vee c > 0 \vee a > 0 \vee b > 0 \wedge a=0} \text{ EQ\_LR, MON}$$

$$\frac{d > 0 \quad a \in \mathbb{N} \quad b \in \mathbb{N} \quad c = 0}{\vdash a+b < d \wedge c=0 \vee c > 0 \vee a > 0 \vee b > 0 \wedge a=0} \text{ ARI}$$

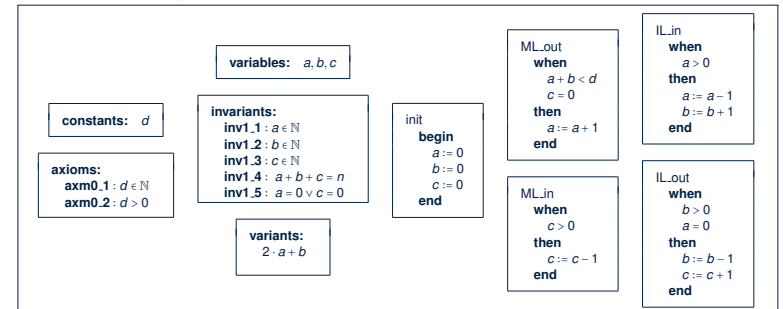
$$\frac{d > 0 \quad a \in \mathbb{N} \quad b \in \mathbb{N} \quad c = 0}{\vdash a+b < d \wedge c=0 \vee c > 0 \vee a > 0 \vee b > 0 \wedge a=0} \text{ EQ\_LR, MON}$$

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## First Refinement: Summary



- The final version of our **first refinement**  $m_1$  is **provably correct** w.r.t.:
  - Establishment of **Concrete Invariants** [ *init* ]
  - Preservation of **Concrete Invariants** [ old & new events ]
  - Strengthening of **guards** [ old events ]
  - Convergence** (a.k.a. livelock freedom, non-divergence) [ new events ]
  - Relative **Deadlock Freedom**
- Here is the final specification of  $m_1$ :



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## Model $m_2$ : “More Concrete” Abstraction

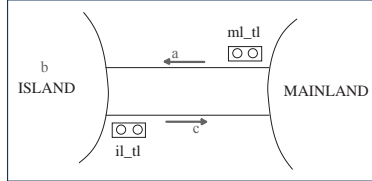


- 2nd **refinement** has even more **concrete** perception of the bridge controller:
  - We “**zoom in**” by observing the system from **even closer to the ground**, so that the one-way traffic of the bridge is controlled via:

**ml\_tl**: a traffic light for exiting the ML

**il\_tl**: a traffic light for exiting the IL

**abstract** variables **a, b, c** from  $m_1$  still **used** (instead of being replaced)



- Nonetheless, sensors remain **abstracted** away!
- That is, we focus on these three **environment constraints**:

ENV1	The system is equipped with two traffic lights with two colors: green and red.
ENV2	The traffic lights control the entrance to the bridge at both ends of it.
ENV3	Cars are not supposed to pass on a red traffic light, only on a green one.

- We are **obliged to prove** this **added concreteness** is **consistent** with  $m_1$ .

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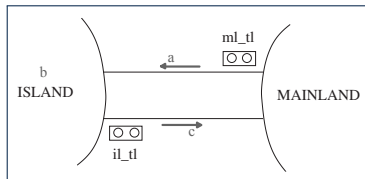
## Model $m_2$ : Refined, Concrete State Space



- The **static** part introduces the notion of traffic light colours:

<b>sets:</b> COLOR	<b>constants:</b> red, green	<b>axioms:</b> axm2.1 : COLOR = {green, red} axm2.2 : green ≠ red
--------------------	------------------------------	---

- The **dynamic** part shows the **superposition refinement** scheme:



- Abstract** variables **a, b, c** from  $m_1$  are still in use in **m.2**.
- Two new, **concrete** variables are introduced: **ml\_tl** and **il\_tl**
- Constraint**: In  $m_1$ , **abstract** variable **n** is replaced by **concrete** variables **a, b, c**.

<b>variables:</b> a, b, c ml_tl il_tl	<b>invariants:</b> inv2.1 : ml_tl ∈ COLOUR inv2.2 : il_tl ∈ COLOUR inv2.3 : ?? inv2.4 : ??
--	--

- inv2.1 & inv2.2: typing constraints
- inv2.3: being allowed to exit ML **means** cars within **limit** and **no** opposite traffic
- inv2.4: being allowed to exit IL **means** some car in IL and **no** opposite traffic

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## Model $m_2$ : Refining Old, Abstract Events



- The system acts as an **ABSTRACT STATE MACHINE (ASM)**: it **evolves** as **actions of enabled events** change values of variables, subject to **invariants**.

- Concrete/Refined** version of **event ML\_out**:

```
ML_out
when
  ??
then
  a := a + 1
end
```

- Recall the **abstract** guard of **ML\_out** in  $m_1$ :  $(c = 0) \wedge (a + b < d)$   
⇒ **Unrealistic** as drivers should **not** know about **a, b, c**!

- ML\_out** is **refined**: a car **exits** the ML (to the bridge) only when:

- the traffic light **ml\_tl** allows

- Concrete/Refined** version of **event IL\_out**:

```
IL_out
when
  ??
then
  b := b - 1
  c := c + 1
end
```

- Recall the **abstract** guard of **IL\_out** in  $m_1$ :  $(a = 0) \wedge (b > 0)$   
⇒ **Unrealistic** as drivers should **not** know about **a, b, c**!

- IL\_out** is **refined**: a car **exits** the IL (to the bridge) only when:

- the traffic light **il\_tl** allows

**Q1.** How about the other two “old” **events** **IL\_in** and **ML\_in**?

**A1.** No need to **refine** as already **guarded** by **ML\_out** and **IL\_out**.

**Q2.** What if the driver disobeys **ml\_tl** or **il\_tl**?

[ **A2.** ENV3 ]

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## Model $m_2$ : New, Concrete Events



- The system acts as an **ABSTRACT STATE MACHINE (ASM)**: it **evolves** as **actions of enabled events** change values of variables, subject to **invariants**.

- Considered **events** **already** existing in  $m_1$ :

- ML\_out** & **IL\_out**

[ **REFINED** ]

- IL\_in** & **ML\_in**

[ **UNCHANGED** ]

- New event ML\_tl\_green**:

```
ML_tl_green
when
  ??
then
  ml_tl := green
end
```

- ML\_tl\_green** denotes the traffic light **ml\_tl** turning green.
- ML\_tl\_green** **enabled** only when:
  - the traffic light **not** already green
  - limited** number of cars on the **bridge** and the **island**
  - No** opposite traffic

[ ⇒ **ML\_out**'s **abstract** guard in  $m_1$  ]

- New event IL\_tl\_green**:

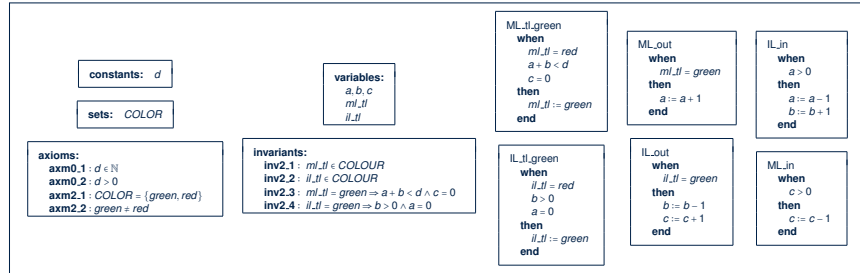
```
IL_tl_green
when
  ??
then
  il_tl := green
end
```

- IL\_tl\_green** denotes the traffic light **il\_tl** turning green.
- IL\_tl\_green** **enabled** only when:
  - the traffic light **not** already green
  - some** cars on the island (i.e., island not empty)
  - No** opposite traffic

[ ⇒ **IL\_out**'s **abstract** guard in  $m_1$  ]

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## Invariant Preservation in Refinement $m_2$



Recall the **PO/VC Rule of Invariant Preservation for Refinement**:

$A(c)$   
 $I(c, v)$   
 $J(c, v, w)$   
 $H(c, w)$   
 $\vdash$   
 $J_i(c, E(c, v), F(c, w))$

**INV** where  $J_i$  denotes a single concrete invariant

- How many **sequents** to be proved? [ # **concrete** evts  $\times$  # **concrete** invariants =  $6 \times 4$  ]
- We discuss two sequents: **ML\_out/inv2.4/INV** and **IL\_out/inv2.3/INV**

**Exercises.** Specify and prove (some of) other twenty-two POs of Invariant Preservation.

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## INV PO of $m_2$ : IL\_out/inv2.3/INV



<b>axm0.1</b> $d \in \mathbb{N}$ <b>axm0.2</b> $d > 0$ <b>axm2.1</b> $COLOR = \{green, red\}$ <b>axm2.2</b> $green \neq red$ <b>inv0.1</b> $n \in \mathbb{N}$ <b>inv0.2</b> $n \leq d$ <b>inv1.1</b> $a \in \mathbb{N}$ <b>inv1.2</b> $b \in \mathbb{N}$ <b>inv1.3</b> $c \in \mathbb{N}$ <b>inv1.4</b> $a + b + c = n$ <b>inv1.5</b> $a = 0 \vee c = 0$ <b>inv2.1</b> $ml\_tl \in COLOR$ <b>inv2.2</b> $il\_tl \in COLOR$ <b>inv2.3</b> $ml\_tl = green \Rightarrow a + b < d \wedge c = 0$ <b>inv2.4</b> $il\_tl = green \Rightarrow b > 0 \wedge a = 0$ <b>Concrete</b> guards of <b>IL_out</b> <b>Concrete</b> invariant <b>inv2.3</b> with <b>ML_out</b> 's effect in the <u>post-state</u>	$\vdash$ $\{ ml\_tl = green \Rightarrow a + (b - 1) < d \wedge (c + 1) = 0$
---	--

IL\_out/inv2.3/INV

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## INV PO of $m_2$ : ML\_out/inv2.4/INV



<b>axm0.1</b> $d \in \mathbb{N}$ <b>axm0.2</b> $d > 0$ <b>axm2.1</b> $COLOR = \{green, red\}$ <b>axm2.2</b> $green \neq red$ <b>inv0.1</b> $n \in \mathbb{N}$ <b>inv0.2</b> $n \leq d$ <b>inv1.1</b> $a \in \mathbb{N}$ <b>inv1.2</b> $b \in \mathbb{N}$ <b>inv1.3</b> $c \in \mathbb{N}$ <b>inv1.4</b> $a + b + c = n$ <b>inv1.5</b> $a = 0 \vee c = 0$ <b>inv2.1</b> $ml\_tl \in COLOR$ <b>inv2.2</b> $il\_tl \in COLOR$ <b>inv2.3</b> $ml\_tl = green \Rightarrow a + b < d \wedge c = 0$ <b>inv2.4</b> $il\_tl = green \Rightarrow b > 0 \wedge a = 0$ <b>Concrete</b> guards of <b>ML_out</b> <b>Concrete</b> invariant <b>inv2.4</b> with <b>ML_out</b> 's effect in the <u>post-state</u>	$\vdash$ $\{ il\_tl = green \Rightarrow b > 0 \wedge (a + 1) = 0$
---	--

ML\_out/inv2.4/INV

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## Example Inference Rules (7)



$\frac{H, P, Q \vdash R}{H, P, P \Rightarrow Q \vdash R}$	<b>IMP_L</b>
---	--------------

If a hypothesis **P** matches the assumption of another **implicative hypothesis**  $P \Rightarrow Q$ , then the conclusion **Q** of the **implicative hypothesis** can be used as a new hypothesis for the sequent.

$\frac{H, P \vdash Q}{H \vdash P \Rightarrow Q}$	<b>IMP_R</b>
--	--------------

To prove an **implicative goal**  $P \Rightarrow Q$ , it suffices to prove its conclusion **Q**, with its assumption **P** serving as a new hypotheses.

$\frac{H, \neg Q \vdash P}{H, \neg P \vdash Q}$	<b>NOT_L</b>
---	--------------

To prove a goal **Q** with a **negative hypothesis**  $\neg P$ , it suffices to prove the negated hypothesis  $\neg(\neg P) \equiv P$  with the negated original goal  $\neg Q$  serving as a new hypothesis.

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## Proving ML\_out/inv2\_4/INV: First Attempt

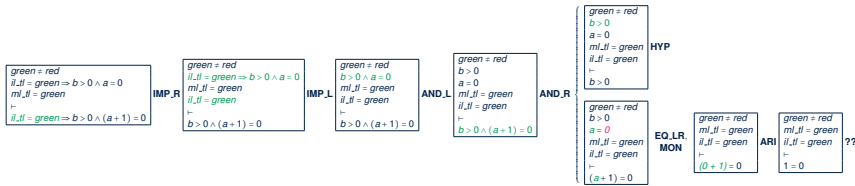


```

d < N
d > 0
COLOUR = {green, red}
green ≠ red
n ∈ N
n ≤ d
a ∈ N
b ∈ N
c ∈ N
a + b + c = n
a = 0 ∨ c = 0
ml_tl ∈ COLOUR
il_tl ∈ COLOUR
ml_tl = green ⇒ a + b < d ∧ c = 0
il_tl = green ⇒ b > 0 ∧ a = 0
ml_tl = green
├
il_tl = green ⇒ b > 0 ∧ (a + 1) = 0

```

MON



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## Proving IL\_out/inv2\_3/INV: First Attempt



```

d ∈ N
d > 0
COLOUR = {green, red}
green ≠ red
n ∈ N
n ≤ d
a ∈ N
b ∈ N
c ∈ N
a + b + c = n
a = 0 ∨ c = 0
ml_tl ∈ COLOUR
il_tl ∈ COLOUR
ml_tl = green ⇒ a + b < d ∧ c = 0
il_tl = green ⇒ b > 0 ∧ a = 0
ml_tl = green
├
ml_tl = green ⇒ a + (b - 1) < d ∧ (c + 1) = 0

```

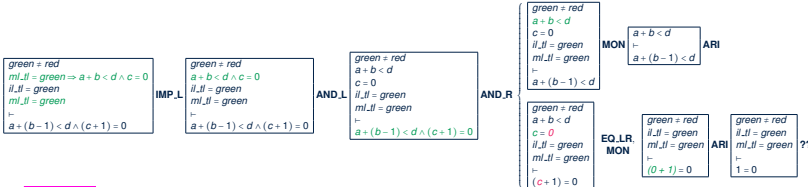
MON

```

green = red
ml_tl = green ⇒ a + b < d ∧ c = 0
il_tl = green
├
ml_tl = green ⇒ a + (b - 1) < d ∧ (c + 1) = 0

```

IMP\_R



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## Failed: ML\_out/inv2\_4/INV, IL\_out/inv2\_3/INV



- Our first attempts of proving **ML\_out/inv2\_4/INV** and **IL\_out/inv2\_3/INV** both failed the 2nd case (resulted from applying IR **AND\_R**):

$$green \neq red \wedge il\_tl = green \wedge ml\_tl = green \vdash 1 = 0$$

- This **unprovable** sequent gave us a good hint:
  - Goal  $1 = 0 \equiv \text{false}$  suggests that the **safety requirements**  $a = 0$  (for **inv2\_4**) and  $c = 0$  (for **inv2\_3**) **contradict** with the current  $m_2$ .
  - Hyp.  $il\_tl = green = ml\_tl$  suggests a **possible, dangerous state** of  $m_2$ , where two cars heading **different** directions are on the **one-way** bridge:

init	ML_tl.green	ML_out	IL_in	IL_tl.green	IL_out	ML_out
d = 2	d = 2	d = 2	d = 2	d = 2	d = 2	d = 2
a' = 0	a' = 0	a' = 1	a' = 0	a' = 0	a' = 0	a' = 1
b' = 0	b' = 0	b' = 0	b' = 1	b' = 1	b' = 0	b' = 0
c' = 0	c' = 0	c' = 0	c' = 0	c' = 0	c' = 1	c' = 1
ml_tl' = red	ml_tl' = green	ml_tl' = green	ml_tl' = green	ml_tl' = green	ml_tl' = green	ml_tl' = green
il_tl' = red	il_tl' = red	il_tl' = red	il_tl' = red	il_tl' = green	il_tl' = green	il_tl' = green

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## Fixing $m_2$ : Adding an Invariant



- Having understood the **failed** proofs, we add a proper **invariant** to  $m_2$ :

invariants:

$$\dots$$

$$\text{inv2\_5} : ml\_tl = red \vee il\_tl = red$$

- We have effectively resulted in an improved  $m_2$  more faithful w.r.t. **REQ3**:

REQ3

The bridge is one-way or the other, not both at the same time.

- Having added this new invariant **inv2\_5**:
  - Original  $6 \times 4$  generated sequents to be **updated**: **inv2\_5** a new hypothesis e.g., Are **ML\_out/inv2\_4/INV** and **IL\_out/inv2\_3/INV** now **provable**?
  - Additional  $6 \times 1$  sequents to be generated due to this new invariant e.g., Are **ML\_tl.green/inv2\_5/INV** and **IL\_tl.green/inv2\_5/INV** **provable**?

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## INV PO of $m_2$ : ML\_out/inv2\_4/INV – Updated

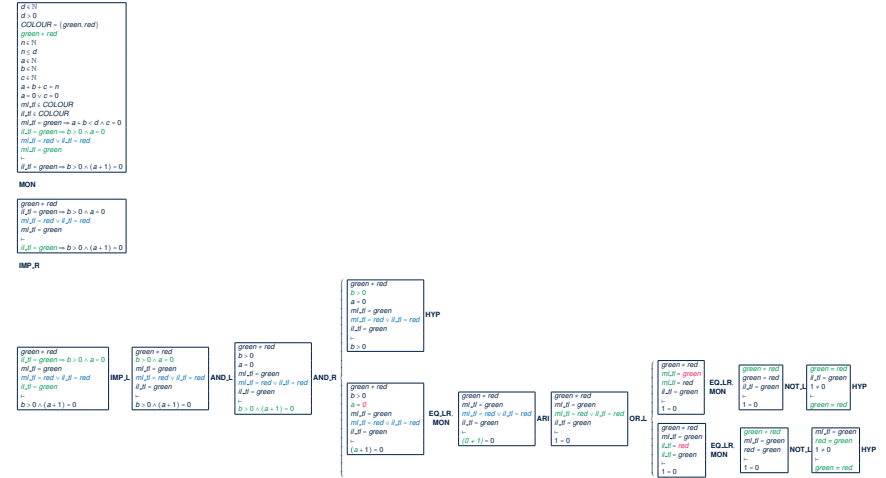


axm0.1  $d \in \mathbb{N}$   
 axm0.2  $d > 0$   
 axm2.1  $COLOUR = \{green, red\}$   
 axm2.2  $green \neq red$   
 inv0.1  $n \in \mathbb{N}$   
 inv0.2  $n \leq d$   
 inv1.1  $a \in \mathbb{N}$   
 inv1.2  $b \in \mathbb{N}$   
 inv1.3  $c \in \mathbb{N}$   
 inv1.4  $a + b + c = n$   
 inv1.5  $a = 0 \vee c = 0$   
 inv2.1  $ml\_tl \in COLOUR$   
 inv2.2  $il\_tl \in COLOUR$   
 inv2.3  $ml\_tl = green \Rightarrow a + b < d \wedge c = 0$   
 inv2.4  $il\_tl = green \Rightarrow b > 0 \wedge a = 0$   
 inv2.5  $ml\_tl = red \vee il\_tl = red$   
*Concrete* guards of ML\_out  
*Concrete* invariant inv2.4  
 with ML\_out's effect in the post-state

ML\_out/inv2\_4/INV

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## Proving ML\_out/inv2\_4/INV: Second Attempt



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## INV PO of $m_2$ : IL\_out/inv2\_3/INV – Updated

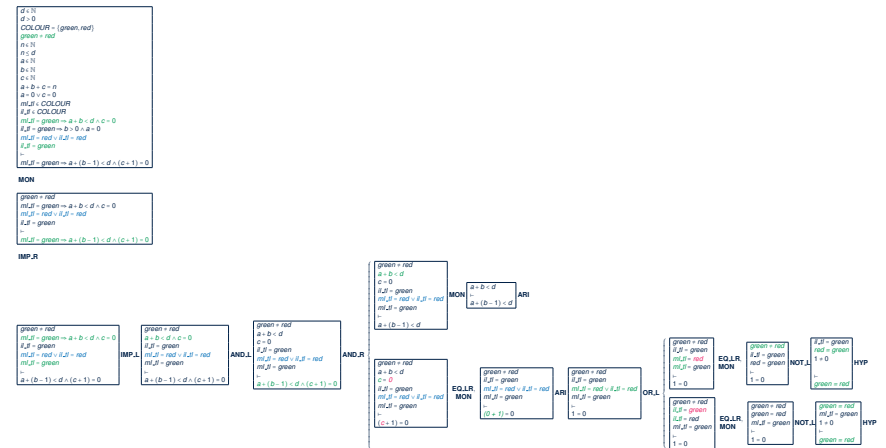


axm0.1  $d \in \mathbb{N}$   
 axm0.2  $d > 0$   
 axm2.1  $COLOUR = \{green, red\}$   
 axm2.2  $green \neq red$   
 inv0.1  $n \in \mathbb{N}$   
 inv0.2  $n \leq d$   
 inv1.1  $a \in \mathbb{N}$   
 inv1.2  $b \in \mathbb{N}$   
 inv1.3  $c \in \mathbb{N}$   
 inv1.4  $a + b + c = n$   
 inv1.5  $a = 0 \vee c = 0$   
 inv2.1  $ml\_tl \in COLOUR$   
 inv2.2  $il\_tl \in COLOUR$   
 inv2.3  $ml\_tl = green \Rightarrow a + b < d \wedge c = 0$   
 inv2.4  $il\_tl = green \Rightarrow b > 0 \wedge a = 0$   
 inv2.5  $ml\_tl = red \vee il\_tl = red$   
*Concrete* guards of IL\_out  
*Concrete* invariant inv2.3  
 with ML\_out's effect in the post-state

IL\_out/inv2\_3/INV

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## Proving IL\_out/inv2\_3/INV: Second Attempt



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## Fixing $m_2$ : Adding Actions



- Recall that an *invariant* was added to  $m_2$ :

invariants:  
inv2.5 :  $ml\_tl = red \vee il\_tl = red$

- Additional  $6 \times 1$  sequents to be generated due to this new invariant:
  - e.g.,  $ML\_tl\_green/inv2.5/INV$  [ for  $ML\_tl\_green$  to preserve inv2.5 ]
  - e.g.,  $IL\_tl\_green/inv2.5/INV$  [ for  $IL\_tl\_green$  to preserve inv2.5 ]
- For the above *sequents* to be *provable*, we need to revise the two events:

ML\_tl.green  
when  
   $ml\_tl = red$   
   $a + b < d$   
   $c = 0$   
then  
   $ml\_tl := green$   
   $il\_tl := red$   
end

IL\_tl.green  
when  
   $il\_tl = red$   
   $b > 0$   
   $a = 0$   
then  
   $il\_tl := green$   
   $ml\_tl := red$   
end

**Exercise:** Specify and prove  $ML\_tl\_green/inv2.5/INV$  &  $IL\_tl\_green/inv2.5/INV$ .

108.6.122

## INV PO of $m_2$ : $ML\_out/inv2.3/INV$



```
axm0.1 { d ∈ ℕ
axm0.2 { d > 0
axm2.1 { COLOUR = { green, red }
axm2.2 { green ≠ red
inv0.1 { n ∈ ℕ
inv0.2 { n ≤ d
inv1.1 { a ∈ ℕ
inv1.2 { b ∈ ℕ
inv1.3 { c ∈ ℕ
inv1.4 { a + b + c = n
inv1.5 { a = 0 ∨ c = 0
inv2.1 { ml_tl ∈ COLOUR
inv2.2 { il_tl ∈ COLOUR
inv2.3 { ml_tl = green ⇒ a + b < d ∧ c = 0
inv2.4 { il_tl = green ⇒ b > 0 ∧ a = 0
inv2.5 { ml_tl = red ∨ il_tl = red
ml_tl = green
```

Concrete guards of  $ML\_out$

Concrete invariant inv2.3  
with  $ML\_out$ 's effect in the post-state

$ML\_out/inv2.3/INV$

108.6.122

## Proving $ML\_out/inv2.3/INV$ : First Attempt



```
d ∈ ℕ
d > 0
COLOUR = { green, red }
green ≠ red
n ∈ ℕ
n ≤ d
a ∈ ℕ
b ∈ ℕ
c ∈ ℕ
a + b + c = n
a = 0 ∨ c = 0
ml_tl ∈ COLOUR
il_tl ∈ COLOUR
ml_tl = green ⇒ a + b < d ∧ c = 0
il_tl = green ⇒ b > 0 ∧ a = 0
ml_tl = red ∨ il_tl = red
ml_tl = green
⊢ ml_tl = green ⇒ (a + 1) + b < d ∧ c = 0
```

MON

$ml\_tl = green \Rightarrow a + b < d \wedge c = 0$   
⊢  $ml\_tl = green \Rightarrow (a + 1) + b < d \wedge c = 0$

IMP.R  $ml\_tl = green \Rightarrow a + b < d \wedge c = 0$   
⊢  $(a + 1) + b < d \wedge c = 0$

IMP.R  $a + b < d \wedge c = 0$   
⊢  $(a + 1) + b < d \wedge c = 0$

AND.L  $a + b < d$   
⊢  $(a + 1) + b < d$

AND.R  $a + b < d$   
⊢  $(a + 1) + b < d$   
HYP  $a + b < d$   
⊢  $(a + 1) + b < d$

108.6.122

## Failed: $ML\_out/inv2.3/INV$



- Our first attempt of proving  $ML\_out/inv2.3/INV$  failed the 1st case (resulted from applying IR AND.R):

$$a + b < d \wedge c = 0 \wedge ml\_tl = green \vdash (a + 1) + b < d$$

- This *unprovable* sequent gave us a good hint:
  - Goal  $(a + 1) + b < d$  specifies the *capacity requirement*.
  - Hypothesis  $c = 0 \wedge ml\_tl = green$  assumes that it's safe to exit the ML.
  - Hypothesis  $a + b < d$  is *not* strong enough to entail  $(a + 1) + b < d$ .
 

e.g., $d = 3, b = 0, a = 0$	$(a + 1) + b < d$ evaluates to <b>true</b>
e.g., $d = 3, b = 1, a = 0$	$(a + 1) + b < d$ evaluates to <b>true</b>
e.g., $d = 3, b = 0, a = 1$	$(a + 1) + b < d$ evaluates to <b>true</b>
e.g., $d = 3, b = 0, a = 2$	$(a + 1) + b < d$ evaluates to <b>false</b>
e.g., $d = 3, b = 1, a = 1$	$(a + 1) + b < d$ evaluates to <b>false</b>
e.g., $d = 3, b = 2, a = 0$	$(a + 1) + b < d$ evaluates to <b>false</b>
  - Therefore,  $a + b < d$  (allowing one more car to exit ML) should be split:
 

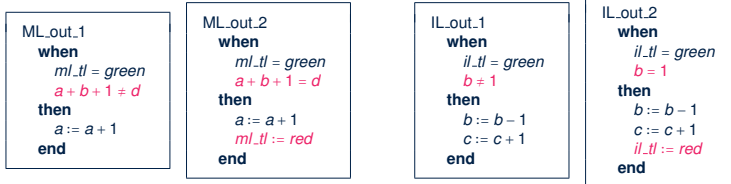
$a + b + 1 \neq d$	[ more later cars may exit ML, $ml\_tl$ remains <b>green</b> ]
$a + b + 1 = d$	[ no more later cars may exit ML, $ml\_tl$ turns <b>red</b> ]

108.6.122

## Fixing $m_2$ : Splitting $ML\_out$ and $IL\_out$



- Recall that  $ML\_out/inv2.3/INV$  failed  $\therefore$  two cases not handled separately:  
 $a + b + 1 \neq d$  [ more later cars may exit ML,  $ml\_tl$  remains **green** ]  
 $a + b + 1 = d$  [ no more later cars may exit ML,  $ml\_tl$  turns **red** ]
- Similarly,  $IL\_out/inv2.4/INV$  would fail  $\therefore$  two cases not handled separately:  
 $b - 1 \neq 0$  [ more later cars may exit IL,  $il\_tl$  remains **green** ]  
 $b - 1 = 0$  [ no more later cars may exit IL,  $il\_tl$  turns **red** ]
- Accordingly, we split  $ML\_out$  and  $IL\_out$  into two with corresponding guards.



**Exercise:** Given the latest  $m_2$ , how many sequents to prove for **invariant preservation**?  
**Exercise:** Specify and prove  $ML\_out.i/inv2.3/INV$  &  $IL\_out.i/inv2.4/INV$  (where  $i \in 1 \dots 2$ ).  
**Exercise:** Each split event (e.g.,  $ML\_out\_1$ ) refines its **abstract** counterpart (e.g.,  $ML\_out$ )?

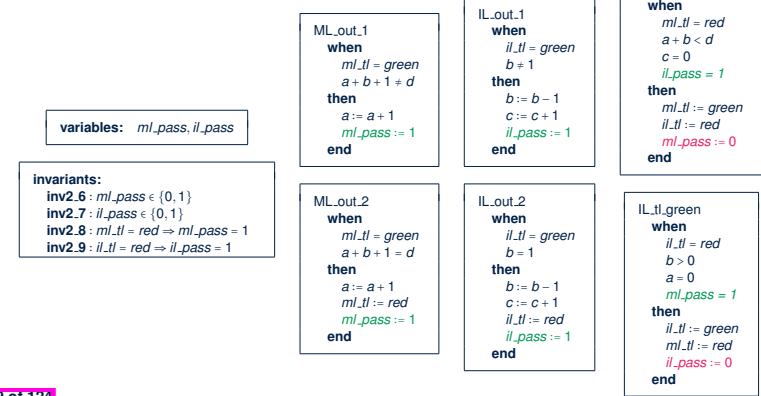
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## Fixing $m_2$ : Regulating Traffic Light Changes



We introduce two variables/flags for regulating traffic light changes:

- $ml\_pass$  is **1** if, since  $ml\_tl$  was last turned **green**, at least one car exited the ML onto the bridge. Otherwise,  $ml\_pass$  is **0**.
- $il\_pass$  is **1** if, since  $il\_tl$  was last turned **green**, at least one car exited the IL onto the bridge. Otherwise,  $il\_pass$  is **0**.

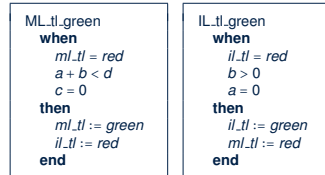


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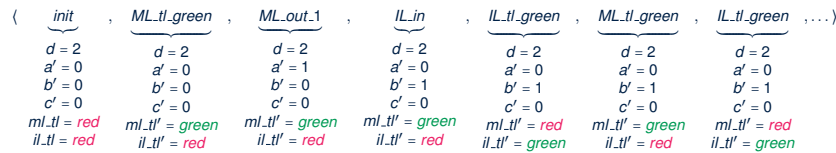
## $m_2$ Livelocks: New Events Diverging



- Recall that a system may **livelock** if the new events diverge.
- Current  $m_2$ 's two new events  $ML\_tl\_green$  and  $IL\_tl\_green$  may **diverge**:



- $ML\_tl\_green$  and  $IL\_tl\_green$  both **enabled** and may occur **indefinitely**, preventing other "old" events (e.g.,  $ML\_out$ ) from ever happening:



$\Rightarrow$  Two traffic lights keep changing colors so rapidly that **no** drivers can ever pass!

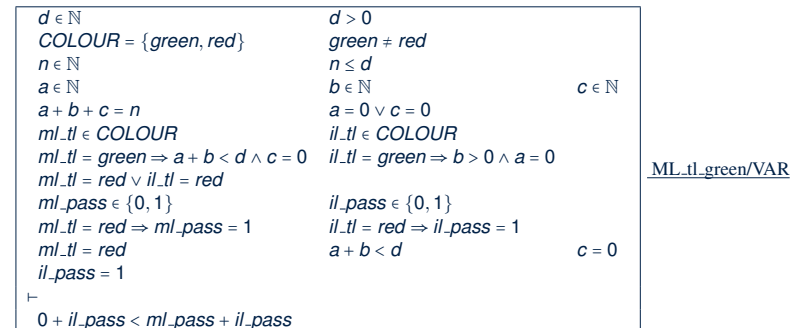
- Solution:** Allow color changes between traffic lights in a disciplined way.

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## Fixing $m_2$ : Measuring Traffic Light Changes



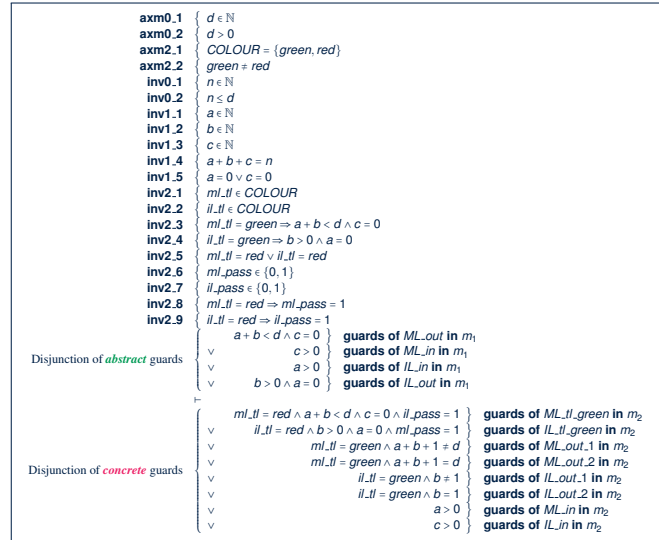
- Recall:
  - Interleaving of **new** events characterized as an integer expression: **variant**.
  - A variant  $V(c, w)$  may refer to constants and/or **concrete** variables.
  - In the latest  $m_2$ , let's try **variants** :  $ml\_pass + il\_pass$
- Accordingly, for the **new** event  $ML\_tl\_green$ :



**Exercises:** Prove  $ML\_tl\_green/VAR$  and Formulate/Prove  $IL\_tl\_green/NAT$ .

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## PO Rule: Relative Deadlock Freedom of $m_2$



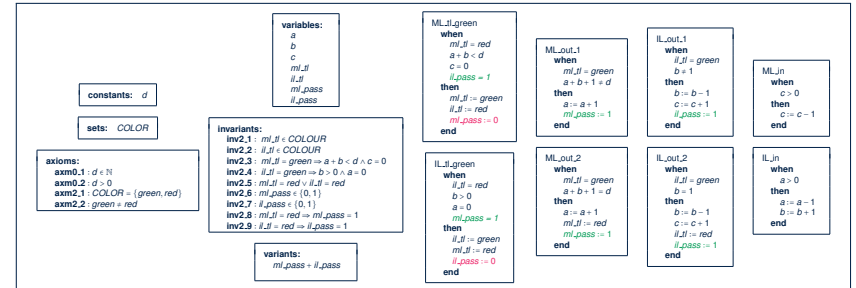
DLF

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## Second Refinement: Summary



- The final version of our *second refinement*  $m_2$  is **provably correct** w.r.t.:
  - Establishment of **Concrete Invariants** [ *init* ]
  - Preservation of **Concrete Invariants** [ old & new events ]
  - Strengthening of **guards** [ old events ]
  - Convergence** (a.k.a. livelock freedom, non-divergence) [ new events ]
  - Relative **Deadlock** Freedom
- Here is the final specification of  $m_2$ :



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## Proving Refinement: DLF of $m_2$



$d \in \mathbb{N}$   
 $d > 0$   
 $\text{COLOUR} = \{\text{green}, \text{red}\}$   
 $\text{green} \neq \text{red}$   
 $n \in \mathbb{N}$   
 $n \leq d$   
 $a \in \mathbb{N}$   
 $b \in \mathbb{N}$   
 $c \in \mathbb{N}$   
 $a + b + c = n$   
 $a = 0 \vee c = 0$   
 $m\_tl \in \text{COLOUR}$   
 $il\_tl \in \text{COLOUR}$   
 $m\_tl = \text{green} \Rightarrow a + b < d \wedge c = 0$   
 $il\_tl = \text{green} \Rightarrow b > 0 \wedge a = 0$   
 $m\_tl = \text{red} \vee il\_tl = \text{red}$   
 $m\_pass \in \{0, 1\}$   
 $il\_pass \in \{0, 1\}$   
 $m\_tl = \text{red} \Rightarrow m\_pass = 1$   
 $il\_tl = \text{red} \Rightarrow il\_pass = 1$   
 $a + b < d \wedge c = 0$   
 $c > 0$   
 $a > 0$   
 $b > 0 \wedge a = 0$

$m\_tl = \text{red} \wedge a + b < d \wedge c = 0 \wedge il\_pass = 1$   
 $il\_tl = \text{red} \wedge b > 0 \wedge a = 0 \wedge m\_pass = 1$   
 $m\_tl = \text{green}$   
 $il\_tl = \text{green}$   
 $a > 0$   
 $c > 0$

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Requirements Document: E-Descriptions

Requirements Document: R-Descriptions

Requirements Document:

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Model  $m_0$ : Actions vs. Before-After Predicates

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PO of Invariant Preservation: Components

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Second Refinement: Summary

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