

# Network Effects and Cascading Behavior

Thanks to Jure Leskovec, Stanford and Panayiotis Tsaparas,  
Univ. of Ioannina for slides

# Agenda

- Spreading Through Networks
- Granovetter's Model of Collective Action
- Decision Based Model of Diffusion
  - Game Theoretic Model of Cascades

# Spreading Through Networks

- **Spreading through networks:**

- Cascading behavior
- Diffusion of innovations
- Network effects
- Epidemics

- **Behaviors that cascade from node to node like an epidemic**

- **Examples:**

- **Biological:**

- Diseases via contagion

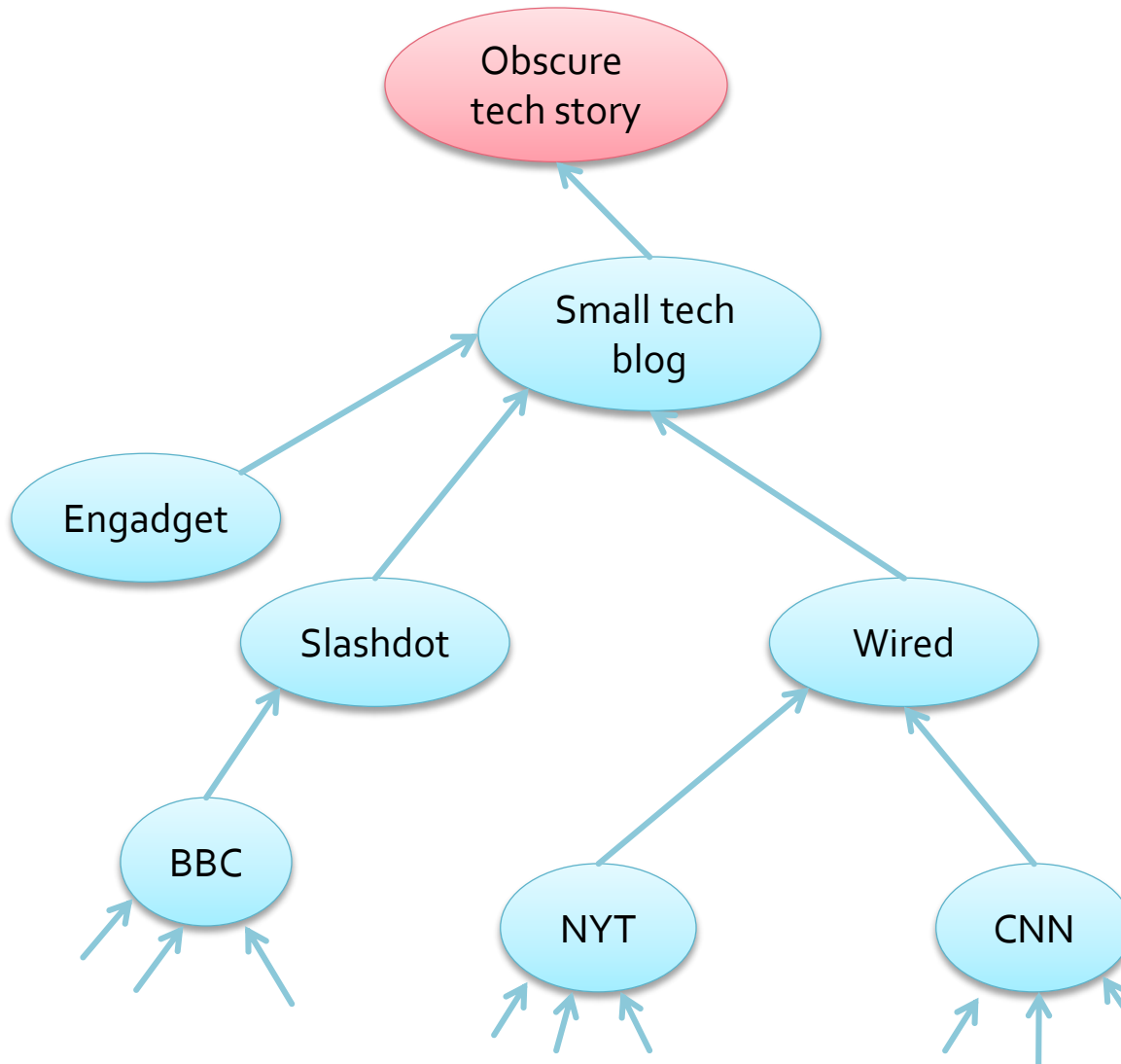
- **Technological:**

- Cascading failures
- Spread of information

- **Social:**

- Rumors, news, new technology
- Viral marketing

# Information Diffusion: Media



# Twitter & Facebook post sharing



**Lada Adamic** shared a [link](#) via Erik Johnston.

January 16, 2013

When life gives you an almost empty jar of nutella, add some ice cream...  
(and other useful tips)



## 50 Life Hacks to Simplify your World

[twistedstifter.com](http://twistedstifter.com)

Life hacks are little ways to make our lives easier. These low-budget tips and trick can help you organize and de-clutter space; prolong and preserve your products; or teach you...

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## Timeline Photos

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$$V = \pi z^2 a$$

$$V = \text{Pi}(z * z) a$$

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**I fucking love science**

Seriously. If you have a pizza with radius "z" and thickness "a", its volume is  $\text{Pi}(z * z)a$ .

Lina von DerStein, Iman Khallaf, 周明佳 and 73,191 others like this.

27,761 shares

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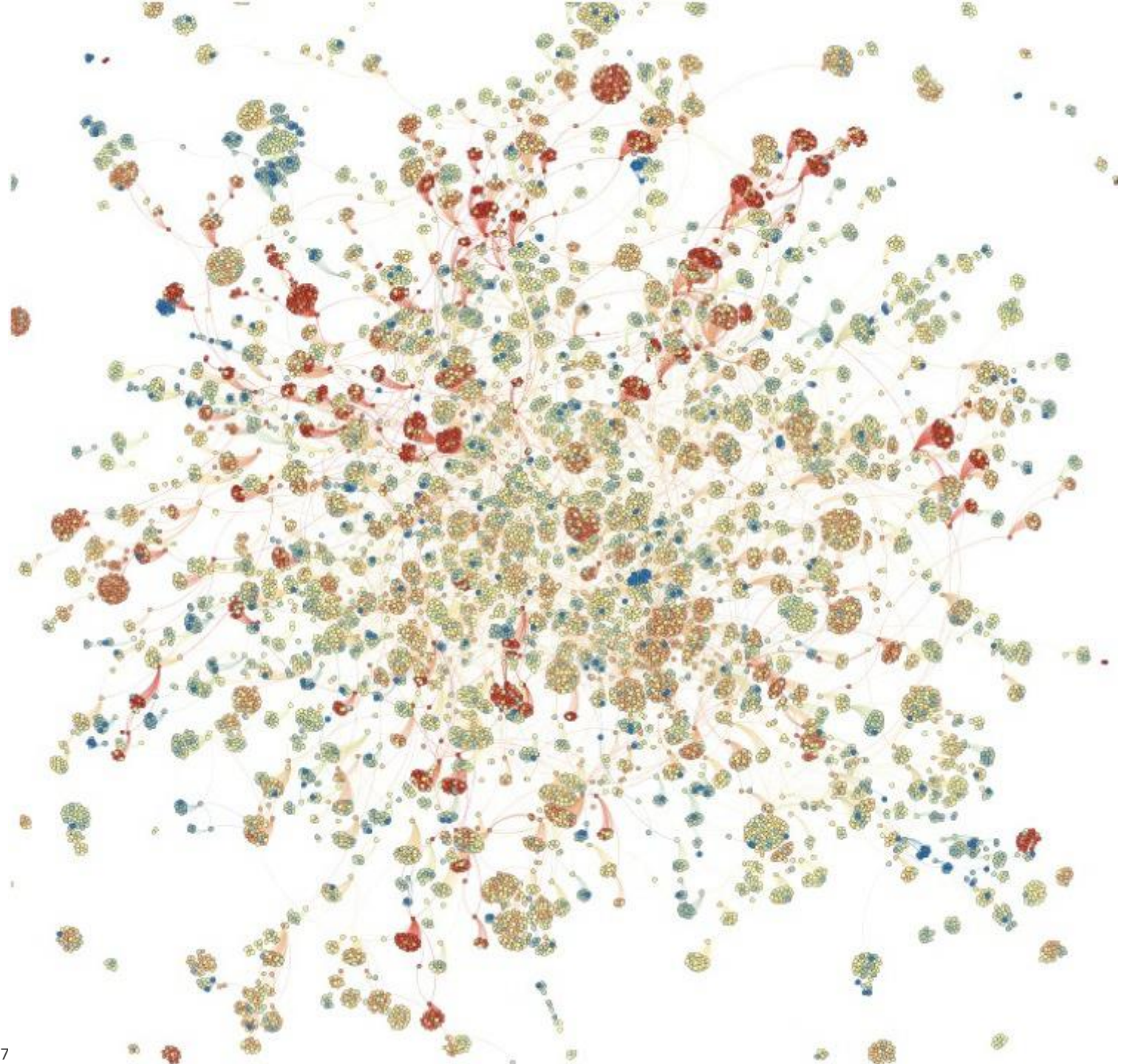
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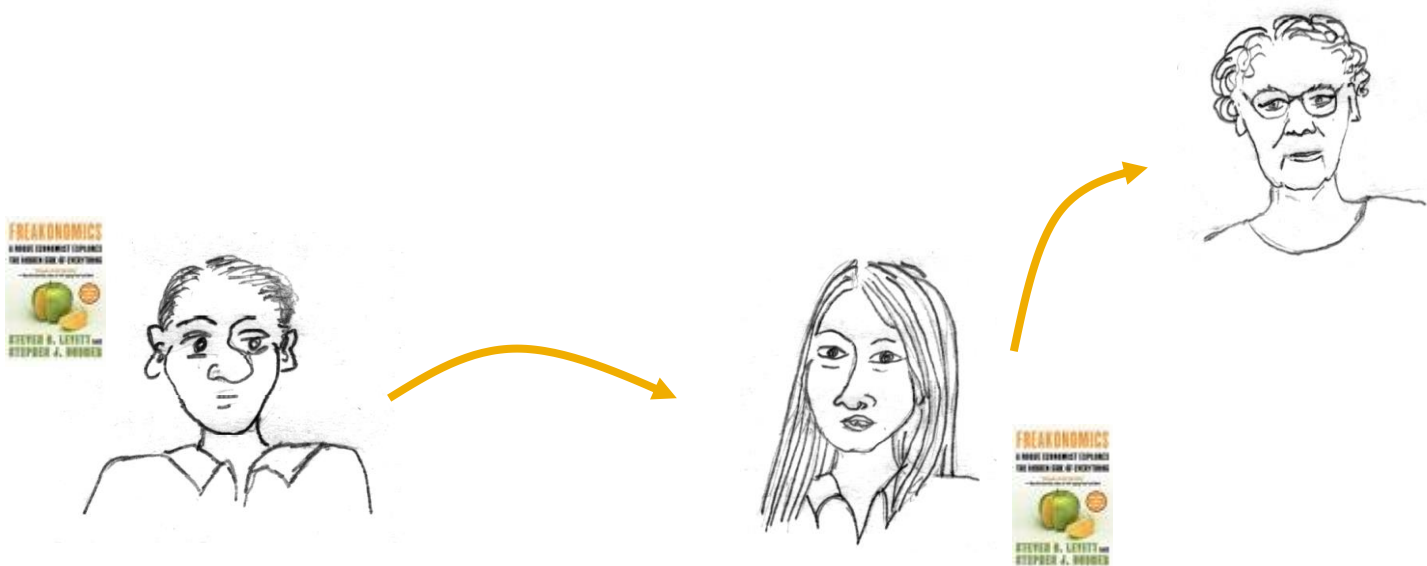
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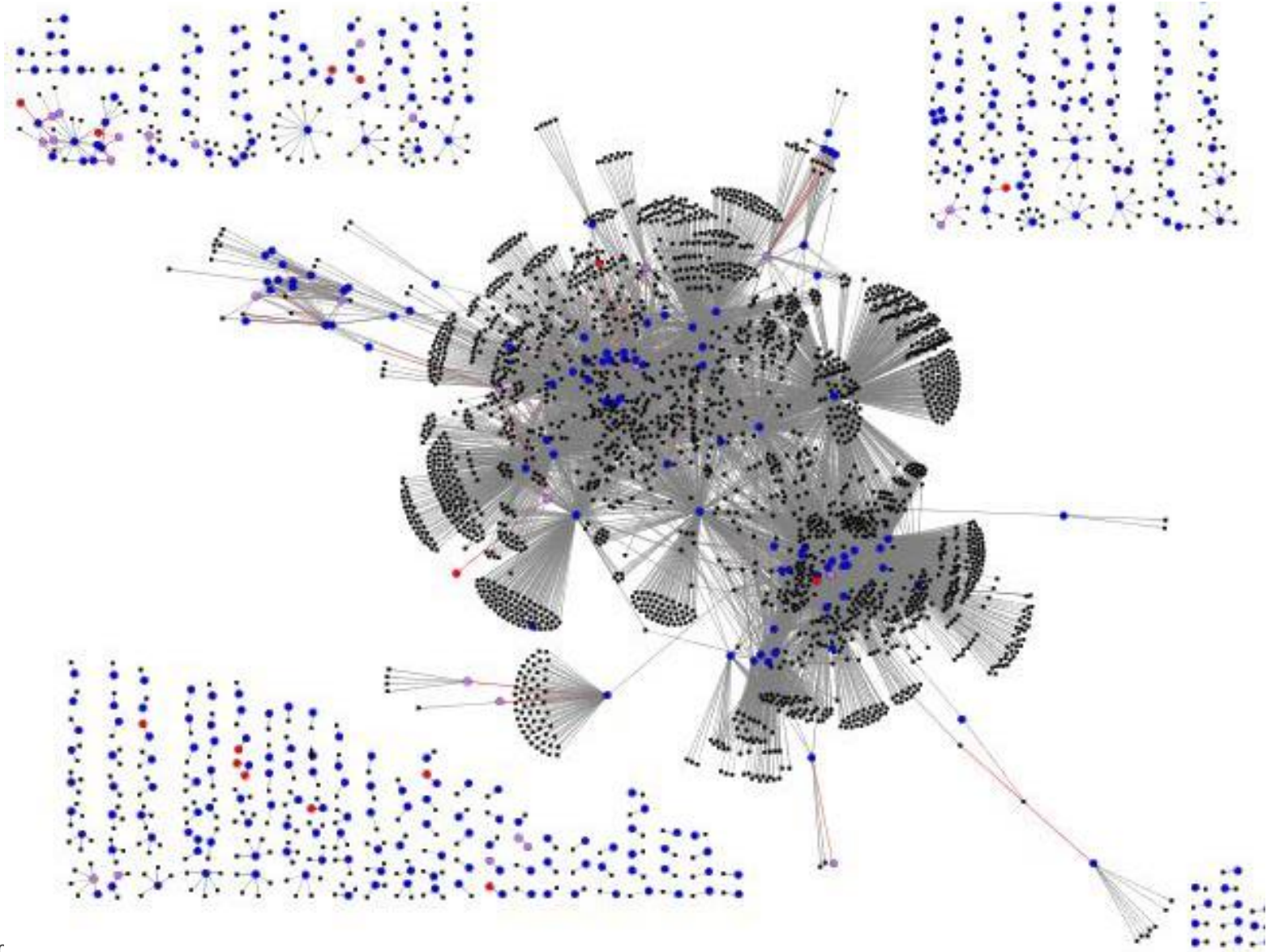
# Diffusion in Viral Marketing

- **Product adoption:**
  - Senders and followers of recommendations

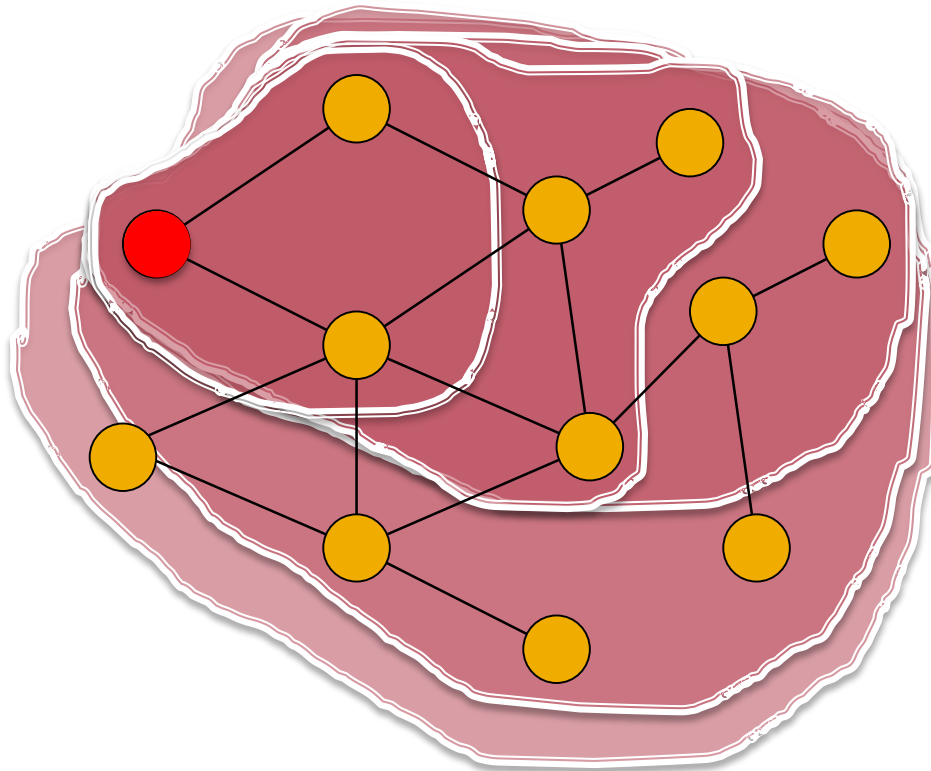




# Diffusion in Viral Marketing

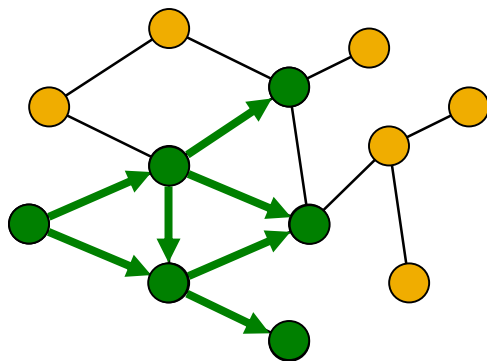


# Spread of Diseases (e.g., Ebola)

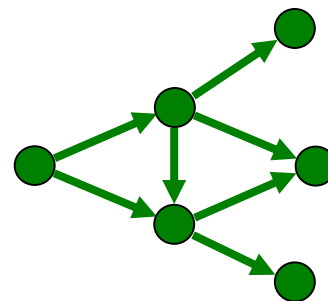


# Network Cascades

- Contagion that spreads over the edges of the network
- It creates a propagation tree, i.e., **cascade**



Network



**Cascade**

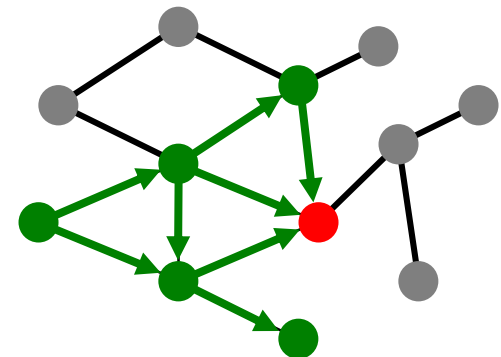
(propagation graph)

## Terminology:

- Stuff that spreads: Contagion
- “Infection” event: Adoption, infection, activation
- We have: Infected/active nodes, adoptors

# How Do We Model Diffusion?

- **Decision based models (today!):**
  - Models of product adoption, decision making
    - A node observes decisions of its neighbors and makes its own decision
  - **Example:**
    - You join demonstrations if  $k$  of your friends do so too
- **Probabilistic models (later):**
  - **Models of influence or disease spreading**
    - An infected node tries to “push” the contagion to an uninfected node
  - **Example:**
    - You “catch” a disease with some prob. from each active neighbor in the network



# Granovetter's Model of Collective Action

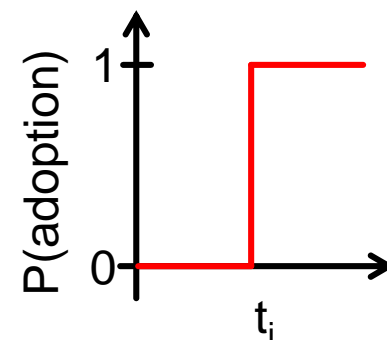
# Decision Based Models

- **Collective Action** [Granovetter, '78]
  - **Model where everyone sees everyone else's behavior** (that is, we assume a complete graph)
  - **Examples:**
    - Clapping or getting up and leaving in a theater
    - Keeping your money or not in a stock market
    - Neighborhoods in cities changing ethnic composition
    - Riots, protests, strikes
- **How does the number of people participating in a given activity grow or shrink over time?**



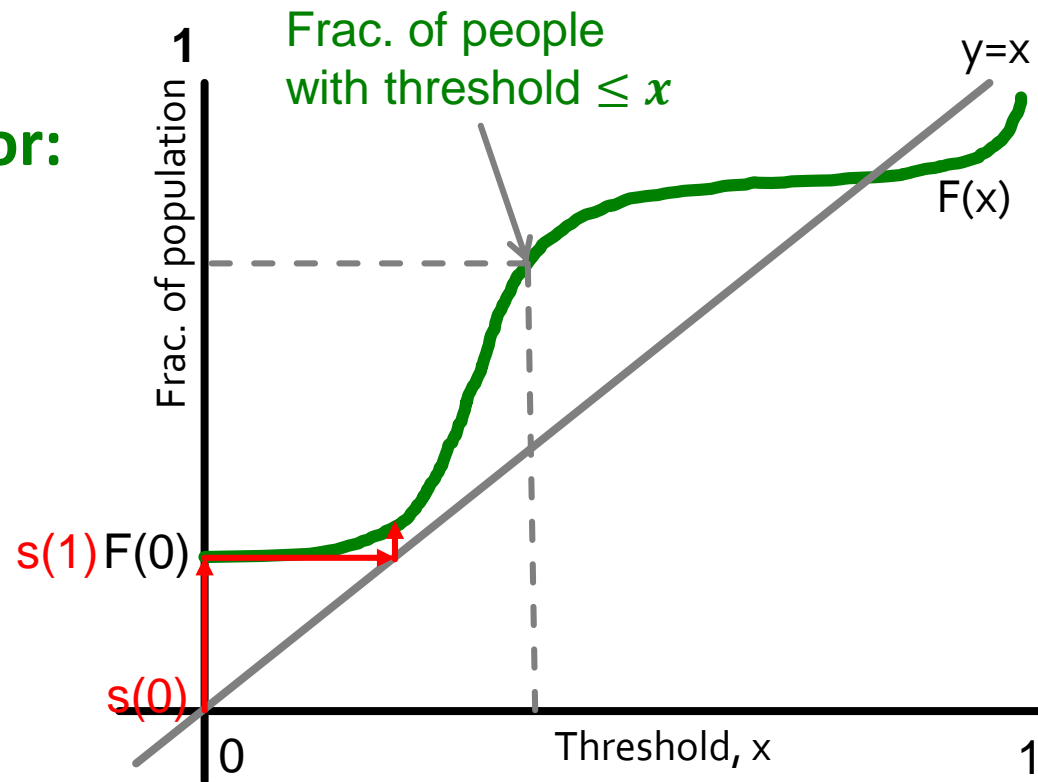
# Collective Action: The Model

- $n$  people – everyone observes all actions
- Each person  $i$  has a threshold  $t_i$  ( $0 \leq t_i \leq 1$ )
  - Node  $i$  will adopt the behavior iff at least  $t_i$  fraction of people have already adopted:
    - Small  $t_i$ : early adopter
    - Large  $t_i$ : late adopter
  - Time moves in discrete steps
- The population is described by  $\{t_1, \dots, t_n\}$ 
  - $F(x)$  ... fraction of people with threshold  $t_i \leq x$ 
    - $F(x)$  is a property of the contagion given to us.  $F(x)$  is the **c.d.f.** of  $x$



# Collective Action: Dynamics

- $F(x)$  ... fraction of people with threshold  $t_i \leq x$ 
  - $F(x)$  is non-decreasing:  $F(x + \varepsilon) \geq F(x)$
- The model is dynamic:
  - Step-by-step change in number of people adopting the behavior:
    - $F(x)$  ... frac. of people with threshold  $\leq x$
    - $s(t)$  ... frac. of people participating at time  $t$
  - Simulate:
    - $s(0) = 0$
    - $s(1) = F(0)$
    - $s(2) = F(s(1)) = F(F(0))$



# Collective Action: Dynamics

- **Step-by-step change in number of people :**

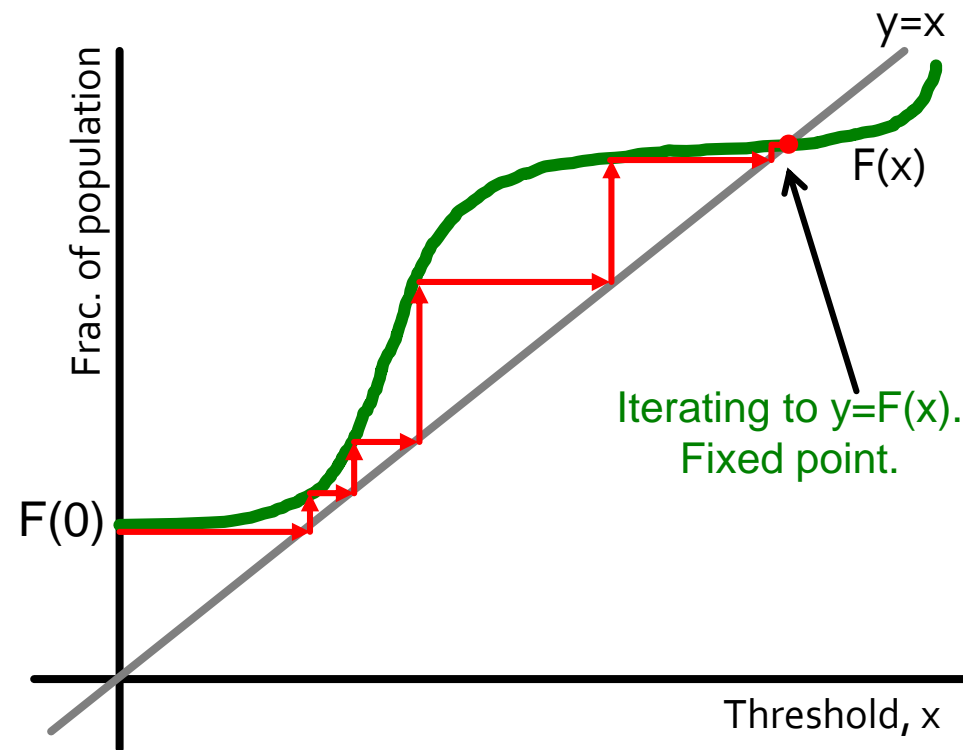
- $F(x)$  ... fraction of people with threshold  $\leq x$
- $s(t)$  ... number of participants at time  $t$

- **Easy to simulate:**

- $s(0) = 0$
- $s(1) = F(0)$
- $s(2) = F(s(1)) = F(F(0))$
- $s(t+1) = F(s(t)) = F^{t+1}(0)$

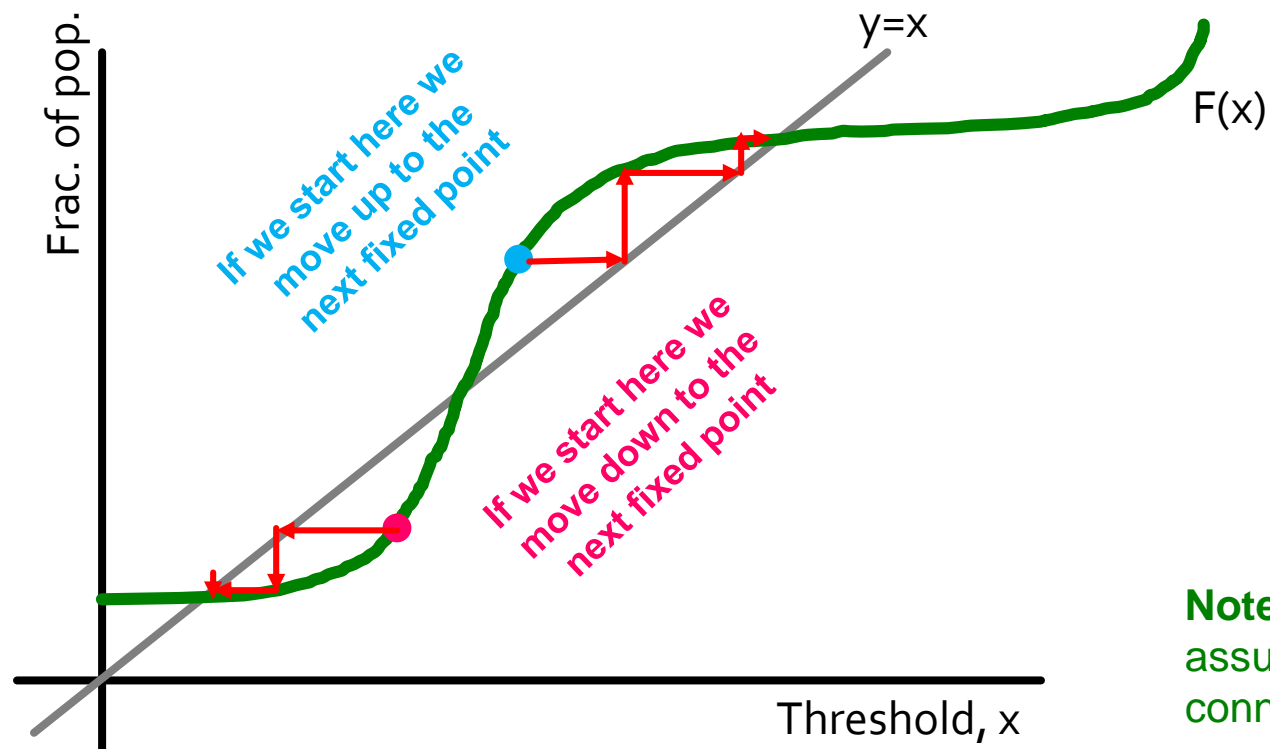
- **Fixed point:  $F(x)=x$**

- Updates to  $s(t)$  to converge to a stable fixed point
- There could be other fixed points but starting from **0** we only reach the first one



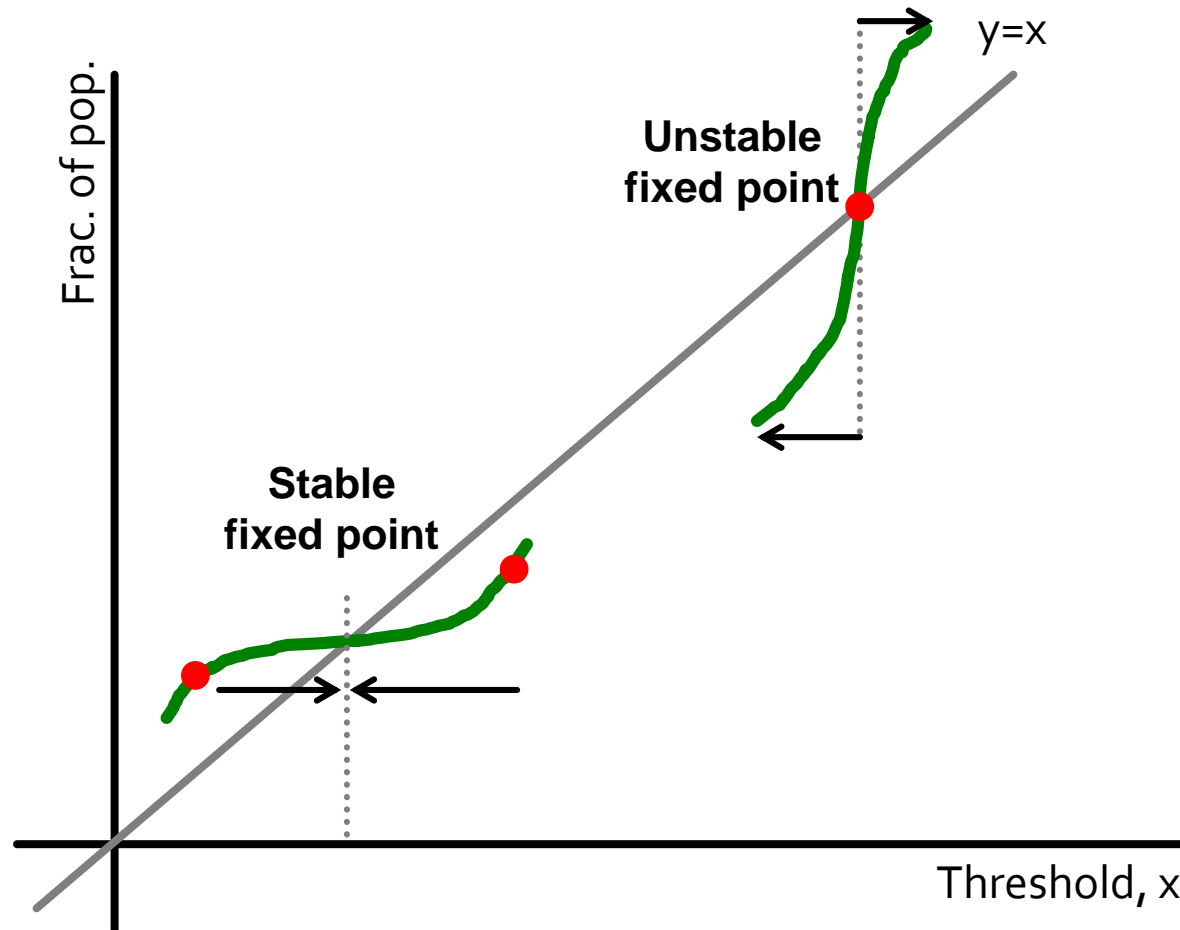
# Starting Elsewhere

- What if we start the process somewhere else?
  - We move up/down to the next fixed point
  - How is market going to change?



**Note:** we are assuming a fully connected graph

# Stable vs. Unstable Fixed Point

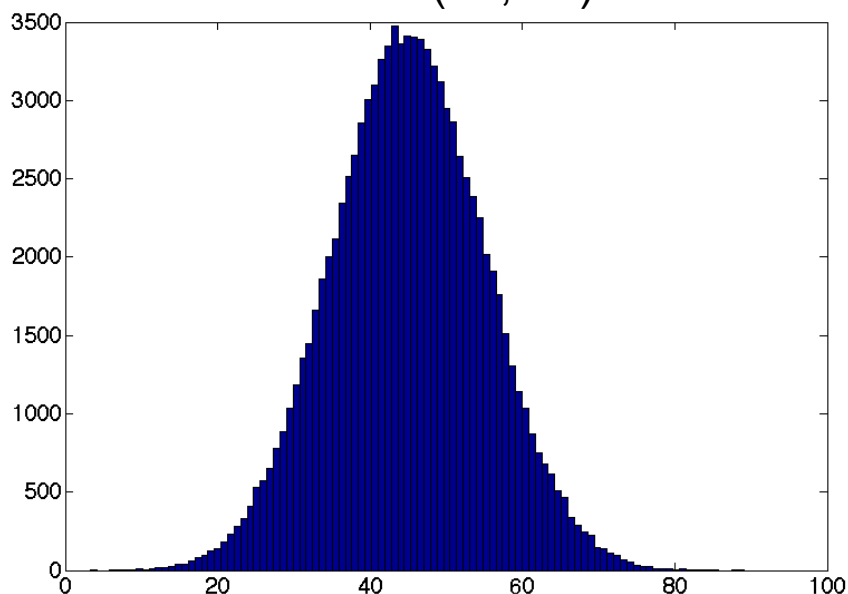


# Discontinuous Transition

- Each threshold  $t_i$  is drawn independently from some distribution  $F(x) = \Pr[\text{thresh} \leq x]$ 
  - **Suppose:** Normal with  $\mu=n/2$ , variance  $\sigma$

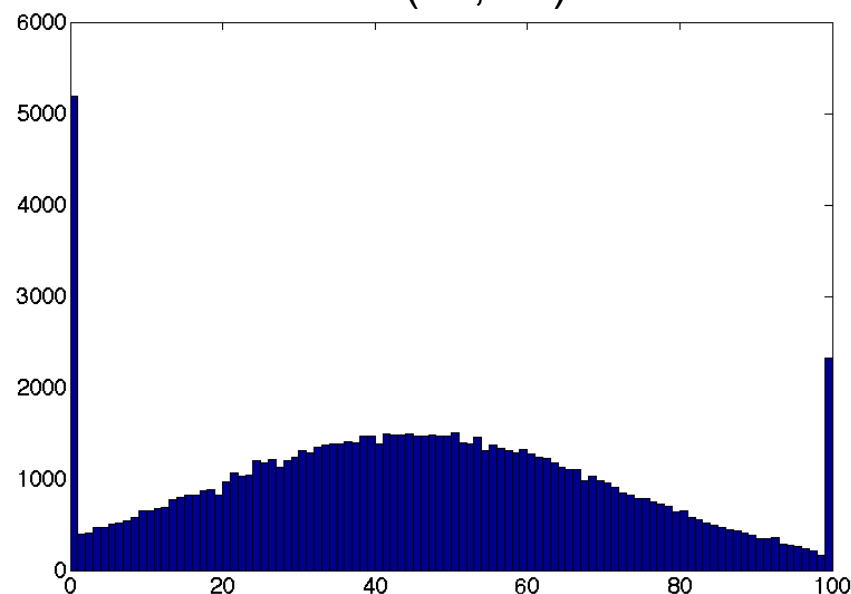
**Small  $\sigma$ :**

Normal(45, 10)



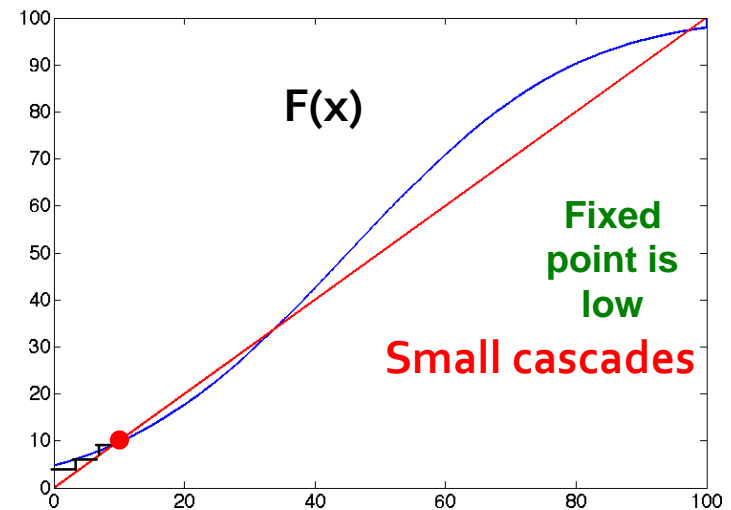
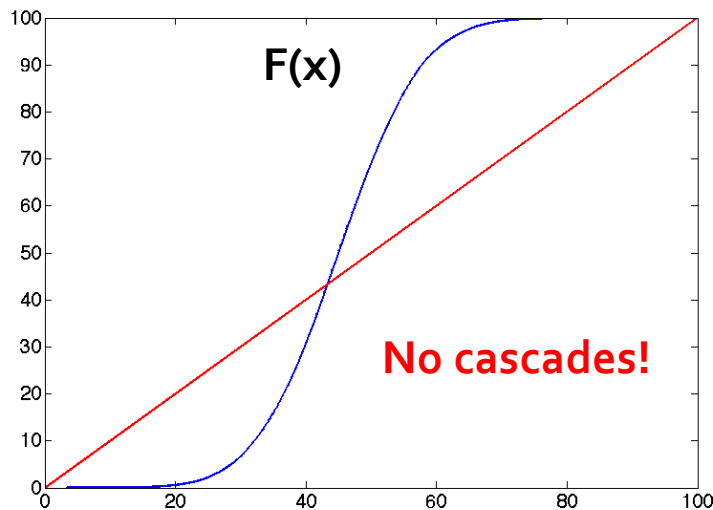
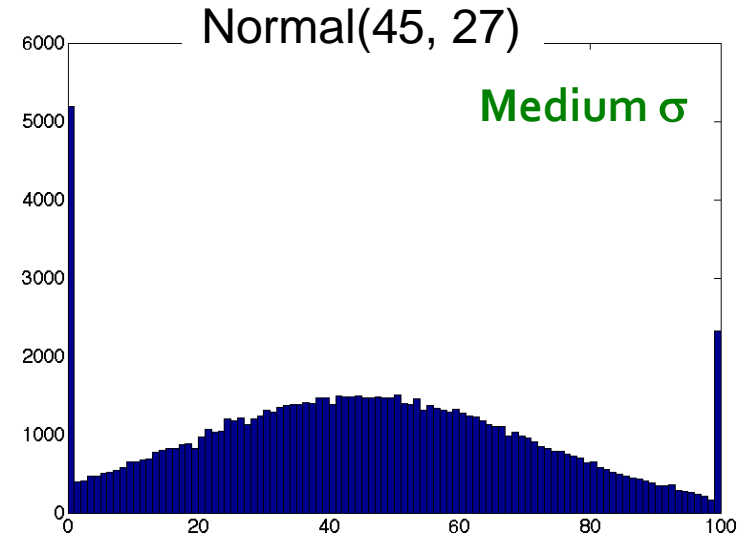
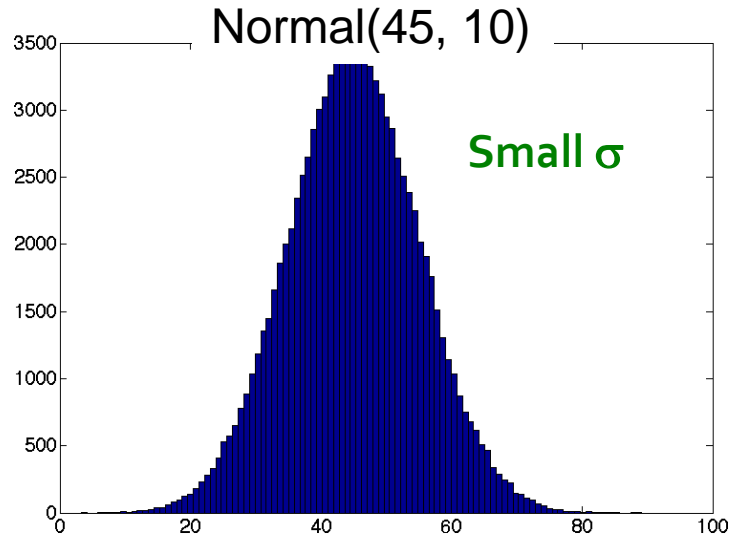
**Large  $\sigma$ :**

Normal(45, 27)



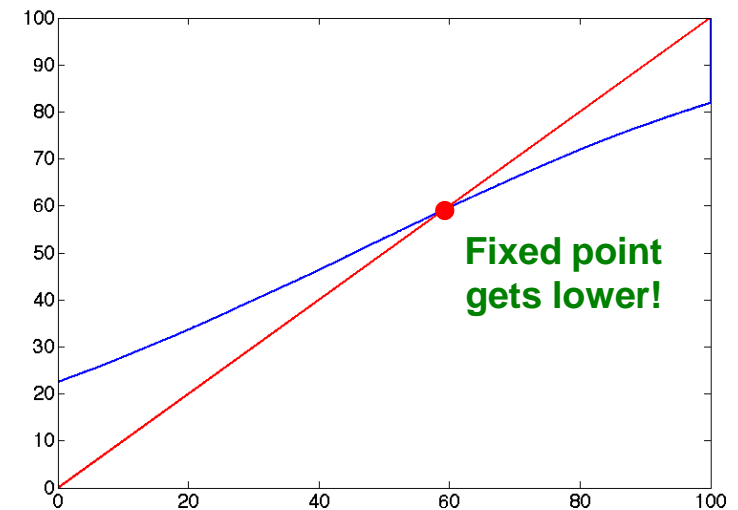
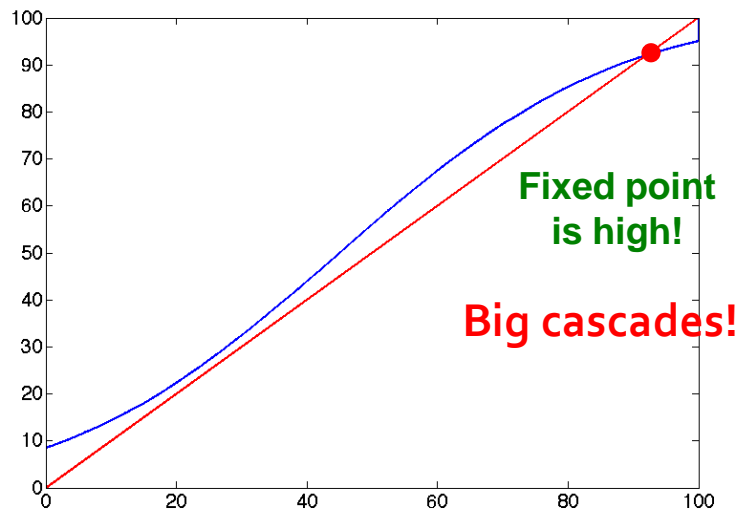
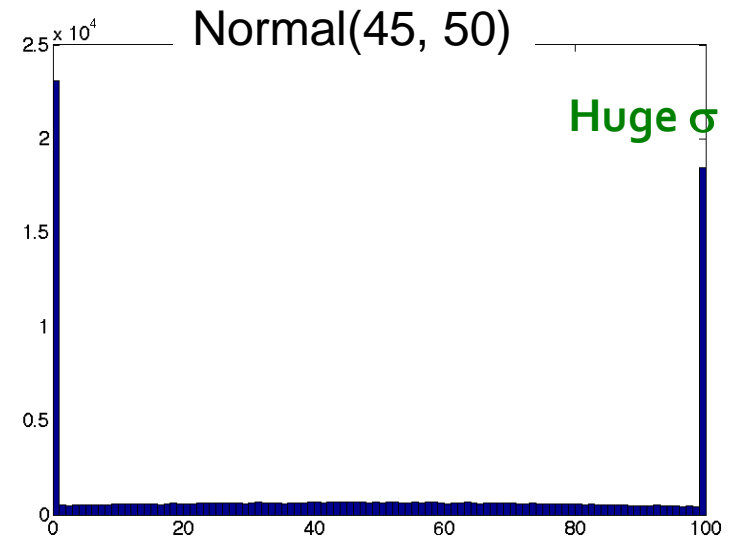
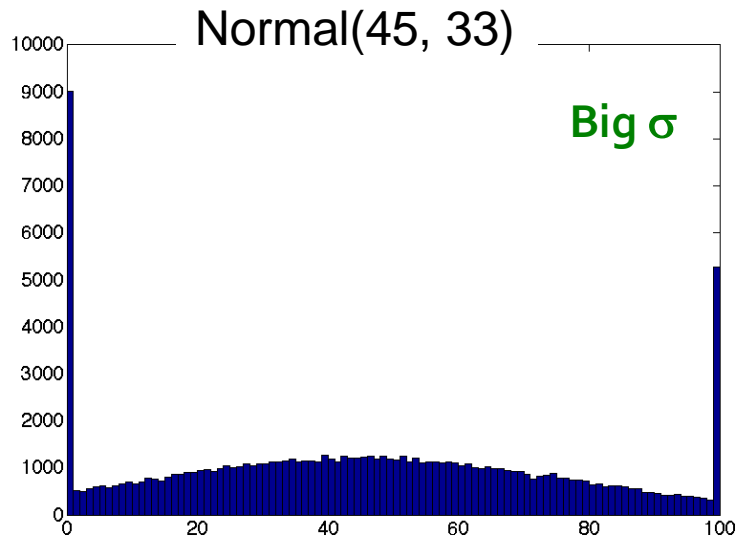


# Discontinuous Transition



**Bigger variance let's you build a bridge from early adopters to mainstream**

# Discontinuous Transition

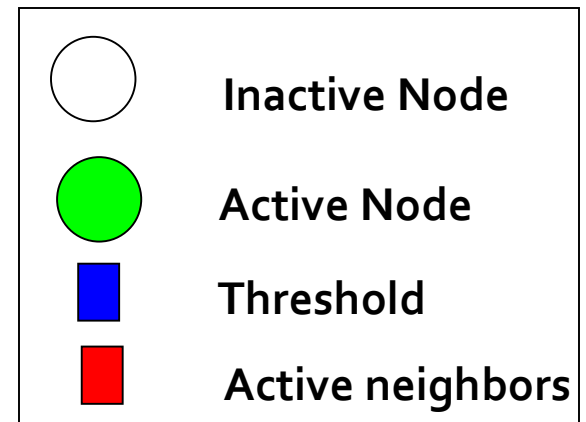
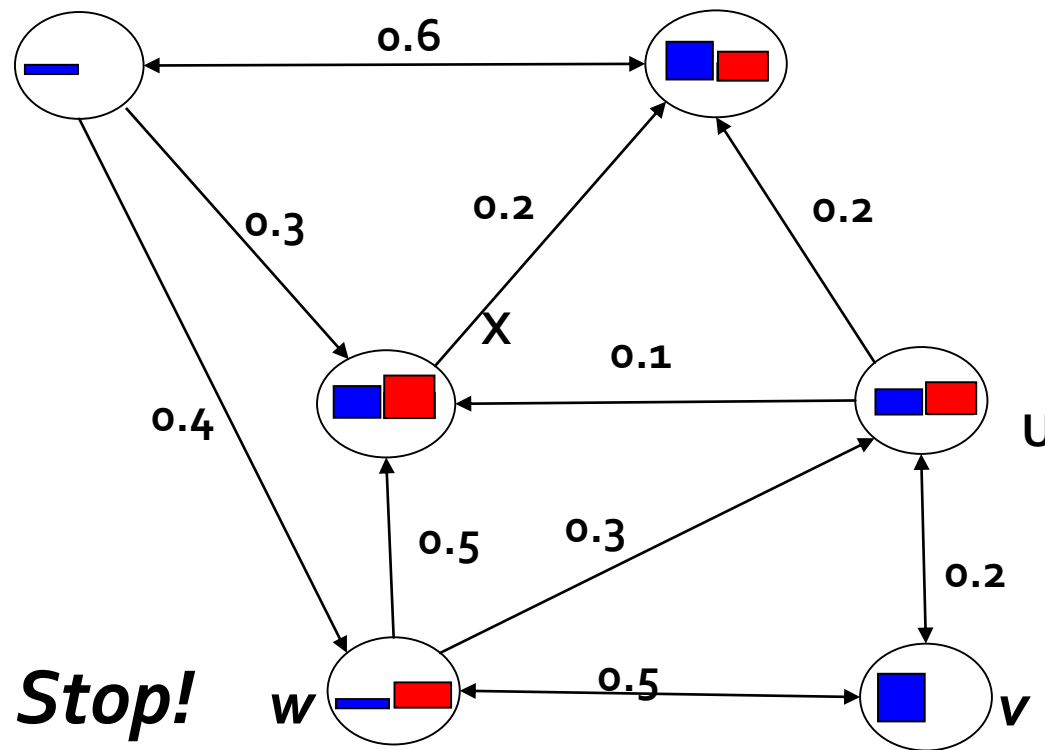


But if we increase the variance the fixed point starts going down

# Weaknesses of the Model

- **No notion of social network:**
  - Some people are more influential
  - It matters who the early adopters are, not just how many
- **Models people's awareness** of size of participation  
**not just actual number of people participating**
  - Modeling perceptions of who is adopting the behavior vs. who you believe is adopting
  - Non-monotone behavior – dropping out if too many people adopt
  - People get “locked in” to certain choice over a period of time
- **Modeling thresholds**
  - Richer distributions
  - Deriving thresholds from more basic assumptions
    - game theoretic models

# Linear Threshold Model



Thresholds:

$$\vartheta_v \sim U[0,1]$$

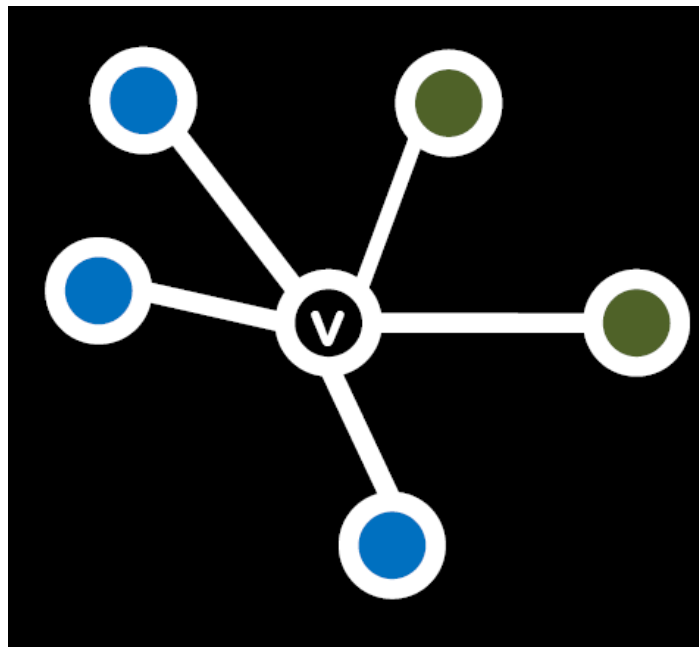
Influenced when:

$$\sum_{w \text{ active neighbor of } v} b_{v,w} \geq \theta_v$$

# Decision Based Model of Diffusion

# Game Theoretic Model of Cascades

- **Based on 2 player coordination game**
  - 2 players – each chooses technology A or B
  - Each person can only adopt **one** “behavior”, **A or B**
  - You gain more payoff if your friend has adopted the **same** behavior as you



Local view of the  
network of node  $v$



# Example: VHS vs. BetaMax



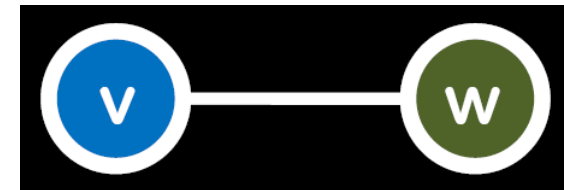
# Example: BlueRay vs. HD DVD



# The Model for Two Nodes

- **Payoff matrix:**

- If both **v** and **w** adopt behavior **A**, they each get payoff  **$a > 0$**
- If **v** and **w** adopt behavior **B**, they each get payoff  **$b > 0$**
- If **v** and **w** adopt the opposite behaviors, they each get **0**

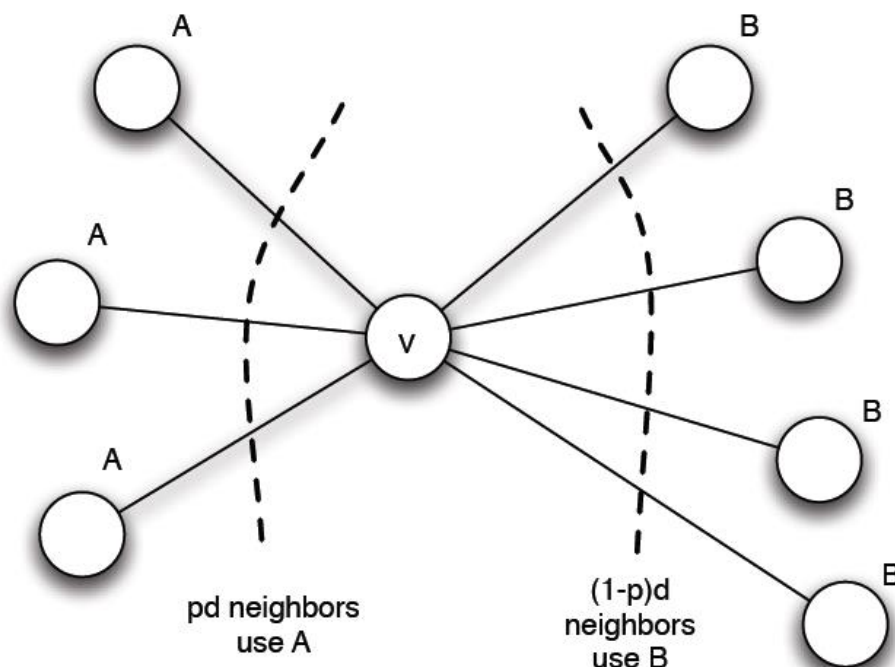


- **In some large network:**

- Each node **v** is playing a copy of the game with each of its neighbors
- **Payoff:** sum of node payoffs per game

|   |   | w    |      |
|---|---|------|------|
|   |   | A    | B    |
| v | A | a, a | 0, 0 |
|   | B | 0, 0 | b, b |

# Calculation of Node $v$



**Threshold:**

$v$  chooses **A** if

$$p > \frac{b}{a+b} = q$$

$p$ ... frac.  $v$ 's nbrs. with A  
 $q$ ... payoff threshold

- Let  $v$  have  $d$  neighbors
- Assume fraction  $p$  of  $v$ 's neighbors adopt **A**
  - $Payoff_v = a \cdot p \cdot d$  , if  $v$  chooses A
  - $= b \cdot (1-p) \cdot d$  , if  $v$  chooses B
- **Thus:  $v$  chooses A if:  $a \cdot p \cdot d > b \cdot (1-p) \cdot d$**

# Example Scenario

- Scenario:

Graph where everyone starts with **B**

Small set **S** of early adopters of **A**

- Hard-wire **S** – they keep using **A** no matter what payoffs tell them to do

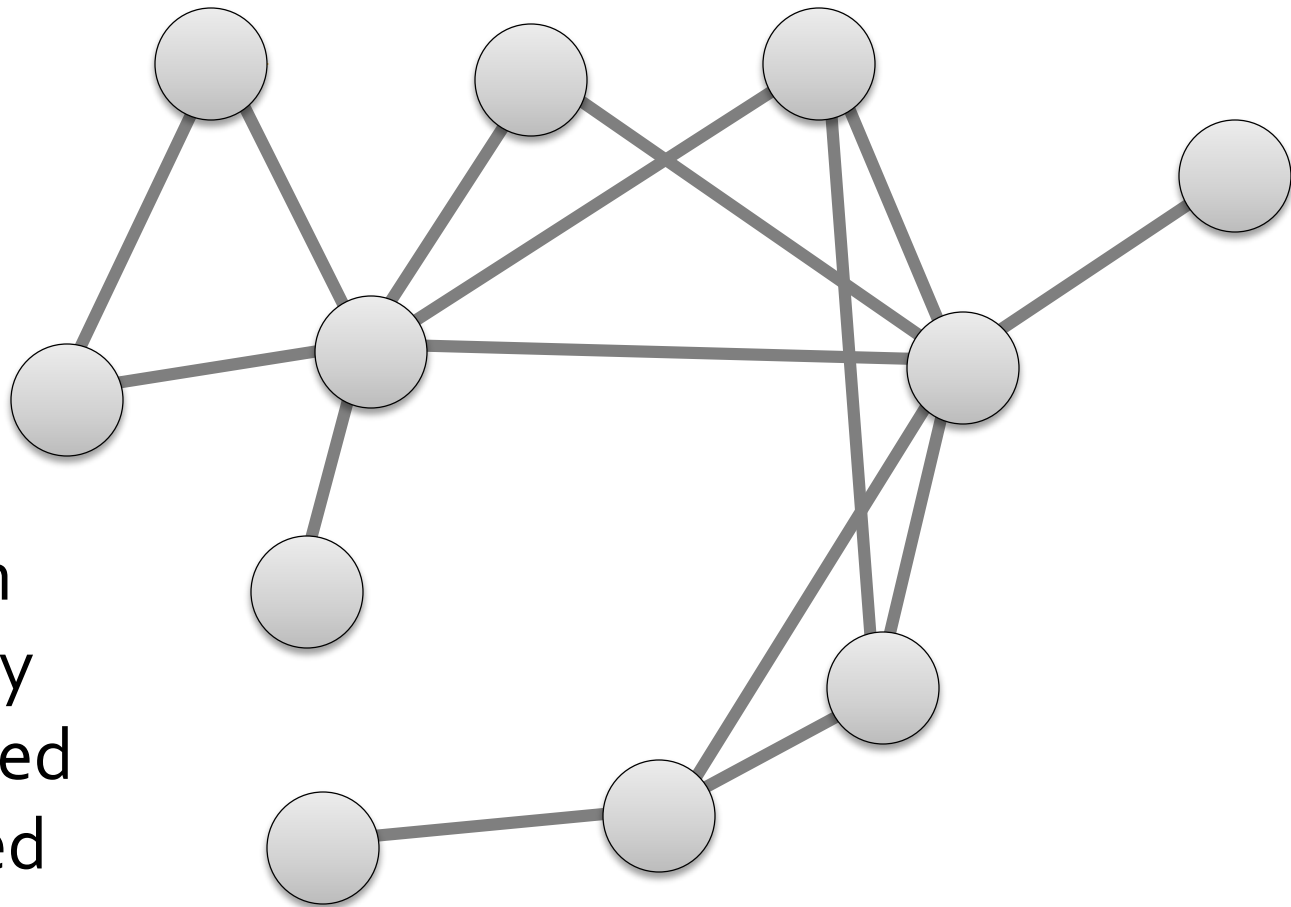
- Assume payoffs are set in such a way that nodes say:

If **more than** 50% of my friends take **A**  
I'll also take **A**

(this means:  $a = b - \epsilon$  and  $q > 1/2$ )

# Example Scenario

$$S = \{u, v\}$$

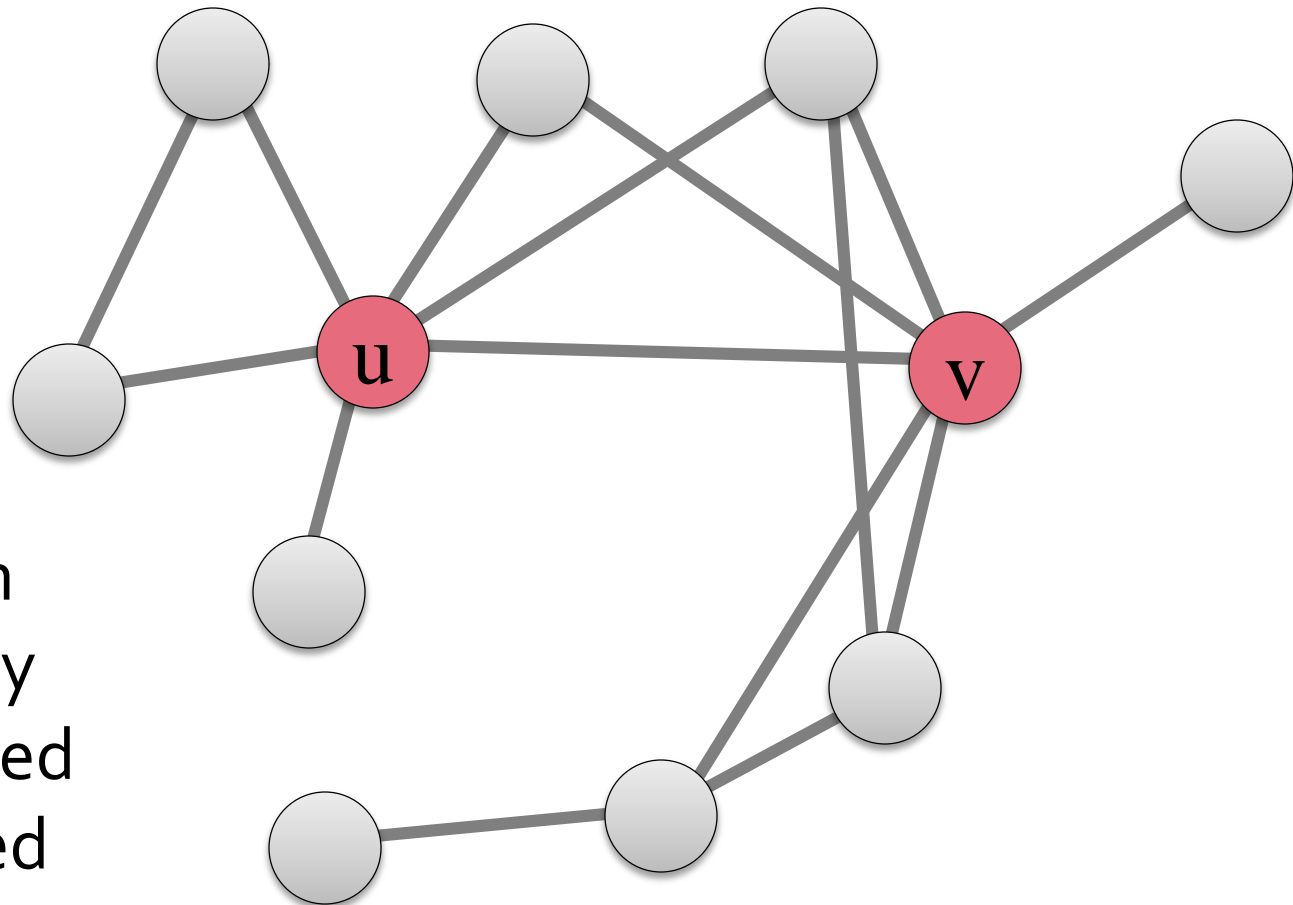


If **more** than  
 $q=50\%$  of my  
friends are red  
I'll also be red



# Example Scenario

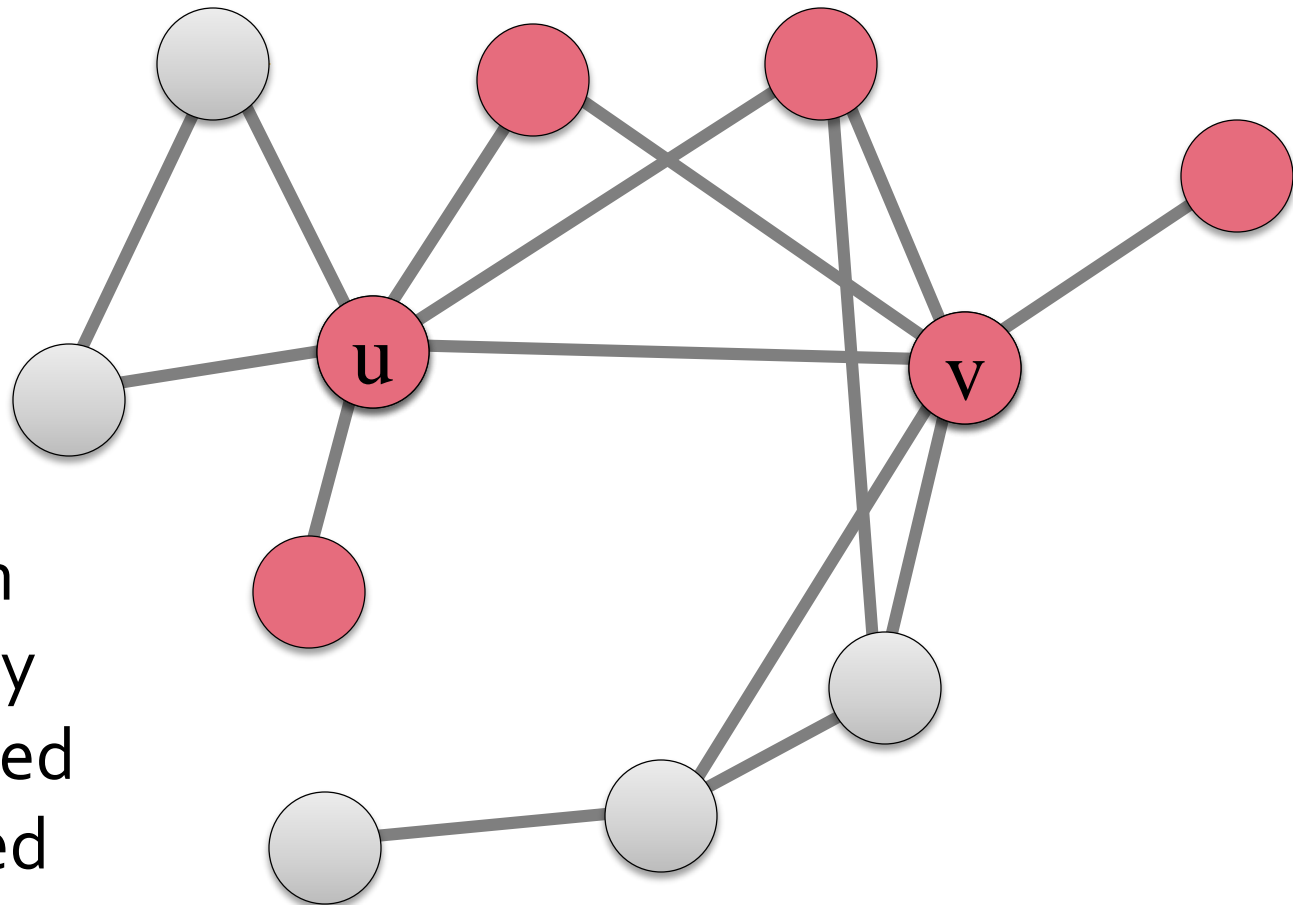
$$S = \{u, v\}$$



If **more** than  
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# Example Scenario

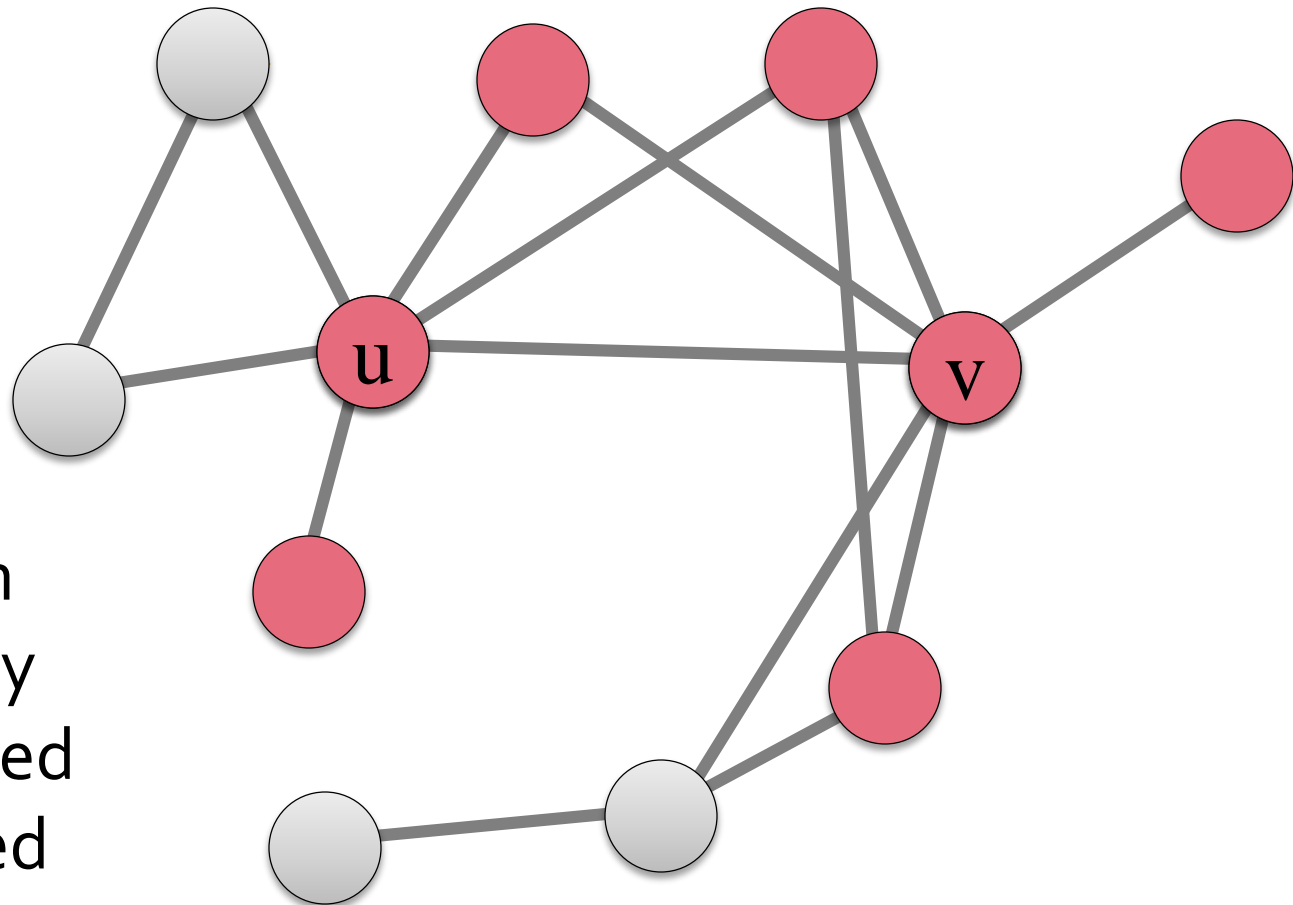
$$S = \{u, v\}$$



If **more** than  
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# Example Scenario

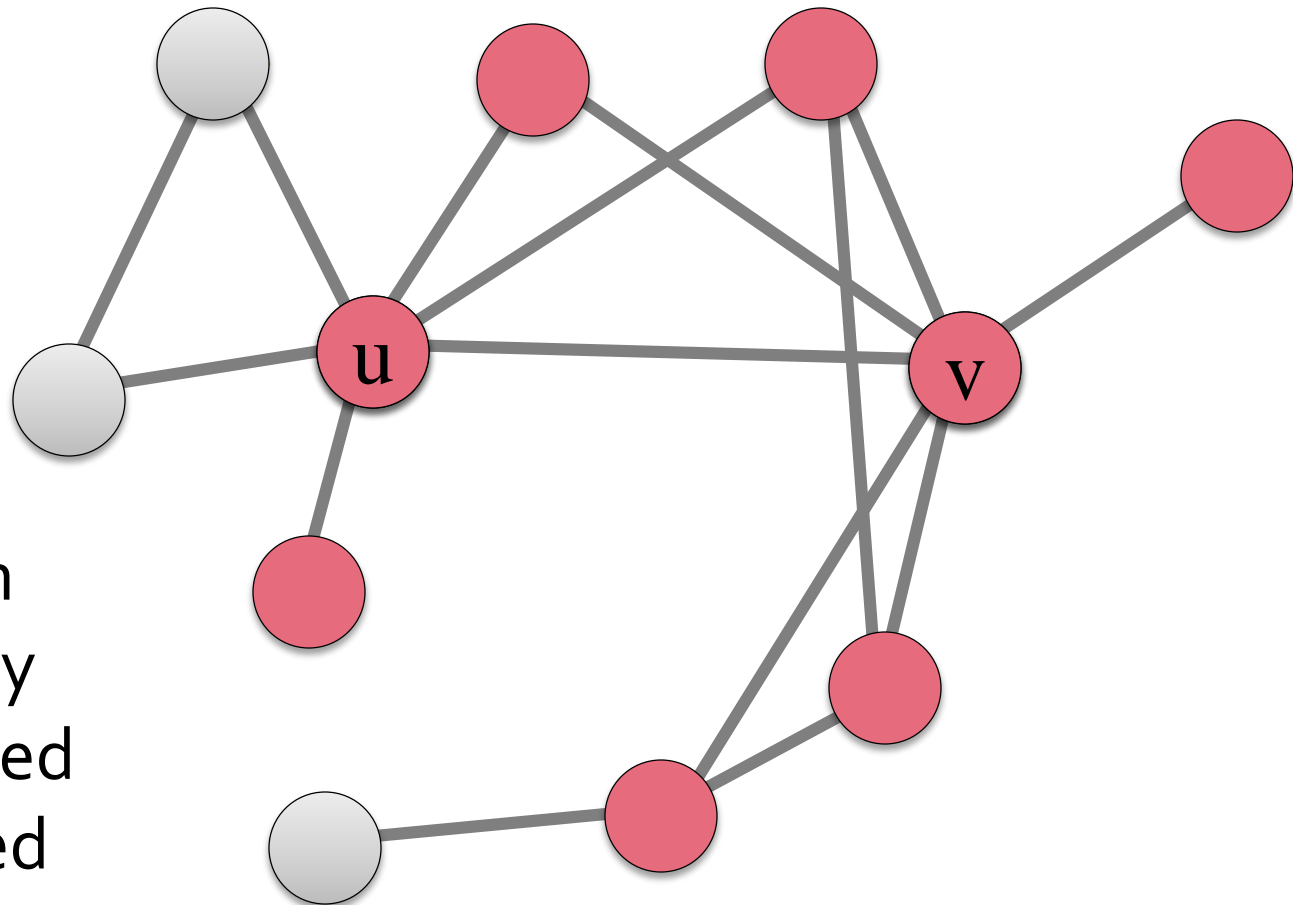
$$S = \{u, v\}$$



If **more** than  
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I'll also be red

# Example Scenario

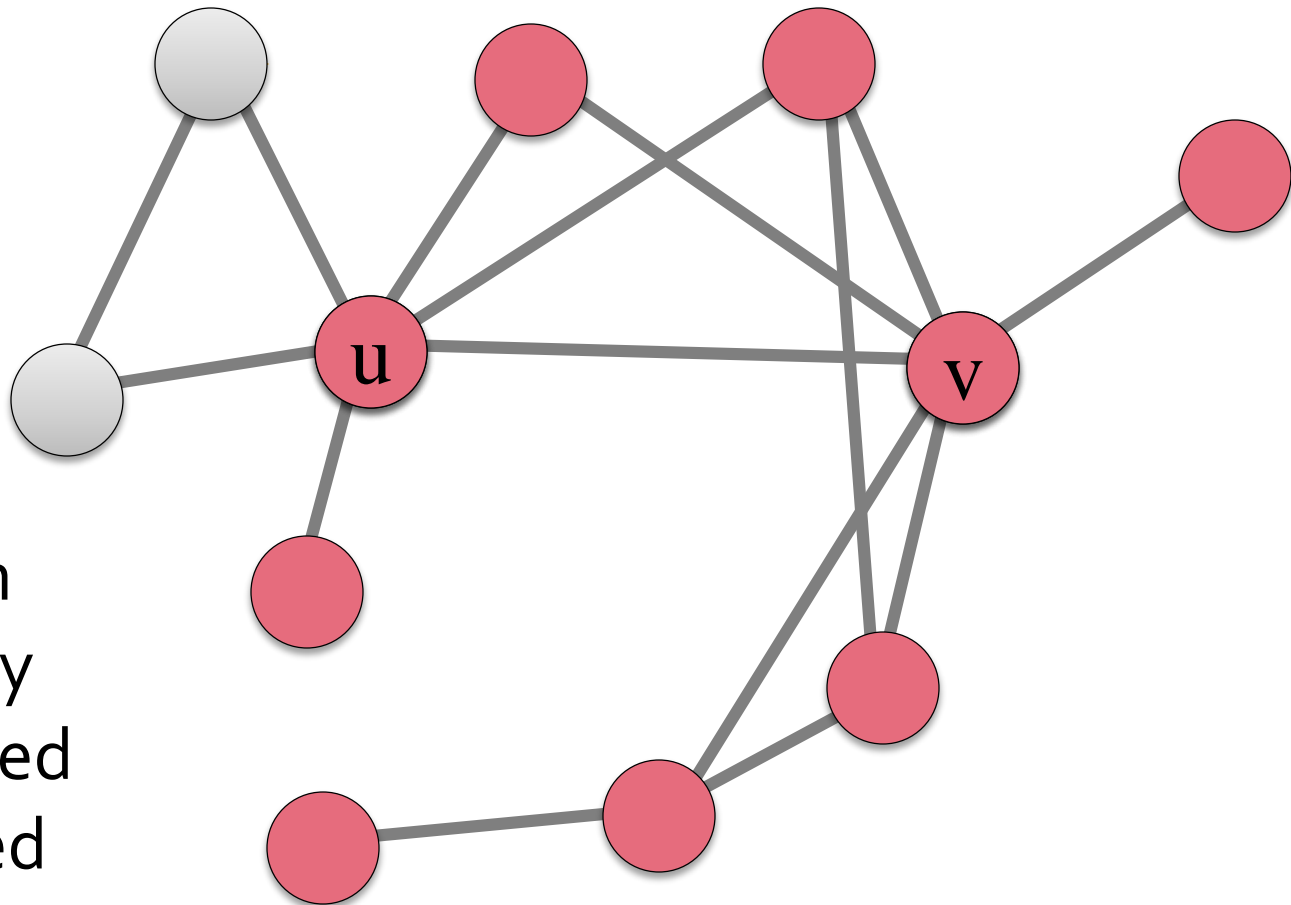
$$S = \{u, v\}$$



If **more** than  
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# Example Scenario

$$S = \{u, v\}$$



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# Infinite Graphs

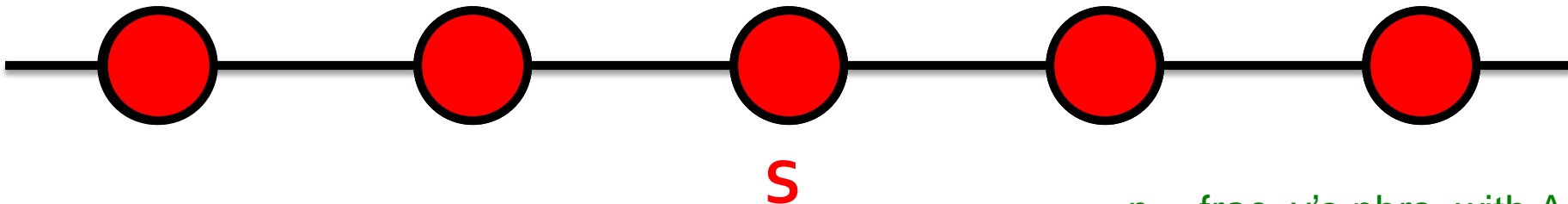
- Consider infinite graph  $G$

- (but each node has finite number of neighbors!)

- We say that a finite set  $S$  causes a cascade in  $G$  with threshold  $q$  if, when  $S$  adopts  $A$ , eventually **every node in  $G$  adopts  $A$**

- Example: **Path**

If  $q < 1/2$  then cascade occurs



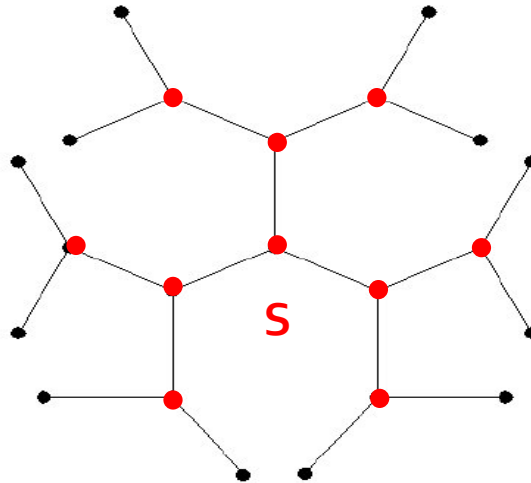
$v$  chooses  $A$  if  $p > q$

$$q = \frac{b}{a+b}$$

$p$ ... frac.  $v$ 's nbrs. with  $A$   
 $q$ ... payoff threshold

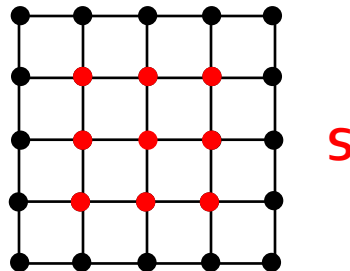
# Infinite Graphs

## ■ Infinite Tree:



If  $q < 1/3$  then  
cascade occurs

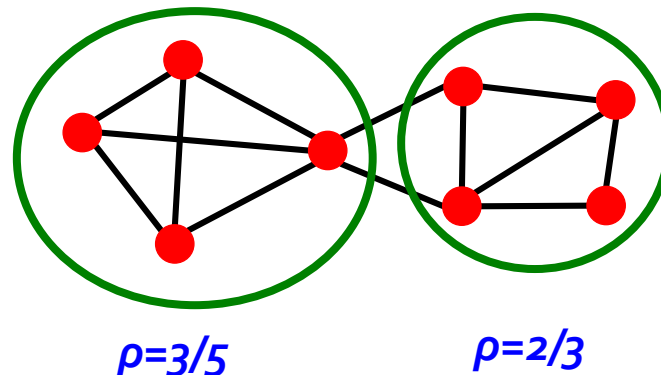
## ■ Infinite Grid:



If  $q < 1/4$  then  
cascade occurs

# Stopping Cascades

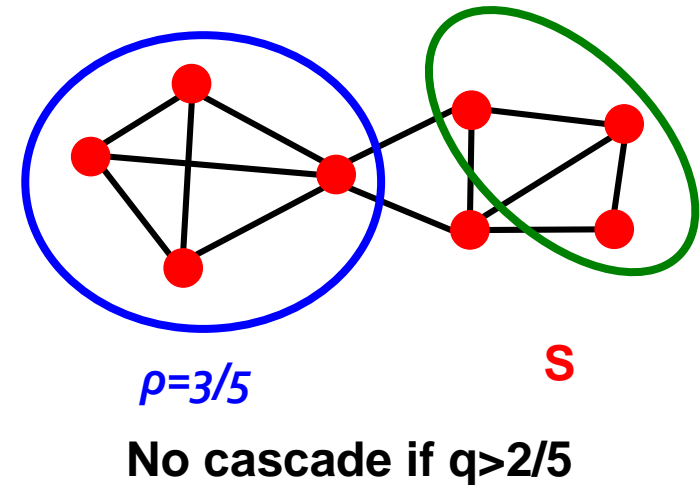
- What prevents cascades from spreading?
- Def: **Cluster of density  $\rho$**  is a **set of nodes  $C$**  where each node in the set has at least  $\rho$  fraction of edges in  $C$





# Stopping Cascades

- Let  $S$  be an initial set of adopters of  $A$
- All nodes apply threshold  $q$  to decide whether to switch to  $A$
- **Two facts:**
  - 1) If  $G \setminus S$  contains a cluster of density  $>(1-q)$  then  $S$  can not cause a cascade
  - 2) If  $S$  fails to create a cascade, then there is a cluster of density  $>(1-q)$  in  $G \setminus S$



**Extending the Model:  
Allow People to Adopt A and B**

# Cascades & Compatibility

## ■ So far:

- Behaviors **A** and **B** compete
- Can only get utility from neighbors of same behavior: **A-A** get **a**, **B-B** get **b**, **A-B** get **0**

## ■ Let an extra strategy “**AB**”

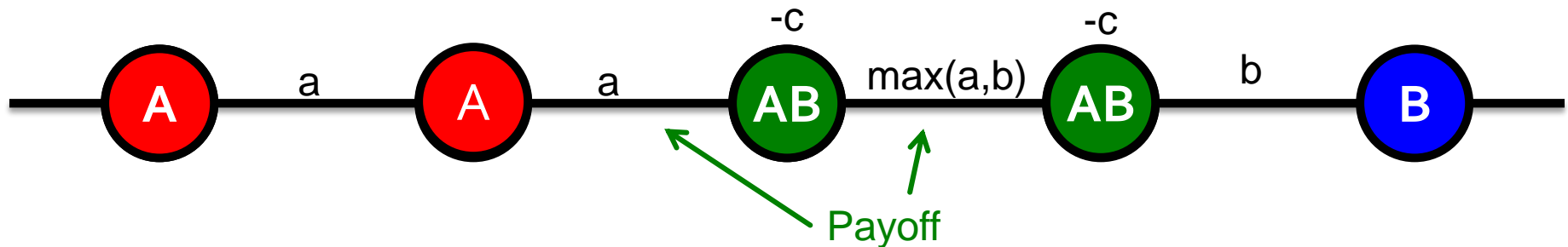
- **AB-A** : gets **a**
- **AB-B** : gets **b**
- **AB-AB** : gets **max(a, b)**
- **Also:** Some **cost c** for the effort of maintaining both strategies (summed over all interactions)

|   |    | w    |     |                    |
|---|----|------|-----|--------------------|
|   |    | A    | B   | AB                 |
| v | A  | a, a | 0,0 | a, a               |
|   | B  | 0,0  | b,b | b,b                |
|   | AB | a, a | b,b | max(a,b), max(a,b) |

- Note: a given node can receive **a** from one neighbor and **b** from another by playing **AB**, which is why it could be worth the cost **c**

# Cascades & Compatibility: Model

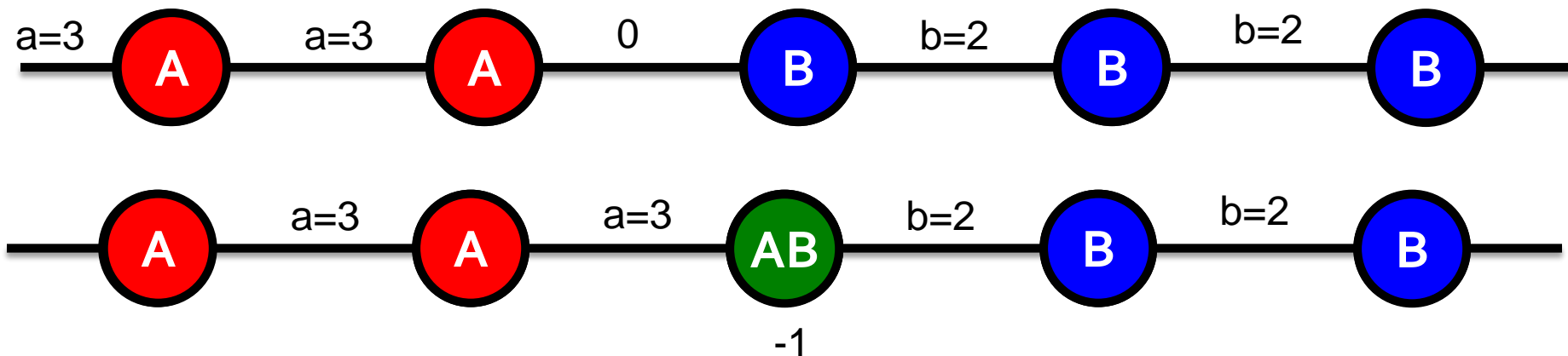
- Every node in an infinite network starts with **B**
- Then a finite set **S** initially adopts **A**
- Run the model for  $t=1,2,3,\dots$ 
  - Each node selects behavior that will optimize payoff (given what its neighbors did in at time  $t-1$ )



- How will nodes switch from **B** to **A** or **AB**?

# Example: Path Graph (1)

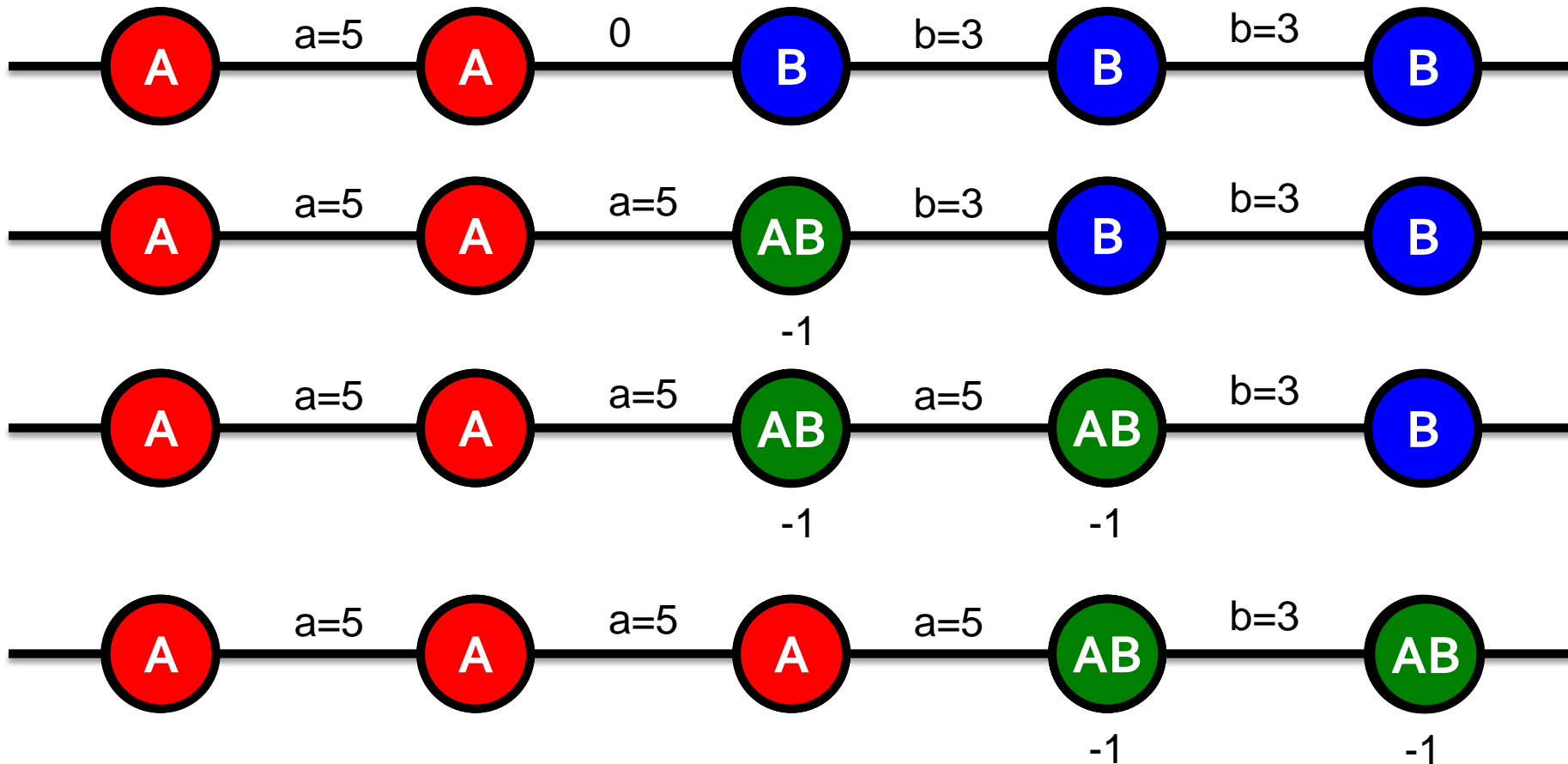
- **Path graph:** Start with all **B**s,  $a > b$  (**A** is better)
- **One node switches to A – what happens?**
  - With just **A**, **B**: **A** spreads if  $a > b$
  - With **A**, **B**, **AB**: Does **A** spread?
- **Example:  $a=3, b=2, c=1$**



**Cascade stops**

# Example: Path Graph (2)

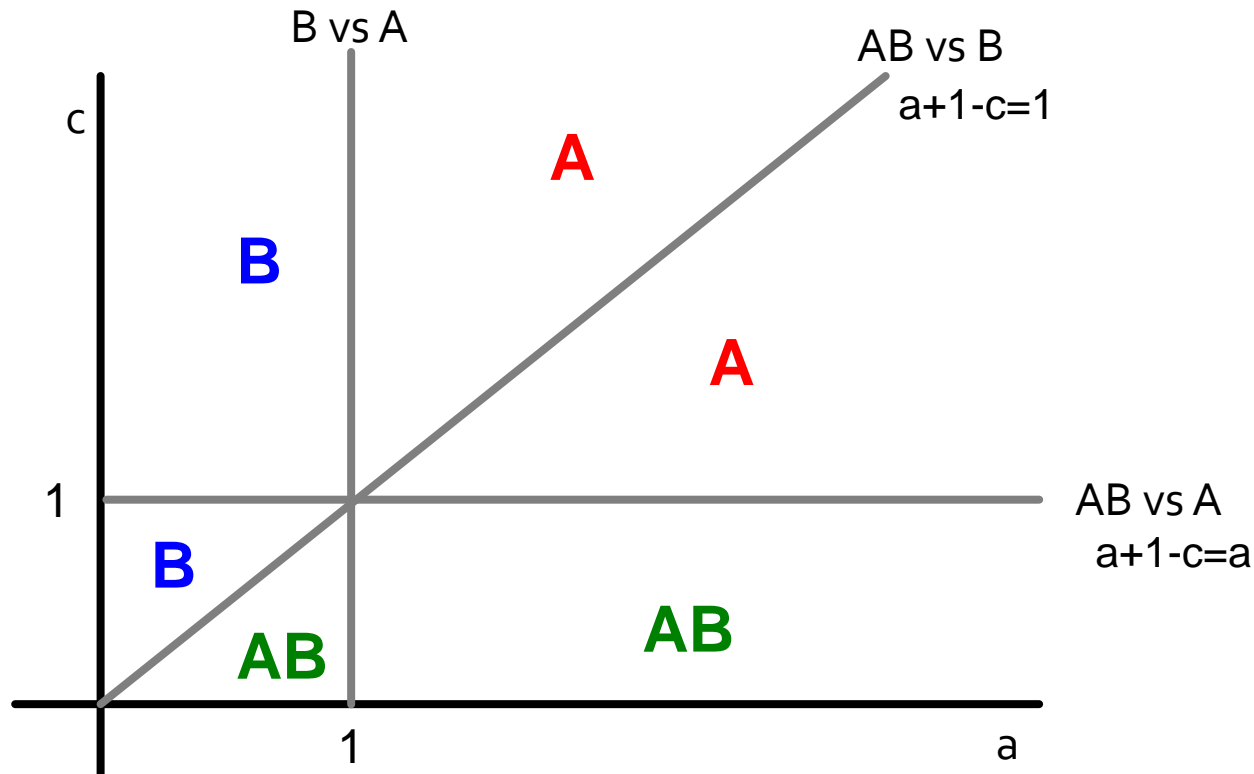
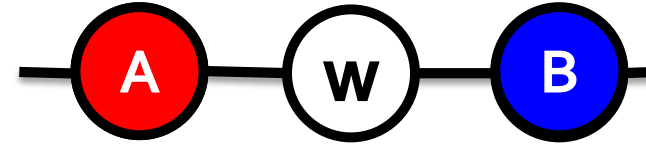
## ■ Example: $a=5$ , $b=3$ , $c=1$



**Cascade never stops!**

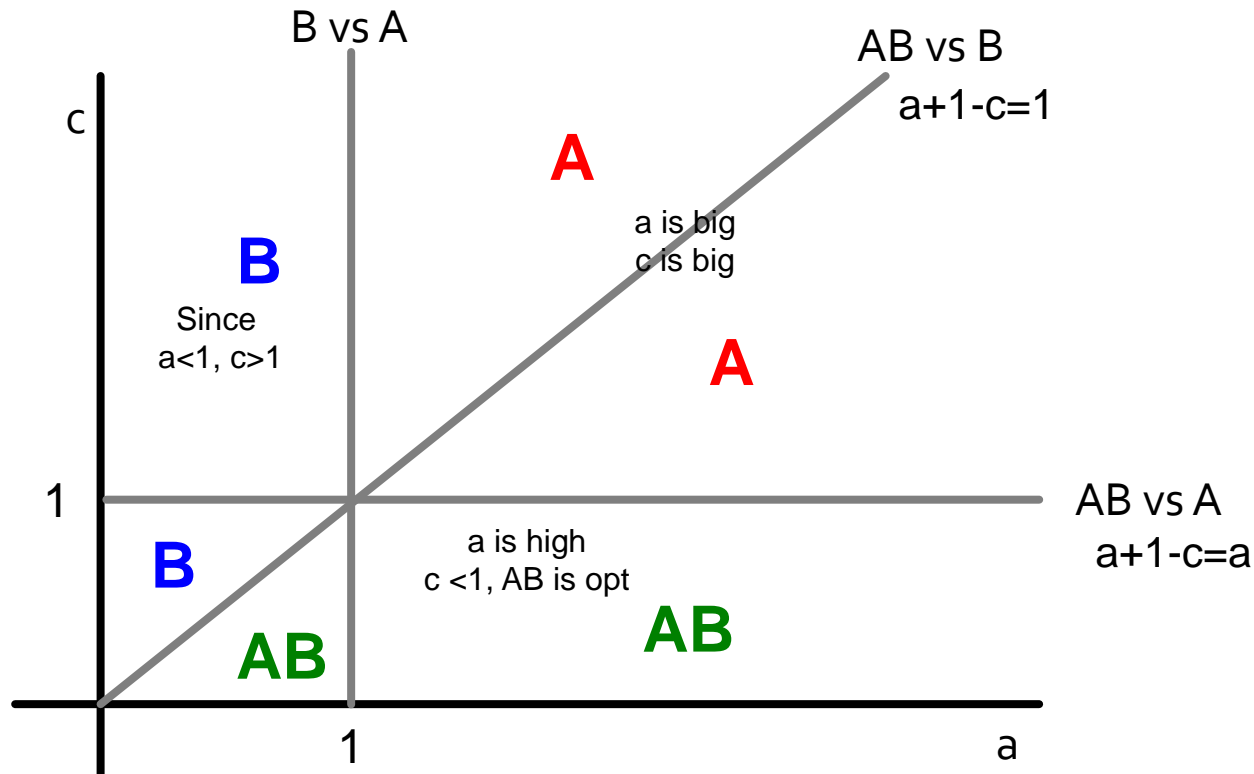
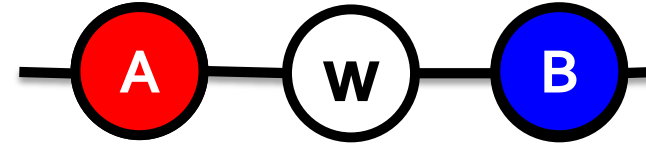
# For what pairs $(c, a)$ does A spread?

- Infinite path, start with all Bs
- **Payoffs for  $w$ :** A: $a$ , B: $1$ , AB: $a+1-c$
- What does node  $w$  in A- $w$ -B do?



# For what pairs $(c,a)$ does A spread?

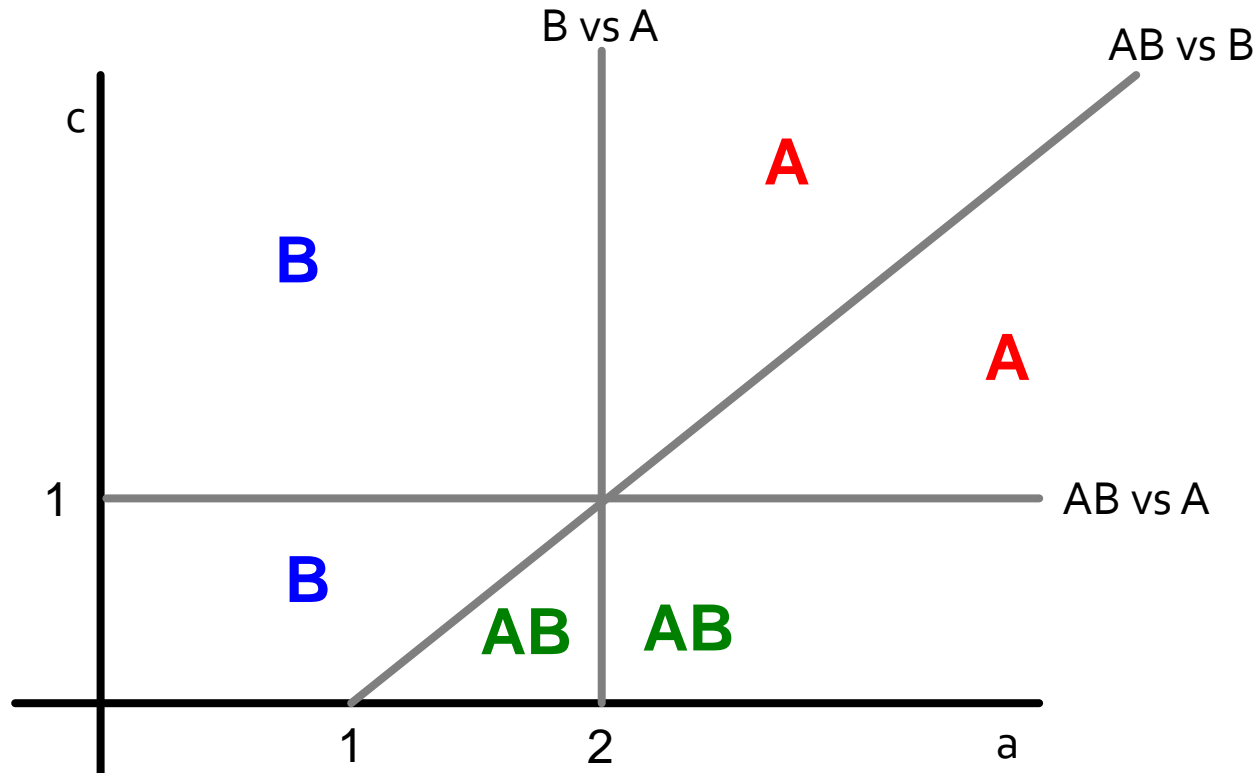
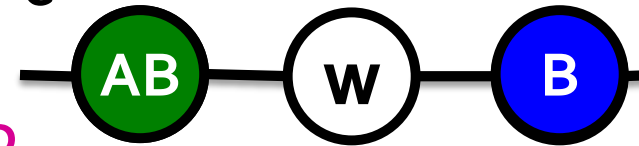
- Infinite path, start with all Bs
- Payoffs for  $w$ : A: $a$ , B: $1$ , AB: $a+1-c$
- What does node  $w$  in A- $w$ -B do?





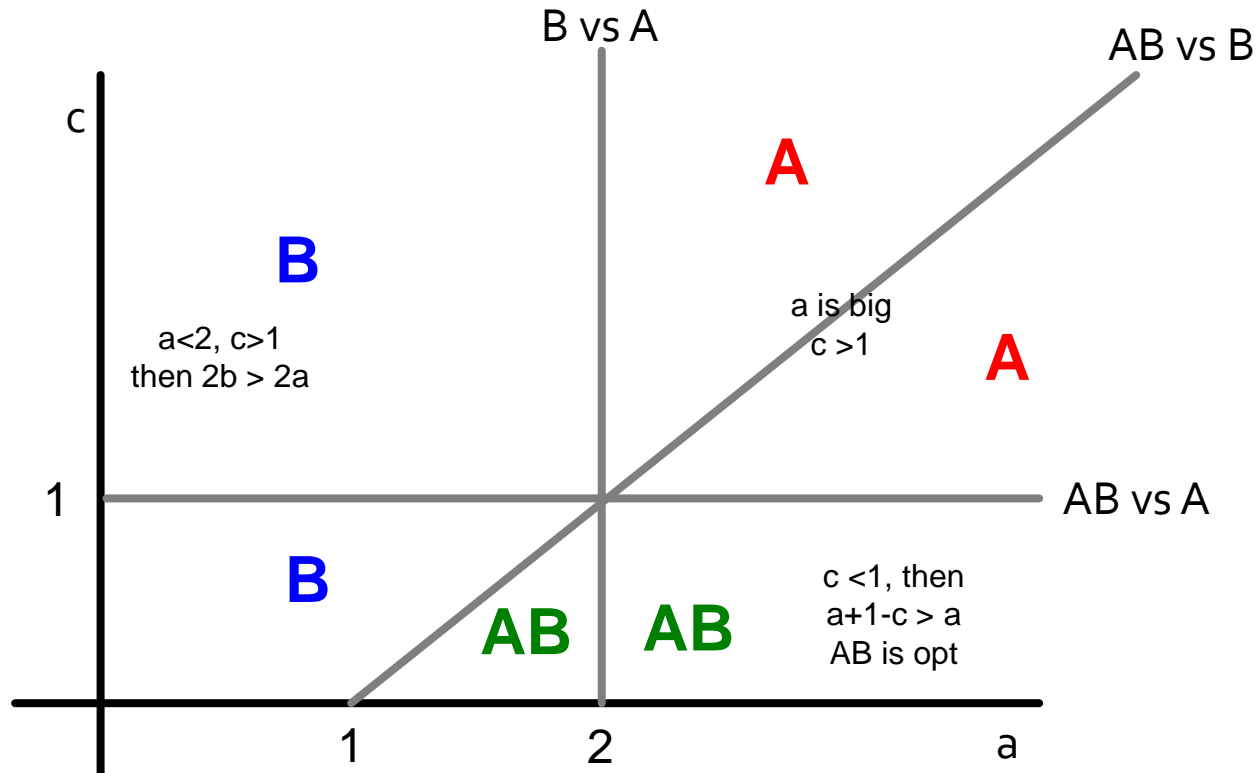
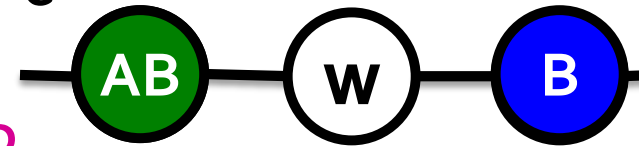
# For what pairs $(c,a)$ does A spread?

- Same reward structure as before but now payoffs for  $w$  change: **A**: $a$ , **B**: $1+1$ , **AB**: $a+1-c$
- Notice: Now also **AB** spreads
- What does node  $w$  in **AB-w-B** do?



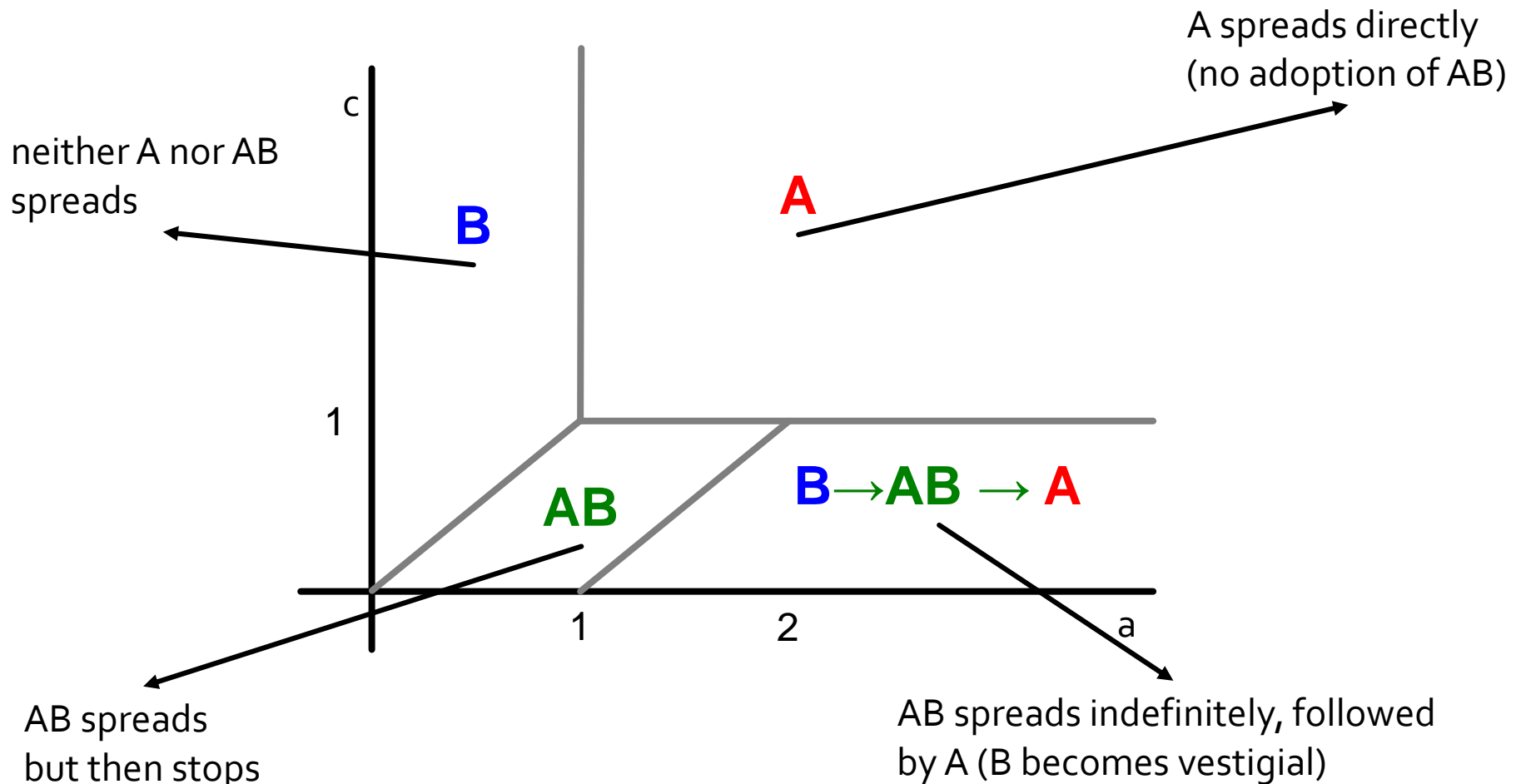
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# For what pairs $(c,a)$ does $A$ spread?

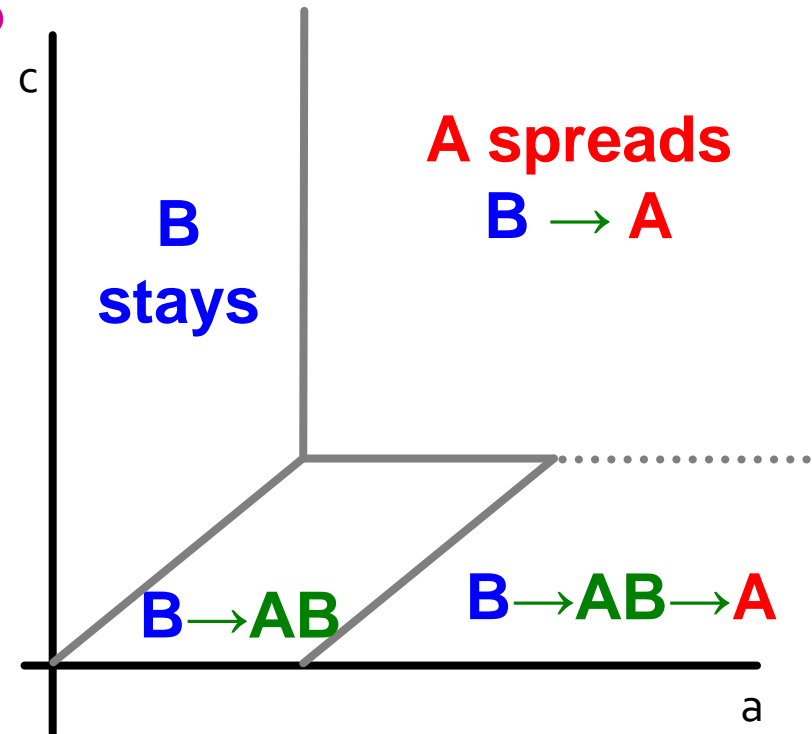
## ■ Joining the two pictures:



# Lesson

- **B** is the default throughout the network until new/better **A** comes along. What happens?

- **Infiltration:** If **B** is **too compatible** then people will take on both and then drop the worse one (**B**)
- **Direct conquest:** If **A** makes itself **not compatible** – people on the border must choose. They pick the better one (**A**)
- **Buffer zone:** If you choose an optimal level then you keep a static “buffer” between **A** and **B**



# Models of Cascading Behavior

## ■ So far:

### Decision Based Models

- Utility based
- Deterministic
- “Node” centric: A node observes decisions of its neighbors and makes its own decision
- Require us to know too much about the data

## ■ Next: Probabilistic Models

- Let's you do things by observing data
- We lose “why people do things”

