

# Linear Algebra

## Review & Recent Progress

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- What is linear algebra?
- Why should I care?
- System of Linear Equations
- Eigen-decomposition

# What is Linear Algebra?

- At the risk of over-simplification, linear algebra solves two problems:

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<sup>1</sup>Matrix  $\mathbf{A}$  and vector  $\mathbf{y}$  can also be complex:  $\mathbf{A} \in \mathbb{C}^{n \times n}$ ,  $\mathbf{y} \in \mathbb{C}^n$ .

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$$\mathbf{Ax} = \mathbf{y} \quad (1)$$

② **Eigen-decomposition:**

given matrix  $\mathbf{A} \in \mathbb{R}^{n \times n}$ , find eigen-pair<sup>2</sup>  $(\lambda, \mathbf{v})$ , where  $\lambda \in \mathbb{R}$  and  $\mathbf{v} \in \mathbb{R}^n$ , such that

$$\mathbf{Av} = \lambda \mathbf{v} \quad (2)$$

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- ③ **Regularization:**

$$\min_{\mathbf{x}} \|\mathbf{y} - \mathbf{Hx}\|_2^2 + \lambda \|\mathbf{Ax}\|_2^2 \quad (7)$$

$$\implies (\mathbf{H}^T \mathbf{H} + \lambda \mathbf{A}^T \mathbf{A}) \mathbf{x}^* = \mathbf{H}^T \mathbf{y} \quad (8)$$

<sup>3</sup>[http://eeweb.poly.edu/iselesni/lecture\\_notes/least\\_squares/index.html](http://eeweb.poly.edu/iselesni/lecture_notes/least_squares/index.html)

## Why should I care? (Part II)

- Evaluate stability of  $\mathbf{Ax} = \mathbf{y}$ .
  - Condition number  $\kappa(\mathbf{A})$  of coefficient matrix  $\mathbf{A}$ :

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- Compute **graph frequencies**<sup>4</sup>:
  - 1 Define variation operator  $\Phi$  on graph, e.g., *graph Laplacian matrix*  $\mathbf{L}$ :

$$\mathbf{L} = \mathbf{D} - \mathbf{W} \quad (11)$$

- 2 Compute Fourier modes for  $\mathbf{L}$  via eigen-decomposition.

$$\mathbf{L} = \mathbf{V}\mathbf{\Lambda}\mathbf{V}^T \quad (12)$$

where  $\mathbf{V}$  contains eigenvectors  $\mathbf{v}_1, \mathbf{v}_2, \dots$  as columns, and  $\mathbf{\Lambda} = \text{diag}(\lambda_1, \lambda_2, \dots)$ .

<sup>4</sup>A. Ortega et al., "Graph signal processing: Overview, challenges, and applications," *Proceedings of the IEEE*, vol. 106, no. 5, pp. 808–828, 2018.

# Graph Frequencies: Discrete Cosine Transform (GCT)

- Cosines are eigenfunctions of differential operator:
  - 1 Construct graph Laplacian  $\mathbf{L}$  for line graph with weights 1.
  - 2 Compute eigenvectors for  $\mathbf{L}$ .

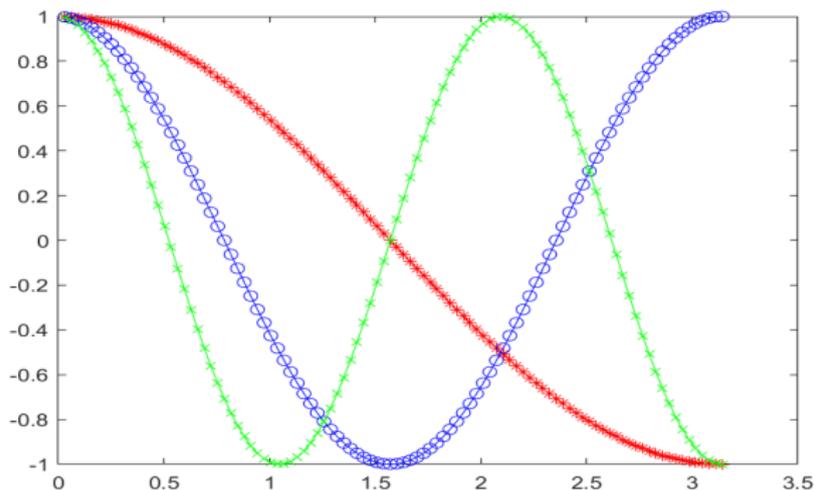


Figure: Eigenvectors of line graph Laplacian matrix  $\mathbf{L} = \mathbf{D} - \mathbf{W}$

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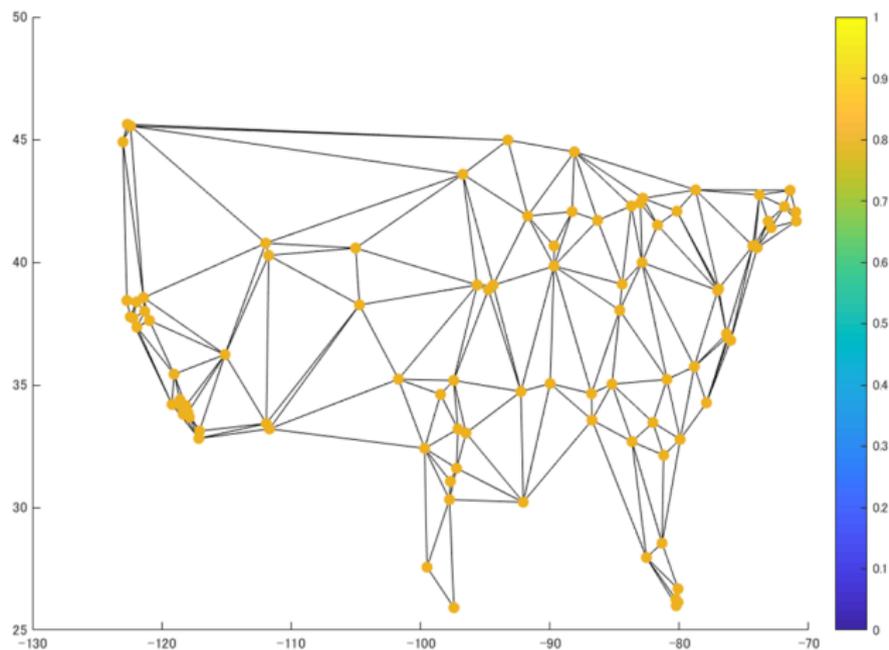


Figure: 1st eigenvector of graph Laplacian matrix  $\mathbf{L} = \mathbf{D} - \mathbf{W}$

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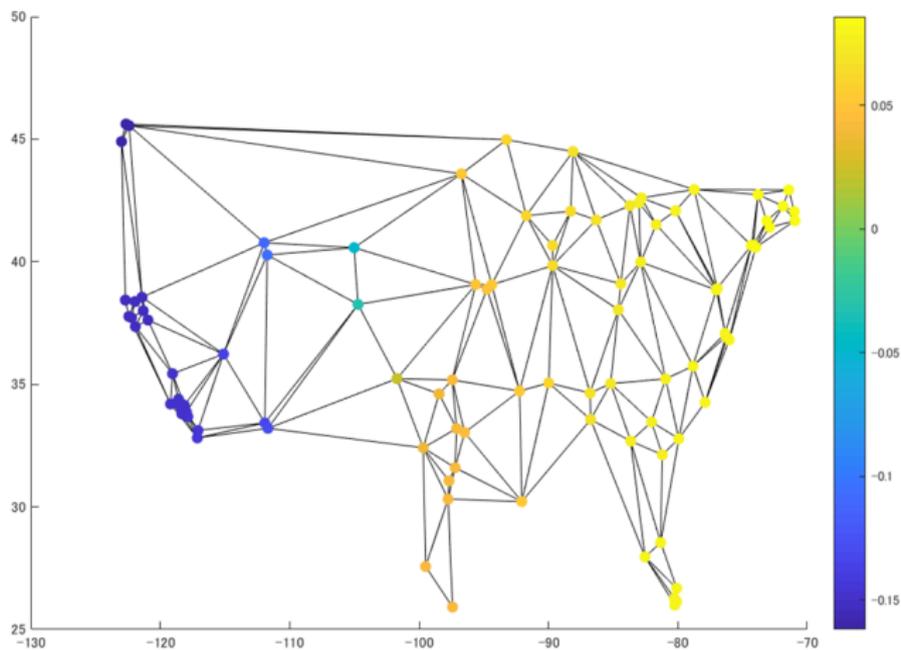


Figure: 2nd eigenvector of graph Laplacian matrix  $\mathbf{L} = \mathbf{D} - \mathbf{W}$

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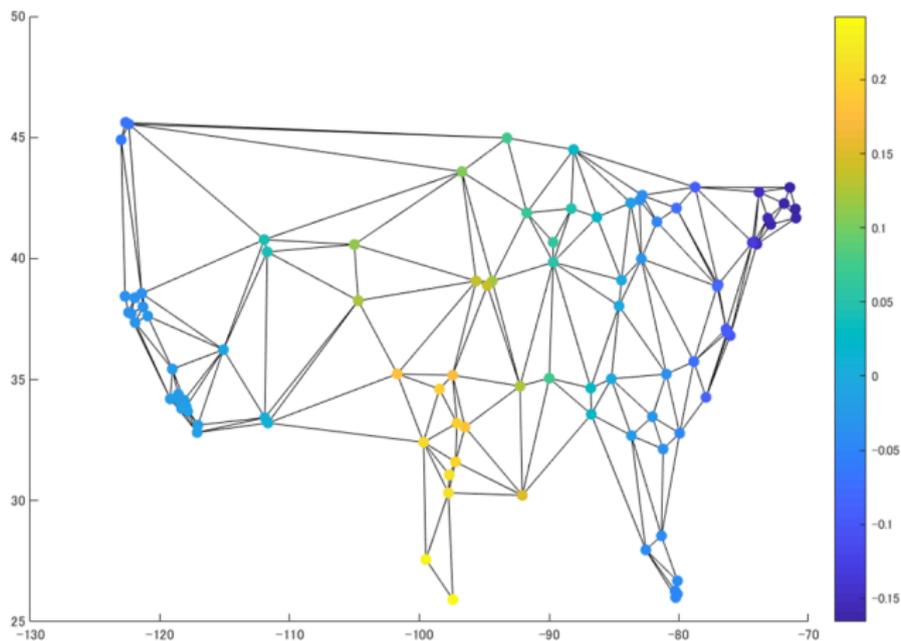


Figure: 3rd eigenvector of graph Laplacian matrix  $\mathbf{L} = \mathbf{D} - \mathbf{W}$

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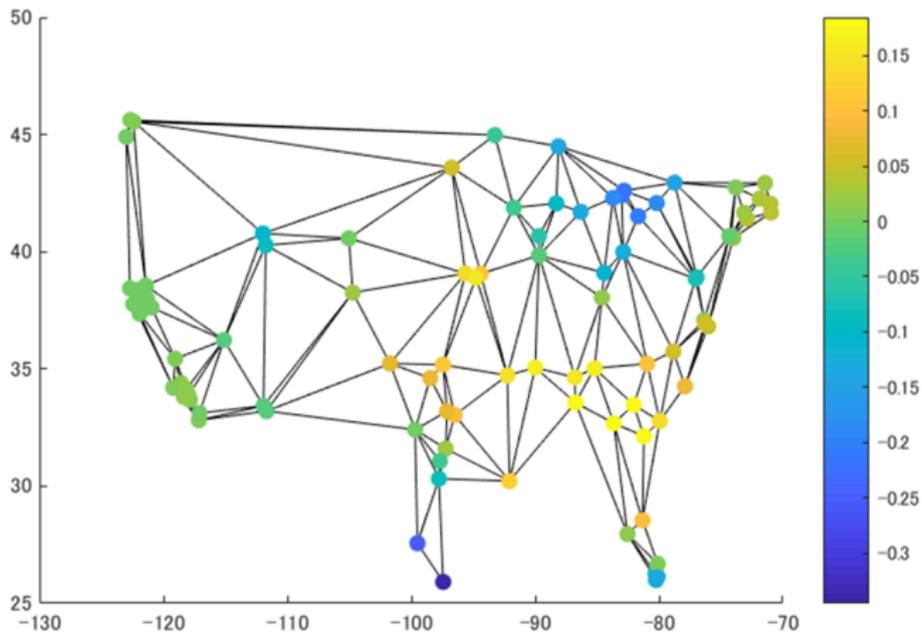


Figure: 9th eigenvector of graph Laplacian matrix  $\mathbf{L} = \mathbf{D} - \mathbf{W}$

# Solving a System of Linear Equations

Q: How to solve  $\mathbf{Ax} = \mathbf{b}$ ?

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  - If  $\mathbf{A}$  symmetric and PD, **Conjugate Gradient**<sup>5</sup>.

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  - If  $\mathbf{A}$  Hermetian, **Lanczos algorithm.**

- Recall E-optimality criteria:

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- Compute a lower bound for  $\lambda_{\min}(\mathbf{A})$  without computing eigen-pairs:

$$\lambda_{\min}^-(\mathbf{A}) = \min_i c_i - r_i \leq \lambda_{\min}(\mathbf{A}) \quad (15)$$

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**Q:** How tight is GCT lower bound  $\lambda_{\min}^-(\mathbf{A})$  for  $\lambda_{\min}(\mathbf{A})$ ?

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**A:** Consider instead similar transform<sup>7</sup>:

$$\mathbf{B} = \mathbf{S}\mathbf{A}\mathbf{S}^{-1} \quad (16)$$

where  $\mathbf{S} = \text{diag}(s_1, s_2, \dots)$ .

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where  $\mathbf{S} = \text{diag}(s_1, s_2, \dots)$ .

- $\mathbf{B}$  has same eigenvalues as  $\mathbf{A}$ .
- If  $\mathbf{A}$  is a *generalized graph Laplacian* with positive edges,  $\exists \mathbf{S}$  such that  $\lambda_{\min}^-(\mathbf{B}) = \lambda_{\min}(\mathbf{B}) = \lambda_{\min}(\mathbf{A})$ .

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$$\mathbf{A} = \begin{bmatrix} \mathbf{A}_{11} & \mathbf{A}_{12} \\ \mathbf{A}_{12}^{\top} & \mathbf{A}_{22} \end{bmatrix} \quad (17)$$

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- Define **Schur Complement**:

$$\mathbf{A}/\mathbf{A}_{11} = \mathbf{A}_{22} - \mathbf{A}_{12}^{\top} \mathbf{A}_{11}^{-1} \mathbf{A}_{12} \quad (18)$$

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- **Haynsworth Inertia Additivity formula**:

$$\text{In}(\mathbf{A}) = \text{In}(\mathbf{A}_{11}) + \text{In}(\mathbf{A}/\mathbf{A}_{11}) \quad (19)$$

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- If  $\mathbf{A}$  is real and symmetric, can compute tight lower bound for  $\lambda_{\min}$  using a recursive procedure plus shifting  $(+\mu\mathbf{I})$ <sup>8</sup>.

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## locally optimal block preconditioned conjugated gradient (LOBPCG) method <sup>9</sup>:

- Compute extreme eigen-pairs for symmetric, PD matrices.
- Cost per iteration competitive with Lanczos.
- Can directly take advantage of preconditioning.
- Can benefit from **warm start**.

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<sup>9</sup>A. Knyazev, "Toward the optimal preconditioned eigensolver: Locally optimal block preconditioned conjugate gradient method," *SIAM journal on scientific computing*, 23(2):517–541, 2001.

- Linear algebra solves:
  - ①  $\mathbf{Ax} = \mathbf{y}$
  - ②  $\mathbf{Av} = \lambda \mathbf{v}$ .
- Mature algorithms to solve  $\mathbf{Ax} = \mathbf{y}$  using Krylov methods.
- Fast algorithms to find extreme eigen-pairs  $(\lambda_i, \mathbf{v}_i)$ .
- New algorithms to find tight lower bounds for  $\lambda_{\min}$ .