

## Homework Assignment #2

### Due: June 2, 2020 at 11:30 a.m.

1. Let  $m \geq 2$  be a fixed positive integer. Consider the following ADT. A state of the ADT is an  $m$ -tuple of integers  $\langle v_1, v_2, \dots, v_m \rangle$ . The ADT supports two operations:

- INCREMENT( $i$ ) which increases the value of  $v_i$  by 1.
- MAX returns an index of the maximum value, that is it returns an  $i$  such that  $v_i \geq v_j$  for all  $j$ .

Assume that the initial state of the ADT is  $\langle 0, 0, \dots, 0 \rangle$ . We shall use  $m$  as the measure of the size of the ADT and state time complexity in terms of  $m$ .

Our goal is to design a data structure for this ADT. Each component  $v_i$  will be stored in binary in a dynamically-sized table  $T_i$ . Each entry of  $T_i$  stores a single bit of  $v_i$ . This allows each component to grow arbitrarily large, because we can resize the table to get longer and longer as the value grows. Assume  $size[i]$  stores the current size of the dynamically-sized table  $T_i$ . It gets updated automatically whenever  $T_i$  is enlarged. Initially,  $size[i] = 1$  for all  $i$ .

If this is all we do for the data structure, INCREMENTS will have good amortized time but MAX operations could be very expensive (as you will show in part (b)). In part (c), you will see how to make the MAX operation faster by storing some additional information in the data structure.

- (a) Given two numbers represented in binary, give a simple algorithm to compare them. It should output 0 if they are the same, 1 if the first number is bigger, and  $-1$  if the second one is bigger. If accessing a bit takes  $O(1)$  time, the time required by your comparison algorithm should be linear in the lengths of the input numbers.
- (b) Suppose we compute the MAX as follows.

```

1  MAX
2      res ← 1
3      for i ← 2..m
4          if (number represented in  $T_i$ ) > (number represented in  $T_{res}$ ) then
5              res ← i
6          end if
7      end for
8      return res
9  end MAX

```

Line 4 uses your algorithm from part (a).

Show that there is a sequence of  $s$  operations (starting from the initial state  $\langle 0, 0, \dots, 0 \rangle$ ) that takes a total of at least  $s \cdot 2^m$  steps. This proves that the amortized cost per operation is  $\Omega(2^m)$ .

Hint: start by doing lots of INCREMENT operations to make the values big so that the comparisons needed by MAX will be slow.

- (c) We now add a little more information to our data structure. We store the index  $max$  of a maximum component. Now a MAX operation can simply return  $max$ . But we need to do some work to update  $max$  when an INCREMENT occurs. To do so efficiently, we also store an array  $diff[1..m]$ , where  $diff[i]$  is the index of the most significant position where component  $T_i$  differs from the maximum component. Assume the least significant bit is indexed by 0. If  $T_i$  is a maximum component, then  $diff[i] = -1$ . For example, if  $m = 4$  and

$$\begin{aligned}
 T_1 &= 1001001011 \\
 T_2 &= 0010010101 \\
 T_3 &= 1001000110 \\
 T_4 &= 1001001011
 \end{aligned}$$

then,  $max$  can be either 1 or 4 and

$$diff[1] = -1$$

$$diff[2] = 9$$

$$diff[3] = 3$$

$$diff[4] = -1$$

Give pseudocode for  $INCREMENT(i)$ , including how it updates  $max$  and  $diff$ , and use the accounting method or the potential method to prove that the amortized time per  $INCREMENT$  operation is  $O(m)$  using your scheme.

You do *not* have to give a formal proof of correctness for your algorithm but your code should be well commented so that a reader can understand how and why it works.