

# CSE 3101 Design and Analysis of Algorithms

## Solutions for Practice Test for Unit 4

### Greedy Algorithms

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#### 1. Integer-Knapsack Problem:

**Instances:** An instance consists of  $\langle V, \langle v_1, p_1 \rangle, \dots, \langle v_n, p_n \rangle \rangle$ . Here,  $V$  is the total volume of the knapsack. There are  $n$  objects in a store. The volume of the  $i^{\text{th}}$  object is  $v_i$ , and its price is  $p_i$ .

**Solutions:** A solution is a subset  $S \subseteq [1..n]$  of the objects that fit into the knapsack, i.e.,  $\sum_{i \in S} v_i \leq V$ .

**Measure Of Success:** The cost (or success) of a solution  $S$  is the total value of what is put in the knapsack, i.e.,  $\sum_{i \in S} p_i$ .

**Goal:** Given a set of objects and the size of the knapsack, the goal is fill the knapsack with the greatest possible total price.

Failed Greedy Algorithms: Three obvious greedy algorithms take first the most valuable object,  $\max_i p_i$ , the smallest object,  $\min_i v_i$ , or the object with the highest value per volume,  $\max_i \frac{p_i}{v_i}$ . However, they do not work. For each of this greedy algorithms, give an instance on which it does not work.

- Answer: Consider the counter example  $\langle 8, \langle 5, 5 \rangle, \langle 4, 3 \rangle, \langle 4, 3 \rangle, \langle 1, 0 \rangle \rangle$ . If one takes the highest value or highest density, then one takes the first object. If one takes the smallest volume, then one takes the last object. The only optimal solution contains the middle two objects.

#### 2. We proved that the greedy algorithm does not work for the making change problem when the denominations of the coins are 4, 3, and 1 cent, but it does work when the denominations are 25, 10, 5, and 1. Does it work when the denominations are 25, 10, and 1, with no nickels?

- Answer: The greedy algorithm does not work for the making change problem, when the denominations of the coins are 25, 10, and 1, with no nickels. Suppose the amount is 30. The greedy algorithm will take on quarter and five pennies. However, the optimal has only three dimes.

#### 3. Greedy Algorithms: A man is standing on the bank of a river that he must cross by jumping on stepping stones which are spread in a line across the river. Though he can't jump far, he wants to jump on as few stones as possible. An *instance* to the problem specifies $\langle d_0, d_1, d_2, \dots, d_n \rangle$ , where $d_0 = 0$ is the man's initial location, $d_i$ for $i \in [1, \dots, n-1]$ is a real number giving the distance in meters that the $i^{\text{th}}$ stone is from him, and $d_n$ is the distance to the opposite shore. Assume that the stones are in order, i.e. $0 = d_0 \leq d_1 \leq d_2 \leq \dots \leq d_n$ . Also assume that the stones are not more than one meter apart, i.e. $\forall i \ d_{i+1} - d_i \leq 1$ .

A *solution* is a sequence  $\langle i_0, i_1, i_2, \dots, i_\ell \rangle$  of the indexes of the stones indicating that at time  $t$  the man jumps onto the  $i_t^{\text{th}}$  stone. Such a solution is *valid* if at time  $t = 0$  the man is in fact on the close shore, i.e.  $i_0 = 0$ , he finishes on the far shore, i.e.  $i_\ell = n$ , and at each time step  $t'$  the distance he jumps is at most a distance of one meter, i.e.  $d_{i_{t'}} - d_{i_{t'-1}} \leq 1$ . The *cost* of a solution is the number  $\ell$  of stones jumped onto.

Note that the assumption on the input ensures that a valid solution always exists.

Specify a greedy algorithm for finding an optimal solution for this problem. Imagine that you are crossing a river on stones. How would you choose which stone to jump on next.

As done in the steps, prove that your algorithm always returns an optimal solution.

Warning: To ensure that a solution is valid, you really must check the distance jumped at *each* time step  $t'$ .

- Answer:

**The Greedy Choice:** Each iteration the algorithm grabs the object which according to some simple criteria, seems to be the “best” (or “worst”) from amongst the unconsidered objects in the instance. **Suppose that the current time is  $t - 1$  and the last stone jumped on is the  $i_{t-1}^{th}$  stone. In a greedy way, have the man jump on the stone that is as far from  $i_{t-1}$  as he can jump, i.e. the largest  $i_t$  for which  $d_{i_t} - d_{i_{t-1}} \leq 1$ . This is an adaptive decision, i.e. it does depend on what objects have been seen already.**

You can think of any stone that is before stone  $i_{t-1}$  as having greedy criteria weight  $-\infty$  because we don’t want to jump backwards and any stone that is more than one meter ahead of stone  $i_{t-1}$  also has the greedy criteria weight  $-\infty$  because we don’t want to land in the water and each other stone  $j$  has greedy criteria  $d_j - d_{i_{t-1}}$ . Then you let  $i_t$  be the stone  $j$  that maximizes this greedy criteria. The algorithm then makes an irrevocable decision about this object. **Assuming such a stone exists, the algorithm has the man jump on it. Otherwise, the algorithm stops and states that it is impossible.**

**The Loop Invariant:** We have not gone wrong. If there is a solution, then there is at least one optimal solution  $S_t$  extending the choices  $A_t$  made so far by the algorithm.

**Initially ( $\langle pre \rangle \rightarrow \langle LI \rangle$ ):** Initially no choices have been made and hence all optimal solutions are consistent with these choices.

**Maintaining the Loop Invariant ( $\langle LI_{t-1} \rangle$  & not  $\langle exit \rangle$  &  $code_{loop} \rightarrow \langle LI_t \rangle$ ):** Consider an arbitrary iteration.

**Fly in From Mars:** The algorithm has iterated a few times. **Assume that it is time  $t - 1$  and that the algorithm has already decided for the man to step on the stones indexed by  $\langle i_0, i_1, i_2, \dots, i_{t-1} \rangle$ . All that we know is that the loop invariant is true and the exit condition is not.**

$S_{t-1}$ : The loop invariant states that there is at least one optimal solution extends the choices  $A_{t-1}$  made by the algorithm before this iteration. **Let  $S_{t-1} = \langle i_0, i_1, i_2, \dots, i_{t-1}, j_t, j_{t+1}, j_{t+2}, \dots, j_\ell \rangle$  denote one such solution.** (Note that this is a full solution and as such specifies a decision about each object in the instance and that the first  $t$  stones do agree with what the algorithm has done.) I like to have a fairy god mother hold it.

**Taking a Step:** During the iteration, the algorithm proceeds to choose the “best” object from amongst those not considered so far and makes an irrevocable decision about it. **In a greedy way, the algorithm just had the man jump on the stone that is as far from  $i_{t-1}$  as he can jump, i.e. the largest  $i_t$  for which  $d_{i_t} - d_{i_{t-1}} \leq 1$ . There is only this case, because we are assuming that such a stone exists.**

**Instructions for Modifying  $S_{t-1}$ :** The prover says to the fairy god mother, “Fairy god mother, I know that you have your full sequence of stones across the river planned out and that like the algorithm, at time  $t - 1$ , you are standing on the  $i_{t-1}^{th}$  stone. If from there you jump to the same stone as the algorithm did, i.e.  $j_t = i_t$ , then no changes need to be made to your solution, i.e.  $S_t = S_{t-1}$ .” Otherwise, because the algorithm stepped as far as possible, she must have stepped closer, i.e. her stone  $j_t$  must be between the stones  $i_{t+1}$  and  $i_t$ . (If she jumped on more than this one stone between  $i_{t+1}$  and  $i_t$  then her solution could not have been optimal.) Tell her to jump from stone  $i_{t-1}$  not to  $j_t$  but to go farther to  $i_t$ . From  $i_t$ , she should continue on as she did before, i.e.  $S_t = S_{t-1} - j_t + i_t = \langle i_0, i_1, i_2, \dots, i_{t-1}, i_t, j_{t+1}, j_{t+2}, \dots, j_\ell \rangle$ .

**Proving  $S_t$  is an Optimal Solution:** By the loop invariant,  $S_{t-1}$  is one of the valid solutions for this instance with minimum number of stones. We must prove that going from  $S_{t-1}$  to  $S_t$  does not increase the number of stones. We added one stone so we must make sure that we also delete at least one. To prove this it is sufficient to prove that the next stone  $j_t$  that she jumps on after  $i_{t-1}$  is

to the left of stone  $i_t$ . We know that the algorithm chose to jump from stone  $i_{t-1}$  to stone  $i_t$  because  $i_t$  is as the farthest from the initial shore that can be jumped on from  $i_{t-1}$ . We also know that the fairy god mother legally jumps from  $i_{t-1}$  to  $j_t$ . We conclude that  $j_t$  is either the same as stone  $i_t$  or is closer to stone  $i_{t-1}$  than it. It follows that at least one stone  $j_t$  is included in the sequence deleted. Hence  $S_t$  is at least as good as  $S_{t-1}$ . Hence,  $S_t$  is also an optimal solution.

**Proving  $S_t$  is a Valid Solution:** By the loop invariant  $S_{t-1}$  is a valid solution. (i.e. the initial stone is on the initial shore, the final stone is on the final shore, and each jump has distance at most one.) The prover made sure that his modifications did not make it invalid. We have  $S_t = \langle i_0, i_1, i_2, \dots, i_{t-1}, i_t, j_{t+1}, j_{t+2}, \dots, j_\ell \rangle$ . We know all the jumps from  $i_{t'}$  to  $i_{t'+1}$  for  $t' \in [0, t-2]$ , have distance at most one because both the algorithm and the fairy god mother in  $S_{t-1}$  have assured it. We know the jump from  $i_{t-1}$  to  $i_t$  has distance at most one because the algorithm chose it this way. We know the jump from  $i_t$  to  $j_{t+1}$  has distance at most the distance from  $j_t$  to  $j_{t+1}$  because we proved that  $j_t$  is to the left of  $i_t$ , and we know that this distance is at most one because the fairy god mother manages to jump this in  $S_{t-1}$ . Finally, we know all the jumps from  $j_{t'}$  to  $j_{t'+1}$  for  $t' \geq t+r$  have distance at most one because the fairy god mother in  $S_{t-1}$  has assured it. In conclusion,  $S_t$  is a valid solution.

**Proving  $S_t$  Extends  $A_t$ :** By the loop invariant  $S_{t-1}$  extends all the decisions  $\langle i_0, i_1, i_2, \dots, i_{t-1} \rangle$  made by algorithm before this iteration. The prover made sure that his modifications did not change any of these decisions and changed  $S_{t-1}$ 's decision  $j_t$  about the latest object to be consistent with what the algorithm did, i.e.  $i_{t+1}$ . Hence,  $S_t$  is consistent with both the earlier decisions made by algorithm and this most recent decision, i.e. extends  $A_t$ .

→  **$\langle LI_t \rangle$ :** Because  $S_t$  witnesses the fact that there is at least one valid optimal solution that extends  $A_t$ , we know that the loop invariant has been maintained.

**Second Case:** With MST, now suppose the the algorithm rejects the next best edge  $\langle u, v \rangle$  because it creates a cycle with the previously committed to edges. In this case, the god mother must have the same the previously committed to edges and hence also can't take  $\langle u, v \rangle$ . Let  $S_t = S_{t-1}$ .

**Exiting Loop ( $\langle LI \rangle$  &  $\langle exit \rangle \rightarrow \langle post \rangle$ ):** By the exit condition the algorithm has made a decision about every object in the instance. Hence, the algorithm has a full solution  $A_{exit}$ . By the loop invariant, this extends an optimal valid solution  $S_{exit}$ . Hence, the algorithm must have an optimal valid solution.

#### 4. Job/event scheduling problem with multiple rooms.

- Answer: Algorithms (a), (b), and (d) are sub-optimal for the following counterexample instance.

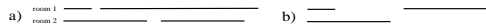


Fig a gives the events in the instance and the optimal schedule in two rooms. Fig b gives the suboptimal schedule produced by these three algorithms. Note that the third algorithm, which schedules the next event in the room with the latest last-scheduled finishing time, gives the optimal schedule. We will now prove that it always gives an optimal solution.

**Specifications:** The objects are the events. For each, we must either choose a room for it to be scheduled in or choose not to schedule it. Such a sequence of decisions makes a valid solution if no two events scheduled in the same room overlap. The measure according to which the solution is optimal is the total number of rooms scheduled.

**The Greedy Choice:** Each iteration the algorithm grabs the object which according to some simple criteria, seems to be the “best” (or “worst”) from amongst the unconsidered objects in

the instance. This algorithm considers the events in the *fixed* order sorted by their finishing times. For each object, the algorithm then makes an irrevocable decision about this object. Here, the next event is scheduled in the room with the latest last-scheduled finishing time.

**The Loop Invariant:** We have not gone wrong. If there is a solution, then there is at least one optimal solution  $S_t$  that extends the choices  $A_t$  made so far by the algorithm.

**Initially ( $\langle pre \rangle \rightarrow \langle LI \rangle$ ):** Initially no choices have been made and hence all optimal solutions extend choices  $A_0$ .

**Maintaining the Loop Invariant ( $\langle LI_{t-1} \rangle \& \text{ not } \langle exit \rangle \& \text{ code}_{loop} \rightarrow \langle LI_t \rangle$ ):** Consider an arbitrary iteration.

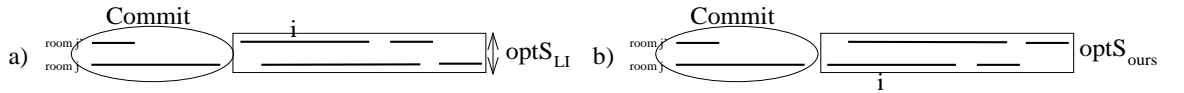
**$S_{t-1}$ :** The loop invariant states that there is at least one optimal solution that extends the choices  $A_{t-1}$  made by the algorithm before this iteration. Let  $S_{t-1}$  denote one such solution. (Note that this is a full solution and as such specifies a decision about each object in the instance.) If you like have a fairy god mother hold it.

**Taking a Step:** During the iteration, the algorithm either schedules the next event in some room or not. If our greedy algorithm did not schedule the next event  $i$ , then this event must conflict in each room with a previously scheduled event. Hence,  $S_{t-1}$  cannot have this next event  $i$  scheduled either because it too has scheduled these previous events. Hence,  $S_{t-1}$  itself is already consistent this with the most recent choice. Now assume that our greedy algorithm scheduled the next event  $i$  in room  $j$ .

**Instructions for Modifying  $S_{t-1}$ :** There are three cases. If both our greedy algorithm and  $S_{t-1}$  scheduled the next event  $i$  in room  $j$  then no changes need to be made and we are done.

If our greedy algorithm scheduled the next event  $i$  in room  $j$  and  $S_{t-1}$  does not schedule this event at all, then we modifying the schedule  $S_{t-1}$  into  $S_t$  by adding  $i$  to room  $j$  and removing any events from  $j$  that conflict with it. Just as done with the one room scheduling algorithm in Section 16.2.1, we can prove that only one event is removed and hence  $S_t$  is valid, is optimal, and extends  $A_t$ .

The remaining case occurs when our greedy algorithm scheduled the next event  $i$  in room  $j$  and  $S_{t-1}$  schedules it in room  $j'$ . (See fig a.)



We modify the schedule  $S_{t-1}$  into  $S_t$  as follows. (See fig b.) We cannot move the events whose schedule has already been committed to by the algorithm because  $S_t$  must continue to extend these choices. (See the events in the *Commit* circle.) We need to move event  $i$  from room  $j'$  to room  $j$  so that it too is consistent with what the algorithm has done. But doing this change may create conflicts. To fix these, we swap every event scheduled by  $S_{t-1}$  in room  $j'$  with finishing time of event  $i$  or later with every such job scheduled in room  $j$ . (See the events in the rectangle.)

We now prove that the resulting solution  $S_t$  is valid, extends  $A_t$ , and is optimal.

**Proving  $S_t$  is a Valid Solution:** By the loop invariant  $S_{t-1}$  is a valid solution. (i.e. its decisions do not conflict in any way.) The prover made sure that his modifications did not make it invalid. The changes may have made conflicts, but all of these conflicts were fixed. Hence,  $S_t$  is a valid solution. More specifically, there are no new conflicts between the previously committed events (circle) because they did not change. There are no new conflicts between the later committed events (rectangle) because they flipped rooms all together. Event  $i$  does not conflict with the preciously committed events in room  $j$ , because the algorithm scheduled it there. The even later events that were in room  $j'$  don't either because they are even later. The later events that were in room  $j$  wont conflict with the previously scheduled events in room  $j'$  because they did not conflict with those in room  $j$  and we know by the algorithm's choice of room  $j$  that the last-scheduled finishing time for  $j$  is later than that for room  $j'$ .

**Proving  $S_t$  Extends Algorithm's Choices  $A_t$ :** By the loop invariant  $S_{t-1}$  extends all the decisions made by algorithm before this iteration. The prover made sure that his modifications did not change any of these decisions and changed  $S_{t-1}$ 's decision about the latest object to be consistent with what the algorithm did. We did not move any events in *Commit*. We moved event  $i$  from room  $j'$  to room  $j$  to make  $S_t$  consistent with this most recent choice. Hence,  $S_t$  is consistency both with earlier decisions made by algorithm and this most recent decision and hence extends  $A_t$ .

**Proving  $S_t$  is an Optimal Solution:** By the loop invariant  $S_{t-1}$  is one of the valid solutions for this instance with optimal (minimum or maximum as the case may be) measure of success. The prover made sure that his modifications did not make  $S_t$  worse than  $S_{t-1}$ . The schedule  $S_t$  has the same number of events as  $S_{t-1}$ . Hence,  $S_{t-1}$  is an optimal solution.

→  **$\langle LI' \rangle$ :** Because  $S_t$  witnesses the fact that there is at least one optimal solution that extends  $A_t$ , we know that the loop invariant has been maintained.

**Exiting Loop ( $\langle LI \rangle$  &  $\langle exit \rangle \rightarrow \langle post \rangle$ ):** By the exit condition the algorithm has made a decision about every object in the instance. Hence, the algorithm has a full solution. By the loop invariant, this extends an optimal valid solution. Hence, the algorithm must have an optimal valid solution.