EECS 1028 E: Discrete Mathematics for Engineers

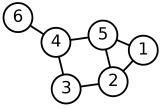
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Course page: http://www.eecs.yorku.ca/course/1028 Also on eClass

Graphs: Motivations and Basic Idea

Sec 10.1, 10.2

- Tool for modeling many real applications
- Abstract model that throws away many non-essential aspects of a problem
- Nodes, connected by edges

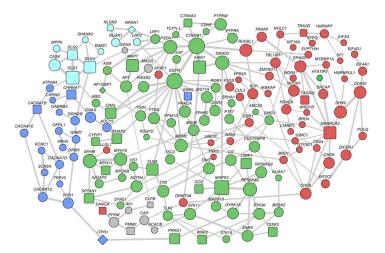


• No geographical locations attached to node positions, no significance of edge lengths

Many Applications, including:

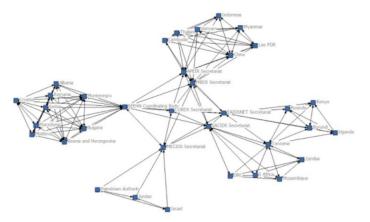
- Road networks
- Subway/Train networks
- Airline networks
- Social Networks
- Power Grid
- Electronic Communication Networks
- Electrical Circuits
- Biological Networks
- Ecological Networks

- The web graph
- Software module dependencies
- Computation structure
- Scheduling constraints
- Collaboration graphs
- State graphs of machines and protocols
- Many, many others



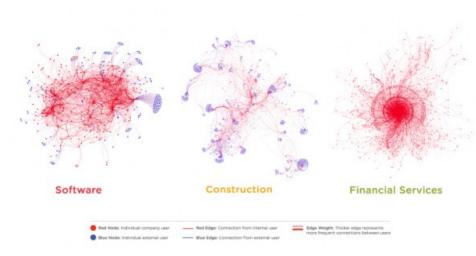
Article: Gene networks offer entry point to unraveling autism

From https://spectrumnews.org/news/gene-networks-offer-entry-point-to-unraveling-autism/



A social network graph illustrating the connections among countries and regional networks in CORDS (CORDS=Connecting Organizations for Regional Disease Surveillance;

From https://openi.nlm.nih.gov/detailedresult.php?img=PMC3557911_EHTJ-6-19913-g001&req=4



Collaboration graph among people in the same company

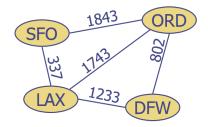
From https://linkurio.us/blog/visualizing-business-organizations-the-collaboration-graph/

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G = (V, E), V = set of nodes/vertices, E = set of edges

- Edges incident on a vertex
- Adjacent vertices
- degree of a node
- neighborhood of a node
- Self-loops
- Edge weights



Definitions - 2

- Edge Types:
 - Directed edge: ordered pair of vertices (u, v)
 - u : origin, v : destination
 - Undirected edge: unordered pair of vertices (u, v)
- Graph Types:
 - Directed graph: all the edges are directed
- Undirected graph: all the edges are undirectedPaths:
 - Simple Paths
 - Cycles
 - Simple cycles: no vertex repeated

Adjacency list

• Adjacency matrix

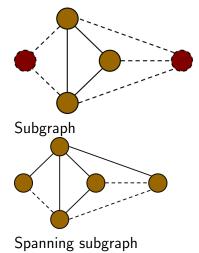
Incidence matrix

• Handshaking Theorem, Thm 1 (pg 686): Sum of degrees equals twice the number of edges in an undirected graph

• Thm 3 (pg 687) Sum of indegrees equals sum of outdegrees in a digraph, which in turn equals |E|

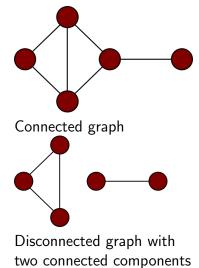
• In an undirected graph $m \le \frac{n(n-1)}{2}$ What is the bound for directed graphs?

- A subgraph S of a graph G is a graph such that
 - The vertices of S are a subset of the vertices of G
 - The edges of S are a subset of the edges of G
- A spanning subgraph of G is a subgraph that contains all the vertices of G



Connected graphs

- A graph is connected if there is a path between every pair of vertices
- A connected component of a graph *G* is a maximal connected subgraph of *G*



Trees (Ch 11.1)

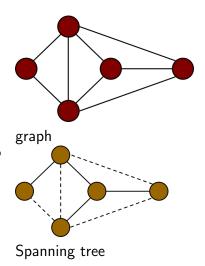
- Defn 1 (pg 782) A tree is a connected, acyclic, undirected graph
- A forest is a set of trees
- Theorem [pg 782] An undirected graph is a tree iff there is a unique, simple path between any 2 of its vertices



Tree, forest, a cyclic graph

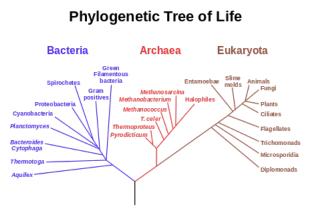
- Internal vertices, leaves
- Defn 2 (pg 783) Rooted tree: tree with a designated vertex called root; all edges directed away from the root.
- Defn 2 (pg 784) A rooted tree is called a *m*-ary tree if every internal vertex has no more than *m* children.
 m = 2: binary tree
- If every internal vertex has exactly *m* children, the tree is called **full**.
- If a full tree has every leaf at the same depth, it is called **complete**

- A spanning tree of a connected graph is a spanning subgraph that is a tree
- A spanning tree is not unique unless the graph is a tree
- Spanning trees have applications to the design of communication networks
- A spanning forest of a graph is a spanning subgraph that is a forest

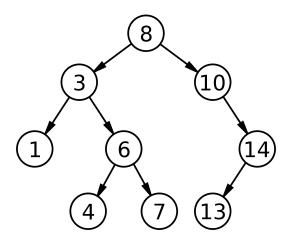


More on Trees

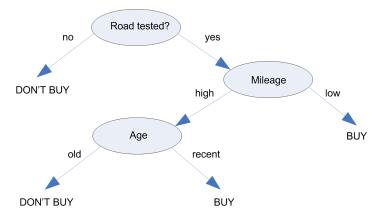
Sec 11.1



More on Trees: Binary Search Trees



More on Trees: Decision Trees



From https:

//www.ibm.com/support/knowledgecenter/en/SS3RA7_15.0.0/com.ibm.spss.modeler.help/nodes_treebuilding.htm

• Org charts

• Directory structures

• Organic molecules

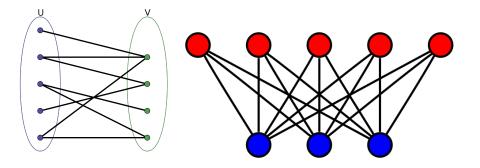
- **Theorem** (page 782): An undirected graph is a tree iff there is a unique simple path between any two vertices
- **Theorem** (page 788): A tree with *n* nodes has n 1 edges
- **Theorem** (page 789): A full *m*-ary tree with *i* internal vertices has *mi* + 1 vertices
- **Theorem** (page 790): There are at most m^h leaves in a *m*-ary tree of height *h*

Sec 10.1, 10.2

Some special families

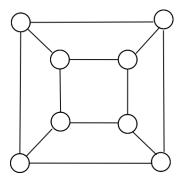
• Computational problems on graphs

Bipartite Graphs

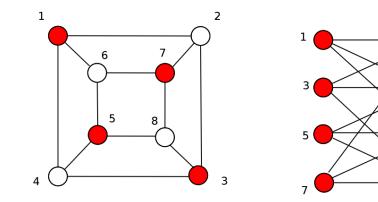


Bipartite Graphs - 2

- Vertex set V partitioned into V_1 , V_2 , all edges are between V_1 , V_2
- How can you recognize a bipartite graph?



Bipartite Graphs - 3



2

4

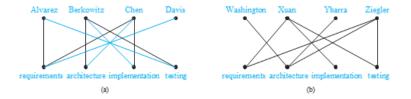
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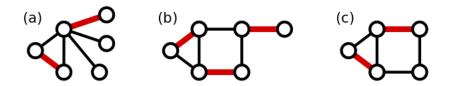
Bipartite Graphs - Coloring

- Theorem(page 690): A graph is bipartite iff it is 2 colorable
- **Proof:** A given 2-coloring implies it is bipartite; it is easy to get a 2-coloring if it is known to be bipartite
- How to get a valid 2-coloring? Greedy algorithm: color a node white, its neighbours red and so on
- Proof of correctness: later courses
- Any graph containing an odd length cycle is **not** bipartite

Bipartite Graphs - Matching



- A matching is a subset of edges such that no 2 edges are incident on the same vertex
- A maximum matching is a matching with the maximum number of edges



• Same definitions hold

• Are these graphs bipartite?

Bipartite Graphs - Maximum Matching

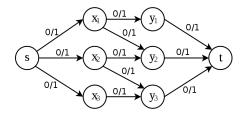
• When does a maximum matching possible?

• Let A be a set of vertices; N(A) is the set of its neighbour vertices

 Hall's Theorem (page 693): A bipartite graph has a complete matching iff |N(A)| ≥ |A| for all subsets A ⊆ V₁

Bipartite Graphs - Finding a Maximum Matching

- Hall's Theorem (page 693) only guarantees the existence of a matching
- It does not yield an efficient algorithm to find a maximum matching
- Most commonly used algorithm uses Network Flow to find a maximal matching



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Connectivity

• Graph Isomorphism

• Graph Coloring