

EECS 2011 M: Fundamentals of Data Structures

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Course page: <http://www.eecs.yorku.ca/course/2011M>
Also on Moodle

Hash Tables

Ch. 9.1, 9.2

Applications

- Dictionaries
- Set membership queries
- Union, intersection of sets

Note: Some slides in this presentation have been adapted from the authors' slides.

Dictionaries

set S of elements, each with an associated *key*, *value* pairs.

Complexity of lookup in a set of size n :

- Unsorted list: $\Omega(n)$ worst-case time
- Sorted list: $\Omega(\log n)$ worst-case time
- Search trees (later topic): $\Omega(\log n)$ worst-case time

Q: (how) can we do better?

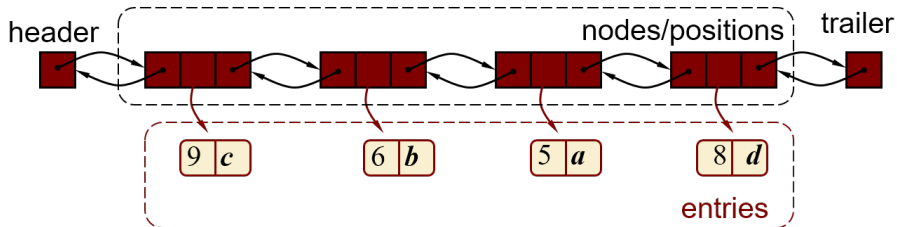
The Map ADT

A map M is a searchable collection of key-value entries

- Main operations: search, insert, and delete items
- Multiple entries with the same key are not allowed
- ADT:
 - $get(k)$: return value of entry with key k , or null
 - $put(k, v)$: insert entry (k, v) ; return old value associated with k , or null
 - $remove(k)$: remove entry with key k , return its value/null
 - $size()$, $isEmpty()$
 - $entrySet()$: returns an iterable collection of entries in M
 - $keySet()$: return an iterable collection of the keys in M
 - $values()$: return an iterable collection of the values in M

List-based Maps

Doubly linked list implementation:



List-based Maps

Performance:

- put, get and remove take $\theta(n)$ time since in the worst case (the item is not found) we traverse the entire sequence to look for an item with the given key
- The unsorted list implementation is effective only for small maps

Direct Access Tables

- Define a one-to-one function from keys to natural numbers
- Allocate an array large enough to have entire key space as indices
- Ignoring space and array initialization overhead, add/delete/find are all $\theta(1)$ operations

Q: Can we get “similar” times for smaller arrays?

Hash Tables

- A hash table is a data structure that can be used to make map operations faster. While worst-case is still $\theta(n)$, average case is typically $\theta(1)$
- A hash table for a given key type consists of
 - Hash function h
 - Array (called table) of size N
- the goal is to store item (k, v) at index $i = h(k)$ of the hash table where $h()$ is a hash function whose input is the key of the element and output is a location in the hash table

Hash Functions

- A hash function h maps keys of a given type to integers in a fixed interval $[0, N - 1]$,
E.g., $h(k) = k \bmod N$ is a hash function for integer keys. The size N is usually chosen to be a prime.
- Hash functions are many-to-one, there can be *collisions*
- Since different keys map to the same location, need to resolve collisions carefully

Hash Functions - examples

- $h_2(y) = y \bmod N$
- Multiply, Add and Divide (MAD):
 $h_2(y) = (ay + b) \bmod N$, a, b non-negative integers, and $a \bmod N \neq 0$
- Integer cast: We reinterpret the bits of the key as an integer
- Component sum: partition the bits of the key into components of fixed length (e.g., 16 or 32 bits) and sum the components (ignoring overflows)

Polynomial Hash Functions

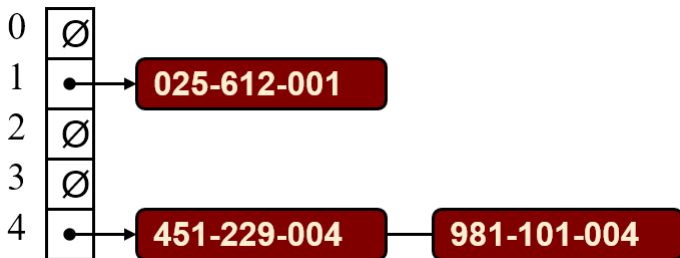
- Partition the key into fixed length (e.g., 8, 16 or 32 bits) chunks $a_0, a_1, \dots, a_{n-1}$. Fix a constant $z > 1$.
- Evaluate (ignoring overflows)
$$p(z) = a_0 + a_1z + a_2z^2 + \dots + a_{n-1}z^{n-1}$$
- Especially suitable for strings
- Horner's rule for computing $p(z)$ in $\theta(n)$ time
 - 1 $p_0(z) = a_{n-1}$
 - 2 $p_i(z) = a_{n-i-1} + zp_{i-1}(z) (i = 1, 2, \dots, n-1)$
 - 3 $p(z) = p_{n-1}(z)$

Clustering Behaviour of Hash Functions

- Desirable in some applications: like searching with approximate keys.
- Undesirable in some scenarios: e.g. cryptographic hash functions

Handling Collisions - Techniques

- Chaining



- Open addressing with Linear Probing
- Open addressing with Double Hashing

Chaining

- A new data structure at each location
- Often a linked list

For linked list based chaining:

- Worst case time for insert: $\theta(1)$
- Worst case time for delete, search: $\Omega(n)$
- In practice, the array size can be chosen to tradeoff array initialization costs with search/delete costs

Open Addressing with Linear Probing

the colliding item is placed in another cell of the table

- Linear Probing: colliding item in the next (circularly) available table cell
- Each table cell inspected is referred to as a “probe”
- Colliding items lump together, so that future collisions cause a longer sequence of probes

Linear Probing ($h(k) = k \bmod 7$)

0	1	2	3	4	5	6
	50					

Insert 50

	50				47	
--	----	--	--	--	----	--

Insert 47

	50	43			47	
--	----	----	--	--	----	--

Insert 43

	50	43	31		47	
--	----	----	----	--	----	--

Insert 31

	50	43	31	36	47	
--	----	----	----	----	----	--

Insert 36

	50	43	31	36	47	20
--	----	----	----	----	----	----

Insert 20

27	50	43	31	36	47	20
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Insert 27

Linear Probing - Details

get(k)

- start at cell $h(k)$
- probe consecutive locations until
 - An item with key k is found, or
 - An empty cell is found, or N cells have been unsuccessfully probed

Insertions and deletions:
problem

0	1	2	3	4	5	6
27	50	43	31	36	47	20

Delete 50

27		43	31	36	47	20
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Delete 43

↑
Fails?

Solution: introduce a special object, called DEFUNCT, to replace deleted elements

Linear Probing: Add and Remove

remove(k)

- search for an entry with key k
- If such an entry (k, o) is found, replace it with the special item DEFUNCT and return o
- Else, return null

put(k, o)

- throw an exception if the table is full
- start at cell $h(k)$
- probe consecutive cells until
 - A cell i is found that is either empty or stores DEFUNCT, or
 - N cells have been unsuccessfully probed
- We store (k, o) in cell i

Open addressing with Double Hashing

Suppose that $i = h(k)$ leads to a collision.

- uses a secondary hash function $h'(k)$ in addition to the primary hash function $h(x)$
- iteratively probe the locations $(i + jh'(k)) \bmod N$ for $j = 0, 1, \dots, N - 1$
- $h'(k)$ cannot have zero values
- Choose N to be prime. Common choices for $h'(k)$:
 - $h'(k) = q - k \bmod q$, where
 - $q < N$ and q is prime
- The possible values for $h'(k)$ are $1, 2, \dots, q$

Performance of Hashing Schemes

- In the worst case, searches, insertions and removals on a hash table take $\Omega(n)$ time
- worst case: all keys collide
- The load factor $\lambda = n/N$ affects the performance of a hash table
 - chaining: performance is typically good for $\lambda < 0.9$
 - open addressing: performance is usually good for $\lambda < 0.5$
 - `java.util.HashMap` maintains $\lambda < 0.75$
- Open addressing can be more memory efficient than separate chaining
- However, chaining is typically as fast or faster than open addressing.

Application of Hashing

- small databases
- compilers
- browser caches
- Finding Set Intersection
 - Complexity: Average case $\theta(m + n)$
 - Alternative: Merge sort modification

Rehashing

When the load factor λ exceeds threshold, the table must be rehashed.

- A larger table is allocated (typically at least double the size)
- A new hash function is defined.
- All existing entries are copied to this new table using the new hash function.

Cryptographic Hash Functions

- Used for digital signatures. A digital signature must
 - depend on the content being signed, and
 - be short
 - Must be hard to forge

Demo at www.hashemall.com