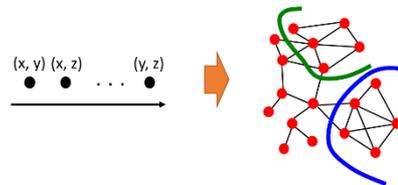
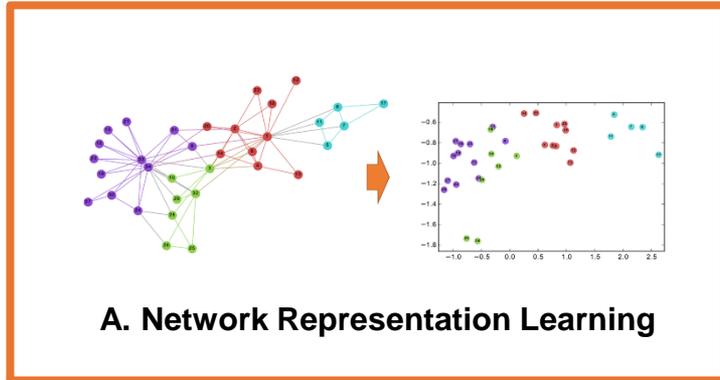


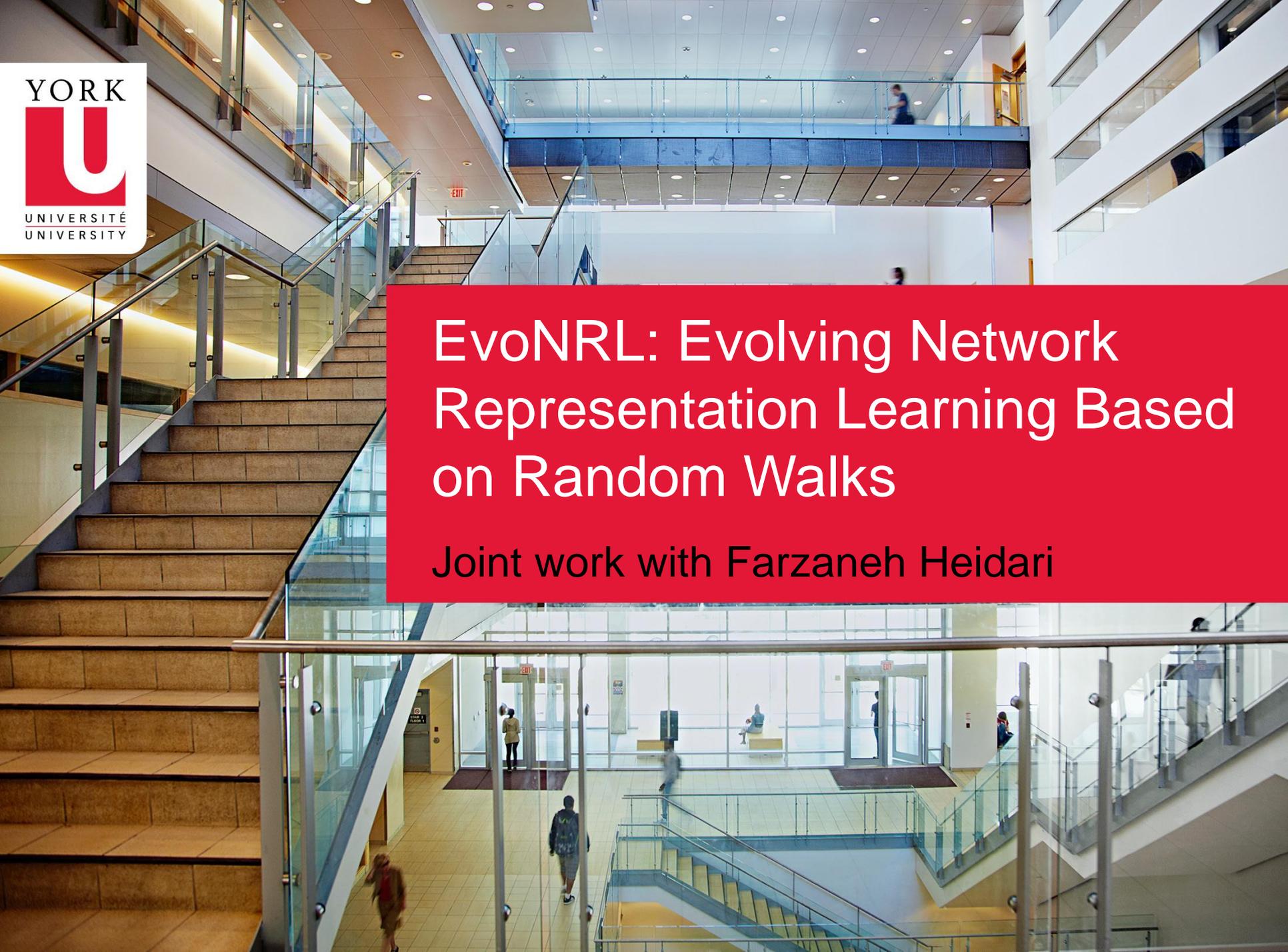
Fast and Accurate Mining of Evolving & Trajectory Networks

Manos Papagelis

York University, Toronto, Canada

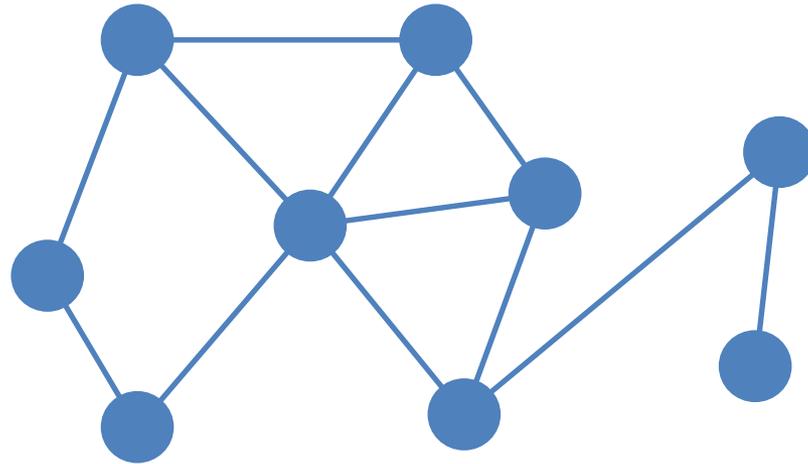
Current Research focus





EvoNRL: Evolving Network Representation Learning Based on Random Walks

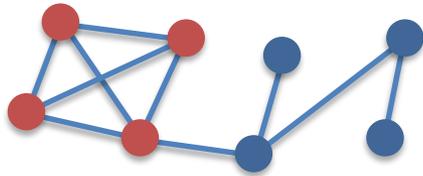
Joint work with Farzaneh Heidari



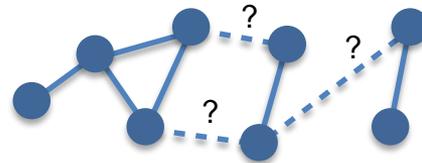
networks

(universal language for describing complex data)

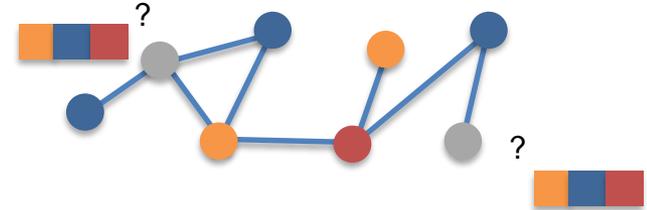
Classical ML Tasks in Networks



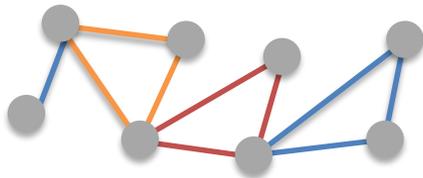
community detection



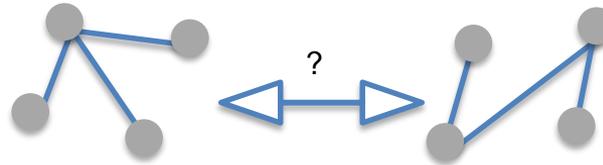
link prediction



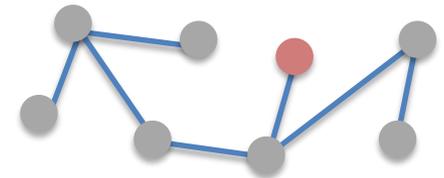
node classification



triangle count



graph similarity

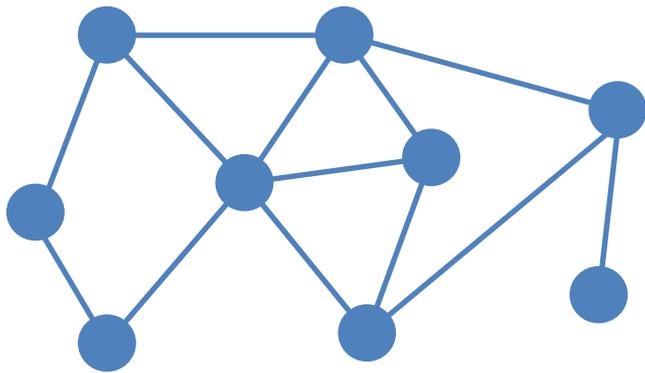


anomaly detection

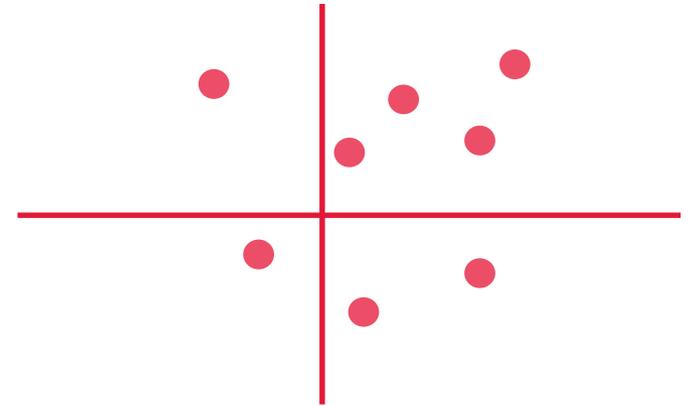
Limitations of Classical ML:

- expensive computation (**high dimension computations**)
- extensive domain knowledge (**task specific**)

Network Representation Learning (NRL)



Network



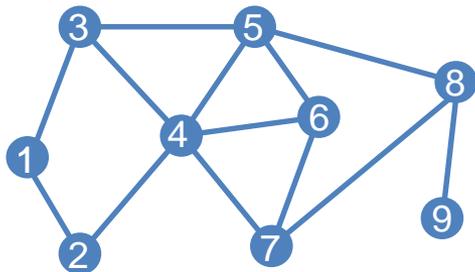
Low-dimension space

several network structural properties can be learned/embedded
(nodes, edges, subgraphs, graphs, ...)

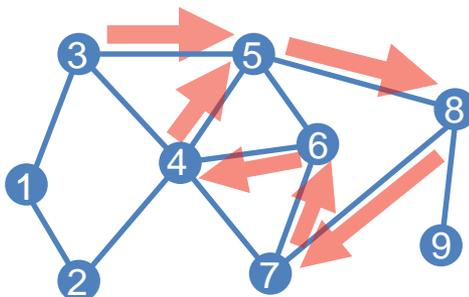
Premise of NRL:

- faster computations (low dimension computations)
- agnostic domain knowledge (task independent)

Random Walk-based NRL



Input network

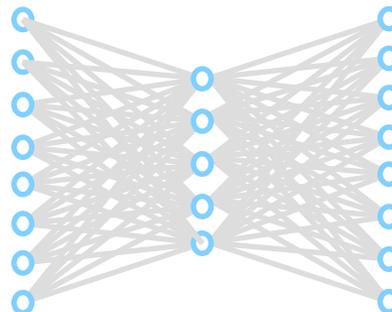


Obtain a set of random walks

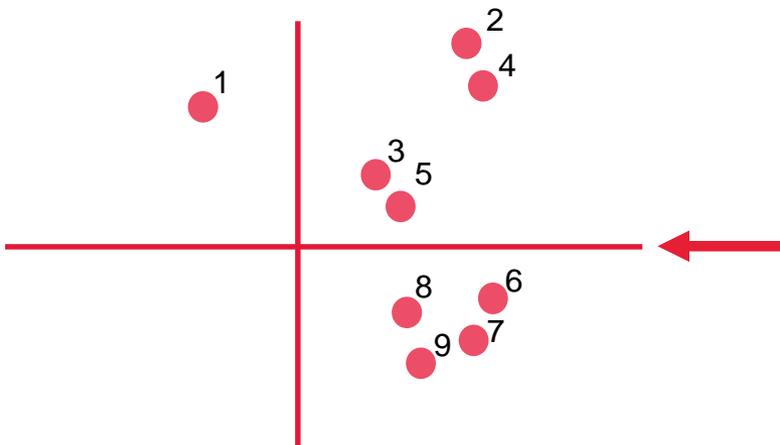


1	3 5 8 7 6 4 5
2	1 3 5 8 7 6 5
.	.
.	.
.	.
.	.
87	8 5 4 3 5 6 7
88	4 5 6 7 8 9
89	2 1 3 5 6 7 8
90	7 4 2 1 3 5 6

Treat the set of random walks as sentences



Feed sentences to a Skip-gram NN model



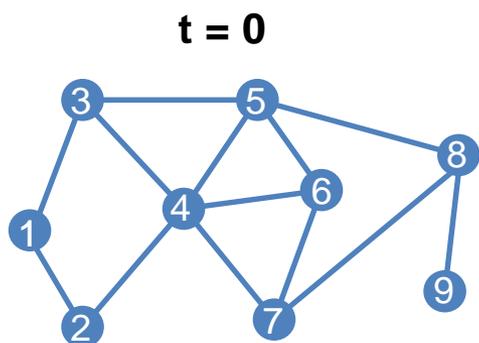
Learn a vector representation for each node

StaticNRL
(DeepWalk, node2vec, ...)

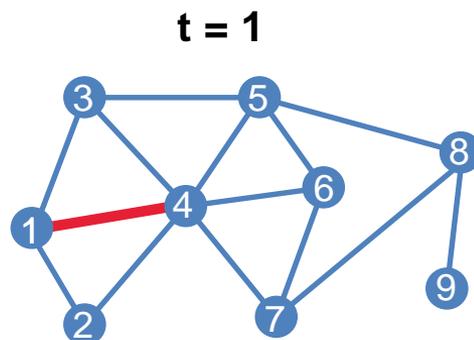
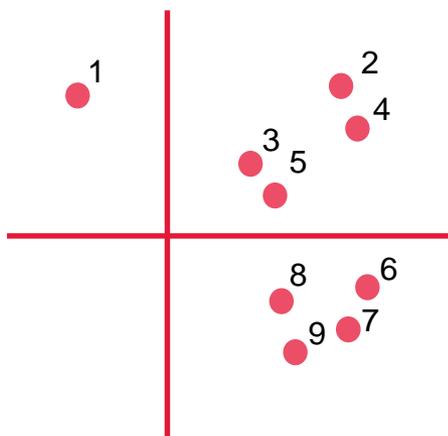
but real-world networks are
constantly evolving

Evolving Network Representations Learning

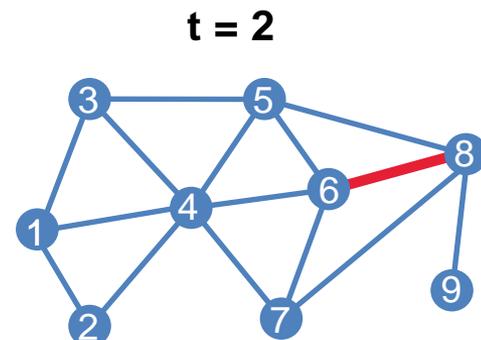
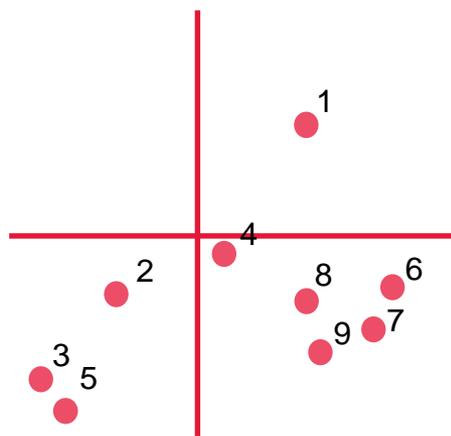
Naive Approach



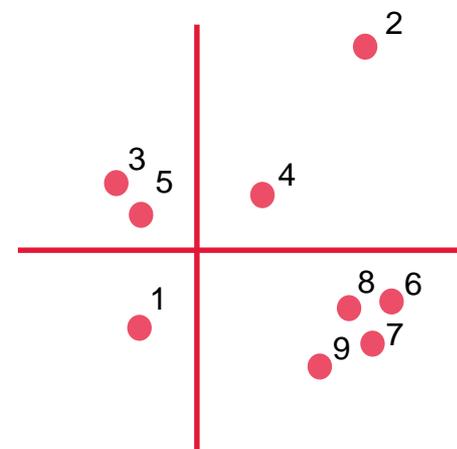
StaticNRL



StaticNRL

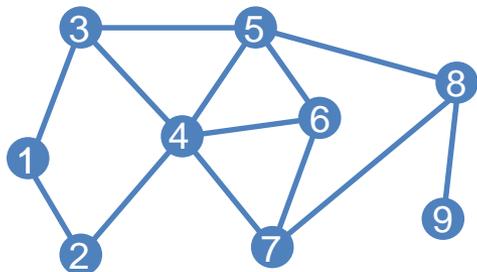


StaticNRL

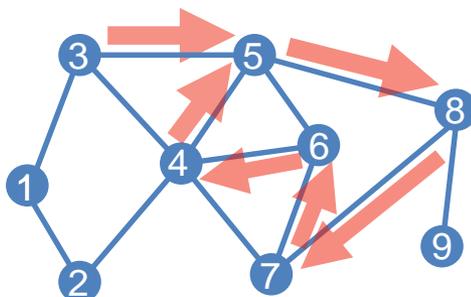


Impractical (**expensive, incomparable representations**)

EvoNRL Key Idea



Input network



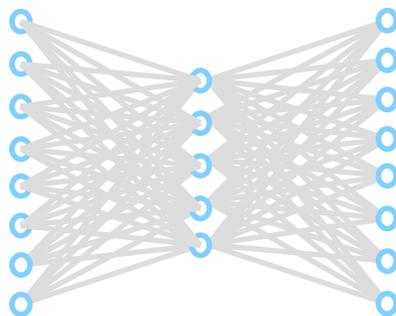
Obtain a set of random walks

dynamically maintain a valid set of random walks for every change in the network

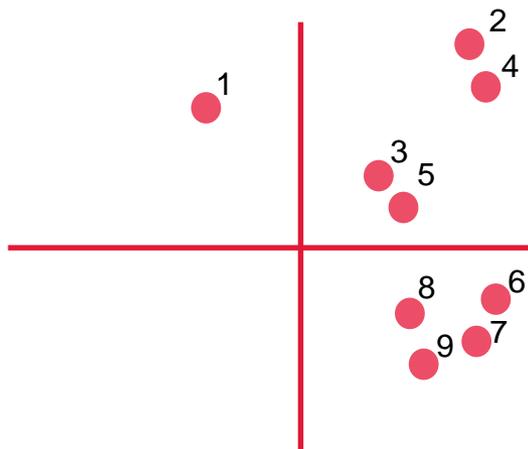


1	3 5 8 7 6 4 5
2	1 3 5 8 7 6 5
.	.
.	.
.	.
.	.
87	8 5 4 3 5 6 7
88	4 5 6 7 8 9
89	2 1 3 5 6 7 8
90	7 4 2 1 3 5 6

Treat the set of random walks as sentences



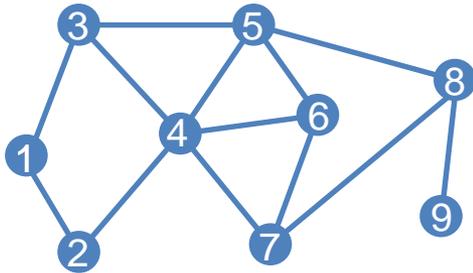
Feed sentences to a Skip-gram NN model



Learn a vector representation for each node

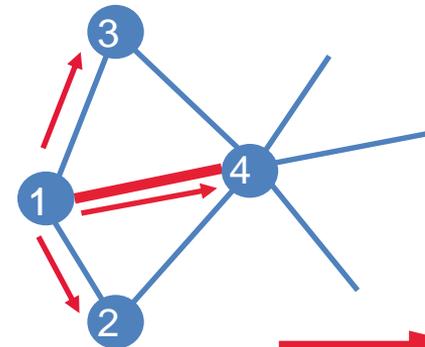
Example: Edge Addition

t = 0



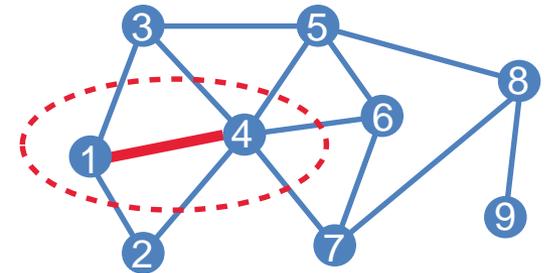
1	3 5 8 7 6 4 5
2	1 3 5 8 7 6 5
.	.
.	.
.	.
.	.
87	8 5 4 3 5 6 7
88	4 5 6 7 8 9 8
89	2 1 3 5 6 7 8
90	7 4 2 1 3 5 6

addition of edge (1, 4)



need to update the RW set

t = 1



simulate the rest of the RW

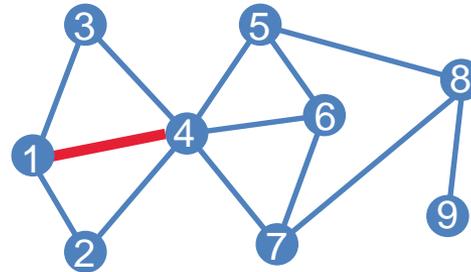
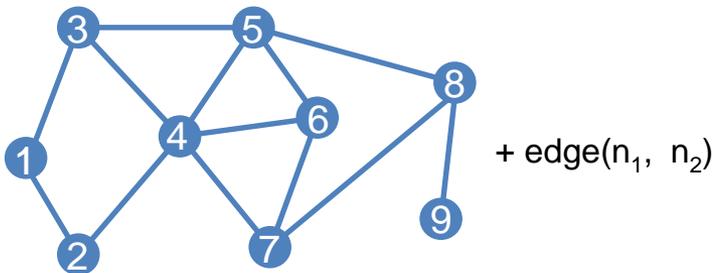
2	1 4 3 5 6 7 8
---	---------------

1	3 5 8 7 6 4 5
2	1 3 5 8 7 6 5
.	.
.	.
.	.
.	.
87	8 5 4 3 5 6 7
88	4 5 6 7 8 9 8
89	2 1 3 5 6 7 8
90	7 4 2 1 3 5 6

similarly for **edge deletion, node addition/deletion**

Efficiently Maintaining a Set of Random Walks

EvoNRL Operations



1	3 5 8 7 6 4 5
2	1 3 5 8 7 6 5
.	.
.	.
.	.
.	.
87	8 5 4 3 5 6 7
88	4 5 6 7 8 9
89	2 1 3 5 6 7 8
90	7 4 2 1 3 5 6



1	3 5 8 7 6 4 5
2	1 3 5 8 7 6 5
.	.
.	.
.	.
.	.
87	8 5 4 3 5 6 7
88	4 5 6 7 8 9
89	2 1 3 5 6 7 8
90	7 4 2 1 3 5 6

Operations on RW

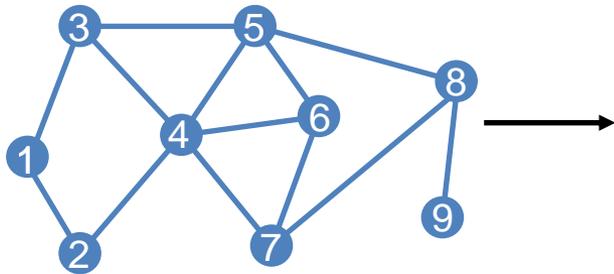
Search a node

Delete a RW

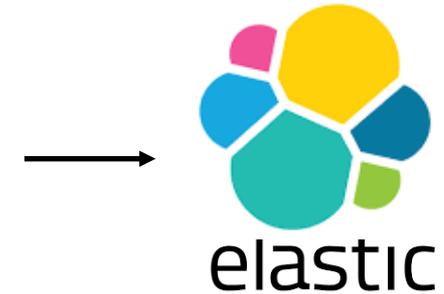
Insert a new RW

need for an **efficient indexing** data structure

EvoNRL Indexing



1	3 5 8 7 6 4 5
2	1 3 5 8 7 6 5
.	.
.	.
.	.
.	.
87	8 5 4 3 5 6 7
88	4 5 6 7 8 9
89	2 1 3 5 6 7 8
90	7 4 2 1 3 5 6



each node is a **keyword**
 each RW is a **document**
 a set of RWs is a **collection of documents**

Term	Frequency	Postings and Positions
1	3	< 2, 1 >, < 89, 2 >, < 90, 4 >
2	2	<89, 1>, <90, 3>
3	5	<1, 1>, <2, 1>, <87, 3>, <89, 3>, <90, 5>
4	4	<1, 6>, <87, 3>, <90, 2>
5	9	<1, 2>, <1, 7>, <2, 3>, <2, 7>, <87, 5>, <88, 2>, <89, 4>, <90, 6>
6	6	<1, 5>, <2, 6>, <87, 6>, <88, 3>, <89, 3>, <90, 5>
7	5	<1, 4>, <2, 5>, <87, 7>, <88, 4>, <89, 6>, <90, 7>
8	5	<1, 3>, <2, 4>, <87, 1>, <88, 6>, <89, 7>
9	1	<88, 7>

Evaluation of EvoNRL

Evaluation: EvoNRL vs StaticNRL

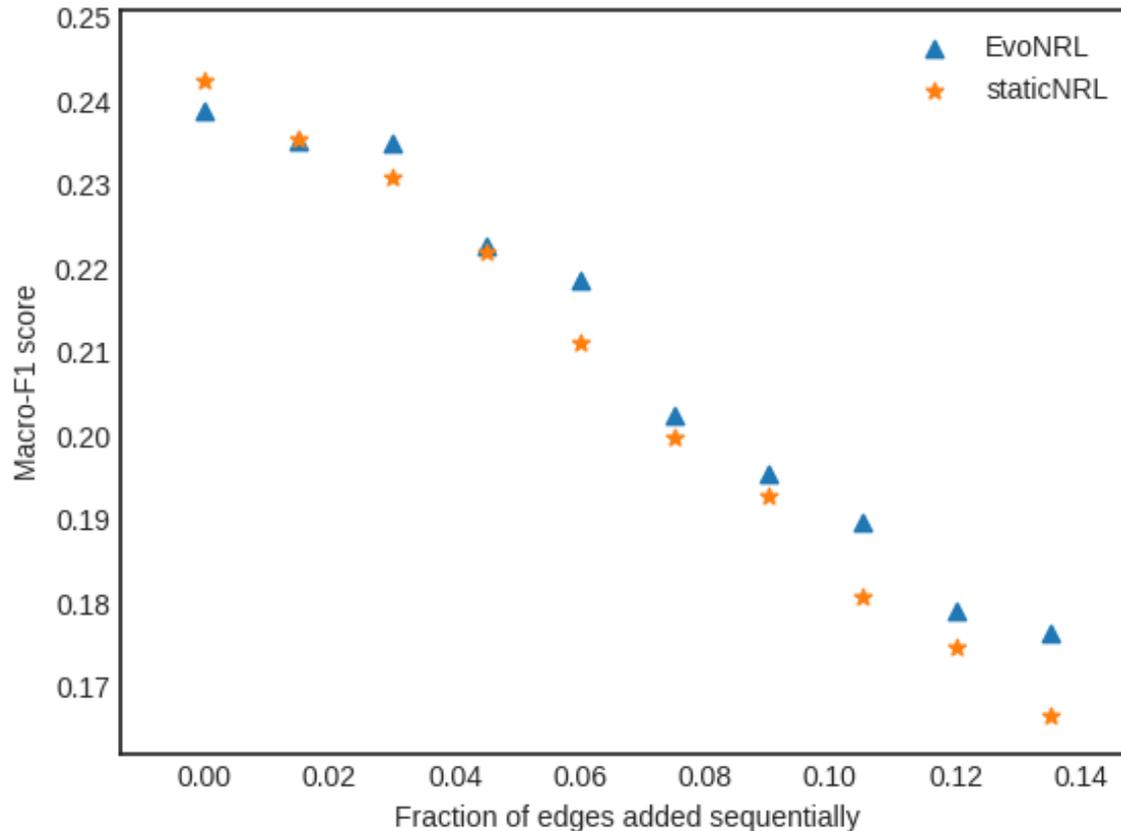
Accuracy

❓ EvoNRL \approx StaticNRL

Running Time

❓ EvoNRL \ll StaticNRL

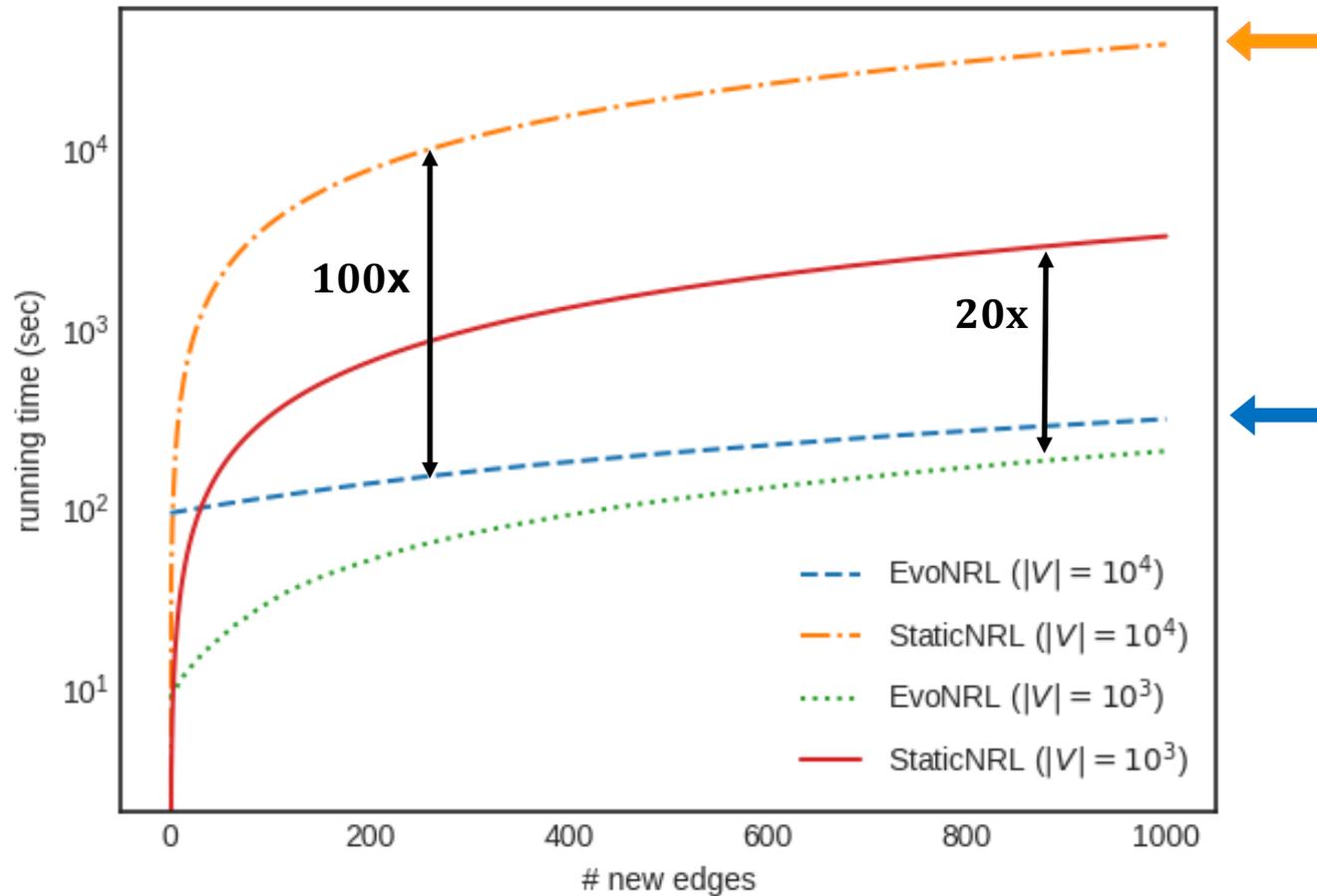
Accuracy: edge addition



EvoNRL has similar accuracy to StaticNRL

(similar results for edge deletion, node addition/deletion)

Time Performance



EvoNRL performs **orders of time faster** than StaticNRL

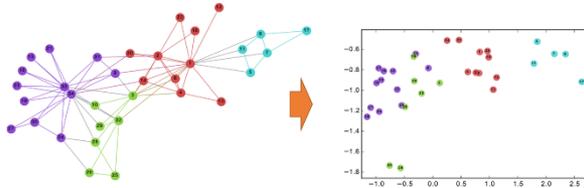
Takeaway

how can we learn representations of an evolving network?

EvoNRL

time efficient
accurate
generic method

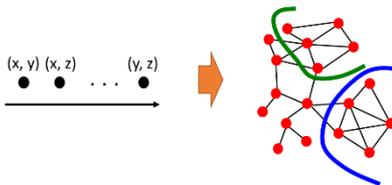
Current Research focus



A. Network Representation Learning



B. Trajectory Network Mining



C. Streaming & Dynamic Graphs



D. Social Media Mining & Analysis



E. City Science / Urban Informatics / IoT



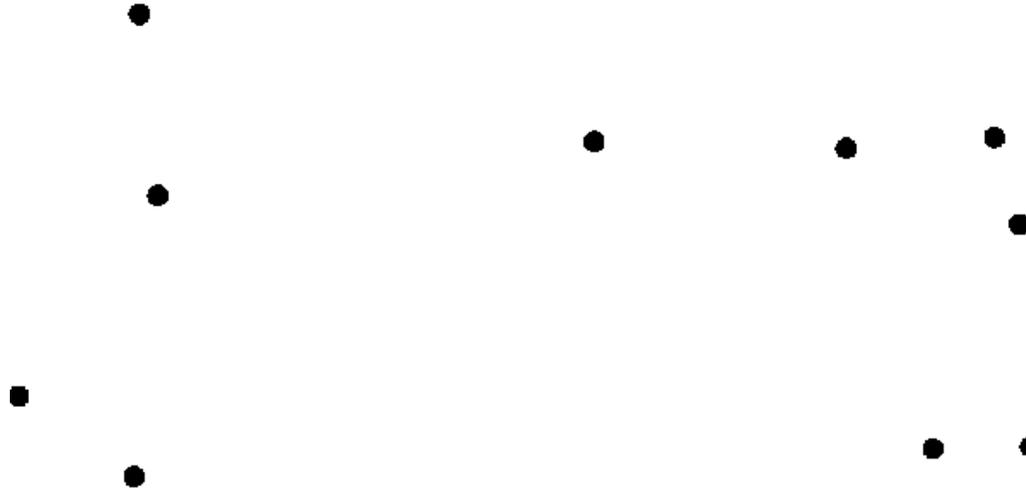
F. Natural Language Processing

Node Importance in Trajectory Networks

Joint work with Tilemachos Pechlivanoglou

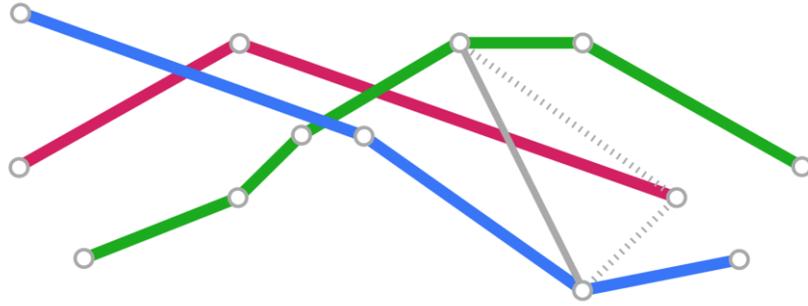
Trajectories of moving objects

7.2.2.1

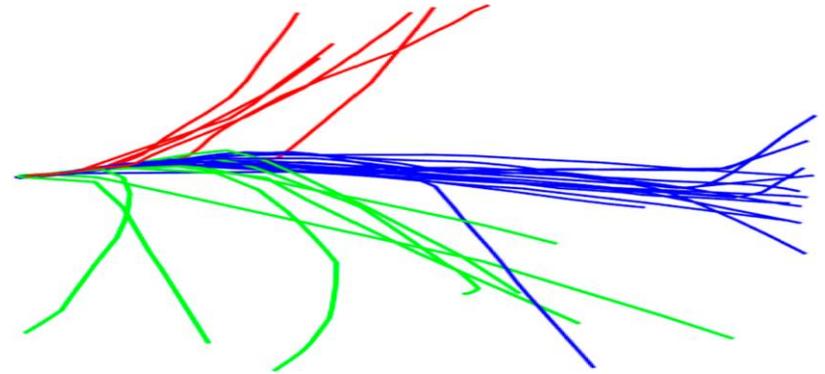


every moving object, forms a **trajectory** – in 2D it is a sequence of (x, y, t)
there are trajectories of moving cars, people, birds, ...

Trajectory data mining



trajectory similarity

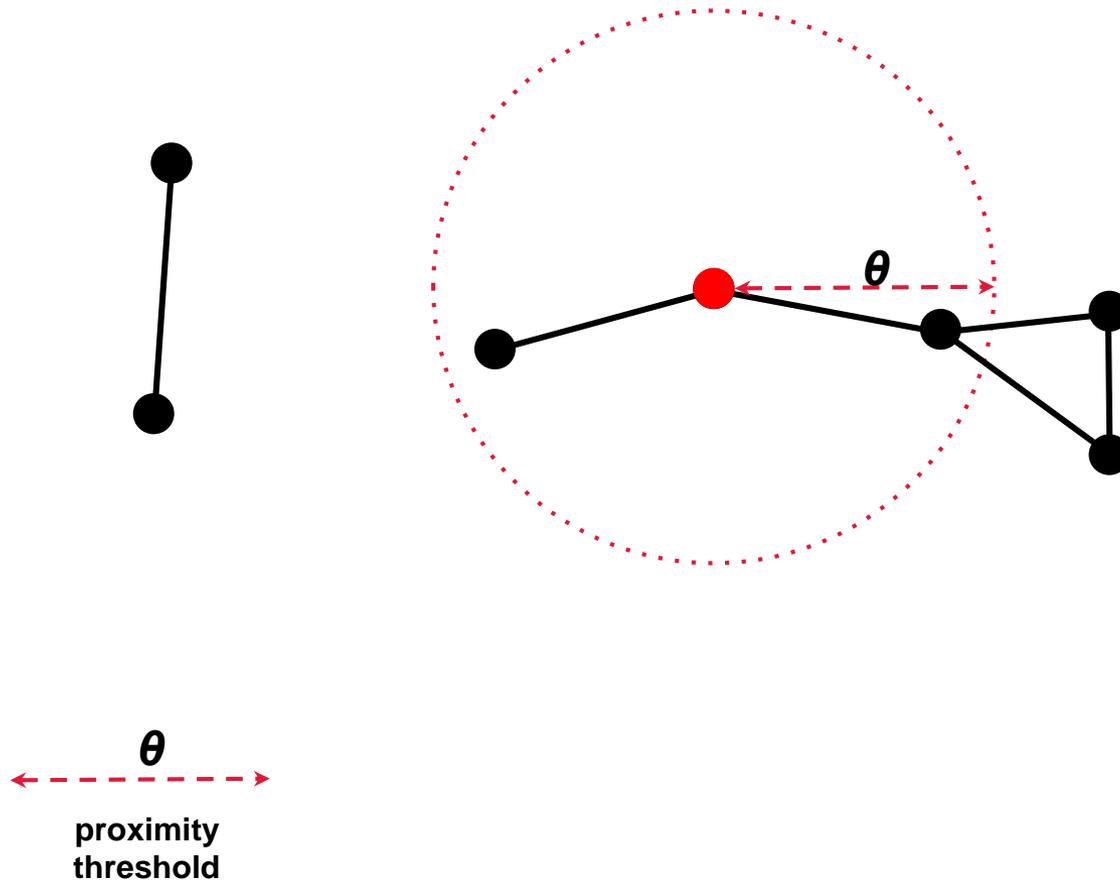


trajectory clustering

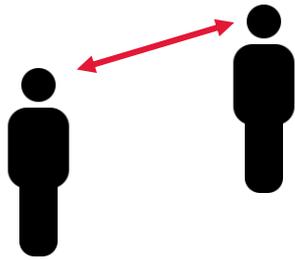
trajectory anomaly detection
trajectory pattern mining
trajectory classification
...more

we care about **network analysis** of moving objects

Proximity networks



Distance can represent



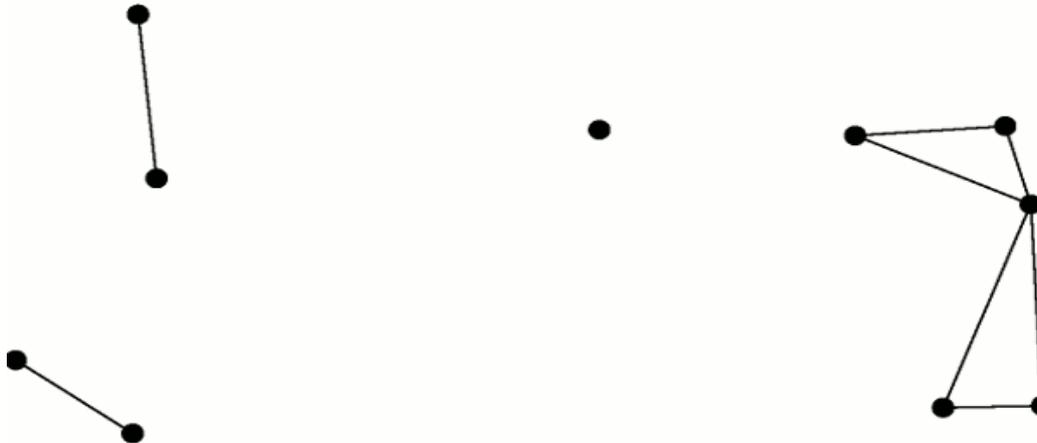
line of sight



wifi/bluetooth signal range

Trajectory networks

0



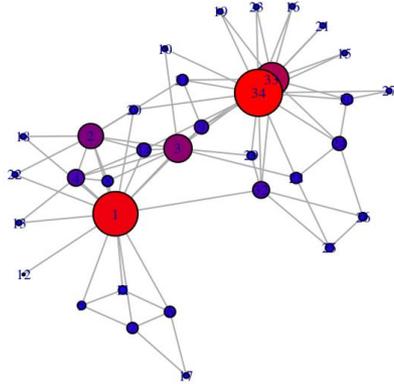
The Problem

Input: logs of trajectories (x, y, t) in time period $[0, T]$

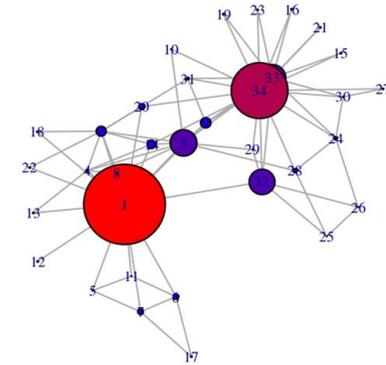
Output: node importance metrics

Node Importance

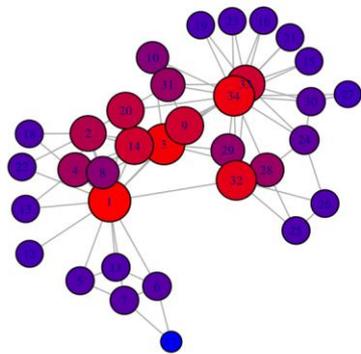
Node importance in static networks



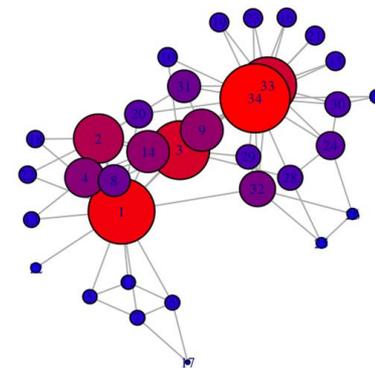
Degree centrality



Betweenness centrality

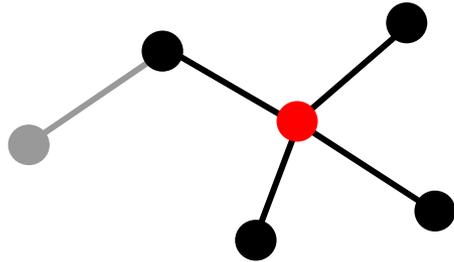


Closeness centrality

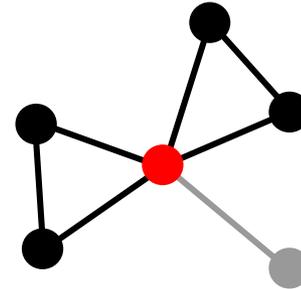


Eigenvector centrality

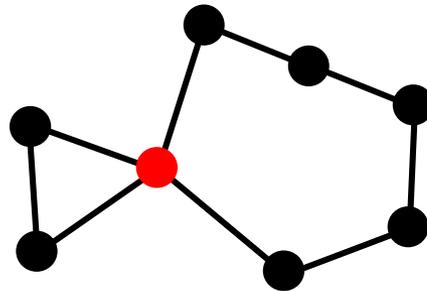
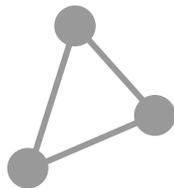
Node importance in TNs



node degree **over time**

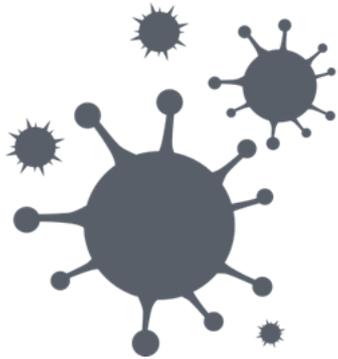


triangles **over time**



connected components **over time**
(connectedness)

Applications



infection spreading



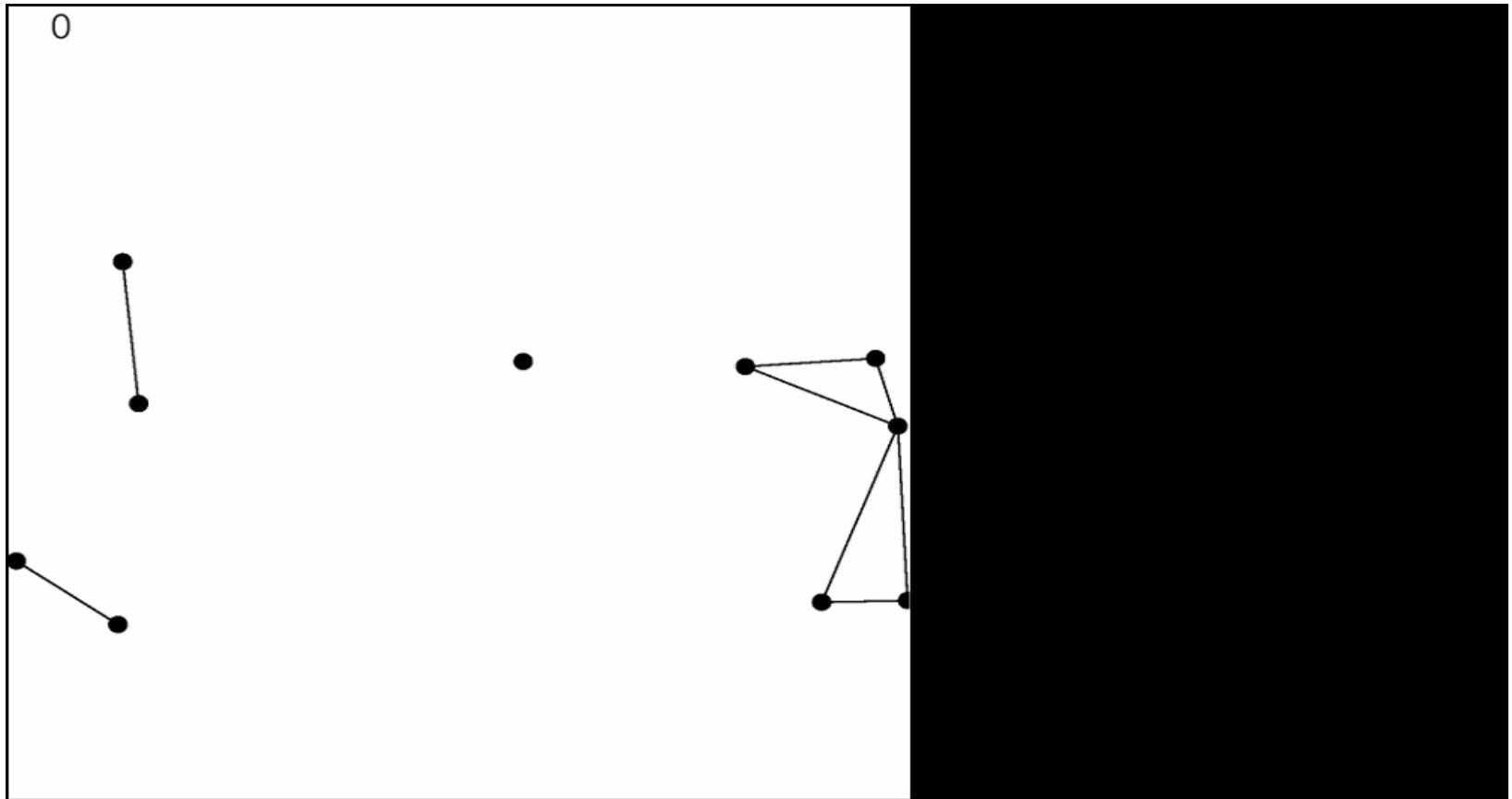
security in autonomous
vehicles



rich dynamic network analytics

Evaluation of Node Importance in Trajectory Networks

Naive approach



For **every** discrete time unit t :

1. obtain static **snapshot** of the proximity network
2. run **static** node importance **algorithms** on snapshot

Aggregate results at the end

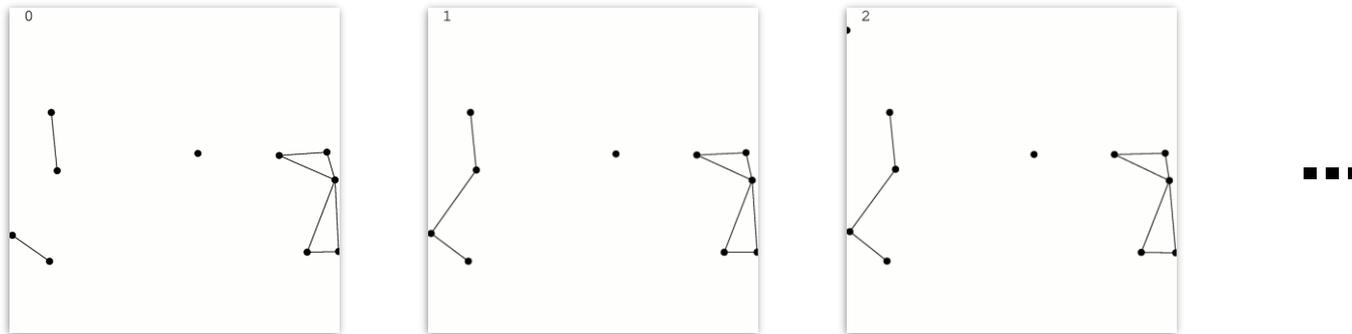
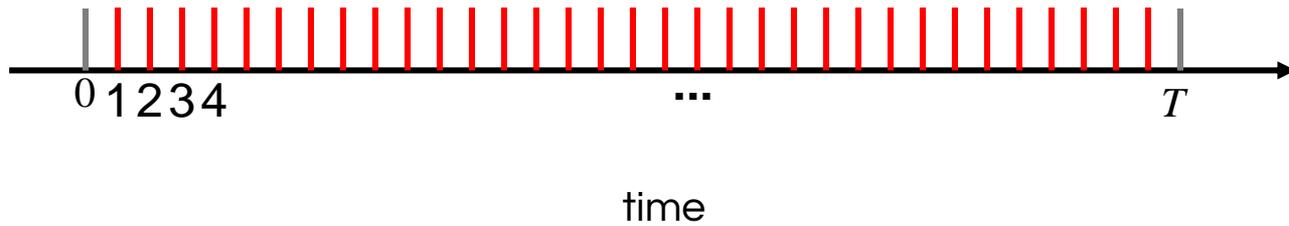
Streaming approach

Similar to naive, but:

- **no final aggregation**
- results calculated **incrementally** at every step

Still **every time** unit

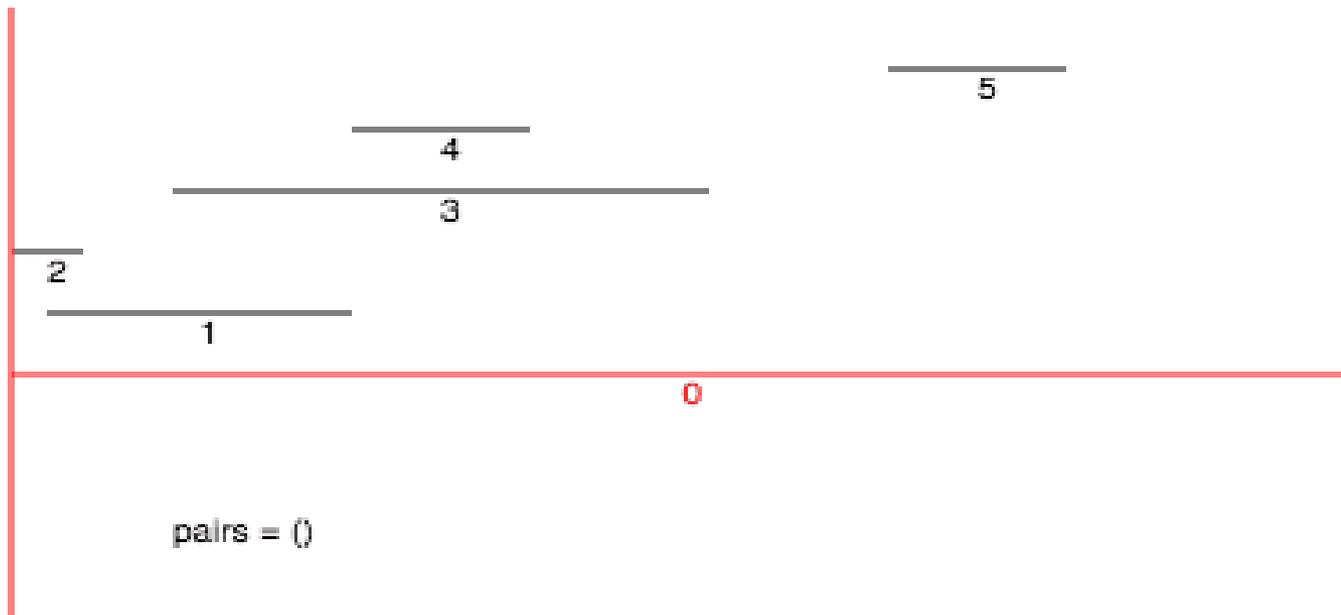
Every discrete time unit



Sweep Line Over Trajectories (SLOT)

Sweep line algorithm

A **computational geometry** algorithm that given **line segments** computes line segment **overlaps**



Efficient **one pass** algorithm that only processes line segments at the **beginning** and **ending** points

SLOT: Sweep Line Over Trajectories

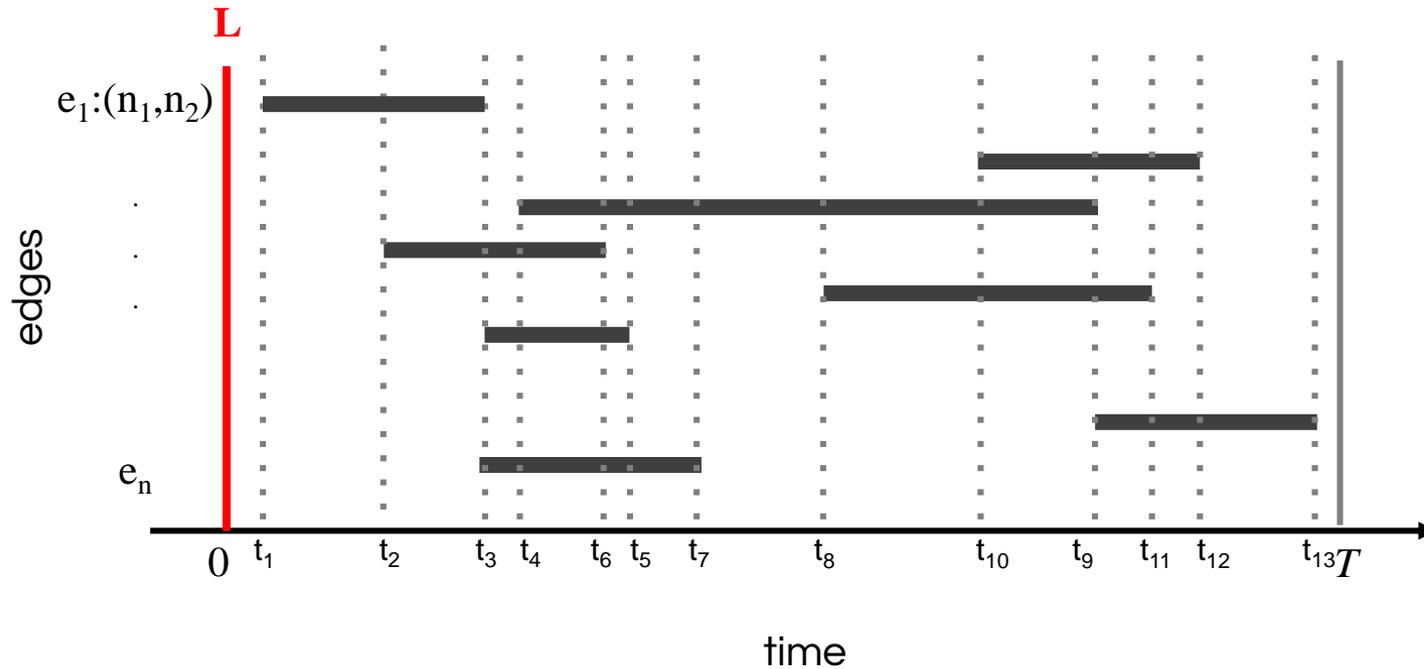
(algorithm sketch)

represent TN **edges** as **time intervals**

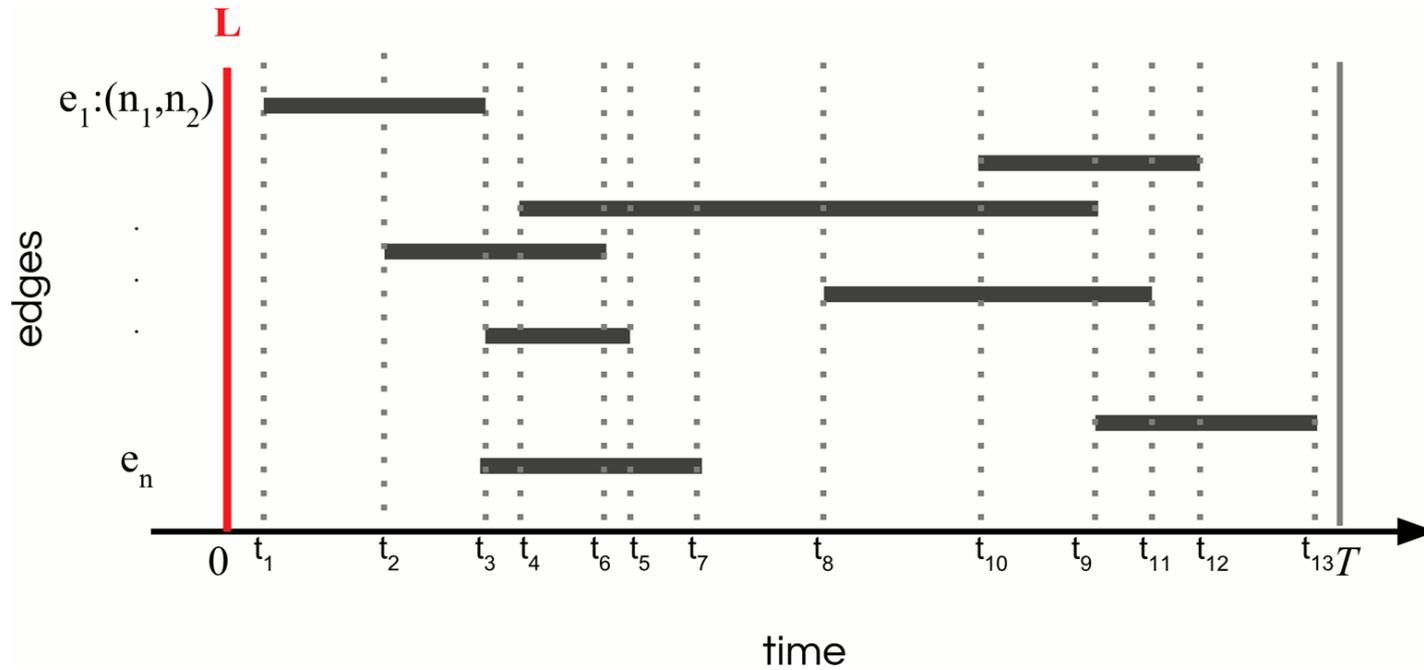
apply **variation** of sweep line algorithm

simultaneously compute *node degree, triangle membership, connected components* in **one pass**

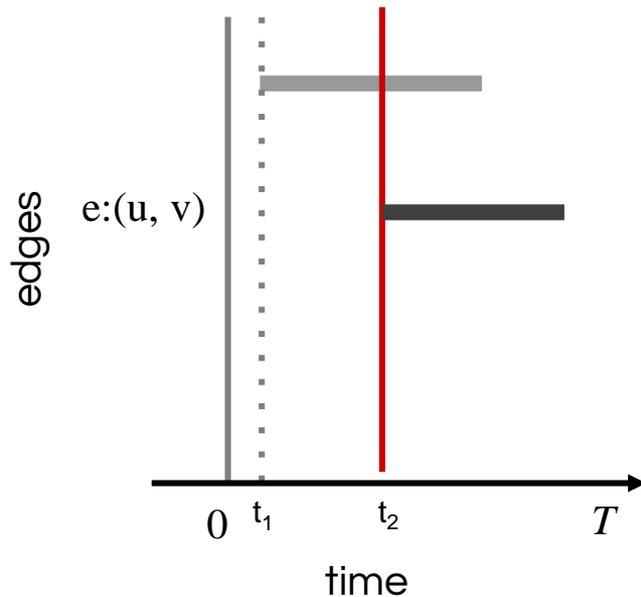
Represent edges as time intervals



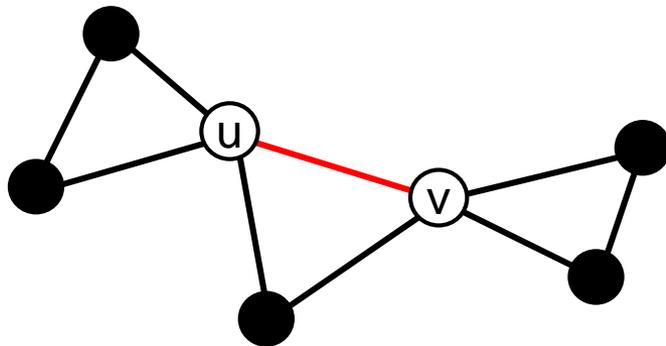
SLOT: Sweep Line Over Trajectories



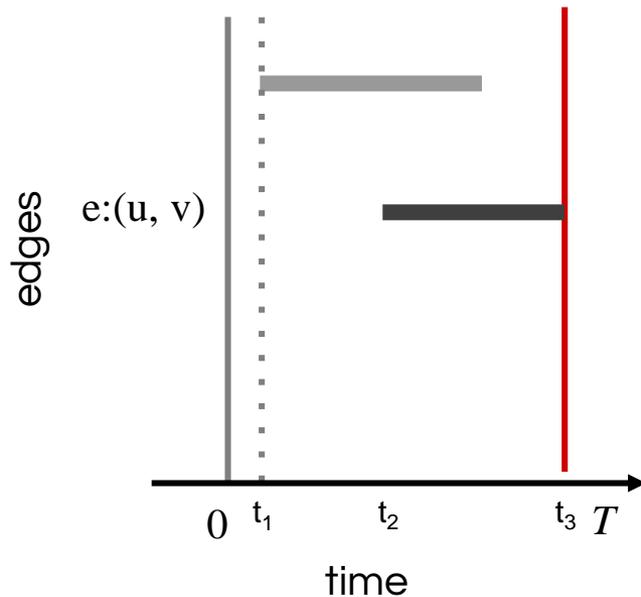
At every edge **start**



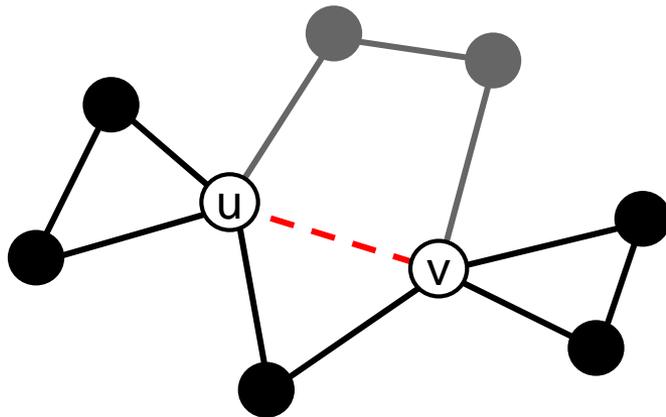
- **node degree**
 - nodes **u**, **v** now connected
 - increment **u**, **v** node degrees
- **triangle membership**
 - did a triangle just form?
 - look for **u**, **v** common neighbors
 - increment triangle (**u**, **v**, **common**)
- **connected components**
 - did two previously disconnected components connect?
 - compare old components of **u**, **v**
 - if no overlap, merge them



At every edge **stop**



- node degree
 - nodes **u**, **v** now disconnected
 - decrement **u**, **v** degree
- triangle membership
 - did a triangle just break?
 - look for **u**, **v** common neighbors
 - decrement triangle (**u**, **v**, **common**)
- connected components
 - did a conn. compon. separate?
 - BFS to see if **u**, **v** still connected
 - if not, split component to two



SLOT: At the end of the algorithm ...

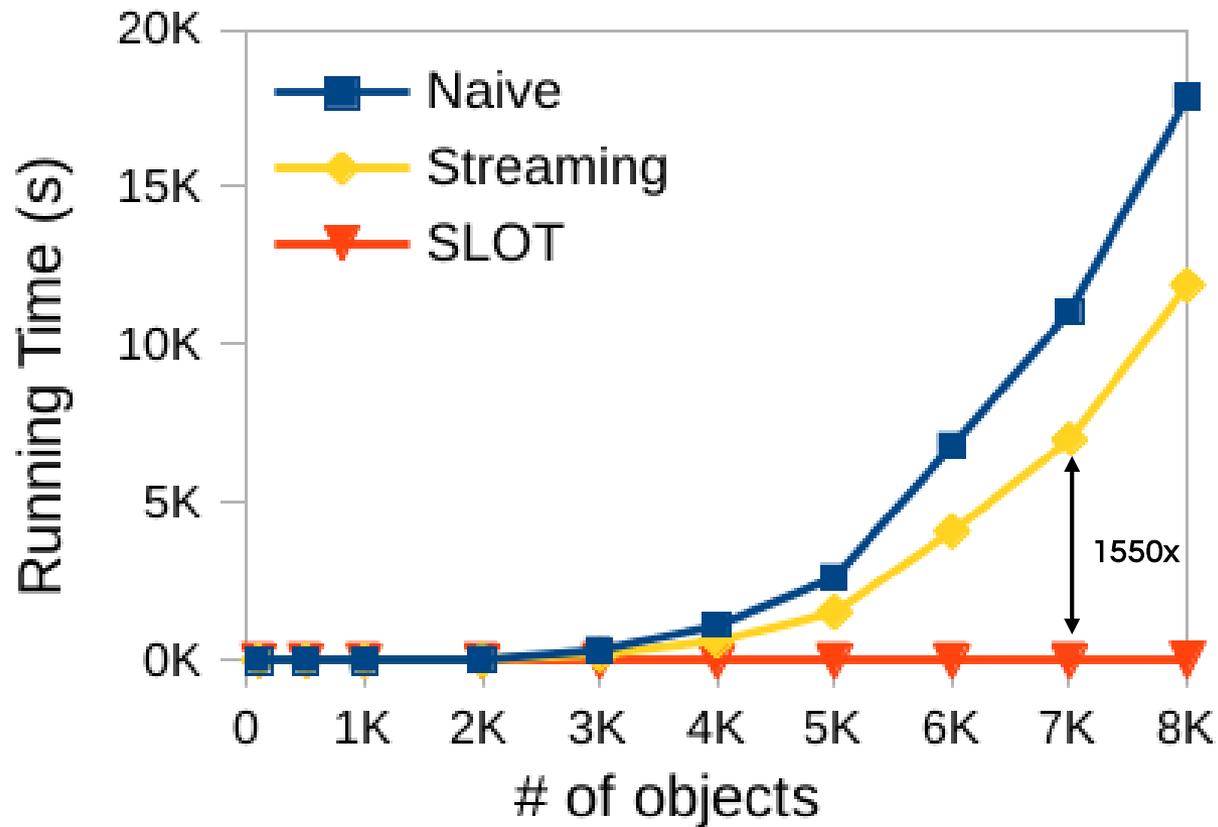
Rich Analytics

- node degrees: start/end time, duration
- triangles: start/end time, duration
- connected components: start/end time, duration

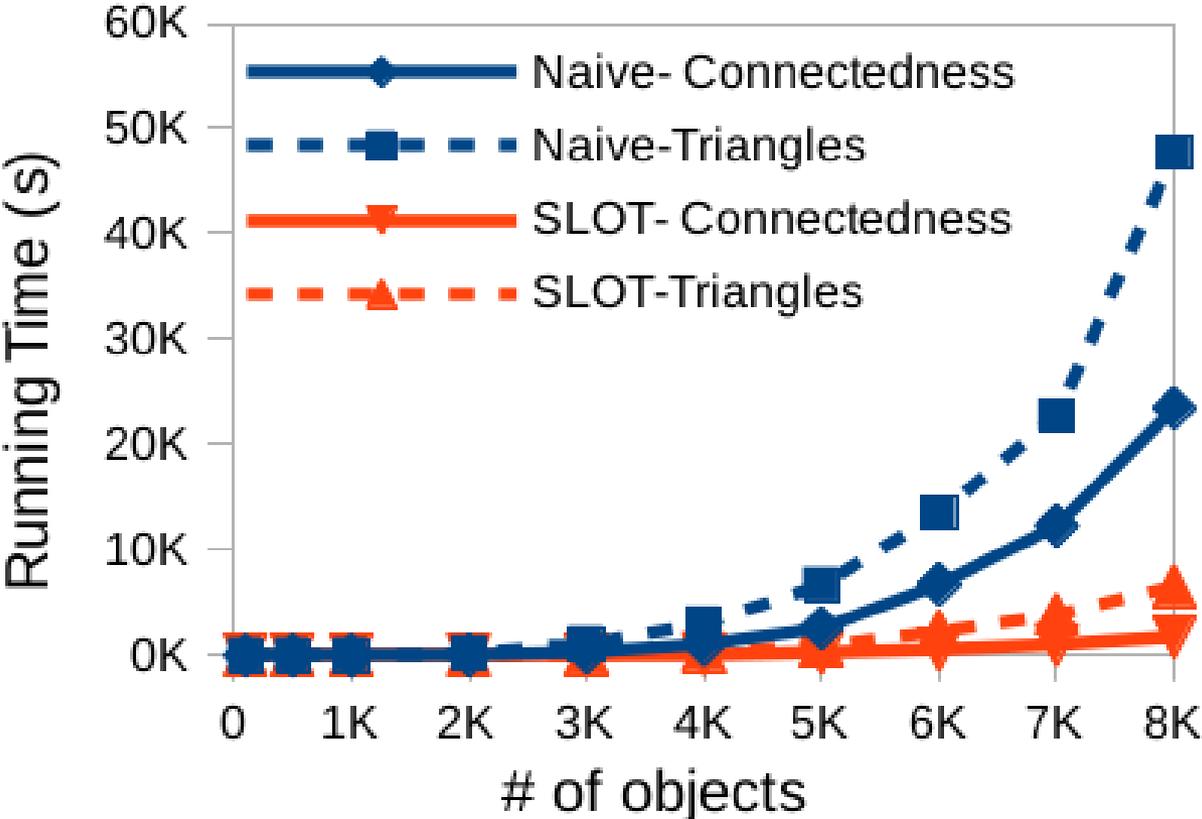
Exact results (not approximations)

Evaluation of SLOT

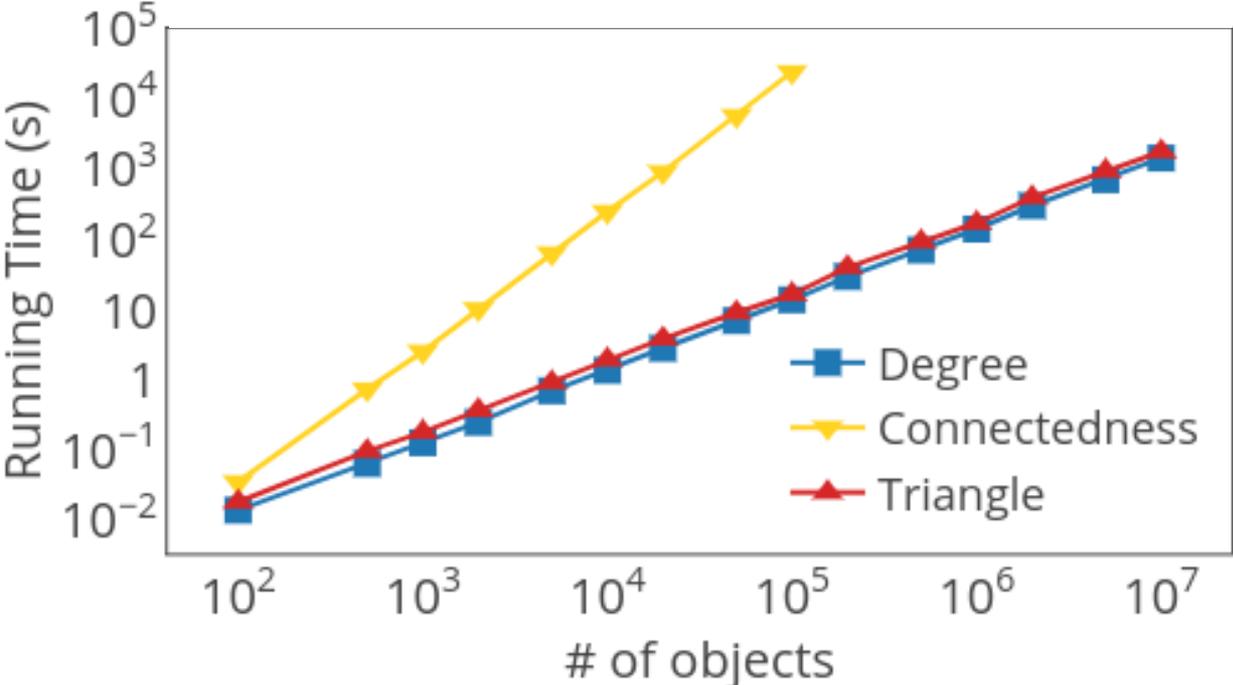
Node degree



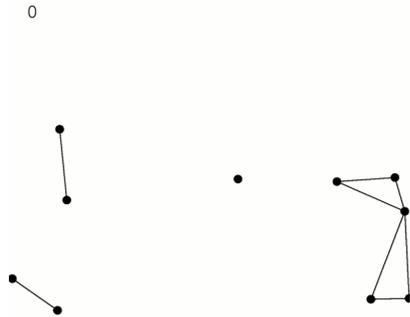
Triangle membership / connected components



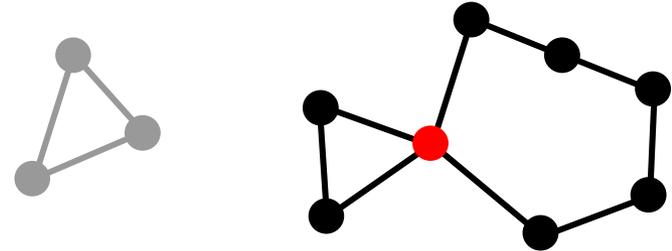
SLOT Scalability



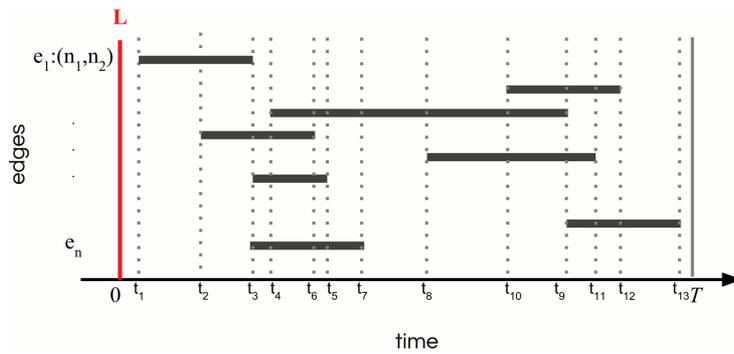
Takeaway



trajectory networks



network importance **over time**



SLOT algorithm

SLOT properties:

- fast
- exact
- scalable

Seagull migration trajectories



data from Wikelski et al. 2015

Credits



Farzaneh Heidari

[Complex Networks 2018] **EvoNRL: Evolving Network Representation Learning Based on Random Walks.** Farzaneh Heidari and Manos Papagelis.

Source code: <https://github.com/farzana0/EvoNRL/>



Tilemachos Pechlivanoglou

[IEEE Big Data 2018] **Fast and Accurate Mining of Node Importance in Trajectory Networks.** Tilemachos Pechlivanoglou and Manos Papagelis.

Source code: <https://github.com/tipech/trajectory-networks>

For more info visit: [Data Mining Lab @ YorkU](#)

Thank you!

Questions?