Basic Search Methods

Block World

Rearrange blocks in a block world



Word Puzzle

- Rearrange letters into a particular order
 - Tiles can move horizontally or vertically into the empty space



Knapsack Packing

- Put items into a container
 - Here, put rectangles into a box



Travelling Salesman

 Travel from home to each of the cities once and return home.



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Commonality of actions

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 - Actions take place
 - Blocks are moved, one at a time
 - Tiles are moved, one at a time
 - Rectangles move, one at a time
 - Salesman moves, one city at a time

• What is a common property of the actions?

Commonality of actions – 2

- What is a common property of the actions?
 - The problem situation changes
 - I.e. the state of the problem changes

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 - You have a subproblem

- What do you do in solving a problem?
 - Given an initial state
 - Given a goal state
 - Given a set of actions
 - Traverse from state to state, by applying actions
 - As an action is done you can consider the new state as being the new initial state
 - You have a sub-problem
 - Stop when a goal state is reached

• What do you need to do in creating a programming solution for a problem?

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- What else do you need?

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- What are its vertices and edges?
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- Is the graph directed or un-directed?
 - Problem dependent
 - Undirected Blocks, Word puzzle
 - Directed Knapsack, travelling salesman

State space solution

In state space, what is a solution?

State space solution – 2

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 - A path from the start state to the goal state
- How do you find a path in the state space graph?
State space solution – 3

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- How do you find a path in the state space graph?
 - Explore the graph by trying different paths

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 - As a tree
- What is the problem?
 - Graphs have loops
 - Need to remove the loops
 - Implies checking that nodes do not repeat in the path
 - Logically breaking edges in the graph

Tree searching

- The state space is logically searched as a tree.
 - We say the tree is traversed
- What are the two fundamental tree traversal methods?

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 - Depth first
 - Breadth first

Tree searching – 3

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 - We say the tree is traversed
- What are the two fundamental tree traversal methods?
 - Depth first
 - Breadth first

 - Bidirectional ← Variation 2

Depth-first search



Depth-first search one iteration

- Candidate paths kept in a list
 - [[D, A], [C, A], [B, A], [A]]
- Remove first path, extend it, add extensions to the front of the list
 - [[I, D, A], [H, D, A], [C A], [B A], [A]]



Why backwards? Each path. Paths found.

- Find shortest solution? (Y, N)
- Time complexity
 - Consider B (branching factor) and Dmax (max depth of search)
 - Why not D?
- Space complexity
 - Consider B (branching factor) and Dmax (max depth of search)

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- Time complexity is O(B^{Dmax})
 - On average have to follow half the paths up to the maximum depth
- Space complexity is O(Dmax)
 - Current path is most of the space, with linear overhead for backtracking

Depth-first problem

What is the major problem with depth-first search?

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Depth-first problem – 4

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- What do can be done to prevent this?
 - Set a maximum depth

• What is the problem with setting a maximum depth of search?

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 - Incremental deepening

Iterative-deepening search

- Depth-first search done repetitively with increasing depth
 - Why is this good?

Iterative-deepening search – 2

- Depth-first search done repetitively with increasing depth
 - Why is this good?
 - Avoids unbounded descent on any path

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- Time complexity is O(B^D)
 - Generate all nodes up to depth D
- Space complexity is O(D)
 - Performs (D+1) depth-first searches

Breadth-first search



Breadth-first search one iteration

- Candidate paths kept in a list
 - [[D,A], [E,B,A], [F,B,A], [G,C,A]]
- Remove first path, extend it, add extensions to the end of the list
 - [[E,B,A], [F,B,A], [G,C,A], [I, D, A], [H, D, A]]



Breadth-first search properties

- Finds shortest solution? (Y, N)
- Time complexity
 - Consider B (branching factor) and D (depth of search)
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- Space complexity is O(B^D)
 - Need to keep all paths to be able to lengthen them

Bidirectional search

What is bidirectional search?

Bidirectional search – 2

- Do breadth-first search from the Start to the Goal
- Simultaneously do a breadth-first search from the Goal to the Start



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- Find shortest solution? (Y, N)
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 - About half of breadth-first depth is searched in each direction
- Space complexity is O(B^{D/2})
 - About half of breadth-first paths are kept in each direction

Bidirectional search problems

What can be a problem with bidirectional search?

Bidirectional search problems – 2

- What can be a problem with bidirectional search
 - Need to know the goal state

Bidirectional search problems

- What can be a problem with bidirectional search
 - Need to know the goal state
 - Need to be able to have inverse of successor function

Bidirectional alias

What alias do you know for bidirectional search?

Bidirectional alias – 2

- What alias do you know for bidirectional search?
 - Forward chaining
 - Backward chaining

Time & space complexity summary

 Breadth-first and iterative deepening guarantee shortest solution

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Time & space complexity summary – 4

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- Breadth-first has high space complexity
- Depth-first has low space complexity May search far below goal state depth
- Iterative deepening has best performance in terms of orders of complexity

What are the problems with basic search?

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- What can we do about it?
 - Use information / knowledge of the state space to make the search more efficient
 - Use heuristics to guide us

Heuristic searches

- Best-first search
- Hill climbing, steepest descent
- A* algorithm
- Beam search
- IDA* algorithm
 - Iterative deepening A*
- RBFS algorithm
 - Recursive Best First Search