

# HEAPS (9.3)

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EECS 2011

## Priority Queue ADT (9.1, 9.2)

- A priority queue stores a collection of entries
- Each **entry** is a pair (key, value)
- Main methods of the Priority Queue ADT
  - **insert**(k, v)  
inserts an entry with key k and value v
  - **removeMin**()  
removes and returns the entry with smallest key, or null if the the priority queue is empty
- Additional methods
  - **min**()  
returns, but does not remove, an entry with smallest key, or null if the the priority queue is empty
  - **size**(), **isEmpty**()
- Applications:
  - Standby flyers
  - Auctions
  - Emergency room waiting list
  - Routing priority at routers in a network

## Example

- A sequence of priority queue methods:

Method	Return Value	Priority Queue Contents
insert(5,A)		{ (5,A) }
insert(9,C)		{ (5,A), (9,C) }
insert(3,B)		{ (3,B), (5,A), (9,C) }
min()	(3,B)	{ (3,B), (5,A), (9,C) }
removeMin()	(3,B)	{ (5,A), (9,C) }
insert(7,D)		{ (5,A), (7,D), (9,C) }
removeMin()	(5,A)	{ (7,D), (9,C) }
removeMin()	(7,D)	{ (9,C) }
removeMin()	(9,C)	{ }
removeMin()	null	{ }
isEmpty()	true	{ }

## Entry ADT

- An **entry** in a priority queue is simply a key-value pair
- Priority queues store entries to allow for efficient insertion and removal based on keys
- Methods:
  - **getKey**: returns the key for this entry
  - **getValue**: returns the value associated with this entry
- As a Java interface:

```
/**
 * Interface for a key-value
 * pair entry
 */
public interface Entry<K,V> {
    K getKey();
    V getValue();
}
```

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## Implementations of PQs

Data structure	<i>insert()</i>	<i>min()</i>	<i>deleteMin()</i>
Unsorted array	$O(\quad)$	$O(\quad)$	$O(\quad)$
Sorted array	$O(\quad)$	$O(\quad)$	$O(\quad)$
Unsorted doubly linked list	$O(\quad)$	$O(\quad)$	$O(\quad)$
Sorted doubly linked list	$O(\quad)$	$O(\quad)$	$O(\quad)$
AVL trees	$O(\quad)$	$O(\quad)$	$O(\quad)$

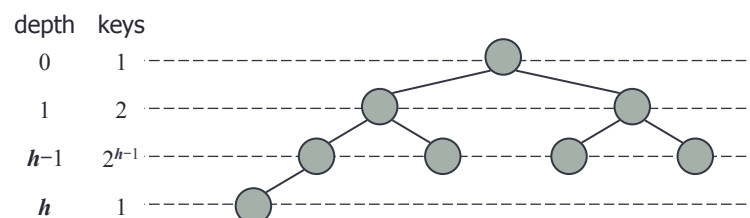
A data structure more efficient for PQs is **heaps**:

- *insert()*, *deleteMin()*:  $O(\log n)$
- *min()*:  $O(1)$

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## Complete Binary Trees

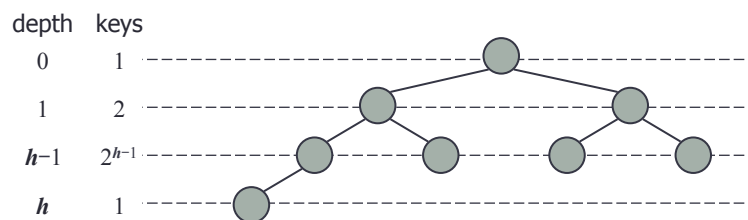
- Let  $h$  be the height of a binary tree.
  - for  $i = 0, \dots, h-1$ , there are  $2^i$  nodes at depth  $i$ .
    - that is, all levels except the last are full.
  - at depth  $h$ , the nodes are filled from left to right.



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## Complete Binary Trees (2)

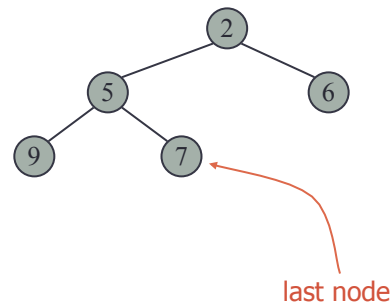
- Given a complete binary tree of height  $h$  and size  $n$ ,  
 $2^h \leq n \leq 2^{h+1} - 1$
- Which data structure is better for implementing complete binary trees, arrays or linked structures?



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## Heaps

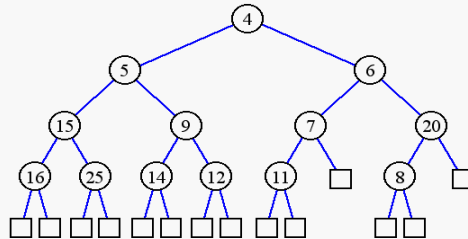
- A heap is a binary tree storing keys at its nodes and satisfying the following properties:
  - Heap-Order:** for every internal node  $v$  other than the root,  $key(v) \geq key(parent(v))$
  - Complete Binary Tree:** let  $h$  be the height of the heap
    - for  $i = 0, \dots, h-1$ , there are  $2^i$  nodes at depth  $i$ .
    - at depth  $h$ , the nodes are filled from left to right.
- The last node of a heap is the rightmost node of depth  $h$ .
- Where can we find the smallest key in a min heap?  
The largest key?



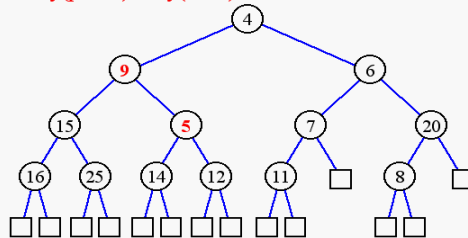
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## Examples that are not heaps

- bottom level is not left-filled



- $\text{key}(\text{parent}) > \text{key}(\text{child})$



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## Height of a Heap

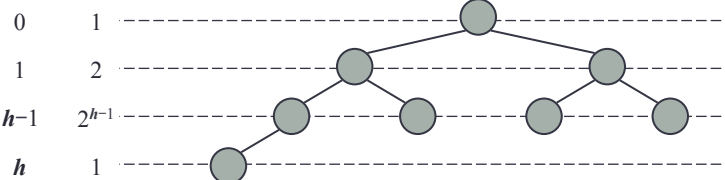
- **Theorem:** A heap storing  $n$  keys has height  $O(\log n)$

Proof: (we apply the complete binary tree property)

- Let  $h$  be the height of a heap storing  $n$  keys
- Since there are  $2^i$  keys at depth  $i = 0, \dots, h-1$  and at least one key at depth  $h$ , we have  $n \geq 1 + 2 + 4 + \dots + 2^{h-1} + 1$
- Thus,  $n \geq 2^h$ , i.e.,  $h \leq \log n$



depth keys



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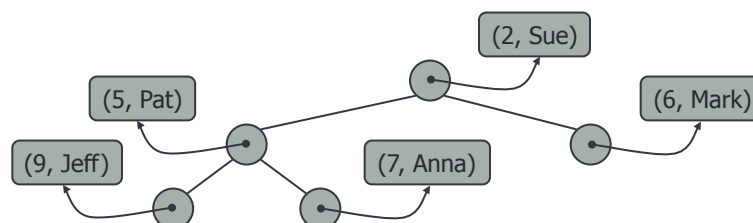
## Max Heap

- The definition we just discussed is for a *min* heap.
- Analogously, we can declare a *max* heap if we need to implement *deleteMax* operation instead of *deleteMin*.

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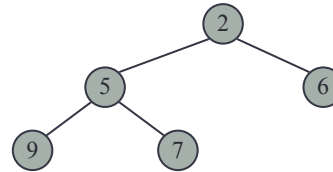
## Heaps and Priority Queues

- We can use a heap to implement a priority queue
- We store a (key, value) item at each internal node
- We keep track of the position of the last node



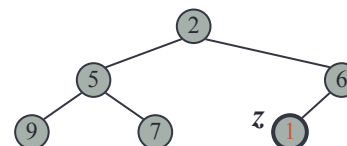
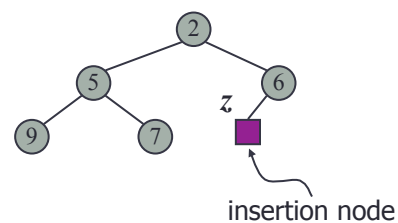
## Array-based Heap Implementation

- We can represent a heap with  $n$  keys by means of an array of length  $n$
- The root is at rank 1.
- For the node at rank  $i$ 
  - the left child is at rank  $2i$
  - the right child is at rank  $2i + 1$



## Insertion into a Heap

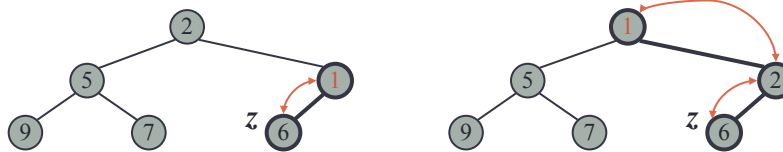
- Method insert of the priority queue ADT corresponds to the insertion of a key  $k$  to the heap
- The insertion algorithm consists of three steps
  1. Find the insertion node  $z$  (the new last node)
  2. Store  $k$  at  $z$
  3. Restore the heap-order property (discussed next)



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## Upheap Percolation (Bubbling)

- After the insertion of a new key  $k$ , the heap-order property may be violated
- Algorithm upheap restores the heap-order property by swapping  $k$  along an upward path from the insertion node
- Upheap terminates when the key  $k$  reaches the root or a node whose parent has a key smaller than or equal to  $k$
- Since a heap has height  $O(\log n)$ , upheap runs in  $O(\log n)$  time

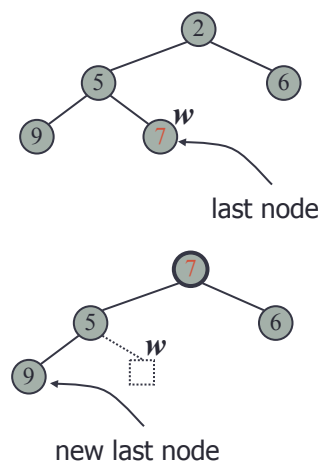


<http://www.cs.usfca.edu/~galles/JavascriptVisual/Heap.html>

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## Removal from a Heap (*deleteMin*)

- Method *deleteMin* of the priority queue ADT corresponds to the removal of the root key from the heap
- The removal algorithm consists of three steps
  1. Replace the root key with the key of the last node  $w$
  2. Remove  $w$
  3. Restore the heap-order property (discussed next)





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## Downheap Percolation

- After replacing the root key with the key  $k$  of the last node, the heap-order property may be violated
- Algorithm downheap restores the heap-order property by swapping key  $k$  along a downward path from the root
- Upheap terminates when key  $k$  reaches a leaf or a node whose children have keys greater than or equal to  $k$
- Since a heap has height  $O(\log n)$ , downheap runs in  $O(\log n)$  time



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## More Heap Operations

Assume a min heap.

- `decreaseKey(i, k)`
  - $T[i] = T[i] - k$ , then percolate up.
  - Example: system admin boosts the priority of his/her jobs.
- `increaseKey(i, k)`
  - $T[i] = T[i] + k$ , then percolate down.
  - Example: penalizing misbehaved processes.
- `delete(i)`
  - Perform `decreaseKey(i,  $\infty$ )` then `deleteMin()`.
    - $\infty$  means a very large number, so  $T[i] = T[i] - \infty$  has the highest priority (root)
  - Example: removing a print job from the priority queue.
- Note: searching for the element at index  $i$  takes  $O(n)$  time in the worst case, but we expect not to use the above methods very often.

## Next lecture ...

- Heap Sort (9.4.2)