Priority Queues, Heaps, and Heap Sort

EECS2011 N & Z:
Fundamentals of Data Structures
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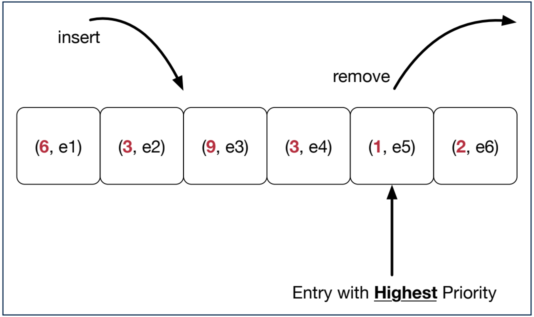
Learning Outcomes of this Lecture

This module is designed to help you understand:

- The ***Priority Queue*** (***PQ***) ADT
- Time Complexities of ***List***-Based ***PQ***
- The ***Heap*** Data Structure (Properties & Operations)
- ***Heap Sort***
- Time Complexities of ***Heap***-Based ***PQ***
- ***Heap*** Construction Methods: Top-Down vs. Bottom-Up
- ***Array***-Based Representation of a ***Heap***

What is a Priority Queue?

- A ***Priority Queue (PQ)*** stores a collection of ***entries***.



  - Each ***entry*** is a pair: an ***element*** and its ***key***.
  - The ***key*** of each ***entry*** denotes its ***element***'s "priority".
  - ***Keys*** in a Priority Queue (PQ) are **not** used for uniquely identifying an entry.

- In a PQ, the next entry to remove has the "***highest***" priority.
  - e.g., In the stand-by queue of a fully-booked flight, ***frequent flyers*** get the higher priority to replace any cancelled seats.
  - e.g., A network router, faced with insufficient bandwidth, may only handle ***real-time tasks*** (e.g., streaming) with highest priorities.

The Priority Queue (PQ) ADT

- ***min***

  [***precondition***: PQ is not empty]
  [***postcondition***: return entry with **highest priority** in PQ]

- ***size***

  [***precondition***: **none**]
  [***postcondition***: return number of entries inserted to PQ]

- ***isEmpty***

  [***precondition***: **none**]
  [***postcondition***: return whether there is no entry in PQ]

- ***insert(k, v)***

  [***precondition***: PQ is not full]
  [***postcondition***: insert the input entry into PQ]

- ***removeMin***

  [***precondition***: PQ is not empty]
  [***postcondition***: remove and return a **min** entry in PQ]

Two List-Based Implementations of a PQ

Consider two strategies for implementing a *PQ*, where we maintain:

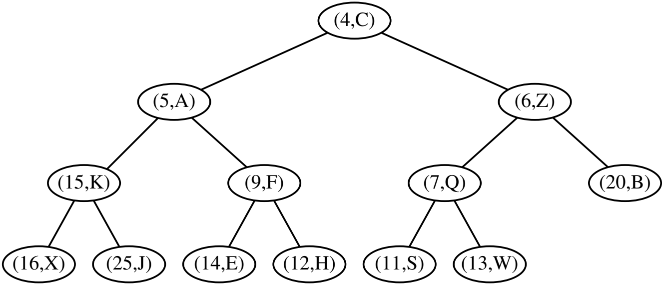
1. A list ***always sorted*** in a non-descending order [≈ **INSERTIONSORT**]
2. An ***unsorted*** list [≈ **SELECTIONSORT**]

PQ Method	**List Method**			
	SORTED LIST		UNSORTED LIST	
size	list.size ***O(1)***			
isEmpty	list.isEmpty ***O(1)***			
min	list.first	***O(1)***	search min	***O(n)***
insert	insert to “right” spot	***O(n)***	insert to front	***O(1)***
removeMin	list.removeFirst	***O(1)***	search min and remove	***O(n)***

Heaps

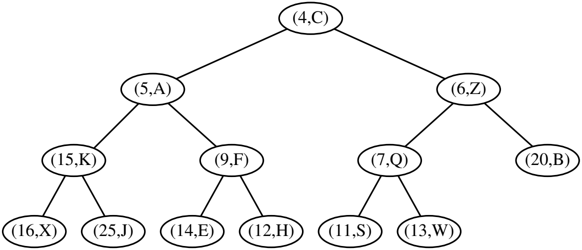
A ***heap*** is a ***binary tree*** which:

1. Stores in each node an ***entry*** (i.e., ***key*** and ***value***).



2. Satisfies a ***relational*** property of stored **keys**
3. Satisfies a ***structural*** property of tree **organization**

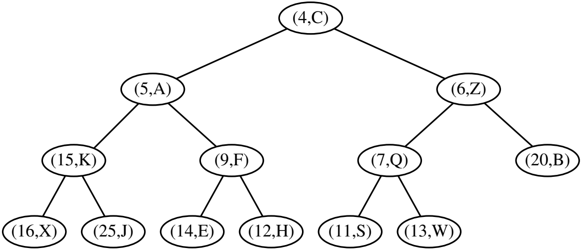
Heap Property 1: Relational



Keys in a ***heap*** satisfy the ***Heap-Order Property***:

- Every node ***n*** (other than the root) is s.t. ***key***(***n***) ≥ ***key***(**parent**(***n***))
  - ⇒ ***Keys*** in a ***root-to-leaf path*** are sorted in a non-descending order.
    - e.g., Keys in entry path $\langle (4, C), (5, A), (9, F), (14, E) \rangle$ are sorted.
  - ⇒ The ***minimal key*** is stored in the ***root***.
    - e.g., Root $(4, C)$ stores the minimal key 4.
- ***Keys*** of nodes from ***different subtrees*** are **not** constrained at all.
  - e.g., For node $(5, A)$, key of its ***LST***'s root (15) is not minimal for its ***RST***.

Heap Property 2: Structural



A ***heap*** with ***height h*** satisfies the ***Complete BT Property***:

- Nodes with ***depth*** $\leq$ **h − 2** has two child nodes.
- Nodes with ***depth h - 1*** may have zero, one, or two child nodes.
- Nodes with ***depth h*** are filled from left to right.

Q. When the # of nodes is *n*, what is *h*? $\lfloor \log_2 n \rfloor$

Q. # of nodes from Level 0 through Level *h* − 1? $2^h - 1$

Q. # of nodes at Level *h*? $n - (2^h - 1)$

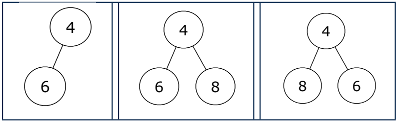
Q. **Minimum** # of nodes of a complete BT? 2^h

Q. **Maximum** # of nodes of a complete BT? $2^{h+1} - 1$

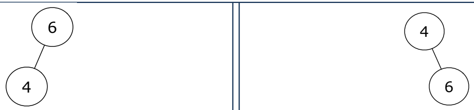
Heaps: More Examples

- The ***smallest*** *heap* is just an empty binary tree.
- The ***smallest*** **non-empty** *heap* is a one-node heap.
  e.g.,

- Two-node and Three-node Heaps:



- These are **not** two-node heaps:



relational property violated | ***structural*** property violated

Heap Operations

- There are three main operations for a ***heap***:
  1. **Extract the Entry with Minimal Key**:
     Return the stored entry of the ***root***. [***O(1)***]
  2. **Insert a New Entry**:
     A single ***root-to-leaf path*** is affected. [***O(h)*** or ***O(log n)***]
  3. **Delete the Entry with Minimal Key**:
     A single ***root-to-leaf path*** is affected. [***O(h)*** or ***O(log n)***]
- After performing each operation,
  both ***relational*** and ***structural*** properties must be maintained.

Updating a Heap: Insertion

To insert a new entry (k, v) into a heap with ***height h***:

1. Insert (k, v), possibly **temporarily** breaking the ***relational property***.

- **1.1** Create a new entry **e** $= (k, v)$.
- **1.2** Create a new ***right-most*** node ***n*** at ***Level h***.
- **1.3** Store entry **e** in node ***n***.

  After steps **1.1** and **1.2**, the ***structural property*** is maintained.

2. Restore the **heap-order property** (**HOP**) using *Up-Heap Bubbling*:

- **2.1** Let ***c*** = ***n***.
- **2.2** While **HOP** is not restored and ***c*** is not the root:
  - **2.2.1** Let ***p*** be ***c***'s parent.
  - **2.2.2** **If** $key(p) \leq key(c)$, then **HOP** is restored.

    Else, swap nodes ***c*** and ***p***. ["upwards" along ***n***'s ***ancestor path***]

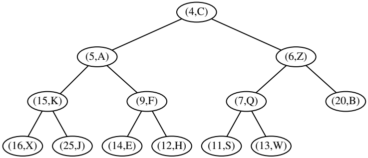
Running Time?

- All sub-steps in **1**, as well as steps **2.1**, **2.2.1**, and **2.2.2** take ***O(1)***.
- Step **2.2** may be executed up to ***O(h)*** (or ***O(log n)***) times.

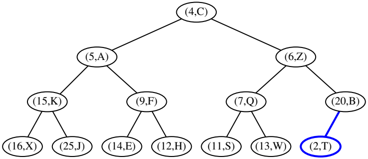
[*O(log n)*]

Updating a Heap: Insertion Example (1.1)

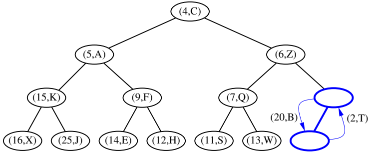
(0) A heap with height 3.



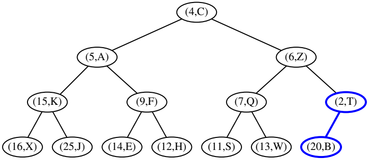
(1) Insert a new entry $(2, T)$ as the ***right-most*** node at Level 3. Perform *up-heap bubbling* from here.



(2) **HOP** violated $\because 2 < 20 \therefore$ Swap.

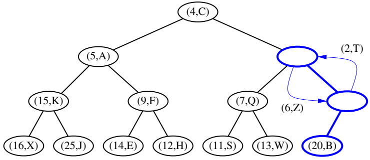


(3) After swap, entry $(2, T)$ prompted up.

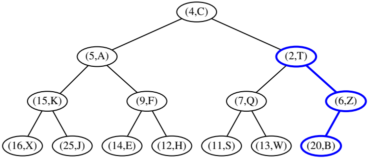


Updating a Heap: Insertion Example (1.2)

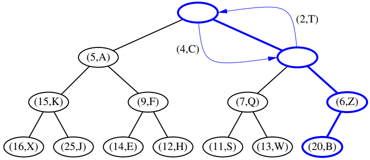
(4) **HOP** violated ∵ $2 < 6$ ∴ Swap.



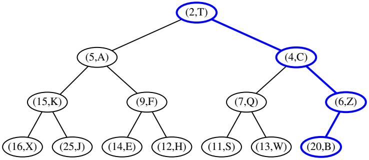
(5) After swap, entry $(2, T)$ prompted up.



(6) **HOP** violated ∵ $2 < 4$ ∴ Swap.



(7) Entry $(2, T)$ becomes root ∴ Done.



Updating a Heap: Deletion

To delete the **root** (with the ***minimal*** key) from a heap with ***height h***:

1. Delete the **root**, possibly **temporarily** breaking **HOP**.
   - **1.1** Let the ***right-most*** node at ***Level h*** be ***n***.
   - **1.2** Replace the **root**'s entry by ***n***'s entry.
   - **1.3** Delete ***n***.

   After steps **1.1** – **1.3**, the ***structural property*** is maintained.
2. Restore **HOP** using *Down-Heap Bubbling*:
   - **2.1** Let ***p*** be the **root**.
   - **2.2** While **HOP** is not restored and ***p*** is not external:
     - **2.2.1** **IF** ***p*** has no **right child**, let ***c*** be ***p***'s ***left child***.
       Else, let ***c*** be ***p***'s child with a ***smaller key value***.
     - **2.2.2** **If** $key(p) \leq key(c)$, then **HOP** is restored.
       Else, swap nodes ***p*** and ***c***. ["downwards" along a ***root-to-leaf path***]

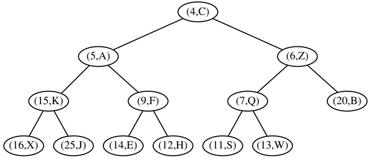
Running Time?

- All sub-steps in **1**, as well as steps **2.1**, **2.2.1**, and **2.2.2** take ***O(1)***.
- Step **2.2** may be executed up to ***O(h)*** (or ***O(log n)***) times.

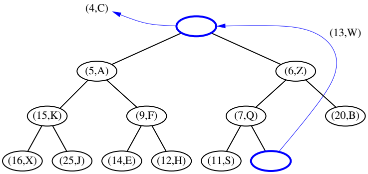
[*O(log n)*]

Updating a Heap: Deletion Example (1.1)

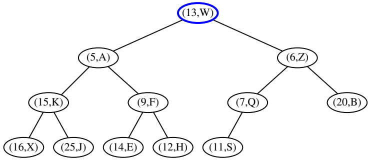
(0) Start with a heap with height 3.



(1) Replace root with $(13, W)$ and delete ***right-most*** node from Level 3.

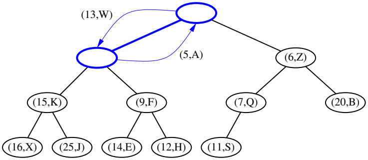


(2) $(13, W)$ becomes the root. Perform *down-heap bubbling* from here.



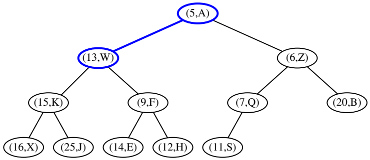
(3) Child with smaller key is $(5, A)$.

HOP violated $\because 13 > 5 \therefore$ Swap.

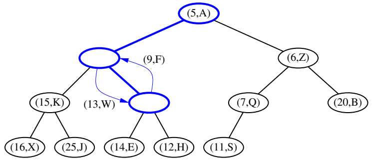


Updating a Heap: Deletion Example (1.2)

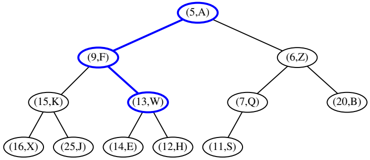
(4) After swap, entry $(13, W)$ demoted down.



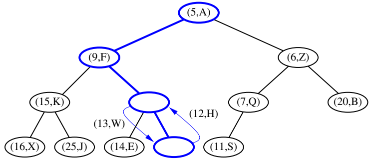
(5) Child with smaller key is $(9, F)$. **HOP** violated $\because$ 13 > 9 $\therefore$ Swap.



(6) After swap, entry $(13, W)$ demoted down.

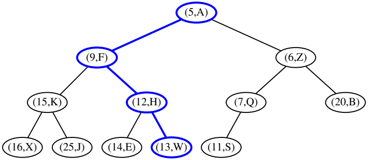


(7) Child with smaller key is $(12, H)$. **HOP** violated $\because$ 13 > 12 $\therefore$ Swap.



Updating a Heap: Deletion Example (1.3)

(8) After swap, entry $(13, W)$ becomes an external node $\therefore$ Done.



Heap-Based Implementation of a PQ

PQ Method	Heap Operation	RT
min	root	***O(1)***
insert	insert then up-heap bubbling	***O(log n)***
removeMin	delete then down-heap bubbling	***O(log n)***

Top-Down Heap Construction: List of Entries is Not Known in Advance

Problem: Build a heap out of ***N*** entires, supplied one at a time.

- Initialize an ***empty heap h***. [***O(1)***]
- As each new entry **e** = (k, v) is supplied, **insert** **e** into ***h***.
  - Each insertion triggers an ***up-heap bubbling*** step, which takes ***O(log n)*** time. [$n = 0, 1, 2, \ldots,$ ***N - 1***]
  - There are ***N*** insertions.

∴ Running time is $O(\boldsymbol{N} \cdot log\ \boldsymbol{N})$

Bottom-Up Heap Construction: List of Entries is Known in Advance

Problem: Build a heap out of N entires, supplied all at once.

- **Assume**: The resulting heap will be ***completely filled*** at **all** levels.
  $\Rightarrow N = 2^{h+1} - 1$ for some ***height*** $h \geq 1$ $\quad$ [$h = (log\ (N + 1)) - 1$]
- Perform the following steps called *Bottom-Up Heap Construction*:

  Step 1: Treat the first $\frac{N+1}{2^1}$ list entries as heap roots.

  $\therefore \frac{N+1}{2^1}$ heaps with height 0 and size $2^1 - 1$ constructed.

  Step 2: Treat the next $\frac{N+1}{2^2}$ list entries as heap roots.

  ◇ Each ***root*** sets two heaps from **Step 1** as its ***LST*** and ***RST***.
  ◇ Perform ***down-heap bubbling*** to restore **HOP** if necessary.
  $\therefore \frac{N+1}{2^2}$ heaps, each with height 1 and size $2^2 - 1$, constructed.

  ...

  Step $h+1$: Treat next $\frac{N+1}{2^{h+1}} = \frac{(2^{h+1}-1)+1}{2^{h+1}} = 1$ list entry as heap root.

  ◇ Each ***root*** sets two heaps from **Step h** as its ***LST*** and ***RST***.
  ◇ Perform ***down-heap bubbling*** to restore **HOP** if necessary.
  $\therefore \frac{N+1}{2^{h+1}} = 1$ heap, each with height h and size $2^{h+1} - 1$, constructed.

Bottom-Up Heap Construction: Example (1.1)

- Build a heap from the following list of 15 keys:

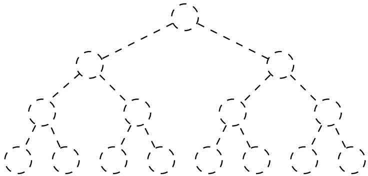
$$\langle 16, 15, 4, 12, 6, 7, 23, 20, 25, 9, 11, 17, 5, 8, 14 \rangle$$

- The resulting heap has:
  - ***Size N*** is 15
  - ***Height h*** is $(log(15 + 1)) - 1 = 3$
- According to the ***bottom-up heap construction*** technique, we will need to perform $\boldsymbol{h} + 1 = 4$ steps, utilizing 4 sublists:

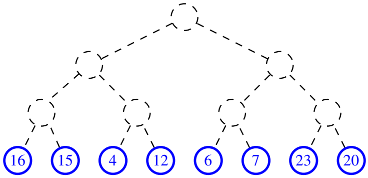
$$\langle \underbrace{16, 15, 4, 12, 6, 7, 23, 20}_{\frac{15+1}{2^1} = 8}, \underbrace{25, 9, 11, 17}_{\frac{15+1}{2^2} = 4}, \underbrace{5, 8}_{\frac{15+1}{2^3} = 2}, \underbrace{14}_{\frac{15+1}{2^4} = 1} \rangle$$

Bottom-Up Heap Construction: Example (1.2)

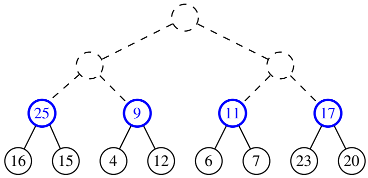
We know in advance to build a heap with height 3 and size $2^{3+1} - 1 = 15$



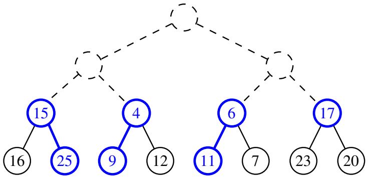
(**Step 1**) Treat first $\frac{15+1}{2^1}$ entries as roots.
∴ 8 one-node heaps.



(**Step 2**) Treat next $\frac{15+1}{2^2}$ entries as roots.
Set LST and RST of each root.

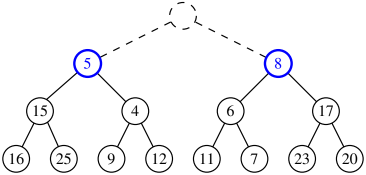


(**Step 2** cont.) Down-heap bubbling.
∴ 4 three-node heaps.

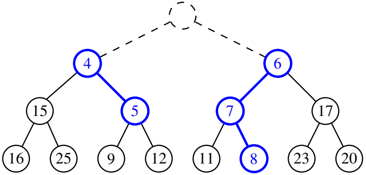


Bottom-Up Heap Construction: Example (1.3)

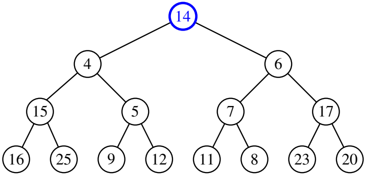
(**Step 3**) Treat next $\frac{15+1}{2^3}$ entries as roots.
Set LST and RST of each root.



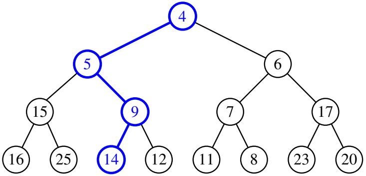
(**Step 3** cont.) Down-heap bubbling.
∴ 2 three-node heaps.



(**Step 4**) Treat next $\frac{15+1}{2^4}$ entry as roots.
Set LST and RST of each root.



(**Step 4** cont.) Down-heap bubbling.
∴ 1 fifteen-node heap.



RT of Bottom-Up Heap Construction

- Intuitively, the majority of the intermediate roots from which we perform ***down-heap bubbling*** are of very ***small height values***:
  - The first $\frac{n+1}{2}$ ***1***-node heaps with ***height 0*** require **no** down-heap bubbling.
    [About 50% of the list entries processed]
  - Next $\frac{n+1}{4}$ ***3***-node heaps with ***height 1*** require down-heap bubbling.
    [Another 25% of the list entries processed]
  - Next $\frac{n+1}{8}$ ***7***-node heaps with ***height 2*** require down-heap bubbling.
    [Another 12.5% of the list entries processed]

  . . .

  - Next two $\frac{N-1}{2}$-node heaps with ***height (h - 1)*** require down-heap
  - Final one ***N***-node heaps with ***height h*** requires down-heap bubbling.
- Running Time of the ***Bottom-Up Heap Construction*** takes only $O(n)$.

The Heap Sort Algorithm

Sorting Problem:

Given a list of **n** numbers $\langle a_1, a_2, \ldots, a_n \rangle$:

Precondition: NONE

Postcondition: A permutation of the input list $\langle a'_1, a'_2, \ldots, a'_n \rangle$ sorted in a non-descending order (i.e., $a'_1 \leq a'_2 \leq \ldots \leq a'_n$)

The *Heap Sort* algorithm consists of two phases:

1. ***Construct*** a ***heap*** of size ***N*** out of the input array.
   - Approach 1: Top-Down "Continuous-Insertions" [$\mathbf{O}(N \cdot \log N)$]
   - Approach 2: Bottom-Up Heap Construction [$\mathbf{O}(N)$]
2. ***Delete*** ***N*** entries from the heap.
   - Each deletion takes $\mathbf{O}(\log N)$ time.
   - 1st deletion extracts the ***minimum***, 2nd deletion the 2nd ***minimum***, . . .
     ⇒ Extracted ***minimums*** from ***N*** deletions form a *sorted* sequence.

∴ Running time of the *Heap Sort* algorithm is $\mathbf{O}(N \cdot \log N)$.

The Heap Sort Algorithm: Exercise

Sort the following array of integers

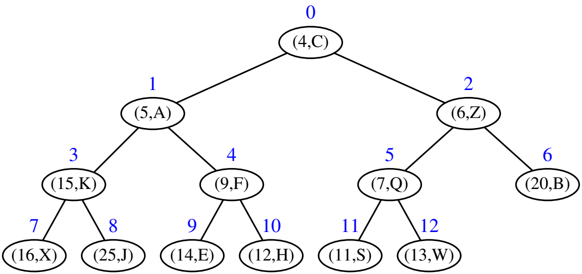
$$\langle 16, 15, 4, 12, 6, 7, 23, 20, 25, 9, 11, 17, 5, 8, 14 \rangle$$

into a ***non-descending*** order using the *Heap Sort Algorithm*.

Demonstrate:

1. Both top-down and bottom-up heap constructions in Phase 1
2. Extractions of minimums in Phase 2

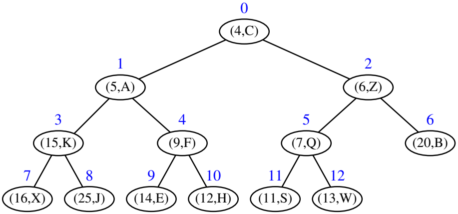
Array-Based Representation of a CBT (1)



$$index(x) = \begin{cases} 0 & \texttt{if } x \texttt{ is the root} \\ 2 \cdot index(\ parent(x)\ ) + 1 & \texttt{if } x \texttt{ is a left child} \\ 2 \cdot index(\ parent(x)\ ) + 2 & \texttt{if } x \texttt{ is a right child} \end{cases}$$

(4,C)	(5,A)	(6,Z)	(15,K)	(9,F)	(7,Q)	(20,B)	(16,X)	(25,J)	(14,E)	(12,H)	(11,S)	(13,W)
0	1	2	3	4	5	6	7	8	9	10	11	12

Array-Based Representation of a CBT (2)



(4,C)	(5,A)	(6,Z)	(15,K)	(9,F)	(7,Q)	(20,B)	(16,X)	(25,J)	(14,E)	(12,H)	(11,S)	(13,W)
0	1	2	3	4	5	6	7	8	9	10	11	12

- **Q1:** Where are nodes at ***Levels*** $0 .. h-1$ stored in the array?
  Indices $0 .. (2^h - 2) \equiv 0 .. (2^{\lfloor \log_2 N \rfloor} - 2)$ [e.g., Indices $0 .. 2^3 - 2$]
- **Q2:** Where are nodes at ***Level*** h stored in the array?
  Indices $2^h - 1 .. (N - 1) \equiv 2^{\lfloor \log_2 N \rfloor} - 1 .. (N - 1)$ [e.g., Indices 7 .. 12]
- **Q3:** How do we determine if a non-root node x is a ***left or right child***?
  IF $index(x) \% 2 == 1$ **THEN** *left* **ELSE** *right*
- **Q4:** Given a non-root node x, how do we determine the ***index of x's parent***?
  IF $index(x) \% 2 == 1$ **THEN** $\frac{index(x)-1}{2}$ **ELSE** $\frac{index(x)-2}{2}$

Index (1)

Index (2)

Index (3)