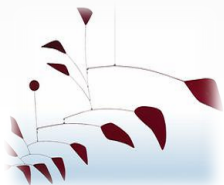


# EECS 4101-5101

## Advanced Data Structures

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**Shahin Kamali**

Topic 1c - Competitive Analysis

CLRS 17-1, 17-2, 17-3, 17-4

York University

Picture is from the cover of the textbook CLRS.



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## Offline vs. Online Algorithms

- Traditional algorithms are 'offline' in the sense that they have the whole input in their hand.
- Online algorithms, in contrast, do not have/need the whole input in order to solve a problem
  - The input is a 'sequence' which is processed by the online algorithm **piece-by-piece**
  - The online algorithms often take **irrevocable decisions** to process the input.



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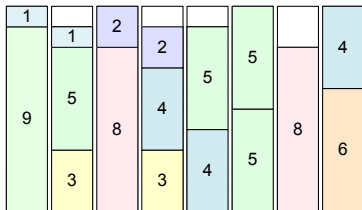
## Bin Packing Problem

- The input is a set/sequence of items of various sizes
  - E.g.,  $\langle 9, 3, 8, 5, 1, 1, 3, 2, 4, 2, 4, 5, 5, 8, 6, 4, 5, \dots \rangle$ .



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  - E.g.,  $\langle 9, 3, 8, 5, 1, 1, 3, 2, 4, 2, 4, 5, 5, 8, 6, 4, 5, \dots \rangle$ .
- The goal is to pack these items into a minimum number of bins of uniform capacity.





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## Bin Packing Problem (cntd.)

- In the online setting:
  - an algorithm receives items one by one
  - when it receives an item, it has to place it in a bin without any knowledge about forthcoming items
  - decisions of the algorithms are irrevocable (i.e., cannot move items between bins)



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## First Fit (FF) Algorithm

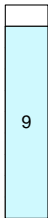
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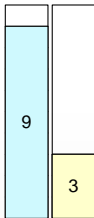




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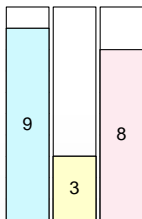




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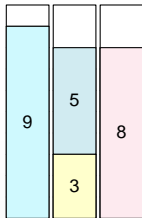




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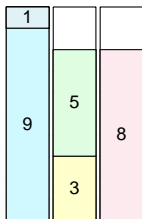




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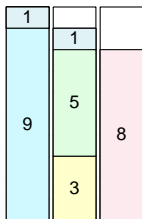




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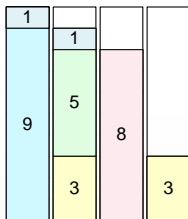




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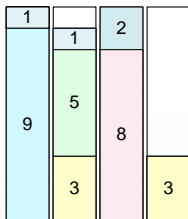




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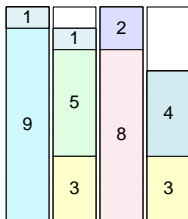




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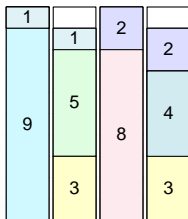




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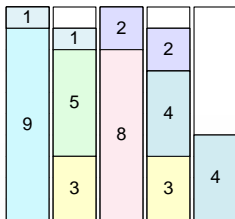




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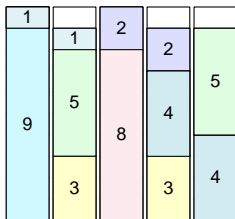




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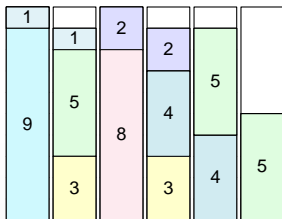




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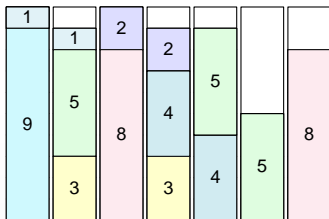




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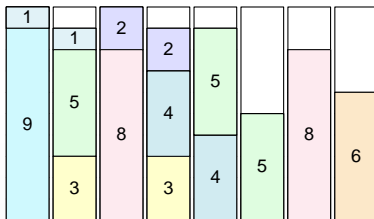




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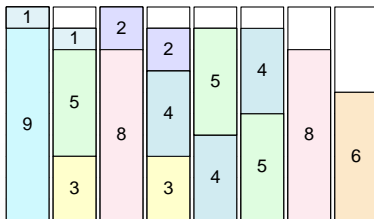




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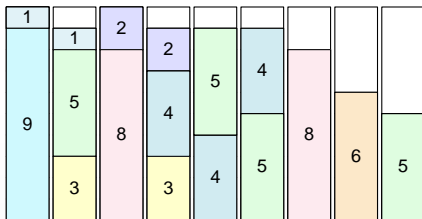




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- Let  $\text{Opt}$  denote the best possible offline solution.
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  - Given a sequence  $\sigma$ ,  $\text{Opt}$  is an algorithm which packs items in  $\sigma$  in a minimum number of bins
- Competitive ratio of an algorithm  $A$  is the maximum ratio between the cost of  $A$  and that of  $\text{Opt}$  over all sequences

$$cr(A) \equiv \max_{\sigma} \frac{cost_A(\sigma)}{cost_{\text{Opt}}(\sigma)}$$



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- No algorithm can be better than 1.54037-competitive (best general lower bound) [Balogh et al. 2015].



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- What is the competitive ratio of an algorithm that always rent?
  - In the worst-case, we go skiing  $n$  days for large  $n$
  - The competitive ratio is  $\frac{n}{b}$ , which can be arbitrary large (very bad).



## Ski-rental problem (cntd.)

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- What is the competitive ratio of Break-even algorithm?
- It is  $\frac{(b-1)+b}{b} \approx 2$

### *Theorem*

*Competitive ratio is roughly 2, and it is the best for any **deterministic** online algorithm.*



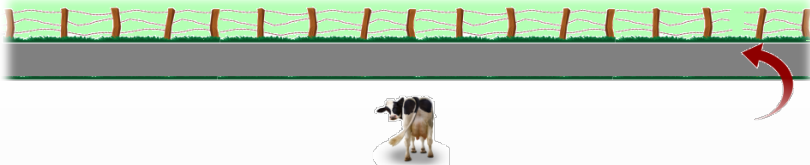


# Cow-Path Problem



## Problem Definition

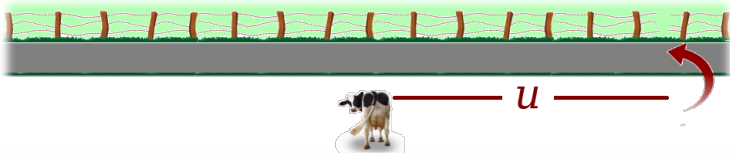
- A cow faces a fence, infinite in both directions
- She wants to find a hole in order to get to the green pasture on the other side
- The cow's **online strategy** specifies the path traveled in search of the hole.
- The goal is to minimize the distance traveled.





## Offline Strategy

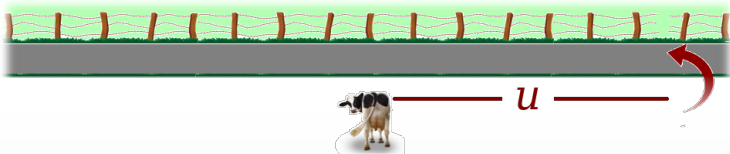
- Let  $u$  an integer indicating the distance between the initial location of the cow and the location of the hole.
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## Offline Strategy

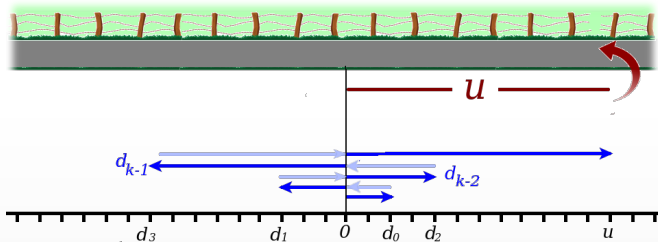
- Let  $u$  an integer indicating the distance between the initial location of the cow and the location of the hole.
  - $u$  is unknown to the cow!
- An optimal offline algorithm  $Opt$  (i.e., a cow which knows the location of the hole), incurs a cost of  $u$





## Smart-Cow Algorithm (SCA)

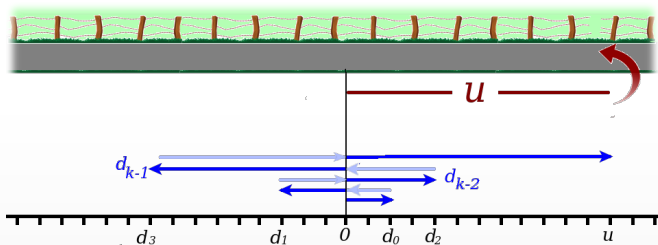
- Gradually extend the explored interval of the fence
- Alternate between left and right!
  - Go right for distance  $d_0$
  - Go back to the origin, left for distance  $d_1$
  - Go back to the origin, right for distance  $d_2$
  - Continue accordingly for  $d_3, \dots, d_k$  until the hole is found.





## Competitive Ratio of SCA

- Recall that the competitive ratio of an online algorithm is the maximum ratio between the cost of that algorithm and an optimal offline Opt algorithm Opt
- The cost of Opt is  $u$
- The cost of SCA is  $2d_0 + 2d_1 + \dots + 2d_{k-2} + 2d_{k-1} + u$ 
  - $d_{k-2} < u \leq d_k$



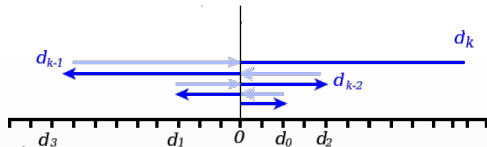


## Competitive Ratio of SCA (cntd.)

- The competitive ratio would be

$$\frac{2d_0 + 2d_1 + \dots + 2d_{k-2} + 2d_{k-1} + u}{u} = 1 + 2\frac{d_0 + d_1 + \dots + d_{k-1}}{u}$$

- what is the value of  $u$  in the worst case?
  - If you are an **adversary** and want to fail the algorithm, where you place the hole?





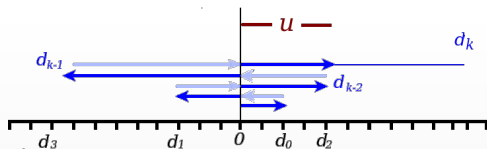
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- In the worst case,  $u = d_{k-2} + \epsilon$ .
  - Just a bit more than the previous probe!
- So, the competitive ratio of a Smart-Cow algorithm is

$$1 + 2\frac{d_0 + d_1 + \dots + d_{k-1}}{d_{k-2} + \epsilon}$$



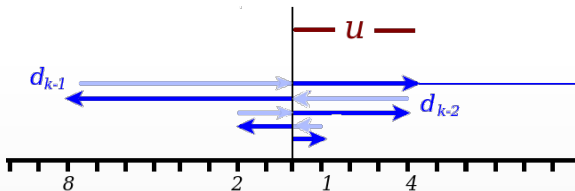




## The Doubling Technique

- Assume  $d_i = 2^i$ , i.e., first go one unit to the right, go back to the origin, go two units to the left, back to origin, four units to the right, etc.
  - We will have
$$d_0 + d_1 + \dots + d_{k-1} = 1 + 2 + 4 + \dots + 2^{k-1} = 2^k - 1 = 4 \cdot 2^{k-2}.$$
  - The competitive ratio would be

$$1 + 2 \frac{d_0 + d_1 + \dots + d_{k-1}}{d_{k-2} + \epsilon} = 1 + 2 \frac{4 \cdot 2^{k-2}}{2^{k-2} + \epsilon} \approx 9$$





## Overview

### *Theorem*

*The smart-cow algorithm with steps that double (i.e.,  $d_i = 2^i$ ) has a competitive ratio of at most 9.*



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- It turns out that no **deterministic** algorithm can achieve a ratio better than 9.
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- So, the doubling technique results an optimal algorithm in this case



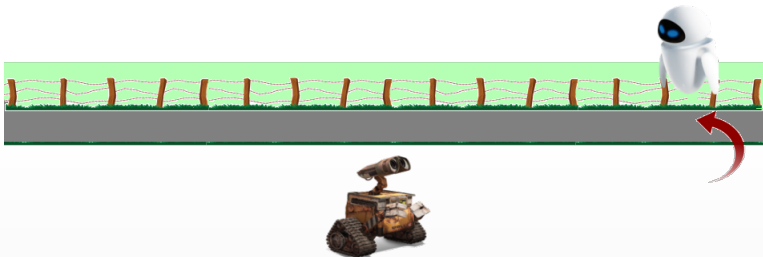
## Semi-online Problem

- We assumed the value of  $u$  is unknown to the algorithm.
- **Question:** what competitive an “almost-online” algorithm can achieve when the value of  $u$  is known?
  - The algorithm knows  $u$  but does not know the side (left or right) where the target is located.



## Search Problems under Uncertainty

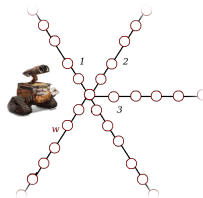
- A cow can be a robot (or the other way around)!
- In practice, robots often do not have full information about their environment.
- Cow-path problem and its variant are a way to model many types of **search problems**.





## Variants of Search Problems

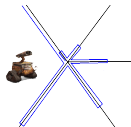
- Path-cow problem is an online search problem on a **path**.
- Consider a **star**, where  $w$  paths have one common endpoint.
- Assume a robot is initially located at the common point, and needs to find a **target** located in an unknown position.
- What is a good algorithm?





## Variants of Search Problems

- The best strategy is to have  $d_i = (w/(w - 1))^i$ .
  - For  $w = 2$ , it requires doubling.
  - For  $w = 3$ , we jump by a factor of  $3/2$ , and so on.

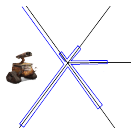






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- The competitive ratio will be at most  $1 + 2 \frac{w^w}{(w-1)^{w-1}} \approx 1 + 2e(w-1)$  (when  $w$  is sufficiently large).
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  - $e \approx 2.71$  is the Euler's constant
- Note that doubling is not optimal here.
  - But it is still **competitive**, i.e., it has a constant competitive ratio.

