











![](_page_3_Figure_1.jpeg)

![](_page_3_Figure_2.jpeg)

## Link State Routing

- □ designed to overcome drawbacks of distance-vector
- each router determines link cost on each interface
- advertises set of link costs to all other routers in topology
- □ if link costs change, router advertises new values
- each router constructs topology of entire configuration
  - can calculate shortest path to each dest
  - use to construct routing table with first hop to each dest
- do not use distributed routing algorithm, but any suitable alg to determine shortest paths, eg. Dijkstra's algorithm
- Open Shortest Path First (OSPF) is a link-state protocol

![](_page_4_Figure_11.jpeg)

![](_page_5_Figure_1.jpeg)

![](_page_5_Figure_2.jpeg)

![](_page_6_Figure_1.jpeg)

Destination	Next Hop	Distance
N1	R3	10
N2	R3	10
N3	R3	7
N4	R3	8
N6	R10	8
N7	R10	12
N8	R10	10
N9	R10	11
N10	R10	13
N11	R10	14
H1	R10	21
R5	R5	6
R7	R10	8
N12	R10	10
N13	R5	14
N14	R5	14
N15	R10	17

![](_page_7_Figure_1.jpeg)

- link-state and distance-vector not effective for exterior routing protocols
- □ distance-vector
  - assumes routers share common distance metric
  - but different ASs may have different priorities & needs
  - but have no info on AS's visited along route
- link-state
  - different ASs may use different metrics and have different restrictions
  - flooding of link state information to all routers unmanageable

![](_page_7_Figure_10.jpeg)

## Border Gateway Protocol (BGP)

- □ developed for use with TCP/IP model
- □ is preferred exterior routing protocol of the Internet
- uses messages sent over TCP connections
- □ current version is BGP-4 (RFC 1771, RFC 4271)

![](_page_8_Figure_6.jpeg)

![](_page_9_Figure_1.jpeg)

Open	Used to open a neighbor relationship with another router.
Update	Used to (1) transmit information about a single route and/or (2) list multiple routes to be withdrawn.
Keepalive	Used to (1) acknowledge an Open message and (2) periodically confirm the neighbor relationship
Notification	Send when an error condition is detected.

## Reference

 Data and Computer Communications, William Stallings, 9<sup>th</sup> edition, section 19.2

## Least Cost Algorithms

- basis for routing decisions
  - can minimize hop with each link cost 1
  - or have link value inversely proportional to capacity
- defines cost of path between two nodes as sum of costs of links traversed
  - □ in network of nodes connected by bi-directional links
  - where each link has a cost in each direction
- for each pair of nodes, find path with least cost
  link costs in different directions may be different
- alternatives: Dijkstra or Bellman-Ford algorithms

![](_page_11_Figure_1.jpeg)

![](_page_11_Figure_2.jpeg)

![](_page_12_Figure_1.jpeg)

Dijkstra's Algorithm Example											
Iter	Т	L(2)	Path	L(3)	Path	L(4)	Path	L(5)	Path	L(6 )	Path
1	{1}	2	1–2	5	1-3	1	1–4	8	-	8	-
2	{1,4}	2	1–2	4	1-4-3	1	1–4	2	1-4–5	8	-
3	{1, 2, 4}	2	1–2	4	1-4-3	1	1–4	2	1-4–5	8	-
4	{1, 2, 4, 5}	2	1–2	3	1-4-5–3	1	1–4	2	1-4–5	4	1-4-5–6
5	{1, 2, 3, 4, 5}	2	1–2	3	1-4-5–3	1	1–4	2	1-4–5	4	1-4-5–6
6	{1, 2, 3, 4, 5, 6}	2	1-2	3	1-4-5-3	1	1-4	2	1-4–5	4	1-4-5-6