

# Specifying & Refining a Bridge Controller

MEB: Chapter 2



EECS3342 Z: System  
Specification and Refinement  
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## Learning Outcomes



This module is designed to help you understand:

- What a **Requirement Document (RD)** is
- What a **refinement** is
- Writing **formal specifications**
  - (Static) **contexts**: constants, axioms, theorems
  - (Dynamic) **machines**: variables, invariants, events, guards, actions
- **Proof Obligations (POs)** associated with proving:
  - **refinements**
  - system **properties**
- Applying **inference rules** of the **sequent calculus**

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## Recall: Correct by Construction



- Directly reasoning about **source code** (written in a programming language) is **too complicated** to be feasible.
- Instead, given a **requirements document**, prior to **implementation**, we develop **models** through a series of **refinement** steps:
  - Each model formalizes an **external observer's** perception of the system.
  - Models are "sorted" with **increasing levels of accuracy** w.r.t. the system.
  - The **first model**, though the most **abstract**, can **already** be proved satisfying **some requirements**.
  - Starting from the **second model**, each model is analyzed and proved **correct** relative to two criteria:
    1. **Some requirements** (i.e., R-descriptions)
    2. **Proof Obligations (POs)** related to the **preceding model** being **refined by** the **current model** (via "extra" **state** variables and **events**).
  - The **last model** (which is **correct by construction**) should be **sufficiently close** to be transformed into a **working program** (e.g., in C).

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## State Space of a Model



- A model's **state space** is the set of **all** configurations:
  - Each **configuration** assigns values to **constants & variables**, subject to:
    - **axiom** (e.g., typing constraints, assumptions)
    - **invariant** properties/theorems
  - Say an initial model of a bank system with two **constants** and a **variable**:  
 $c \in \mathbb{N}1 \wedge L \in \mathbb{N}1 \wedge \text{accounts} \in \text{String} \rightarrow \mathbb{Z}$  /\* typing constraint \*/  
 $\forall id \bullet id \in \text{dom}(\text{accounts}) \Rightarrow -c \leq \text{accounts}(id) \leq L$  /\* desired property \*/
  - **Q.** What is the **state space** of this initial model?  
**A.** All valid combinations of  $c$ ,  $L$ , and  $\text{accounts}$ .
    - Configuration 1:  $(c = 1, 000, L = 500, 000, b = \emptyset)$
    - Configuration 2:  $(c = 2, 375, L = 700, 000, b = \{("id1", 500), ("id2", 1, 250)\})$
    - ... [Challenge: **Combinatorial Explosion**]
  - Model Concreteness  $\uparrow \Rightarrow$  (State Space  $\uparrow \wedge$  Verification Difficulty  $\uparrow$ )
- A model's **complexity** should be guided by those properties intended to be **verified** against that model.
  - $\Rightarrow$  **Infeasible** to prove **all** desired properties on a model.
  - $\Rightarrow$  **Feasible** to **distribute** desired properties over a list of **refinements**.

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## Roadmap of this Module



- We will walk through the **development process** of constructing **models** of a control system regulating cars on a bridge.  
Such controllers exemplify a **reactive system**.  
(with **sensors** and **actuators**)
- Always stay on top of the following roadmap:
  - A **Requirements Document (RD)** of the bridge controller
  - A brief overview of the **refinement strategy**
  - An initial, the most **abstract** model
  - A subsequent **model** representing the **1st refinement**
  - A subsequent **model** representing the **2nd refinement**
  - A subsequent **model** representing the **3rd refinement**

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## Requirements Document: E-Descriptions



Each **E-Description** is an **atomic specification** of a **constraint** or an **assumption** of the system's working environment.

ENV1	The system is equipped with two traffic lights with two colors: green and red.
ENV2	The traffic lights control the entrance to the bridge at both ends of it.
ENV3	Cars are not supposed to pass on a red traffic light, only on a green one.
ENV4	The system is equipped with four sensors with two states: on or off.
ENV5	The sensors are used to detect the presence of a car entering or leaving the bridge: "on" means that a car is willing to enter the bridge or to leave it.

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## Requirements Document: Mainland, Island



Imagine you are asked to build a bridge (as an alternative to ferry) connecting the downtown and Toronto Island.



Page Source: <https://soldbyshane.com/area/toronto-islands/>

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## Requirements Document: R-Descriptions

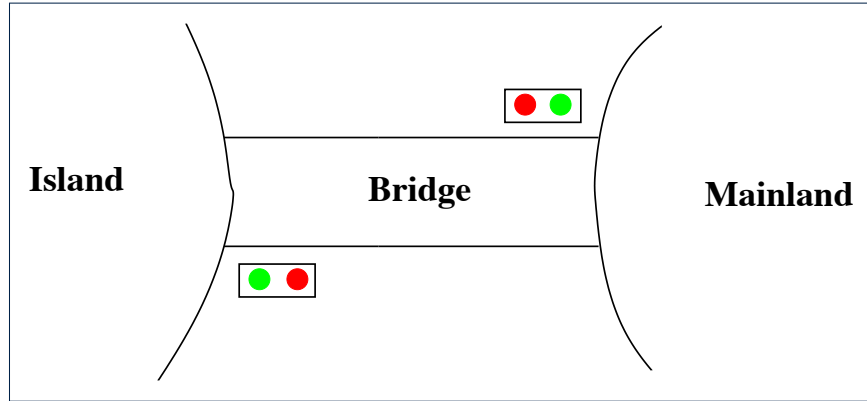


Each **R-Description** is an **atomic specification** of an intended **functionality** or a desired **property** of the working system.

REQ1	The system is controlling cars on a bridge connecting the mainland to an island.
REQ2	The number of cars on bridge and island is limited.
REQ3	The bridge is one-way or the other, not both at the same time.

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# Requirements Document: Visual Summary of Equipment Pieces



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## Refinement Strategy



- Before diving into details of the **models**, we first clarify the adopted **design strategy of progressive refinements**.
  - The **initial model** ( $m_0$ ) will address the intended functionality of a **limited** number of cars on the island and bridge. [ REQ2 ]
  - A **1st refinement** ( $m_1$  which **refines**  $m_0$ ) will address the intended functionality of the **bridge being one-way**. [ REQ1, REQ3 ]
  - A **2nd refinement** ( $m_2$  which **refines**  $m_1$ ) will address the environment constraints imposed by **traffic lights**. [ ENV1, ENV2, ENV3 ]
  - A **final, 3rd refinement** ( $m_3$  which **refines**  $m_2$ ) will address the environment constraints imposed by **sensors** and the **architecture**: controller, environment, communication channels. [ ENV4, ENV5 ]
- Recall **Correct by Construction** :  
From each **model** to its **refinement**, only a **manageable** amount of details are added, making it **feasible** to conduct **analysis** and **proofs**.

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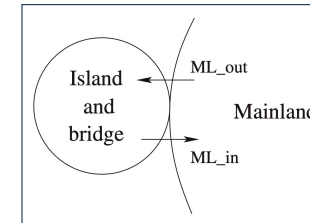
## Model $m_0$ : Abstraction



- In this **most abstract** perception of the bridge controller, we do **not** even consider the bridge, traffic lights, and sensors!
- Instead, we focus on this single **requirement**:

REQ2	The number of cars on bridge and island is limited.
------	---

- Analogies**:
  - Observe the system from the sky: island and bridge appear only as a **compound**.



- "**Zoom in**" on the system as **refinements** are introduced.

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## Model $m_0$ : State Space



- The **static** part is fixed and may be seen/imported.  
A **constant**  $d$  denotes the **maximum** number of cars allowed to be on the **island-bridge compound** at any time.  
(whereas cars on the mainland is **unbounded**)

constants: $d$	axioms: axm0_1 : $d \in \mathbb{N}$
----------------	--

- The **dynamic** part changes as the system **evolves**.  
A **variable**  $n$  denotes the actual number of cars, at a given moment, in the **island-bridge compound**.

variables: $n$	invariants: inv0_1 : $n \in \mathbb{N}$ inv0_2 : $n \leq d$
----------------	---

**Remark. Invariants** should be (subject to **proofs**):

- Established** when the system is first **initialized**
- Preserved/Maintained** after any **enabled event**'s actions take effect

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## Model $m_0$ : State Transitions via Events



- The system acts as an **ABSTRACT STATE MACHINE (ASM)**: it *evolves* as *actions of enabled events* change values of variables, subject to *invariants*.
- At any given *state* (a valid *configuration* of constants/variables):
  - An event is said to be *enabled* if its guard evaluates to *true*.
  - An event is said to be *disabled* if its guard evaluates to *false*.
  - An *enabled* event makes a *state transition* if it occurs and its *actions* take effect.
- 1st event**: A car *exits* mainland (and *enters* the island-bridge *compound*).

```
ML_out
begin
  n := n + 1
end
```

Correct Specification? Say  $d = 2$ .  
**Witness**: *Event Trace* (*init*, *ML.in*)

- 2nd event**: A car *enters* mainland (and *exits* the island-bridge *compound*).

```
ML.in
begin
  n := n - 1
end
```

Correct Specification? Say  $d = 2$ .  
**Witness**: *Event Trace* (*init*, *ML.out*, *ML.out*)

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## Model $m_0$ : Actions vs. Before-After Predicates



- When an *enabled* event  $e$  occurs there are two notions of *state*:
  - Before-/Pre-State**: Configuration just *before*  $e$ 's actions take effect
  - After-/Post-State**: Configuration just *after*  $e$ 's actions take effect
- Remark**. When an *enabled* event occurs, its *action(s)* cause a *transition* from the *pre-state* to the *post-state*.

- As examples, consider *actions* of  $m_0$ 's two events:

Events

```
ML_out
  n := n + 1
```

```
ML_in
  n := n - 1
```

before-after predicates

```
n' = n + 1
```

```
n' = n - 1
```

- An event *action* " $n := n + 1$ " is *not* a variable assignment; instead, it is a **specification**: " $n$  becomes  $n + 1$  (when the state transition completes)".
- The **before-after predicate (BAP)** " $n' = n + 1$ " expresses that  $n'$  (the *post-state* value of  $n$ ) is one more than  $n$  (the *pre-state* value of  $n$ ).

- When we express **proof obligations (POs)** associated with *events*, we use **BAP**.

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## Design of Events: Invariant Preservation



- Our design of the two events

```
ML_out
begin
  n := n + 1
end
```

```
ML.in
begin
  n := n - 1
end
```

only specifies how the *variable*  $n$  should be updated.

- Remember, *invariants* are conditions that should *never* be *violated*!

```
invariants:
inv0.1 : n ∈ ℕ
inv0.2 : n ≤ d
```

- By simulating the system as an **ASM**, we discover *witnesses* (i.e., *event traces*) of the *invariants* *not* being preserved *all* the time.

$$\exists s \bullet s \in \text{STATE SPACE} \Rightarrow \neg \text{invariants}(s)$$

- We formulate such a commitment to preserving *invariants* as a **proof obligation (PO)** rule (a.k.a. a **verification condition (VC)** rule).

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## Sequents: Syntax and Semantics



- We formulate each **PO/VC** rule as a (horizontal or vertical) **sequent**:

```
H ⊢ G
```

```
H
⊢
G
```

- The symbol  $\vdash$  is called the **turnstile**.
- $H$  is a set of predicates forming the **hypotheses/assumptions**. [ assumed as *true* ]
- $G$  is a set of predicates forming the **goal/conclusion**. [ claimed to be *provable* from  $H$  ]

- Informally**:

- $H \vdash G$  is **true** if  $G$  can be proved by assuming  $H$ . [ i.e., We say " $H$  entails  $G$ " or " $H$  yields  $G$ " ]
- $H \vdash G$  is **false** if  $G$  cannot be proved by assuming  $H$ .

- Formally**:  $H \vdash G \iff (H \Rightarrow G)$

Q. What does it mean when  $H$  is empty (i.e., no hypotheses)?

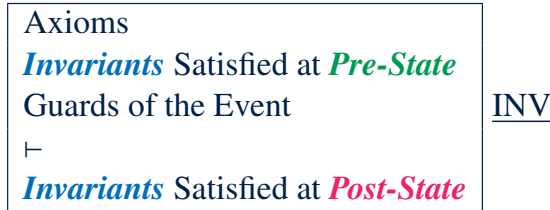
A.  $\vdash G \equiv \text{true} \vdash G$  [ Why not  $\vdash G \equiv \text{false} \vdash G$  ? ]

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## PO of Invariant Preservation: Sketch



- Here is a sketch of the PO/VC rule for **invariant preservation**:



- Informally, this is what the above PO/VC **requires to prove**:  
 Assuming **all** axioms, invariants, and the event's guards hold at the *pre-state*,  
 after the *state transition* is made by the event,  
**all** invariants hold at the *post-state*.

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## Rule of Invariant Preservation: Sequents



- Based on the components ( $c$ ,  $A(c)$ ,  $v$ ,  $I(c, v)$ ,  $E(c, v)$ ), we are able to formally state the **PO/VC Rule of Invariant Preservation**:

$$\frac{\begin{array}{l} A(c) \\ I(c, v) \\ G(c, v) \\ \vdash \\ I_i(c, E(c, v)) \end{array}}{\text{INV}} \quad \text{where } I_i \text{ denotes a single invariant condition}$$

- Accordingly, how many **sequents** to be proved? [ # events  $\times$  # invariants ]
- We have **two** **sequents** generated for **event**  $ML\_out$  of model  $m_0$ :

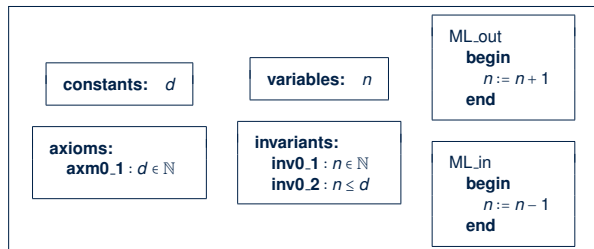
$$\frac{\begin{array}{l} d \in \mathbb{N} \\ n \in \mathbb{N} \\ n \leq d \\ \vdash \\ n + 1 \in \mathbb{N} \end{array}}{ML\_out/inv0\_1/INV} \quad \frac{\begin{array}{l} d \in \mathbb{N} \\ n \in \mathbb{N} \\ n \leq d \\ \vdash \\ n + 1 \leq d \end{array}}{ML\_out/inv0\_2/INV}$$

**Exercise.** Write the **POs of invariant preservation** for event  $ML\_in$ .

- Before claiming that a **model** is **correct**, outstanding **sequents** associated with all **POs** must be proved/discharged.

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## PO of Invariant Preservation: Components



- $c$ : list of **constants**  $\langle d \rangle$
- $A(c)$ : list of **axioms**  $\langle axm0\_1 \rangle$
- $v$  and  $v'$ : list of **variables** in *pre-* and *post-*states  $v \ni \langle n \rangle, v' \ni \langle n' \rangle$
- $I(c, v)$ : list of **invariants**  $\langle inv0\_1, inv0\_2 \rangle$
- $G(c, v)$ : the **event's** list of guards  
 $G(\langle d \rangle, \langle n \rangle)$  of  $ML\_out \ni \langle true \rangle$ ,  $G(\langle d \rangle, \langle n \rangle)$  of  $ML\_in \ni \langle true \rangle$
- $E(c, v)$ : effect of the **event's** actions i.t.o. what variable values **become**  
 $E(\langle d \rangle, \langle n \rangle)$  of  $ML\_out \ni \langle n + 1 \rangle$ ,  $E(\langle d \rangle, \langle n \rangle)$  of  $ML\_in \ni \langle n - 1 \rangle$
- $v' = E(c, v)$ : **before-after predicate** formalizing  $E$ 's actions  
 BAP of  $ML\_out$ :  $\langle n' \rangle = \langle n + 1 \rangle$ , BAP of  $ML\_in$ :  $\langle n' \rangle = \langle n - 1 \rangle$

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## Inference Rules: Syntax and Semantics



- An **inference rule (IR)** has the following form:

$$\frac{A}{C} \quad L$$

**Formally:**  $A \Rightarrow C$  is an **axiom**.  
**Informally:** To prove  $C$ , it is **sufficient** to prove  $A$  instead.  
**Informally:**  $C$  is the case, assuming that  $A$  is the case.

- $L$  is a **name** label for referencing the **inference rule** in proofs.
- $A$  is a **set** of sequents known as **antecedents** of rule  $L$ .
- $C$  is a **single** sequent known as **consequent** of rule  $L$ .

- Let's consider **inference rules (IRs)** with two different flavours:

$$\frac{H1 \vdash G}{H1, H2 \vdash G} \quad \text{MON} \quad \frac{}{n \in \mathbb{N} \vdash n + 1 \in \mathbb{N}} \quad \text{P2}$$

- IR **MON**: To prove  $H1, H2 \vdash G$ , it **suffices** to prove  $H1 \vdash G$  instead.
- IR **P2**:  $n \in \mathbb{N} \vdash n + 1 \in \mathbb{N}$  is an **axiom**.  
 [ **proved** automatically without further justifications ]

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## Proof of Sequent: Steps and Structure



- To prove the following sequent (related to *invariant preservation*):

$$\frac{\begin{array}{l} d \in \mathbb{N} \\ n \in \mathbb{N} \\ n \leq d \\ \vdash \\ n + 1 \in \mathbb{N} \end{array}}{\text{ML\_out/inv0\_1/INV}}$$

- Apply a *inference rule*, which *transforms* some “outstanding” **sequent** to one or more other **sequents** to be proved instead.
  - Keep applying *inference rules* until **all transformed sequents** are *axioms* that do **not** require any further justifications.
- Here is a *formal proof* of ML\_out/inv0\_1/INV, by applying IRs **MON** and **P2**:

$$\frac{\begin{array}{l} d \in \mathbb{N} \\ n \in \mathbb{N} \\ n \leq d \\ \vdash \\ n + 1 \in \mathbb{N} \end{array} \quad \text{MON} \quad \frac{\begin{array}{l} n \in \mathbb{N} \\ \vdash \\ n + 1 \in \mathbb{N} \end{array} \quad \text{P2}}$$

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## Example Inference Rules (2)



$$\frac{}{n < m \vdash n + 1 \leq m} \quad \text{INC}$$

$n + 1$  is less than or equal to  $m$ , assuming that  $n$  is strictly less than  $m$ .

$$\frac{}{n \leq m \vdash n - 1 < m} \quad \text{DEC}$$

$n - 1$  is strictly less than  $m$ , assuming that  $n$  is less than or equal to  $m$ .

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## Example Inference Rules (1)



$$\frac{}{\vdash 0 \in \mathbb{N}} \quad \text{P1}$$

1st Peano axiom: 0 is a natural number.

$$\frac{}{n \in \mathbb{N} \vdash n + 1 \in \mathbb{N}} \quad \text{P2}$$

2nd Peano axiom:  $n + 1$  is a natural number, assuming that  $n$  is a natural number.

$$\frac{}{0 < n \vdash n - 1 \in \mathbb{N}} \quad \text{P2'}$$

$n - 1$  is a natural number, assuming that  $n$  is positive.

$$\frac{}{n \in \mathbb{N} \vdash 0 \leq n} \quad \text{P3}$$

3rd Peano axiom:  $n$  is non-negative, assuming that  $n$  is a natural number.

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## Example Inference Rules (3)



$$\frac{H1 \vdash G}{H1, H2 \vdash G} \quad \text{MON}$$

To prove a goal under certain hypotheses, it suffices to prove it under less hypotheses.

$$\frac{H, P \vdash R \quad H, Q \vdash R}{H, P \vee Q \vdash R} \quad \text{OR.L}$$

*Proof by Cases:*  
To prove a goal under a disjunctive assumption, it suffices to prove **independently** the same goal, twice, under each disjunct.

$$\frac{H \vdash P}{H \vdash P \vee Q} \quad \text{OR.R1}$$

To prove a disjunction, it suffices to prove the left disjunct.

$$\frac{H \vdash Q}{H \vdash P \vee Q} \quad \text{OR.R2}$$

To prove a disjunction, it suffices to prove the right disjunct.

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## Revisiting Design of Events: $ML\_out$

- Recall that we already proved  $PO$   $ML\_out/inv0\_1/INV$ :

$$\begin{array}{|l} d \in \mathbb{N} \\ n \in \mathbb{N} \\ n \leq d \\ \vdash \\ n+1 \in \mathbb{N} \end{array} \quad \text{MON} \quad \begin{array}{|l} n \in \mathbb{N} \\ \vdash \\ n+1 \in \mathbb{N} \end{array} \quad \text{P2}$$

$\therefore ML\_out/inv0\_1/INV$  succeeds in being discharged.

- How about the other  $PO$   $ML\_out/inv0\_2/INV$  for the same event?

$$\begin{array}{|l} d \in \mathbb{N} \\ n \in \mathbb{N} \\ n \leq d \\ \vdash \\ n+1 \leq d \end{array} \quad \text{MON} \quad \begin{array}{|l} n \leq d \\ \vdash \\ n+1 \leq d \end{array} \quad ?$$

$\therefore ML\_out/inv0\_2/INV$  fails to be discharged.

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## Fixing the Design of Events

- Proofs of  $ML\_out/inv0\_2/INV$  and  $ML\_in/inv0\_1/INV$  fail due to the two events being **enabled when they should not**.
- Having this feedback, we add proper **guards** to  $ML\_out$  and  $ML\_in$ :

$$\begin{array}{|l} ML\_out \\ \text{when} \\ n < d \\ \text{then} \\ n := n + 1 \\ \text{end} \end{array} \quad \begin{array}{|l} ML\_in \\ \text{when} \\ n > 0 \\ \text{then} \\ n := n - 1 \\ \text{end} \end{array}$$

- Having changed both events, updated **sequents** will be generated for the PO/VC rule of **invariant preservation**.
- All **sequents** ( $\{ML\_out, ML\_in\} \times \{inv0\_1, inv0\_2\}$ ) now **provable**?

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## Revisiting Design of Events: $ML\_in$

- How about the  $PO$   $ML\_in/inv0\_1/INV$  for  $ML\_in$ :

$$\begin{array}{|l} d \in \mathbb{N} \\ n \in \mathbb{N} \\ n \leq d \\ \vdash \\ n-1 \in \mathbb{N} \end{array} \quad \text{MON} \quad \begin{array}{|l} n \in \mathbb{N} \\ \vdash \\ n-1 \in \mathbb{N} \end{array} \quad ?$$

$\therefore ML\_in/inv0\_1/INV$  fails to be discharged.

- How about the other  $PO$   $ML\_in/inv0\_2/INV$  for the same event?

$$\begin{array}{|l} d \in \mathbb{N} \\ n \in \mathbb{N} \\ n \leq d \\ \vdash \\ n-1 \leq d \end{array} \quad \text{MON} \quad \begin{array}{|l} n \leq d \\ \vdash \\ n-1 < d \vee n-1 = d \end{array} \quad \text{OR.1} \quad \begin{array}{|l} n \leq d \\ \vdash \\ n-1 < d \end{array} \quad \text{DEC}$$

$\therefore ML\_in/inv0\_2/INV$  succeeds in being discharged.

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## Revisiting Fixed Design of Events: $ML\_out$

- How about the  $PO$   $ML\_out/inv0\_1/INV$  for  $ML\_out$ :

$$\begin{array}{|l} d \in \mathbb{N} \\ n \in \mathbb{N} \\ n \leq d \\ n < d \\ \vdash \\ n+1 \in \mathbb{N} \end{array} \quad \text{MON} \quad \begin{array}{|l} n \in \mathbb{N} \\ \vdash \\ n+1 \in \mathbb{N} \end{array} \quad \text{P2}$$

$\therefore ML\_out/inv0\_1/INV$  still succeeds in being discharged!

- How about the other  $PO$   $ML\_out/inv0\_2/INV$  for the same event?

$$\begin{array}{|l} d \in \mathbb{N} \\ n \in \mathbb{N} \\ n \leq d \\ n < d \\ \vdash \\ n+1 \leq d \end{array} \quad \text{MON} \quad \begin{array}{|l} n < d \\ \vdash \\ n+1 \leq d \end{array} \quad \text{INC}$$

$\therefore ML\_out/inv0\_2/INV$  now succeeds in being discharged!

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## Revisiting Fixed Design of Events: $ML\_in$



- How about the **PO**  $ML\_in/inv0\_1/INV$  for  $ML\_in$ :

$$\begin{array}{|l}
 d \in \mathbb{N} \\
 n \in \mathbb{N} \\
 n \leq d \\
 n > 0 \\
 \vdash \\
 n - 1 \in \mathbb{N}
 \end{array}
 \text{ MON }
 \begin{array}{|l}
 n > 0 \\
 \vdash \\
 n - 1 \in \mathbb{N}
 \end{array}
 \text{ P2}'$$

$\therefore ML\_in/inv0\_1/INV$  now succeeds in being discharged!

- How about the other **PO**  $ML\_in/inv0\_2/INV$  for the same event?

$$\begin{array}{|l}
 d \in \mathbb{N} \\
 n \in \mathbb{N} \\
 n \leq d \\
 n > 0 \\
 \vdash \\
 n - 1 \leq d
 \end{array}
 \text{ MON }
 \begin{array}{|l}
 n \leq d \\
 \vdash \\
 n - 1 < d \vee n - 1 = d
 \end{array}
 \text{ OR.1 }
 \begin{array}{|l}
 n \leq d \\
 \vdash \\
 n - 1 < d
 \end{array}
 \text{ DEC}$$

$\therefore ML\_in/inv0\_2/INV$  still succeeds in being discharged!

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## PO of Invariant Establishment



```

init
begin
  n := 0
end
    
```

- ✓ An **reactive system**, once **initialized**, should **never** terminate.
- ✓ Event *init* cannot “preserve” the **invariants**.  
 $\therefore$  State before its occurrence (**pre-state**) does **not** exist.
- ✓ Event *init* only required to **establish** invariants for the first time
- A new formal component is needed:
  - $K(c)$ : effect of *init*'s actions i.t.o. what variable values **become**  
 e.g.,  $K((d))$  of *init*  $\hat{=} \langle 0 \rangle$
  - $v' = K(c)$ : **before-after predicate** formalizing *init*'s actions  
 e.g., BAP of *init*:  $\langle n' \rangle = \langle 0 \rangle$
- Accordingly, PO of **invariant establishment** is formulated as a **sequent**:

$$\begin{array}{|l}
 \text{Axioms} \\
 \vdash \\
 \text{Invariants Satisfied at Post-State}
 \end{array}
 \text{ INV }
 \begin{array}{|l}
 A(c) \\
 \vdash \\
 I_i(c, K(c))
 \end{array}
 \text{ INV}$$

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## Initializing the Abstract System $m_0$



- Discharging the four **sequents** proved that both **invariant** conditions are **preserved** between occurrences/interleavings of **events**  $ML\_out$  and  $ML\_in$ .
- But how are the **invariants established** in the first place?

**Analogy.** Proving  $P$  via **mathematical induction**, two cases to prove:

- $P(1), P(2), \dots$  [ **base** cases  $\approx$  **establishing** inv. ]
- $P(n) \Rightarrow P(n+1)$  [ **inductive** cases  $\approx$  **preserving** inv. ]

- Therefore, we specify how the **ASM**'s **initial state** looks like:
  - ✓ The IB compound, once **initialized**, has **no** cars.

```

init
begin
  n := 0
end
    
```

- ✓ Initialization always possible: guard is **true**.
- ✓ There is no **pre-state** for *init*.  
 $\therefore$  The **RHS** of  $:=$  must **not** involve variables.  
 $\therefore$  The **RHS** of  $:=$  may **only** involve constants.
- ✓ There is only the **post-state** for *init*.  
 $\therefore$  Before-**After Predicate**:  $n' = 0$

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## Discharging PO of Invariant Establishment



- How many **sequents** to be proved? [ # invariants ]
- We have **two sequents** generated for **event** *init* of model  $m_0$ :

$$\begin{array}{|l}
 d \in \mathbb{N} \\
 \vdash \\
 0 \in \mathbb{N}
 \end{array}
 \text{ init/inv0\_1/INV }
 \begin{array}{|l}
 d \in \mathbb{N} \\
 \vdash \\
 0 \leq d
 \end{array}
 \text{ init/inv0\_2/INV}$$

- Can we discharge the **PO**  $init/inv0\_1/INV$ ?  
 $\begin{array}{|l} d \in \mathbb{N} \\ \vdash \\ 0 \in \mathbb{N} \end{array} \text{ MON } \begin{array}{|l} \vdash \\ 0 \in \mathbb{N} \end{array} \text{ P1 } \therefore \text{init/inv0\_1/INV}$  succeeds in being discharged.
- Can we discharge the **PO**  $init/inv0\_2/INV$ ?  
 $\begin{array}{|l} d \in \mathbb{N} \\ \vdash \\ 0 \leq d \end{array} \text{ P3 } \therefore \text{init/inv0\_2/INV}$  succeeds in being discharged.

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# System Property: Deadlock Freedom



- So far we have proved that our initial model  $m_0$  is s.t. all invariant conditions are:
  - Established when system is first initialized via *init*
  - Preserved whenever there is a *state transition* (via an enabled event: *ML\_out* or *ML\_in*)
- However, whenever *event occurrences* are conditional (i.e., *guards* stronger than *true*), there is a possibility of **deadlock**:
  - A state where *guards* of all events evaluate to *false*
  - When a **deadlock** happens, none of the *events* is *enabled*.  
 ⇒ The system is blocked and not reactive anymore!
- We express this *non-blocking* property as a new requirement:

REQ4	Once started, the system should work for ever.
------	--

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# PO of Deadlock Freedom (2)



- Deadlock freedom** is not necessarily a desired property.
  - ⇒ When it is (like  $m_0$ ), then the generated *sequents* must be discharged.
- Applying the PO of *deadlock freedom* to the initial model  $m_0$ :

$\begin{array}{l} A(c) \\ I(c, v) \\ \vdash \\ G_1(c, v) \vee \dots \vee G_m(c, v) \end{array}$	DLF	$\begin{array}{l} d \in \mathbb{N} \\ n \in \mathbb{N} \\ n \leq d \\ \vdash \\ n < d \vee n > 0 \end{array}$	DLF
---	-----	---	-----

Our bridge controller being **deadlock-free** means that cars can *always* enter (via *ML\_out*) or leave (via *ML\_in*) the island-bridge compound.

- Can we formally discharge this **PO** for our *initial model*  $m_0$ ?

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# PO of Deadlock Freedom (1)



- Recall some of the formal components we discussed:
  - $c$ : list of *constants*
  - $A(c)$ : list of *axioms* (axm0.1)
  - $v$  and  $v'$ : list of *variables* in *pre-* and *post-*states  $v \triangleq \langle n \rangle, v' \triangleq \langle n' \rangle$
  - $I(c, v)$ : list of *invariants* (inv0.1, inv0.2)
  - $G(c, v)$ : the event's list of *guards*

$$G(\langle d \rangle, \langle n \rangle) \text{ of } ML\_out \triangleq \langle n < d \rangle, G(\langle d \rangle, \langle n \rangle) \text{ of } ML\_in \triangleq \langle n > 0 \rangle$$

- A system is **deadlock-free** if at least one of its *events* is *enabled*:

$\begin{array}{l} \text{Axioms} \\ \text{Invariants Satisfied at Pre-State} \\ \vdash \\ \text{Disjunction of the guards satisfied at Pre-State} \end{array}$	DLF	$\begin{array}{l} A(c) \\ I(c, v) \\ \vdash \\ G_1(c, v) \vee \dots \vee G_m(c, v) \end{array}$	DLF
---	-----	---	-----

To prove about deadlock freedom

- An event's effect of state transition is **not** relevant.
- Instead, the evaluation of all events' *guards* at the *pre-state* is relevant.

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# Example Inference Rules (4)



$\frac{}{H, P \vdash P} \text{ HYP}$	A goal is proved if it can be assumed.
$\frac{}{\perp \vdash P} \text{ FALSE.L}$	Assuming <i>false</i> ( $\perp$ ), anything can be proved.
$\frac{}{P \vdash \top} \text{ TRUE.R}$	<i>true</i> ( $\top$ ) is proved, regardless of the assumption.
$\frac{}{P \vdash E = E} \text{ EQ}$	An expression being equal to itself is proved, regardless of the assumption.

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## Example Inference Rules (5)



$$\frac{H(F), E = F \vdash P(F)}{H(E), E = F \vdash P(E)} \text{EQ\_LR}$$

To prove a goal  $P(E)$  assuming  $H(E)$ , where both  $P$  and  $H$  depend on expression  $E$ , it suffices to prove  $P(F)$  assuming  $H(F)$ , where both  $P$  and  $H$  depend on expression  $F$ , given that  $E$  is equal to  $F$ .

$$\frac{H(E), E = F \vdash P(E)}{H(F), E = F \vdash P(F)} \text{EQ\_RL}$$

To prove a goal  $P(F)$  assuming  $H(F)$ , where both  $P$  and  $H$  depend on expression  $F$ , it suffices to prove  $P(E)$  assuming  $H(E)$ , where both  $P$  and  $H$  depend on expression  $E$ , given that  $E$  is equal to  $F$ .

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## Discharging PO of DLF: Exercise



$$\frac{\begin{array}{l} A(c) \\ I(c, v) \\ \vdash \\ G_1(c, v) \vee \dots \vee G_m(c, v) \end{array}}{\begin{array}{l} d \in \mathbb{N} \\ n \in \mathbb{N} \\ n \leq d \\ \vdash \\ n < d \vee n > 0 \end{array}} \text{DLF} \quad ??$$

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## Discharging PO of DLF: First Attempt



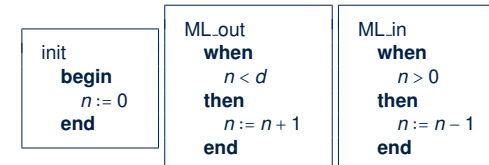
$$\begin{array}{l} d \in \mathbb{N} \\ n \in \mathbb{N} \\ n \leq d \\ \vdash \\ n < d \vee n > 0 \end{array} \equiv \begin{array}{l} d \in \mathbb{N} \\ n \in \mathbb{N} \\ n < d \vee n = d \\ \vdash \\ n < d \vee n > 0 \end{array} \text{MON} \quad \text{OR.L} \left\{ \begin{array}{l} n < d \\ \vdash \\ n < d \vee n > 0 \end{array} \text{OR.R1} \quad \begin{array}{l} n < d \\ \vdash \\ n < d \end{array} \text{HYP} \right. \\ \left. \begin{array}{l} n = d \\ \vdash \\ n < d \vee n > 0 \end{array} \text{EQ.LR, MON} \quad \begin{array}{l} \vdash \\ d < d \vee d > 0 \end{array} \text{OR.R2} \quad \begin{array}{l} \vdash \\ d > 0 \end{array} ? \right.$$

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## Why Did the DLF PO Fail to Discharge?



- In our first attempt, proof of the 2nd case failed:  $\vdash d > 0$
- This **unprovable** sequent gave us a good hint:
  - For the model under consideration ( $m_0$ ) to be **deadlock-free**, it is required that  $d > 0$ . [ $\geq 1$  car allowed in the IB compound]
  - But current **specification** of  $m_0$  **not** strong enough to entail this:
    - $\neg(d > 0) \equiv d \leq 0$  is possible for the current model
    - Given **axm0.1** :  $d \in \mathbb{N}$
    - $\Rightarrow d = 0$  is allowed by  $m_0$  which causes a **deadlock**.
- Recall the *init* event and the two **guarded** events:



When  $d = 0$ , the disjunction of guards evaluates to **false**:  $0 < 0 \vee 0 > 0$   
 $\Rightarrow$  As soon as the system is initialized, it **deadlocks immediately**  
 as no car can either enter or leave the IR compound!!

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## Fixing the Context of Initial Model

- Having understood the failed proof, we add a proper *axiom* to  $m_0$ :

**axioms:**  
axm0.2 :  $d > 0$

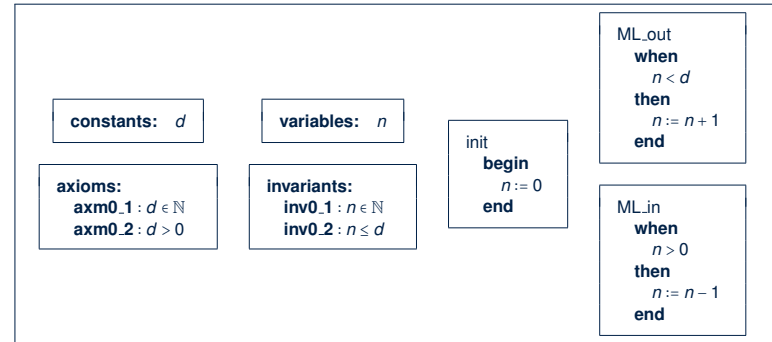
- We have effectively elaborated on **REQ2**:

REQ2	The number of cars on bridge and island is limited but positive.
------	--

- Having changed the context, an updated *sequent* will be generated for the PO/VC rule of *deadlock freedom*.
- Is this new sequent now *provable*?

## Initial Model: Summary

- The final version of our *initial model*  $m_0$  is **provably correct** w.r.t.:
  - Establishment of *Invariants*
  - Preservation of *Invariants*
  - Deadlock** Freedom
- Here is the final *specification* of  $m_0$ :



## Discharging PO of DLF: Second Attempt

$d \in \mathbb{N}$   
 $d > 0$   
 $n \in \mathbb{N}$   
 $n \leq d$   
 $\vdash$   
 $n < d \vee n > 0$

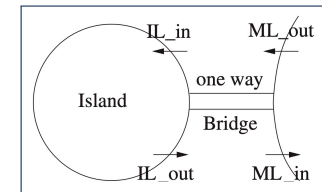
≡



## Model $m_1$ : “More Concrete” Abstraction

- First *refinement* has a more *concrete* perception of the bridge controller:
  - We “zoom in” by observing the system from closer to the ground, so that the island-bridge compound is split into:

- the island
- the (one-way) bridge



- Nonetheless, traffic lights and sensors remain *abstracted* away!
- That is, we focus on these two *requirement*:

REQ1	The system is controlling cars on a bridge connecting the mainland to an island.
REQ3	The bridge is one-way or the other, not both at the same time.

- We are *obliged to prove* this *added concreteness* is *consistent* with  $m_0$ .

## Model $m_1$ : Refined State Space



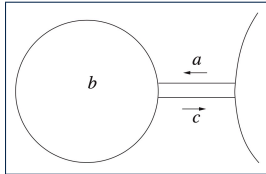
1. The **static** part is the same as  $m_0$ 's:

constants:  $d$

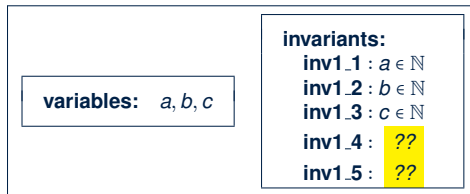
axioms:

axm0.1 :  $d \in \mathbb{N}$   
axm0.2 :  $d > 0$

2. The **dynamic** part of the **concrete state** consists of three **variables**:



- $a$ : number of cars on the bridge, heading to the island
- $b$ : number of cars on the island
- $c$ : number of cars on the bridge, heading to the mainland



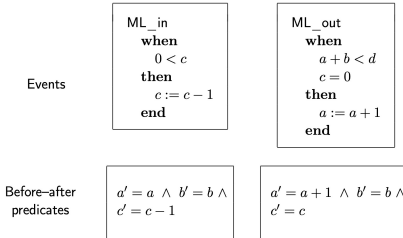
- ✓ inv1.1, inv1.2, inv1.3 are **typing** constraints.
- ✓ inv1.4 **links/glues** the **abstract** and **concrete** states.
- ✓ inv1.5 specifies that the bridge is one-way.

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## Model $m_1$ : Actions vs. Before-After Predicates



- Consider the **concrete/refined** version of **actions** of  $m_0$ 's two events:



- An event's **actions** are a **specification**: "c becomes c - 1 after the transition".
- The **before-after predicate (BAP)** " $c' = c - 1$ " expresses that  $c'$  (the **post-state** value of c) is one less than c (the **pre-state** value of c).
- Given that the **concrete state** consists of **three** variables:
  - An event's **actions** **only** specify those **changing** from **pre-state** to **post-state**. [ e.g.,  $c' = c - 1$  ]
  - Other **unmentioned** variables have their **post-state** values remain **unchanged**. [ e.g.,  $a' = a \wedge b' = b$  ]

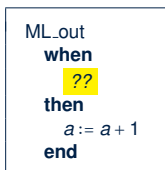
- When we express **proof obligations (POs)** associated with **events**, we use **BAP**.

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## Model $m_1$ : State Transitions via Events

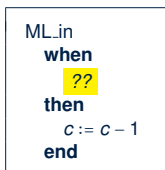


- The system acts as an **ABSTRACT STATE MACHINE (ASM)**: it **evolves** as **actions of enabled events** change values of variables, subject to **invariants**.
- We first consider the "old" **events** already existing in  $m_0$ .
- **Concrete/Refined** version of **event ML\_out**:



- Meaning of **ML\_out** is **refined**: a car **exits** mainland (getting on the bridge).
- **ML\_out** **enabled** only when:
  - the bridge's current traffic **flows to** the island
  - number of cars on both the bridge and the island is **limited**

- **Concrete/Refined** version of **event ML\_in**:



- Meaning of **ML\_in** is **refined**: a car **enters** mainland (getting off the bridge).
- **ML\_in** **enabled** only when: there is some car on the bridge heading to the mainland.

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## States & Invariants: Abstract vs. Concrete



- $m_0$  refines  $m_1$  by introducing more **variables**:

- **Abstract** State (of  $m_0$  being **refined**):

variables:  $n$

- **Concrete** State (of the **refinement** model  $m_1$ ):

variables:  $a, b, c$

- Accordingly, **invariants** may involve different **states**:

- **Abstract** Invariants (involving the **abstract** state **only**):

invariants:  
inv0.1 :  $n \in \mathbb{N}$   
inv0.2 :  $n \leq d$

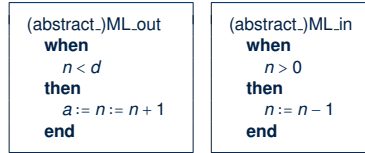
- **Concrete** Invariants (involving **at least** the **concrete** state):

invariants:  
inv1.1 :  $a \in \mathbb{N}$   
inv1.2 :  $b \in \mathbb{N}$   
inv1.3 :  $c \in \mathbb{N}$   
inv1.4 :  $a + b + c = n$   
inv1.5 :  $a = 0 \vee c = 0$

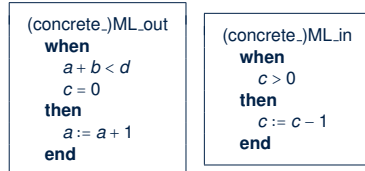
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## Events: Abstract vs. Concrete

- When an **event** exists in both models  $m_0$  and  $m_1$ , there are two versions of it:
  - The **abstract** version modifies the **abstract** state.



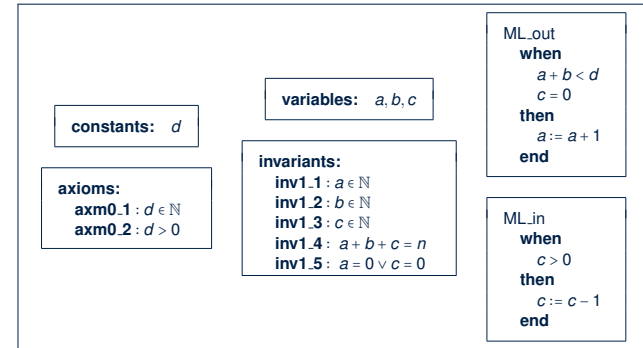
- The **concrete** version modifies the **concrete** state.



- A **new event** may only exist in  $m_1$  (the **concrete** model): we will deal with this kind of events later, separately from “redefined/overridden” events.

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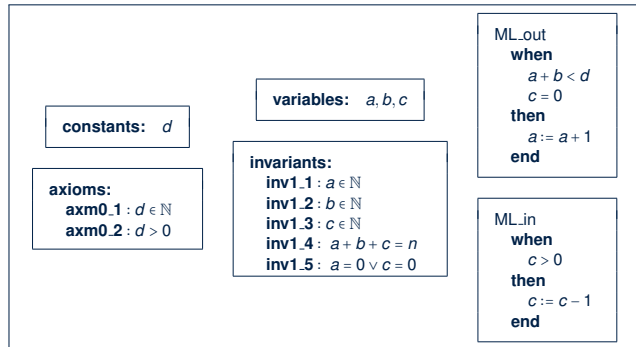
## PO of Refinement: Components (2)



- $G(c, v)$ : list of guards of the **abstract event**  
 $G(\langle d \rangle, \langle n \rangle)$  of  $ML\_out \cong \langle n < d \rangle$ ,  $G(c, v)$  of  $ML\_in \cong \langle n > 0 \rangle$
- $H(c, w)$ : list of guards of the **concrete event**  
 $H(\langle d \rangle, \langle a, b, c \rangle)$  of  $ML\_out \cong \langle a + b < d, c = 0 \rangle$ ,  $H(c, w)$  of  $ML\_in \cong \langle c > 0 \rangle$

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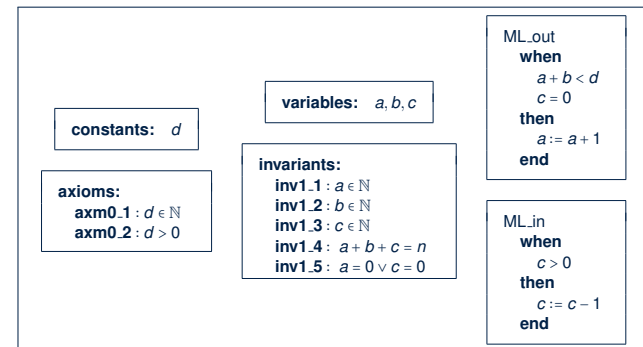
## PO of Refinement: Components (1)



- $c$ : list of **constants**  $\langle d \rangle$
- $A(c)$ : list of **axioms**  $\langle axm0.1 \rangle$
- $v$  and  $v'$ : **abstract variables** in pre- & post-states  $v \cong \langle n \rangle, v' \cong \langle n \rangle$
- $w$  and  $w'$ : **concrete variables** in pre- & post-states  $w \cong \langle a, b, c \rangle, w' \cong \langle a', b', c' \rangle$
- $I(c, v)$ : list of **abstract invariants**  $\langle inv0.1, inv0.2 \rangle$
- $J(c, v, w)$ : list of **concrete invariants**  $\langle inv1.1, inv1.2, inv1.3, inv1.4, inv1.5 \rangle$

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## PO of Refinement: Components (3)



- $E(c, v)$ : effect of the **abstract event**'s actions i.t.o. what variable values **become**  
 $E(\langle d \rangle, \langle n \rangle)$  of  $ML\_out \cong \langle n + 1 \rangle$ ,  $E(\langle d \rangle, \langle n \rangle)$  of  $ML\_out \cong \langle n - 1 \rangle$
- $F(c, w)$ : effect of the **concrete event**'s actions i.t.o. what variable values **become**  
 $F(c, v)$  of  $ML\_out \cong \langle a + 1, b, c \rangle$ ,  $F(c, w)$  of  $ML\_out \cong \langle a, b, c - 1 \rangle$

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## Sketching PO of Refinement

The PO/VC rule for a **proper refinement** consists of two parts:

### 1. Guard Strengthening

Axioms
<i>Abstract Invariants</i> Satisfied at <u>Pre-State</u>
<i>Concrete Invariants</i> Satisfied at <u>Pre-State</u>
<i>Guards</i> of the <i>Concrete Event</i>
⊢
<i>Guards</i> of the <i>Abstract Event</i>

GRD

- A **concrete** event is enabled if its **abstract** counterpart is enabled.
- A **concrete** transition always has an **abstract** counterpart.

### 2. Invariant Preservation

Axioms
<i>Abstract Invariants</i> Satisfied at <u>Pre-State</u>
<i>Concrete Invariants</i> Satisfied at <u>Pre-State</u>
<i>Guards</i> of the <i>Concrete Event</i>
⊢
<i>Concrete Invariants</i> Satisfied at <u>Post-State</u>

INV

- A **concrete** event performs a **transition** on **concrete** states.
- This **concrete** state **transition** must be consistent with how its **abstract** counterpart performs a corresponding **abstract transition**.

**Note.** *Guard strengthening* and *invariant preservation* are only applicable to events that might be **enabled** after the system is launched.

The special, non-guarded *init* event will be discussed separately later.

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## PO Rule: Guard Strengthening of $ML_{out}$

<i>axm0_1</i>	{	$d \in \mathbb{N}$
<i>axm0_2</i>	{	$d > 0$
<i>inv0_1</i>	{	$n \in \mathbb{N}$
<i>inv0_2</i>	{	$n \leq d$
<i>inv1_1</i>	{	$a \in \mathbb{N}$
<i>inv1_2</i>	{	$b \in \mathbb{N}$
<i>inv1_3</i>	{	$c \in \mathbb{N}$
<i>inv1_4</i>	{	$a + b + c = n$
<i>inv1_5</i>	{	$a = 0 \vee c = 0$
<i>Concrete guards of <math>ML_{out}</math></i>	{	$a + b < d$
	{	$c = 0$
	⊢	
<i>Abstract guards of <math>ML_{out}</math></i>	{	$n < d$

ML\_out/GRD

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## Refinement Rule: Guard Strengthening

- Based on the components, we are able to formally state the *PO/VC Rule of Guard Strengthening for Refinement*:

$A(c)$
$I(c, v)$
$J(c, v, w)$
$H(c, w)$
⊢
$G_i(c, v)$

GRD

where  $G_i$  denotes a single **guard** condition of the **abstract** event

- How many **sequents** to be proved? [ # **abstract** guards ]
- For  $ML_{out}$ , only one **abstract** guard, so one **sequent** is generated :

$d \in \mathbb{N}$	$d > 0$				
$n \in \mathbb{N}$	$n \leq d$				
$a \in \mathbb{N}$	$b \in \mathbb{N}$	$c \in \mathbb{N}$	$a + b + c = n$	$a = 0 \vee c = 0$	
$a + b < d$	$c = 0$				
⊢					
$n < d$					

ML\_out/GRD

- **Exercise.** Write  $ML_{in}$ 's *PO of Guard Strengthening for Refinement*.

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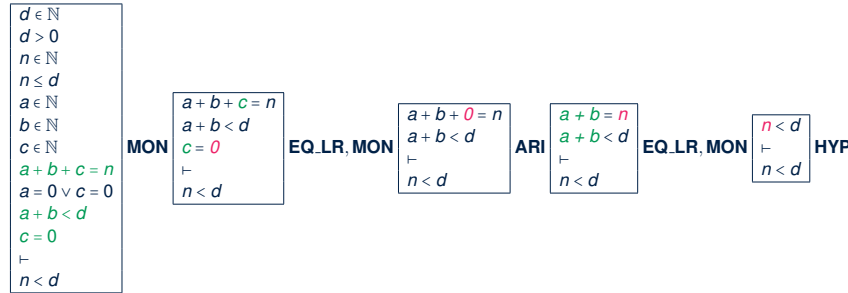
## PO Rule: Guard Strengthening of $ML_{in}$

<i>axm0_1</i>	{	$d \in \mathbb{N}$
<i>axm0_2</i>	{	$d > 0$
<i>inv0_1</i>	{	$n \in \mathbb{N}$
<i>inv0_2</i>	{	$n \leq d$
<i>inv1_1</i>	{	$a \in \mathbb{N}$
<i>inv1_2</i>	{	$b \in \mathbb{N}$
<i>inv1_3</i>	{	$c \in \mathbb{N}$
<i>inv1_4</i>	{	$a + b + c = n$
<i>inv1_5</i>	{	$a = 0 \vee c = 0$
<i>Concrete guards of <math>ML_{in}</math></i>	{	$c > 0$
	⊢	
<i>Abstract guards of <math>ML_{in}</math></i>	{	$n > 0$

ML\_in/GRD

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# Proving Refinement: ML\_out/GRD



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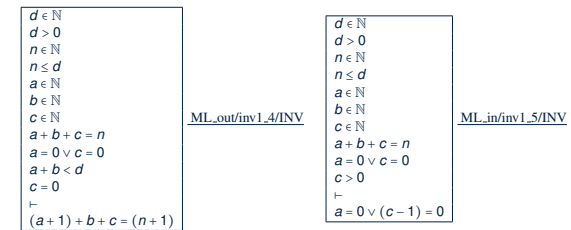
# Refinement Rule: Invariant Preservation



- Based on the components, we are able to formally state the *PO/VC Rule of Invariant Preservation for Refinement*:

$$\begin{array}{l}
 A(c) \\
 I(c, v) \\
 J(c, v, w) \\
 H(c, w) \\
 \vdash \\
 J_i(c, E(c, v), F(c, w))
 \end{array}
 \quad \text{INV} \quad \text{where } J_i \text{ denotes a single concrete invariant}$$

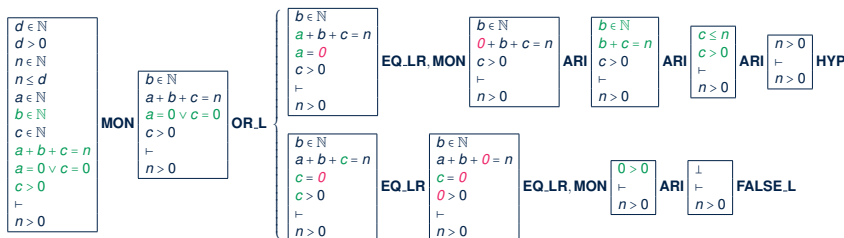
- How many *sequents* to be proved? [ # *concrete* evts × # *concrete* invariants ]
- Here are two (of the ten) *sequents* generated:



- Exercises.** Specify and prove other **eight** *POs of Invariant Preservation*.

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# Proving Refinement: ML\_in/GRD



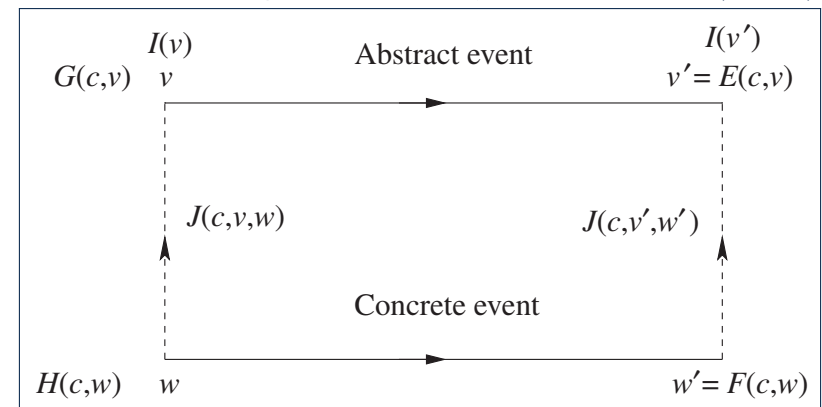
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# Visualizing Inv. Preservation in Refinement



Each *concrete* event ( $w$  to  $w'$ ) is *simulated* by an *abstract* event ( $v$  to  $v'$ ):

- abstract* & *concrete* pre-states related by *concrete* invariants  $J(c, v, w)$
- abstract* & *concrete* post-states related by *concrete* invariants  $J(c, v', w')$



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# INV PO of $m_1$ : ML\_out/inv1\_4/INV



axm0.1	{	$d \in \mathbb{N}$
axm0.2	{	$d > 0$
inv0.1	{	$n \in \mathbb{N}$
inv0.2	{	$n \leq d$
inv1.1	{	$a \in \mathbb{N}$
inv1.2	{	$b \in \mathbb{N}$
inv1.3	{	$c \in \mathbb{N}$
inv1.4	{	$a + b + c = n$
inv1.5	{	$a = 0 \vee c = 0$
<i>Concrete</i> guards of ML_out		{
		$a + b < d$
		$c = 0$
<i>Concrete</i> invariant inv1.4 with ML_out's effect in the post-state		{
		$(a + 1) + b + c = (n + 1)$

ML\_out/inv1\_4/INV

# Proving Refinement: ML\_out/inv1\_4/INV



$\begin{array}{l} d \in \mathbb{N} \\ d > 0 \\ n \in \mathbb{N} \\ n \leq d \\ a \in \mathbb{N} \\ b \in \mathbb{N} \\ c \in \mathbb{N} \\ a + b + c = n \\ a = 0 \vee c = 0 \\ a + b < d \\ c = 0 \\ \vdash \\ (a + 1) + b + c = (n + 1) \end{array}$	MON	$\begin{array}{l} a + b + c = n \\ \vdash \\ (a + 1) + b + c = (n + 1) \end{array}$	ARI	$\begin{array}{l} a + b + c = n \\ \vdash \\ a + b + c + 1 = n + 1 \end{array}$	EQ_LR, MON	$\vdash \\ n + 1 = n + 1$	EQ
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# INV PO of $m_1$ : ML\_in/inv1\_5/INV



axm0.1	{	$d \in \mathbb{N}$
axm0.2	{	$d > 0$
inv0.1	{	$n \in \mathbb{N}$
inv0.2	{	$n \leq d$
inv1.1	{	$a \in \mathbb{N}$
inv1.2	{	$b \in \mathbb{N}$
inv1.3	{	$c \in \mathbb{N}$
inv1.4	{	$a + b + c = n$
inv1.5	{	$a = 0 \vee c = 0$
<i>Concrete</i> guards of ML_in		{
		$c > 0$
<i>Concrete</i> invariant inv1.5 with ML_in's effect in the post-state		{
		$a = 0 \vee (c - 1) = 0$

ML\_in/inv1\_5/INV

# Proving Refinement: ML\_in/inv1\_5/INV



$\begin{array}{l} d \in \mathbb{N} \\ d > 0 \\ n \in \mathbb{N} \\ n \leq d \\ a \in \mathbb{N} \\ b \in \mathbb{N} \\ c \in \mathbb{N} \\ a + b + c = n \\ a = 0 \vee c = 0 \\ c > 0 \\ \vdash \\ a = 0 \vee (c - 1) = 0 \end{array}$	MON	$\begin{array}{l} a = 0 \vee c = 0 \\ c > 0 \\ \vdash \\ a = 0 \vee (c - 1) = 0 \end{array}$	OR_L	$\begin{array}{l} a = 0 \\ c > 0 \\ \vdash \\ a = 0 \vee (c - 1) = 0 \end{array}$	OR_R1	$\begin{array}{l} a = 0 \\ c > 0 \\ \vdash \\ a = 0 \end{array}$	HYP	$\begin{array}{l} 0 > 0 \\ \vdash \\ a = 0 \vee (0 - 1) = 0 \end{array}$	EQ_LR, MON	$\vdash \\ a = 0 \vee (0 - 1) = 0$	ARI	$\perp \\ \vdash \\ a = 0 \vee -1 = 0$	FALSE.L
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## Initializing the Refined System $m_1$



- Discharging the **twelve sequents** proved that:
  - concrete invariants** preserved by  $ML_{out}$  &  $ML_{in}$
  - concrete guards** of  $ML_{out}$  &  $ML_{in}$  entail their **abstract** counterparts
- What's left is the specification of how the **ASM**'s **initial state** looks like:

```

init
begin
  a := 0
  b := 0
  c := 0
end
    
```

- ✓ No cars on bridge (heading either way) and island
- ✓ Initialization always possible: guard is **true**.
- ✓ There is no **pre-state** for *init*.
  - ∴ The **RHS** of := must **not** involve variables.
  - ∴ The **RHS** of := may **only** involve constants.
- ✓ There is only the **post-state** for *init*.
  - ∴ Before-**After Predicate**:  $a' = 0 \wedge b' = 0 \wedge c' = 0$

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## Discharging PO of $m_1$ Concrete Invariant Establishment



- How many **sequents** to be proved? [ # **concrete** invariants ]
- Two (of the **five**) sequents generated for **concrete init** of  $m_1$ :

$$\frac{d \in \mathbb{N} \quad d > 0 \quad \vdash \quad 0 + 0 + 0 = 0}{\text{init/inv1\_4/INV}}$$

$$\frac{d \in \mathbb{N} \quad d > 0 \quad \vdash \quad 0 = 0 \vee 0 = 0}{\text{init/inv1\_5/INV}}$$

- Can we discharge the **PO**  $\text{init/inv1\_4/INV}$ ?
  - ARI, MON  $\vdash$  TRUE\_R ∴ **init/inv1\\_4/INV** succeeds in being discharged.
- Can we discharge the **PO**  $\text{init/inv1\_5/INV}$ ?
  - ARI, MON  $\vdash$  TRUE\_R ∴ **init/inv1\\_5/INV** succeeds in being discharged.

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## PO of $m_1$ Concrete Invariant Establishment



- Some (new) formal components are needed:
  - $K(c)$ : effect of **abstract init**'s actions:
    - e.g.,  $K(\langle d \rangle)$  of *init*  $\cong \langle 0 \rangle$
  - $v' = K(c)$ : **before-after predicate** formalizing **abstract init**'s actions
    - e.g., BAP of *init*:  $\langle n^* \rangle = \langle 0 \rangle$
  - $L(c)$ : effect of **concrete init**'s actions:
    - e.g.,  $K(\langle d \rangle)$  of *init*  $\cong \langle 0, 0, 0 \rangle$
  - $w' = L(c)$ : **before-after predicate** formalizing **concrete init**'s actions
    - e.g., BAP of *init*:  $\langle a', b', c' \rangle = \langle 0, 0, 0 \rangle$
- Accordingly, PO of **invariant establishment** is formulated as a **sequent**:

$$\frac{\text{Axioms} \quad \vdash \quad \text{Concrete Invariants Satisfied at Post-State}}{\text{INV}} \quad \frac{A(c) \quad \vdash \quad J_i(c, K(c), L(c))}{\text{INV}}$$

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## Model $m_1$ : New, Concrete Events



- The system acts as an **ABSTRACT STATE MACHINE (ASM)**: it **evolves** as **actions of enabled events** change values of variables, subject to **invariants**.
- Considered **concrete/refined events** already existing in  $m_0$ :  $ML_{out}$  &  $ML_{in}$
- New event**  $IL_{in}$ :

```

IL_in
when
  ??
then
  ??
end
    
```

- $IL_{in}$  denotes a car entering the island (getting off the bridge).
- $IL_{in}$  **enabled** only when:
  - The bridge's current traffic flows to the island.
  - Q.** Limited number of cars on the bridge and the island?
  - A.** Ensured when the earlier  $ML_{out}$  (of same car) occurred

- New event**  $IL_{out}$ :

```

IL_out
when
  ??
then
  ??
end
    
```

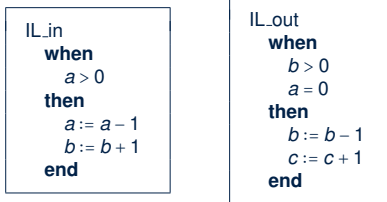
- $IL_{out}$  denotes a car exiting the island (getting on the bridge).
- $IL_{out}$  **enabled** only when:
  - There is some car on the island.
  - The bridge's current traffic flows to the mainland.

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## Model $m_1$ : BA Predicates of Multiple Actions



Consider *actions* of  $m_1$ 's two *new* events:



- What is the **BAP** of  $ML\_in$ 's *actions*?

$$a' = a - 1 \wedge b' = b + 1 \wedge c' = c$$

- What is the **BAP** of  $ML\_in$ 's *actions*?

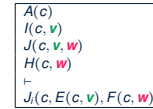
$$a' = a \wedge b' = b - 1 \wedge c' = c + 1$$

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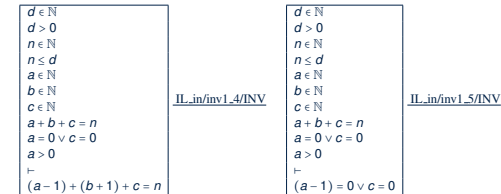
## Refinement Rule: Invariant Preservation



- The new events  $IL\_in$  and  $IL\_out$  do not exist in  $m_0$ , but:
  - They **exist** in  $m_1$  and may impact upon the **concrete** state space.
  - They **preserve** the **concrete invariants**, just as  $ML\_out$  &  $ML\_in$  do.
- Recall the **PO/VC Rule of Invariant Preservation for Refinement**:



- How many **sequents** to be proved? [ # *new* evts × # *concrete* invariants ]
- Here are **two** (of the **ten**) **sequents** generated:



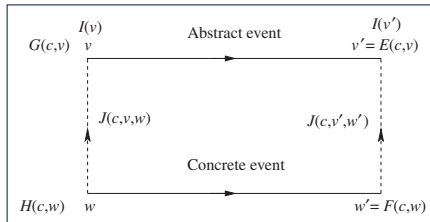
- Exercises.** Specify and prove other **eight POs of Invariant Preservation**.

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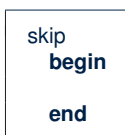
## Visualizing Inv. Preservation in Refinement



- Recall how a **concrete** event is **simulated** by its **abstract** counterpart:



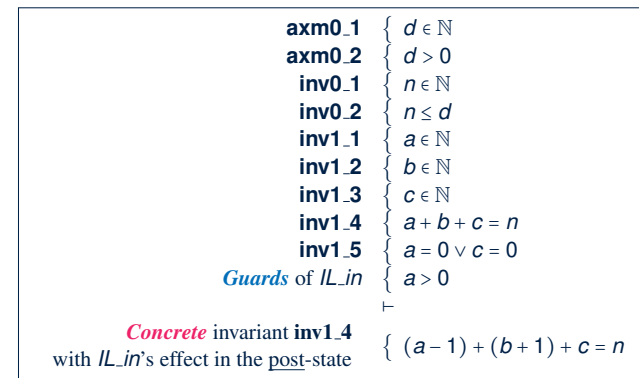
- For each **new** event:
  - Strictly speaking, it does **not** have an **abstract** counterpart.
  - It is **simulated** by a special **abstract** event (transforming  $v$  to  $v'$ ):



- $skip$  is a “dummy” event: **non-guarded** and does **nothing**
- Q. BAP** of the skip event?  
**A.**  $n' = n$

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## INV PO of $m_1$ : IL\_in/inv1\_4/INV



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# INV PO of $m_1$ : IL\_in/inv1\_5/INV



axm0.1	{	$d \in \mathbb{N}$
axm0.2	{	$d > 0$
inv0.1	{	$n \in \mathbb{N}$
inv0.2	{	$n \leq d$
inv1.1	{	$a \in \mathbb{N}$
inv1.2	{	$b \in \mathbb{N}$
inv1.3	{	$c \in \mathbb{N}$
inv1.4	{	$a + b + c = n$
inv1.5	{	$a = 0 \vee c = 0$

*Guards of IL\_in*

	{	$a > 0$
	}	$\vdash$
		$\{ (a - 1) = 0 \vee c = 0$

**IL\_in/inv1\_5/INV**

*Concrete invariant inv1.5*  
with *IL\_in*'s effect in the post-state

# Proving Refinement: IL\_in/inv1\_5/INV



$d \in \mathbb{N}$ $d > 0$ $n \in \mathbb{N}$ $n \leq d$ $a \in \mathbb{N}$ $b \in \mathbb{N}$ $c \in \mathbb{N}$ $a + b + c = n$ $a = 0 \vee c = 0$ $a > 0$ $\vdash$ $(a - 1) = 0 \vee c = 0$	MON	$a = 0 \vee c = 0$ $a > 0$ $\vdash$ $(a - 1) = 0 \vee c = 0$	OR.L	$a = 0$ $a > 0$ $\vdash$ $(a - 1) = 0 \vee c = 0$	EQ.LR.MON	$0 > 0$ $\vdash$ $(0 - 1) = 0 \vee c = 0$	ARI	$\vdash$ $-1 = 0 \vee c = 0$	FALSE.L
			OR.R2	$c = 0$ $a > 0$ $\vdash$ $(a - 1) = 0 \vee c = 0$			HYP	$c = 0$ $a > 0$ $c = 0$	

# Proving Refinement: IL\_in/inv1\_4/INV



$d \in \mathbb{N}$ $d > 0$ $n \in \mathbb{N}$ $n \leq d$ $a \in \mathbb{N}$ $b \in \mathbb{N}$ $c \in \mathbb{N}$ $a + b + c = n$ $a = 0 \vee c = 0$ $a > 0$ $\vdash$ $(a - 1) + (b + 1) + c = n$	MON	$a + b + c = n$ $\vdash$ $(a - 1) + (b + 1) + c = n$	ARI	$a + b + c = n$ $\vdash$ $a + b + c = n$	HYP
--	-----	--	-----	--	-----

# Livelock Caused by New Events Diverging



- An alternative  $m_1$  (with inv1.4, inv1.5, and guards of new events removed):

constants: $d$	axioms: axm0.1: $d \in \mathbb{N}$ axm0.2: $d > 0$	variables: $a, b, c$	invariants: inv1.1: $a \in \mathbb{Z}$ inv1.2: $b \in \mathbb{Z}$ inv1.3: $c \in \mathbb{Z}$
ML_out when $a + b < d$ $c = 0$ then $a := a + 1$ end	ML_in when $c > 0$ then $c := c - 1$ end	IL_in begin $a := a - 1$ $b := b + 1$ end	IL_out begin $b := b - 1$ $c := c + 1$ end

*Concrete invariants* are under-specified: only typing constraints.

**Exercises**: Show that Invariant Preservation is provable, but Guard Strengthening is not.

- Say this alternative  $m_1$  is implemented as is: *IL\_in* and *IL\_out* **always enabled** and may occur **indefinitely**, preventing other "old" events (*ML\_out* and *ML\_in*) from ever happening:  
 $\langle \text{init}, \text{IL\_in}, \text{IL\_out}, \text{IL\_in}, \text{IL\_out}, \dots \rangle$ 

**Q**: What are the corresponding **abstract** transitions?  
**A**:  $\langle \text{init}, \text{skip}, \text{skip}, \text{skip}, \text{skip}, \dots \rangle$  [  $\approx$  executing `while(true);` ]
- We say that these two **new** events **diverge**, creating a **livelock**:
  - Different from a **deadlock**: **always** an event occurring (*IL\_in* or *IL\_out*).
  - But their **indefinite** occurrences contribute **nothing** useful.

## PO of Convergence of New Events



The PO/VC rule for **non-divergence/livelock freedom** consists of two parts:

- Interleaving of **new** events characterized as an integer expression: **variant**.
- A variant  $V(c, w)$  may refer to constants and/or **concrete** variables.
- In the original  $m_1$ , let's try **variants** :  $2 \cdot a + b$

### 1. Variant Stays Non-Negative

$  \begin{array}{l}  A(c) \\  I(c, v) \\  J(c, v, w) \\  H(c, w) \\  \vdash \\  V(c, w) \in \mathbb{N}  \end{array}  $	$\text{NAT}$	<ul style="list-style-type: none"> <li>◦ Variant <math>V(c, w)</math> measures how many more times the <b>new</b> events can occur.</li> <li>◦ If a <b>new</b> event is <b>enabled</b>, then <math>V(c, w) &gt; 0</math>.</li> <li>◦ When <math>V(c, w)</math> reaches 0, some "old" events must happen s.t. <math>V(c, w)</math> goes back <u>above</u> 0.</li> </ul>
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### 2. A New Event Occurrence Decreases Variant

$  \begin{array}{l}  A(c) \\  I(c, v) \\  J(c, v, w) \\  H(c, w) \\  \vdash \\  V(c, F(c, w)) < V(c, w)  \end{array}  $	$\text{VAR}$	<ul style="list-style-type: none"> <li>◦ If a <b>new</b> event is <b>enabled</b> and occurs, the value of <math>V(c, w) \downarrow</math>.</li> </ul>
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## PO of Convergence of New Events: VAR



- Recall: PO related to **A New Event Occurrence Decreases Variant**

$  \begin{array}{l}  A(c) \\  I(c, v) \\  J(c, v, w) \\  H(c, w) \\  \vdash \\  V(c, F(c, w)) < V(c, w)  \end{array}  $	$\text{VAR}$	<p>How many <b>sequents</b> to be proved?</p> <p>[ # <b>new</b> events ]</p>
---	--------------	--

- For the **new** event  $IL\_in$ :

$  \begin{array}{l}  d \in \mathbb{N} \quad d > 0 \\  n \in \mathbb{N} \quad n \leq d \\  a \in \mathbb{N} \quad b \in \mathbb{N} \quad c \in \mathbb{N} \\  a + b + c = n \quad a = 0 \vee c = 0 \\  a > 0 \\  \vdash \\  2 \cdot (a - 1) + (b + 1) < 2 \cdot a + b  \end{array}  $	$\text{IL\_in/VAR}$
--	---------------------

**Exercises:** Prove  $IL\_in/VAR$  and Formulate/Prove  $IL\_out/VAR$ .

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## PO of Convergence of New Events: NAT



- Recall: PO related to **Variant Stays Non-Negative**:

$  \begin{array}{l}  A(c) \\  I(c, v) \\  J(c, v, w) \\  H(c, w) \\  \vdash \\  V(c, w) \in \mathbb{N}  \end{array}  $	$\text{NAT}$	<p>How many <b>sequents</b> to be proved?</p> <p>[ # <b>new</b> events ]</p>
--	--------------	--

- For the **new** event  $IL\_in$ :

$  \begin{array}{l}  d \in \mathbb{N} \quad d > 0 \\  n \in \mathbb{N} \quad n \leq d \\  a \in \mathbb{N} \quad b \in \mathbb{N} \quad c \in \mathbb{N} \\  a + b + c = n \quad a = 0 \vee c = 0 \\  a > 0 \\  \vdash \\  2 \cdot a + b \in \mathbb{N}  \end{array}  $	$\text{IL\_in/NAT}$
---	---------------------

**Exercises:** Prove  $IL\_in/NAT$  and Formulate/Prove  $IL\_out/NAT$ .

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## Convergence of New Events: Exercise



Given the original  $m_1$ , what if the following **variant** expression is used:

**variants** :  $a + b$

Are the formulated sequents still **provable**?

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# PO of Refinement: Deadlock Freedom



- Recall:
  - We proved that the initial model  $m_0$  is deadlock free (see **DLF**).
  - We proved, according to **guard strengthening**, that if a **concrete** event is enabled, then its **abstract** counterpart is enabled.
- PO of **relative deadlock freedom** for a **refinement** model:

$\begin{array}{l} A(c) \\ I(c, v) \\ J(c, v, w) \\ G_1(c, v) \vee \dots \vee G_m(c, v) \\ \vdash \\ H_1(c, w) \vee \dots \vee H_n(c, w) \end{array}$	DLF	If an <b>abstract</b> state does <u>not</u> <b>deadlock</b> (i.e., $G_1(c, v) \vee \dots \vee G_m(c, v)$ ), then its <b>concrete</b> counterpart does <u>not</u> <b>deadlock</b> (i.e., $H_1(c, w) \vee \dots \vee H_n(c, w)$ ).
--	-----	--

- Another way to think of the above PO:
  - The **refinement** does not introduce, in the **concrete**, any “new” **deadlock** scenarios not existing in the **abstract** state.

# Example Inference Rules (6)



$$\frac{H, \neg P \vdash Q}{H \vdash P \vee Q} \text{ OR.R}$$

To prove a **disjunctive goal**, it suffices to prove one of the disjuncts, with the negation of the other disjunct serving as an additional hypothesis.

$$\frac{H, P, Q \vdash R}{H, P \wedge Q \vdash R} \text{ AND.L}$$

To prove a goal with a **conjunctive hypothesis**, it suffices to prove the same goal, with the two conjuncts serving as two separate hypotheses.

$$\frac{H \vdash P \quad H \vdash Q}{H \vdash P \wedge Q} \text{ AND.R}$$

To prove a goal with a **conjunctive goal**, it suffices to prove each conjunct as a separate goal.

# PO Rule: Relative Deadlock Freedom $m_1$



$\begin{array}{l} \text{axm0.1} \\ \text{axm0.2} \\ \text{inv0.1} \\ \text{inv0.2} \\ \text{inv1.1} \\ \text{inv1.2} \\ \text{inv1.3} \\ \text{inv1.4} \\ \text{inv1.5} \end{array} \left\{ \begin{array}{l} d \in \mathbb{N} \\ d > 0 \\ n \in \mathbb{N} \\ n \leq d \\ a \in \mathbb{N} \\ b \in \mathbb{N} \\ c \in \mathbb{N} \\ a + b + c = n \\ a = 0 \vee c = 0 \end{array} \right.$	DLF	$\begin{array}{l} \left. \begin{array}{l} n < d \\ n > 0 \end{array} \right\} \begin{array}{l} \text{guards of } ML\_out \text{ in } m_0 \\ \text{guards of } ML\_in \text{ in } m_0 \end{array} \\ \vdash \\ \left. \begin{array}{l} a + b < d \wedge c = 0 \\ c > 0 \\ a > 0 \\ b > 0 \wedge a = 0 \end{array} \right\} \begin{array}{l} \text{guards of } ML\_out \text{ in } m_1 \\ \text{guards of } ML\_in \text{ in } m_1 \\ \text{guards of } IL\_in \text{ in } m_1 \\ \text{guards of } IL\_out \text{ in } m_1 \end{array} \end{array}$
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Disjunction of **abstract** guards

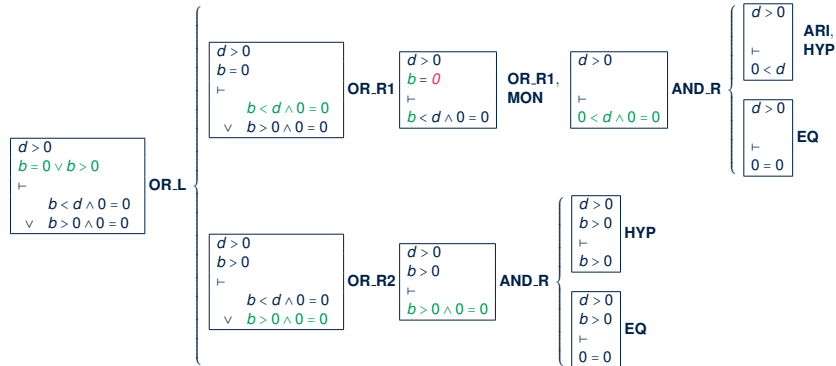
Disjunction of **concrete** guards

# Proving Refinement: DLF of $m_1$



$\begin{array}{l} d \in \mathbb{N} \\ d > 0 \\ n \in \mathbb{N} \\ n \leq d \\ a \in \mathbb{N} \\ b \in \mathbb{N} \\ c \in \mathbb{N} \\ a + b + c = n \\ a = 0 \vee c = 0 \\ n < d \vee n > 0 \\ \vdash \\ a + b < d \wedge c = 0 \\ \vee c > 0 \\ \vee a > 0 \\ \vee b > 0 \wedge a = 0 \end{array}$		$\begin{array}{l} d > 0 \\ a \in \mathbb{N} \\ b \in \mathbb{N} \\ c = 0 \\ \vdash \\ a + b < d \wedge c = 0 \\ \vee c > 0 \\ \vee a > 0 \\ \vee b > 0 \wedge a = 0 \end{array}$	OR.R, ARI	$\begin{array}{l} d > 0 \\ a \in \mathbb{N} \\ b \in \mathbb{N} \\ \vdash \\ a + b < d \wedge 0 = 0 \\ \vee 0 > 0 \\ \vee a > 0 \\ \vee b > 0 \wedge a = 0 \end{array}$	EQ.LR, MON	$\begin{array}{l} d > 0 \\ a = 0 \\ b \in \mathbb{N} \\ \vdash \\ a + b < d \wedge 0 = 0 \\ \vee b > 0 \wedge a = 0 \end{array}$	OR.R, ARI	$\begin{array}{l} d > 0 \\ b \in \mathbb{N} \\ \vdash \\ 0 + b < d \wedge 0 = 0 \\ \vee b > 0 \wedge 0 = 0 \end{array}$	EQ.LR, MON	$\begin{array}{l} d > 0 \\ b = 0 \vee b > 0 \\ \vdash \\ b < d \wedge 0 = 0 \\ \vee b > 0 \wedge 0 = 0 \end{array}$	ARI	$\dots$
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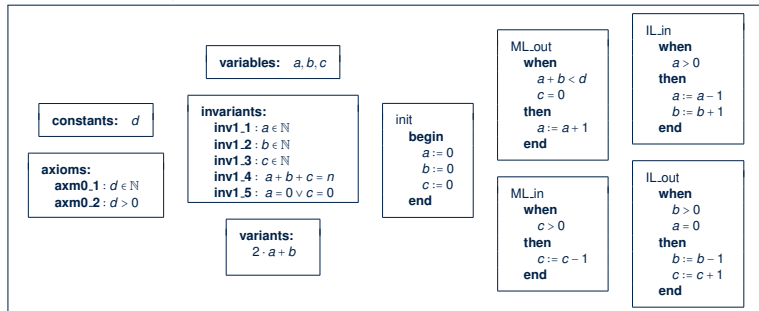
# Proving Refinement: DLF of $m_1$ (continued)



# First Refinement: Summary



- The final version of our **first refinement**  $m_1$  is **provably correct** w.r.t.:
  - Establishment of **Concrete Invariants** [ *init* ]
  - Preservation of **Concrete Invariants** [ old & new events ]
  - Strengthening of **guards** [ old events ]
  - Convergence** (a.k.a. livelock freedom, non-divergence) [ new events ]
  - Relative **Deadlock Freedom**
- Here is the final specification of  $m_1$ :



# Model $m_2$ : “More Concrete” Abstraction

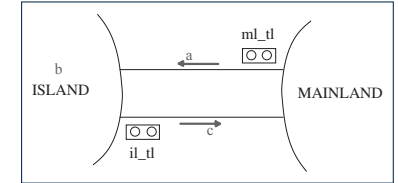


- 2nd **refinement** has even **more concrete** perception of the bridge controller:
  - We “**zoom in**” by observing the system from **even closer to the ground**, so that the one-way traffic of the bridge is controlled via:

**ml\_tl**: a traffic light for exiting the ML

**il\_tl**: a traffic light for exiting the IL

**abstract** variables **a, b, c** from  $m_1$  still used (instead of being replaced)



- Nonetheless, sensors remain **abstracted** away!

- That is, we focus on these three **environment constraints**:

ENV1	The system is equipped with two traffic lights with two colors: green and red.
ENV2	The traffic lights control the entrance to the bridge at both ends of it.
ENV3	Cars are not supposed to pass on a red traffic light, only on a green one.

- We are **obliged to prove** this **added concreteness** is **consistent** with  $m_1$ .

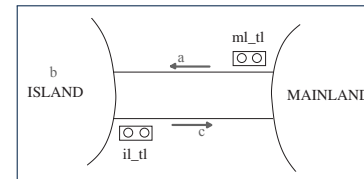
# Model $m_2$ : Refined, Concrete State Space



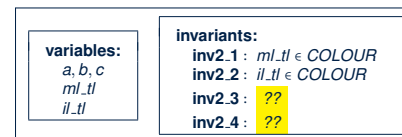
- The **static** part introduces the notion of traffic light colours:



- The **dynamic** part shows the **superposition refinement** scheme:



- Abstract** variables **a, b, c** from  $m_1$  are still in use in  $m_2$ .
- Two new, **concrete** variables are introduced: **ml\_tl** and **il\_tl**
- Constrat**: In  $m_1$ , **abstract** variable **n** is replaced by **concrete** variables **a, b, c**.



- inv2.1** & **inv2.2**: typing constraints
- inv2.3**: being allowed to exit ML **means** cars within **limit** and **no** opposite traffic
- inv2.4**: being allowed to exit IL **means** some car in IL and **no** opposite traffic



## Model $m_2$ : Refining Old, Abstract Events



- The system acts as an **ABSTRACT STATE MACHINE (ASM)**: it *evolves* as *actions of enabled events* change values of variables, subject to *invariants*.
- Concrete/Refined** version of event  $ML\_out$ :
  - Recall the **abstract** guard of  $ML\_out$  in  $m_1$ :  $(c = 0) \wedge (a + b < d)$ 
    - $\Rightarrow$  **Unrealistic** as drivers should **not** know about  $a, b, c$ !
  - $ML\_out$  is **refined**: a car **exits** the ML (to the bridge) only when:
    - the traffic light  $ml\_tl$  allows
- Concrete/Refined** version of event  $IL\_out$ :

```
ML_out
when
  ??
then
  a := a + 1
end
```

```
IL_out
when
  ??
then
  b := b - 1
  c := c + 1
end
```

**Q1.** How about the other two “old” events  $IL\_in$  and  $ML\_in$ ?

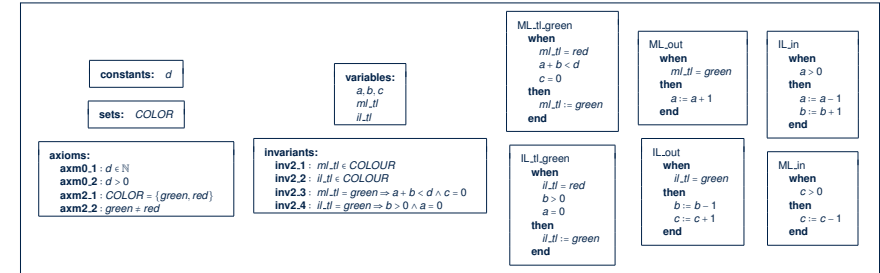
**A1.** No need to **refine** as already **guarded** by  $ML\_out$  and  $IL\_out$ .

**Q2.** What if the driver disobeys  $ml\_tl$  or  $il\_tl$ ?

[ **A2.** ENV3 ]

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## Invariant Preservation in Refinement $m_2$



Recall the **PO/VC Rule of Invariant Preservation for Refinement**:

```
A(c)
I(c, v)
J(c, v, w)
H(c, w)
┌
J_i(c, E(c, v), F(c, w))
```

$INV$  where  $J_i$  denotes a **single concrete invariant**

- How many **sequents** to be proved? [ # **concrete** evts  $\times$  # **concrete** invariants =  $6 \times 4$  ]
- We discuss two sequents:  $ML\_out/inv2.4/INV$  and  $IL\_out/inv2.3/INV$

**Exercises.** Specify and prove (some of) other **twenty-two POs of Invariant Preservation**.

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## Model $m_2$ : New, Concrete Events



- The system acts as an **ABSTRACT STATE MACHINE (ASM)**: it *evolves* as *actions of enabled events* change values of variables, subject to *invariants*.
- Considered **events** **already** existing in  $m_1$ :
  - $ML\_out$  &  $IL\_out$  [ **REFINED** ]
  - $IL\_in$  &  $ML\_in$  [ **UNCHANGED** ]
- New event**  $ML\_tl\_green$ :

```
ML_tl_green
when
  ??
then
  ml_tl := green
end
```

- $ML\_tl\_green$  denotes the traffic light  $ml\_tl$  turning green.
  - $ML\_tl\_green$  **enabled** only when:
    - the traffic light **not** already green
    - limited** number of cars on the **bridge** and the **island**
    - No** opposite traffic
- [  $\Rightarrow ML\_out$ 's **abstract** guard in  $m_1$  ]

- New event**  $IL\_tl\_green$ :

```
IL_tl_green
when
  ??
then
  il_tl := green
end
```

- $IL\_tl\_green$  denotes the traffic light  $il\_tl$  turning green.
  - $IL\_tl\_green$  **enabled** only when:
    - the traffic light **not** already green
    - some** cars on the island (i.e., island **not** empty)
    - No** opposite traffic
- [  $\Rightarrow IL\_out$ 's **abstract** guard in  $m_1$  ]

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## INV PO of $m_2$ : $ML\_out/inv2.4/INV$



```
axm0.1 { d ∈ ℕ
axm0.2 { d > 0
axm2.1 { COLOUR = {green, red}
axm2.2 { green ≠ red
inv0.1 { n ∈ ℕ
inv0.2 { n ≤ d
inv1.1 { a ∈ ℕ
inv1.2 { b ∈ ℕ
inv1.3 { c ∈ ℕ
inv1.4 { a + b + c = n
inv1.5 { a = 0 ∨ c = 0
inv2.1 { ml_tl ∈ COLOUR
inv2.2 { il_tl ∈ COLOUR
inv2.3 { ml_tl = green ⇒ a + b < d ∧ c = 0
inv2.4 { il_tl = green ⇒ b > 0 ∧ a = 0
Concrete guards of ML_out { ml_tl = green
Concrete invariant inv2.4 { il_tl = green ⇒ b > 0 ∧ (a + 1) = 0
with ML_out's effect in the post-state
```

$ML\_out/inv2.4/INV$

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# INV PO of $m_2$ : IL\_out/inv2\_3/INV



axm0.1	$d \in \mathbb{N}$
axm0.2	$d > 0$
axm2.1	$COLOUR = \{green, red\}$
axm2.2	$green = red$
inv0.1	$n \in \mathbb{N}$
inv0.2	$n \leq d$
inv1.1	$a \in \mathbb{N}$
inv1.2	$b \in \mathbb{N}$
inv1.3	$c \in \mathbb{N}$
inv1.4	$a + b + c = n$
inv1.5	$a = 0 \vee c = 0$
inv2.1	$ml,tl \in COLOUR$
inv2.2	$il,tl \in COLOUR$
inv2.3	$ml,tl = green \Rightarrow a + b < d \wedge c = 0$
inv2.4	$il,tl = green \Rightarrow b > 0 \wedge a = 0$

Concrete guards of IL\_out

Concrete invariant inv2.3 with ML\_out's effect in the post-state

$$\{ ml,tl = green \Rightarrow a + (b - 1) < d \wedge (c + 1) = 0 \}$$

## IL\_out/inv2\_3/INV

# Proving ML\_out/inv2\_4/INV: First Attempt



```

d < N
d > 0
COLOUR = {green, red}
green = red
n < N
n <= d
a < N
b < N
c < N
a + b + c = n
a = 0 v c = 0
ml,tl < COLOUR
il,tl < COLOUR
ml,tl = green => a + b < d ^ c = 0
il,tl = green => b > 0 ^ a = 0
ml,tl = green
il,tl = green => b > 0 ^ (a + 1) = 0
    
```

MON

green = red  
b > 0  
a = 0  
ml,tl = green  
il,tl = green  
b > 0

IMP\_R

green = red  
il,tl = green => b > 0 ^ a = 0  
ml,tl = green  
il,tl = green  
b > 0 ^ (a + 1) = 0

IMP\_L

green = red  
b > 0 ^ a = 0  
ml,tl = green  
il,tl = green  
b > 0 ^ (a + 1) = 0

AND\_L

green = red  
b > 0  
a = 0  
ml,tl = green  
il,tl = green  
b > 0 ^ (a + 1) = 0

AND\_R

green = red  
b > 0  
a = 0  
ml,tl = green  
il,tl = green  
b > 0

HYP

green = red  
b > 0  
a = 0  
ml,tl = green  
il,tl = green  
b > 0

EQ.LR MON

green = red  
ml,tl = green  
il,tl = green  
b > 0  
a = 0  
ml,tl = green  
il,tl = green  
b > 0  
(a + 1) = 0

ARI

green = red  
ml,tl = green  
il,tl = green  
b > 0  
a = 0  
ml,tl = green  
il,tl = green  
b > 0  
1 = 0

??

# Example Inference Rules (7)



$$\frac{H, P, Q \vdash R}{H, P, P \Rightarrow Q \vdash R} \text{IMP\_L}$$

If a hypothesis  $P$  matches the assumption of another *implicative hypothesis*  $P \Rightarrow Q$ , then the conclusion  $Q$  of the *implicative hypothesis* can be used as a new hypothesis for the sequent.

$$\frac{H, P \vdash Q}{H \vdash P \Rightarrow Q} \text{IMP\_R}$$

To prove an *implicative goal*  $P \Rightarrow Q$ , it suffices to prove its conclusion  $Q$ , with its assumption  $P$  serving as a new hypotheses.

$$\frac{H, \neg Q \vdash P}{H, \neg P \vdash Q} \text{NOT\_L}$$

To prove a goal  $Q$  with a *negative hypothesis*  $\neg P$ , it suffices to prove the negated hypothesis  $\neg(\neg P) \equiv P$  with the negated original goal  $\neg Q$  serving as a new hypothesis.

# Proving IL\_out/inv2\_3/INV: First Attempt



```

d < N
d > 0
COLOUR = {green, red}
green = red
n < N
n <= d
a < N
b < N
c < N
a + b + c = n
a = 0 v c = 0
ml,tl < COLOUR
il,tl < COLOUR
ml,tl = green => a + b < d ^ c = 0
il,tl = green => b > 0 ^ a = 0
ml,tl = green
il,tl = green => a + (b - 1) < d ^ (c + 1) = 0
    
```

MON

green = red  
ml,tl = green => a + b < d ^ c = 0  
il,tl = green  
ml,tl = green => a + (b - 1) < d ^ (c + 1) = 0

IMP\_R

green = red  
ml,tl = green => a + b < d ^ c = 0  
il,tl = green  
ml,tl = green  
a + (b - 1) < d ^ (c + 1) = 0

IMP\_L

green = red  
a + b < d ^ c = 0  
ml,tl = green  
il,tl = green  
a + (b - 1) < d ^ (c + 1) = 0

AND\_L

green = red  
a + b < d  
c = 0  
ml,tl = green  
il,tl = green  
a + (b - 1) < d ^ (c + 1) = 0

AND\_R

green = red  
a + b < d  
c = 0  
ml,tl = green  
il,tl = green  
a + (b - 1) < d

MON

green = red  
ml,tl = green  
il,tl = green  
a + b < d  
a + (b - 1) < d

ARI

green = red  
ml,tl = green  
il,tl = green  
a + b < d  
a + (b - 1) < d

EQ.LR MON

green = red  
ml,tl = green  
il,tl = green  
a + b < d  
c = 0  
ml,tl = green  
il,tl = green  
a + (b - 1) < d  
(c + 1) = 0

ARI

green = red  
ml,tl = green  
il,tl = green  
a + b < d  
c = 0  
ml,tl = green  
il,tl = green  
(c + 1) = 0

ARI

green = red  
ml,tl = green  
il,tl = green  
a + b < d  
c = 0  
ml,tl = green  
il,tl = green  
1 = 0

??

## Failed: ML\_out/inv2\_4/INV, IL\_out/inv2\_3/INV



- Our first attempts of proving *ML\_out/inv2\_4/INV* and *IL\_out/inv2\_3/INV* both failed the 2nd case (resulted from applying IR **AND\_R**):

$$green \neq red \wedge il\_tl = green \wedge ml\_tl = green \vdash 1 = 0$$

- This **unprovable** sequent gave us a good hint:
  - Goal  $1 = 0 \equiv \text{false}$  suggests that the **safety requirements**  $a = 0$  (for *inv2.4*) and  $c = 0$  (for *inv2.3*) **contradict** with the current  $m_2$ .
  - Hyp.  $il\_tl = green = ml\_tl$  suggests a **possible, dangerous state** of  $m_2$ , where two cars heading different directions are on the one-way bridge:

init	ML_tl_green	ML_out	IL_in	IL_tl_green	IL_out	ML_out
$d = 2$	$d = 2$	$d = 2$	$d = 2$	$d = 2$	$d = 2$	$d = 2$
$a' = 0$	$a' = 0$	$a' = 1$	$a' = 0$	$a' = 0$	$a' = 0$	$a' = 1$
$b' = 0$	$b' = 0$	$b' = 0$	$b' = 1$	$b' = 1$	$b' = 0$	$b' = 0$
$c' = 0$	$c' = 0$	$c' = 0$	$c' = 0$	$c' = 0$	$c' = 1$	$c' = 1$
$ml\_tl' = red$	$ml\_tl' = green$	$ml\_tl' = green$	$ml\_tl' = green$	$ml\_tl' = green$	$ml\_tl' = green$	$ml\_tl' = green$
$il\_tl' = red$	$il\_tl' = red$	$il\_tl' = red$	$il\_tl' = red$	$il\_tl' = green$	$il\_tl' = green$	$il\_tl' = green$

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## INV PO of $m_2$ : ML\_out/inv2\_4/INV – Updated



axm0.1	$d \in \mathbb{N}$
axm0.2	$d > 0$
axm2.1	$COLOUR = \{green, red\}$
axm2.2	$green \neq red$
inv0.1	$n \in \mathbb{N}$
inv0.2	$n \leq d$
inv1.1	$a \in \mathbb{N}$
inv1.2	$b \in \mathbb{N}$
inv1.3	$c \in \mathbb{N}$
inv1.4	$a + b + c = n$
inv1.5	$a = 0 \vee c = 0$
inv2.1	$ml\_tl \in COLOUR$
inv2.2	$il\_tl \in COLOUR$
inv2.3	$ml\_tl = green \Rightarrow a + b < d \wedge c = 0$
inv2.4	$il\_tl = green \Rightarrow b > 0 \wedge a = 0$
inv2.5	$ml\_tl = red \vee il\_tl = red$
	$ml\_tl = green$
	$\vdash$
	$il\_tl = green \Rightarrow b > 0 \wedge (a + 1) = 0$

Concrete guards of ML\_out

Concrete invariant inv2.4 with ML\_out's effect in the post-state

ML\_out/inv2\_4/INV

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## Fixing $m_2$ : Adding an Invariant



- Having understood the failed proofs, we add a proper **invariant** to  $m_2$ :

invariants:

$$\dots$$

$$\text{inv2.5} : ml\_tl = red \vee il\_tl = red$$

- We have effectively resulted in an improved  $m_2$  more faithful w.r.t. **REQ3**:

REQ3	The bridge is one-way or the other, not both at the same time.
------	--

- Having added this new invariant **inv2.5**:
  - Original  $6 \times 4$  generated sequents to be updated: **inv2.5** a new hypothesis e.g., Are *ML\_out/inv2\_4/INV* and *IL\_out/inv2\_3/INV* now **provable**?
  - Additional  $6 \times 1$  sequents to be generated due to this new invariant e.g., Are *ML\_tl\_green/inv2.5/INV* and *IL\_tl\_green/inv2.5/INV* **provable**?

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## INV PO of $m_2$ : IL\_out/inv2\_3/INV – Updated



axm0.1	$d \in \mathbb{N}$
axm0.2	$d > 0$
axm2.1	$COLOUR = \{green, red\}$
axm2.2	$green \neq red$
inv0.1	$n \in \mathbb{N}$
inv0.2	$n \leq d$
inv1.1	$a \in \mathbb{N}$
inv1.2	$b \in \mathbb{N}$
inv1.3	$c \in \mathbb{N}$
inv1.4	$a + b + c = n$
inv1.5	$a = 0 \vee c = 0$
inv2.1	$ml\_tl \in COLOUR$
inv2.2	$il\_tl \in COLOUR$
inv2.3	$ml\_tl = green \Rightarrow a + b < d \wedge c = 0$
inv2.4	$il\_tl = green \Rightarrow b > 0 \wedge a = 0$
inv2.5	$ml\_tl = red \vee il\_tl = red$
	$il\_tl = green$
	$\vdash$
	$ml\_tl = green \Rightarrow a + (b - 1) < d \wedge (c + 1) = 0$

Concrete guards of IL\_out

Concrete invariant inv2.3 with ML\_out's effect in the post-state

IL\_out/inv2\_3/INV

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# Proving ML\_out/inv2\_4/INV: Second Attempt



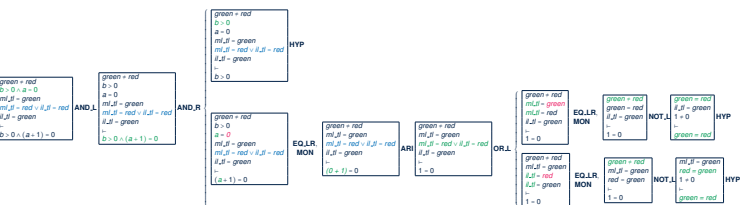
```

d ∈ N
d > 0
COLOUR = { green, red }
green ≠ red
n ∈ N
n ≤ d
a ∈ N
a ≤ b
c ∈ N
a + b = c + n
a + b < c = 0
mL ∈ COLOUR
iL ∈ COLOUR
mL ≠ green ⇒ a + b < d & c = 0
iL ≠ green ⇒ b > 0 & a = 0
mL ≠ red ∨ iL ≠ red
mL = green
=
iL ≠ green ⇒ b > 0 & (a + 1) = 0
    
```

```

MON
green = red
iL ≠ green ⇒ b > 0 & a = 0
mL ≠ red ∨ iL ≠ red
mL = green
=
iL ≠ green ⇒ b > 0 & (a + 1) = 0
    
```

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# Fixing m2: Adding Actions



- Recall that an *invariant* was added to  $m_2$ :

```

invariants:
inv2.5 : mL.tl = red ∨ iL.tl = red
    
```

- Additional  $6 \times 1$  sequents to be generated due to this new invariant:
  - e.g.,  $ML\_tl\_green/inv2\_5/INV$  [ for  $ML\_tl\_green$  to preserve  $inv2.5$  ]
  - e.g.,  $IL\_tl\_green/inv2\_5/INV$  [ for  $IL\_tl\_green$  to preserve  $inv2.5$  ]
- For the above *sequents* to be *provable*, we need to revise the two events:

```

ML.tl.green
when
  mL.tl = red
  a + b < d
  c = 0
then
  mL.tl := green
  iL.tl := red
end
    
```

```

IL.tl.green
when
  iL.tl = red
  b > 0
  a = 0
then
  iL.tl := green
  mL.tl := red
end
    
```

**Exercise:** Specify and prove  $ML\_tl\_green/inv2\_5/INV$  &  $IL\_tl\_green/inv2.5/INV$ .

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# Proving IL\_out/inv2\_3/INV: Second Attempt



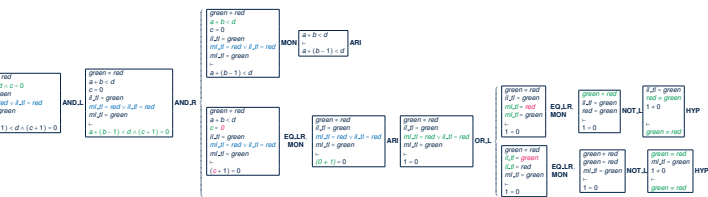
```

d ∈ N
d > 0
COLOUR = { green, red }
green ≠ red
n ∈ N
n ≤ d
a ∈ N
a ≤ b
c ∈ N
a + b = c + n
a + b < c = 0
mL ∈ COLOUR
iL ∈ COLOUR
mL ≠ green ⇒ a + b < d & c = 0
iL ≠ green ⇒ b > 0 & a = 0
mL ≠ red ∨ iL ≠ red
mL = green
=
iL ≠ green ⇒ a + (b - 1) < d & (c + 1) = 0
    
```

```

MON
green = red
mL ≠ green ⇒ a + b < d & c = 0
iL ≠ red ∨ iL ≠ red
iL = green
=
mL ≠ green ⇒ a + (b - 1) < d & (c + 1) = 0
    
```

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# INV PO of m2: ML\_out/inv2\_3/INV



<pre> axm0.1  d ∈ N axm0.2  d &gt; 0 axm2.1  COLOUR = { green, red } axm2.2  green ≠ red inv0.1  n ∈ N inv0.2  n ≤ d inv1.1  a ∈ N inv1.2  b ∈ N inv1.3  c ∈ N inv1.4  a + b + c = n inv1.5  a = 0 ∨ c = 0 inv2.1  mL.tl ∈ COLOUR inv2.2  iL.tl ∈ COLOUR inv2.3  mL.tl = green ⇒ a + b &lt; d ∧ c = 0 inv2.4  iL.tl = green ⇒ b &gt; 0 ∧ a = 0 inv2.5  mL.tl = red ∨ iL.tl = red mL.tl = green                 </pre>	<p><i>Concrete</i> guards of <math>ML.out</math></p> <p><i>Concrete</i> invariant <math>inv2.3</math> with <math>ML.out</math>'s effect in the post-state</p>	$\{ mL.tl = green \Rightarrow (a + 1) + b < d \wedge c = 0$
---	---	---

ML\_out/inv2\_3/INV

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# Proving ML\_out/inv2\_3/INV: First Attempt



```

d ∈ ℕ
d > 0
COLOUR = {green, red}
green ≠ red
n ∈ ℕ
n ≤ d
a ∈ ℕ
b ∈ ℕ
c ∈ ℕ
a + b + c = n
a = 0 ∨ c = 0
ml_tl ∈ COLOUR
il_tl ∈ COLOUR
ml_tl = green ⇒ a + b < d ∧ c = 0
il_tl = green ⇒ b > 0 ∧ a = 0
ml_tl = red ∨ il_tl = red
ml_tl = green
⊢
ml_tl = green ⇒ (a + 1) + b < d ∧ c = 0
    
```

MON



# Failed: ML\_out/inv2\_3/INV



- Our first attempt of proving *ML\_out/inv2\_3/INV* failed the 1st case (resulted from applying IR **AND.R**):

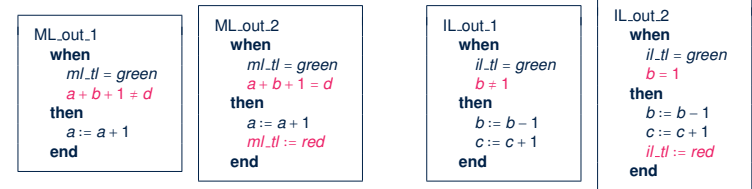
$$a + b < d \wedge c = 0 \wedge ml\_tl = green \vdash (a + 1) + b < d$$

- This **unprovable** sequent gave us a good hint:
  - Goal  $(a+1) + b < d$  specifies the **capacity requirement**.
  - Hypothesis  $c = 0 \wedge ml\_tl = green$  assumes that it's safe to exit the ML.
  - Hypothesis  $a + b < d$  is **not** strong enough to entail  $(a + 1) + b < d$ .
    - e.g.,  $d = 3, b = 0, a = 0$  [ $(a + 1) + b < d$  evaluates to **true**]
    - e.g.,  $d = 3, b = 1, a = 0$  [ $(a + 1) + b < d$  evaluates to **true**]
    - e.g.,  $d = 3, b = 0, a = 1$  [ $(a + 1) + b < d$  evaluates to **true**]
    - e.g.,  $d = 3, b = 0, a = 2$  [ $(a + 1) + b < d$  evaluates to **false**]
    - e.g.,  $d = 3, b = 1, a = 1$  [ $(a + 1) + b < d$  evaluates to **false**]
    - e.g.,  $d = 3, b = 2, a = 0$  [ $(a + 1) + b < d$  evaluates to **false**]
- Therefore,  $a + b < d$  (allowing one more car to exit ML) should be split:
  - $a + b + 1 \neq d$  [more later cars may exit ML, *ml\_tl* remains **green**]
  - $a + b + 1 = d$  [no more later cars may exit ML, *ml\_tl* turns **red**]

# Fixing m2: Splitting ML\_out and IL\_out



- Recall that *ML\_out/inv2\_3/INV* failed  $\therefore$  two cases not handled separately:
  - $a + b + 1 \neq d$  [more later cars may exit ML, *ml\_tl* remains **green**]
  - $a + b + 1 = d$  [no more later cars may exit ML, *ml\_tl* turns **red**]
- Similarly, *IL\_out/inv2\_4/INV* would fail  $\therefore$  two cases not handled separately:
  - $b - 1 \neq 0$  [more later cars may exit IL, *il\_tl* remains **green**]
  - $b - 1 = 0$  [no more later cars may exit IL, *il\_tl* turns **red**]
- Accordingly, we split *ML\_out* and *IL\_out* into two with corresponding guards.

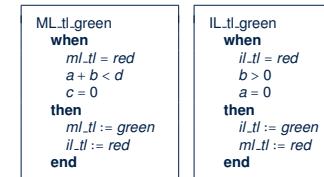


- Exercise:** Specify and prove *ML\_out/inv2\_3/INV* & *IL\_out/inv2\_4/INV*.
- Exercise:** Given the latest  $m_2$ , how many sequents to prove for **invariant preservation**?
- Exercise:** Each split event (e.g., *ML\_out\_1*) refines its **abstract** counterpart (e.g., *ML\_out*)?

# m2 Livelocks: New Events Diverging



- Recall that a system may **livelock** if the new events diverge.
- Current  $m_2$ 's two new events *ML\_tl.green* and *IL\_tl.green* may **diverge**:



- ML\_tl.green* and *IL\_tl.green* both **enabled** and may occur **indefinitely**, preventing other "old" events (e.g., *ML\_out*) from ever happening:

<i>init</i>	<i>ML_tl.green</i>	<i>ML_out_1</i>	<i>IL_in</i>	<i>IL_tl.green</i>	<i>ML_tl.green</i>	<i>IL_tl.green</i>	...
$d = 2$	$d = 2$	$d = 2$	$d = 2$	$d = 2$	$d = 2$	$d = 2$	$d = 2$
$a' = 0$	$a' = 0$	$a' = 1$	$a' = 0$	$a' = 0$	$a' = 0$	$a' = 0$	$a' = 0$
$b' = 0$	$b' = 0$	$b' = 0$	$b' = 1$	$b' = 1$	$b' = 1$	$b' = 1$	$b' = 1$
$c' = 0$	$c' = 0$	$c' = 0$	$c' = 0$	$c' = 0$	$c' = 0$	$c' = 0$	$c' = 0$
$ml\_tl = red$	$ml\_tl' = green$	$ml\_tl' = green$	$ml\_tl' = green$	$ml\_tl' = red$	$ml\_tl' = green$	$ml\_tl' = red$	$ml\_tl' = red$
$il\_tl = red$	$il\_tl' = red$	$il\_tl' = red$	$il\_tl' = red$	$il\_tl' = green$	$il\_tl' = red$	$il\_tl' = green$	$il\_tl' = green$

$\Rightarrow$  Two traffic lights keep changing colors so rapidly that **no** drivers can ever pass!

- Solution:** Allow color changes between traffic lights in a disciplined way.

# Fixing $m_2$ : Regulating Traffic Light Changes



We introduce two variables/flags for regulating traffic light changes:

- $ml\_pass$  is **1** if, since  $ml\_tl$  was last turned **green**, at least one car exited the ML onto the bridge. Otherwise,  $ml\_pass$  is **0**.
- $il\_pass$  is **1** if, since  $il\_tl$  was last turned **green**, at least one car exited the IL onto the bridge. Otherwise,  $il\_pass$  is **0**.

variables:  $ml\_pass, il\_pass$

invariants:

inv2.6 :  $ml\_pass \in \{0, 1\}$

inv2.7 :  $il\_pass \in \{0, 1\}$

inv2.8 :  $ml\_tl = red \Rightarrow ml\_pass = 1$

inv2.9 :  $il\_tl = red \Rightarrow il\_pass = 1$

ML.out.1

```

when
  ml_tl = green
  a + b + 1 = d
then
  a := a + 1
  ml_pass := 1
end
        
```

IL.out.1

```

when
  il_tl = green
  b ≠ 1
then
  b := b - 1
  c := c + 1
  il_pass := 1
end
        
```

ML\_tl.green

```

when
  ml_tl = red
  a + b < d
  c = 0
  il_pass = 1
then
  ml_tl := green
  il_tl := red
  ml_pass := 0
end
        
```

ML.out.2

```

when
  ml_tl = green
  a + b + 1 = d
then
  a := a + 1
  ml_tl := red
  ml_pass := 1
end
        
```

IL.out.2

```

when
  il_tl = green
  b = 1
then
  b := b - 1
  c := c + 1
  il_tl := red
  il_pass := 1
end
        
```

IL\_tl.green

```

when
  il_tl = red
  b > 0
  a = 0
  ml_pass = 1
then
  il_tl := green
  ml_tl := red
  il_pass := 0
end
        
```

# PO Rule: Relative Deadlock Freedom of $m_2$



```

axm0.1  { d ∈ ℕ
axm0.2  { d > 0
axm2.1  { COLOUR = { green, red }
axm2.2  { green = red
inv0.1  { n ∈ ℕ
inv0.2  { n ≤ d
inv1.1  { a ∈ ℕ
inv1.2  { b ∈ ℕ
inv1.3  { c ∈ ℕ
inv1.4  { a + b + c = n
inv1.5  { a = 0 ∨ c = 0
inv2.1  { ml_tl ∈ COLOUR
inv2.2  { il_tl ∈ COLOUR
inv2.3  { ml_tl = green ⇒ a + b < d ∧ c = 0
inv2.4  { il_tl = green ⇒ b > 0 ∧ a = 0
inv2.5  { ml_tl = red ∨ il_tl = red
inv2.6  { ml_pass ∈ {0, 1}
inv2.7  { il_pass ∈ {0, 1}
inv2.8  { ml_tl = red ⇒ ml_pass = 1
inv2.9  { il_tl = red ⇒ il_pass = 1
        
```

Disjunction of *abstract* guards

```

{ a + b < d ∧ c = 0
{ c > 0
{ a > 0
{ b > 0 ∧ a = 0
        
```

guards of ML.out in  $m_1$

guards of ML.in in  $m_1$

guards of IL.in in  $m_1$

guards of IL.out in  $m_1$

Disjunction of *concrete* guards

```

{ ml_tl = red ∧ a + b < d ∧ c = 0 ∧ il_pass = 1
{ il_tl = red ∧ b > 0 ∧ a = 0 ∧ ml_pass = 1
{ ml_tl = green ∧ a + b + 1 ≠ d
{ ml_tl = green ∧ a + b + 1 = d
{ il_tl = green ∧ b = 1
{ il_tl = green ∧ b = 1
{ a > 0
{ c > 0
        
```

guards of ML\_tl.green in  $m_2$

guards of IL\_tl.green in  $m_2$

guards of ML.out.1 in  $m_2$

guards of ML.out.2 in  $m_2$

guards of IL.out.1 in  $m_2$

guards of IL.out.2 in  $m_2$

guards of ML.in in  $m_2$

guards of IL.in in  $m_2$

DLF

# Fixing $m_2$ : Measuring Traffic Light Changes



- Recall:
  - Interleaving of **new** events charactered as an integer expression: **variant**.
  - A variant  $V(c, w)$  may refer to constants and/or **concrete** variables.
  - In the latest  $m_2$ , let's try **variants** :  $ml\_pass + il\_pass$
- Accordingly, for the **new** event  $ML\_tl\_green$ :

<p><math>d \in \mathbb{N}</math></p> <p><math>COLOUR = \{ green, red \}</math></p> <p><math>n \in \mathbb{N}</math></p> <p><math>a \in \mathbb{N}</math></p> <p><math>a + b + c = n</math></p> <p><math>ml\_tl \in COLOUR</math></p> <p><math>ml\_tl = green \Rightarrow a + b &lt; d \wedge c = 0</math></p> <p><math>ml\_tl = red \vee il\_tl = red</math></p> <p><math>ml\_pass \in \{0, 1\}</math></p> <p><math>ml\_tl = red \Rightarrow ml\_pass = 1</math></p> <p><math>ml\_tl = red</math></p> <p><math>il\_pass = 1</math></p> <p>0 + <math>il\_pass &lt; ml\_pass + il\_pass</math></p>	<p><math>d &gt; 0</math></p> <p><math>green \neq red</math></p> <p><math>n \leq d</math></p> <p><math>b \in \mathbb{N}</math></p> <p><math>a = 0 \vee c = 0</math></p> <p><math>il\_tl \in COLOUR</math></p> <p><math>il\_tl = green \Rightarrow b &gt; 0 \wedge a = 0</math></p> <p><math>il\_pass \in \{0, 1\}</math></p> <p><math>il\_tl = red \Rightarrow il\_pass = 1</math></p> <p><math>a + b &lt; d</math></p> <p><math>c \in \mathbb{N}</math></p> <p><math>c = 0</math></p>	<p>ML_tl_green/VAR</p>
--	---	------------------------

**Exercises:** Prove ML\_tl.green/VAR and Formulate/Prove IL\_tl.green/VAR.

# Proving Refinement: DLF of $m_2$



```

d ∈ ℕ
d > 0
COLOUR = { green, red }
green = red
n ∈ ℕ
n ≤ d
a ∈ ℕ
b ∈ ℕ
c ∈ ℕ
a + b + c = n
a = 0 ∨ c = 0
ml_tl ∈ COLOUR
il_tl ∈ COLOUR
ml_tl = green ⇒ a + b < d ∧ c = 0
il_tl = green ⇒ b > 0 ∧ a = 0
ml_tl = red ∨ il_tl = red
ml_pass ∈ {0, 1}
il_pass ∈ {0, 1}
ml_tl = red ⇒ ml_pass = 1
il_tl = red ⇒ il_pass = 1
a + b < d ∧ c = 0
c > 0
a > 0
b > 0 ∧ a = 0
ml_tl = red ∧ a + b < d ∧ c = 0 ∧ il_pass = 1
il_tl = red ∧ b > 0 ∧ a = 0 ∧ ml_pass = 1
ml_tl = green
il_tl = green
a > 0
c > 0
        
```

ARI

ORL

OR,R2

HYP

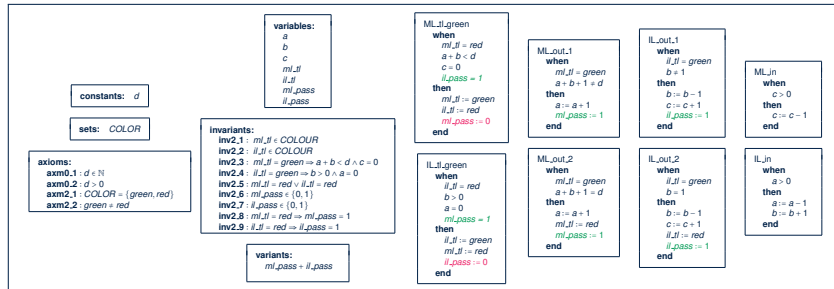
EQ,LR,MON

OR,R1

HYP

## Second Refinement: Summary

- The final version of our *second refinement*  $m_2$  is **provably correct** w.r.t.:
  - Establishment of **Concrete Invariants** [ *init* ]
  - Preservation of **Concrete Invariants** [ old & new events ]
  - Strengthening of **guards** [ old events ]
  - Convergence** (a.k.a. livelock freedom, non-divergence) [ new events ]
  - Relative **Deadlock Freedom**
- Here is the final specification of  $m_2$ :



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