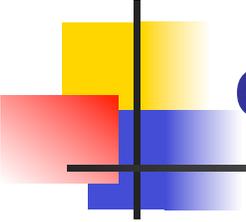


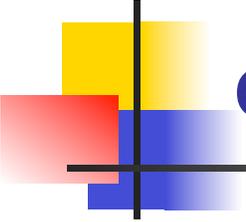
System Testing

Chapter 14



Overview system testing

- Common experience
 - In everyday live – not just programming
 - Use functional testing
 - Looking for correct behaviour, not looking for faults
- Intuitively familiar
 - Too informal

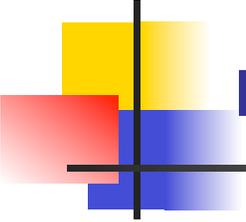


Overview system testing – 2

- Little test time due to delivery deadlines
 - **Too informal**

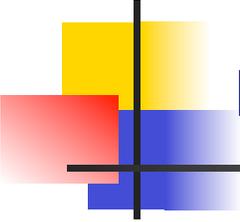
- Need a good understanding and theory
 - **Use threads**

 - **Atomic system functions**



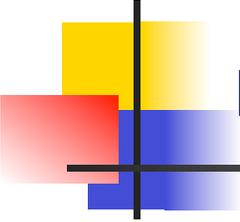
Possible thread definitions

- Difficult to define
 - **A scenario of normal usage**
 - **A system-level test case**
 - **A stimulus-response pair**



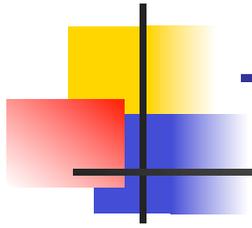
Possible thread definitions – 2

- **Behaviour that results from a sequence of system-level inputs**
- **An interleaved sequence of port input and output events**
- **A sequence of transitions in a state machine description of the system**



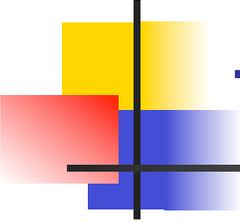
Possible thread definitions – 3

- **An interleaved sequence of object messages and executions**
- **A sequence of**
 - **Machine instructions**
 - **MM-paths**
 - **Program statements**
 - **Atomic system functions**



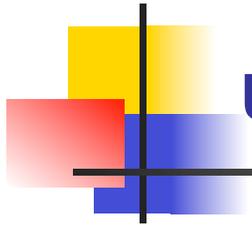
Thread levels

- **Threads can occur at what levels?**



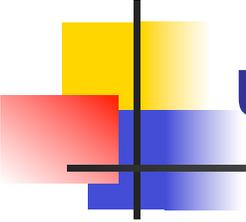
Thread levels – 2

- Unit level
- Integration level
- System level



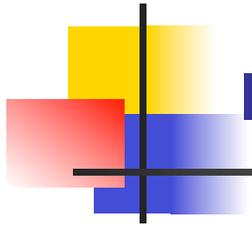
Unit level thread

- **Describe a unit level thread?**



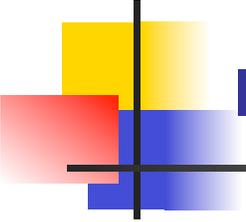
Unit level thread – 2

- An execution-time path of program text statements / fragments
- A sequence of DD-paths
- Tests individual functions



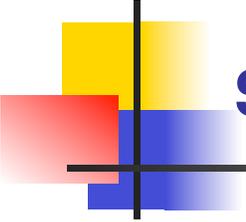
Integration level thread

- **Describe an integration level thread.**



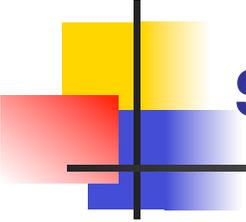
Integration level thread – 2

- An MM-path
- Tests interactions among units



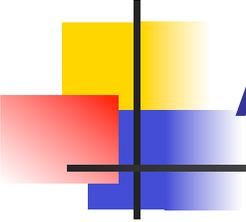
System level thread

- **Describe a system level thread.**



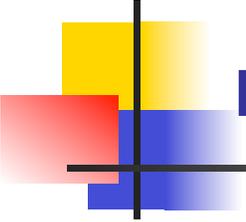
System level thread – 2

- A sequence of atomic system functions
 - **Results in an interleaved sequence of port input and output events**
- Tests interactions among atomic system functions



Atomic system function

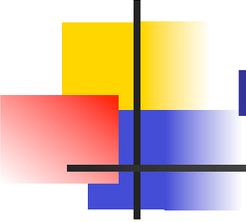
- **Describe an atomic system function.**



Definition – atomic system function

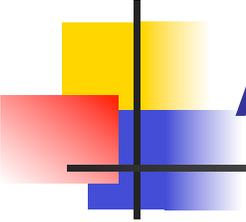
- Is an action that is observable at the system level in terms of
 - **Port input events**
 - **Port output events**

- Separated by points of event quiescence
 - **Analogous to message quiescence at the integration level**
 - **Natural end point**



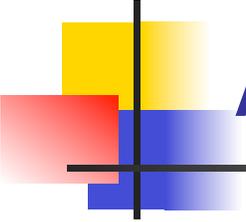
Definition – atomic system function – 2

- At system level no interest in finer resolution
- Seam between integration and system testing
 - **Largest item for integration testing**
 - **Smallest for system testing**



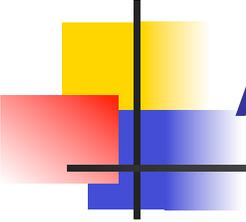
Atomic system function begin & end

- **Where would an atomic system function**
 - **Begin?**
 - **End?**



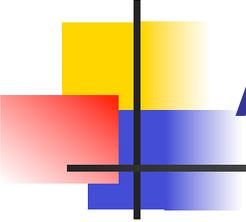
Atomic system function begin & end – 2

- Begin at a port input event
- Terminate with a port output event



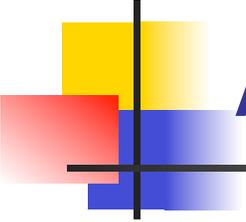
Atomic system function graph

- **Describe an atomic system function graph.**



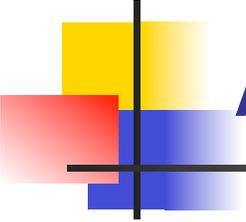
Atomic system function graph – 2

- **A directed graph where**
 - **Nodes are ASFs**
 - **Edges represent sequential flow from ASF to ASF**



ASF graph sink & source nodes

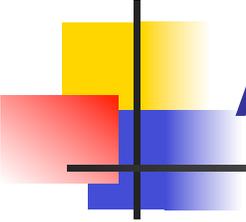
- **Describe the sink and source nodes of an ASF graph.**



ASF graph sink & source nodes – 2

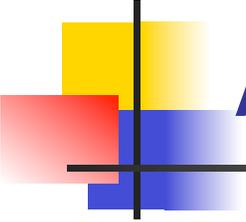
- **A source node is an entry point in the graph**
 - **In SATM the card entry function is a source**

- **A sink node is an exit node in the graph**
 - **In SATM the session termination function is a sink**



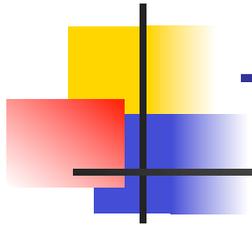
ASF graph thread

- **Describe a thread in an ASF graph.**



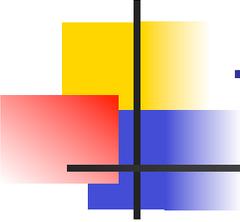
ASF graph thread – 2

- **A path from a source ASF to a sink ASF**



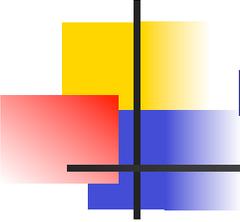
Thread graph

- **Describe a thread graph.**



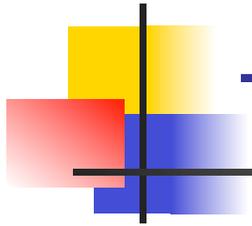
Thread graph – 2

- **A directed graph where**
 - **Nodes are system threads**
 - **Edges represent sequential execution of threads**



Basis for requirements specifications

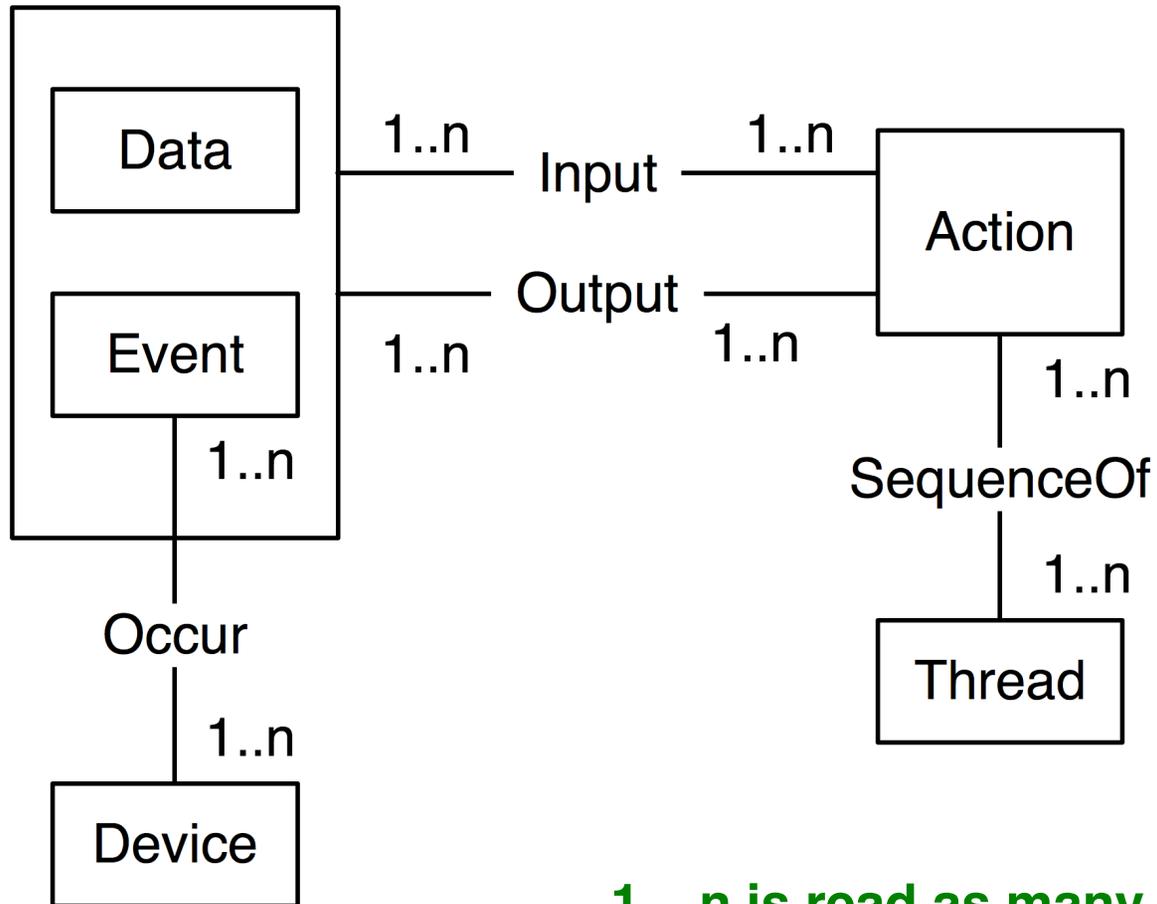
- All requirement specifications are composed of the following basis set of constructs
 - **Data**
 - **Events**
 - **Threads**
 - **Actions**
 - **Devices**
- All systems can be described in terms of the basis set of constructs



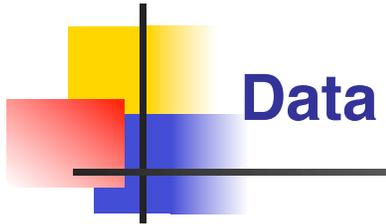
Thread graph

- **Describe a thread graph.**

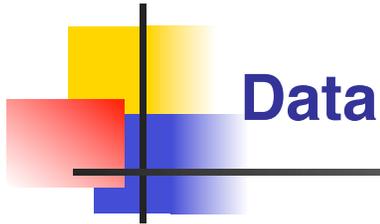
Basis concepts E/R model



1 .. n is read as many



- **In a system what is data.**



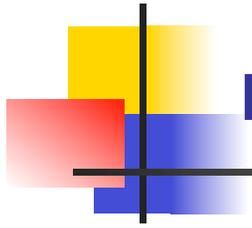
Data

- Focus on information used and created by the system

- Data is described using
 - **Variables, data structures, fields, records, data stores and files**

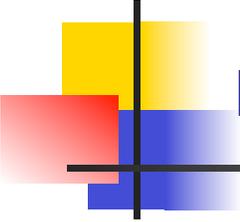
 - **Entity-relationship models describe highest level**

 - **Regular expressions used at more detailed level**
 - **Structure charts**
 - from Jackson System Development



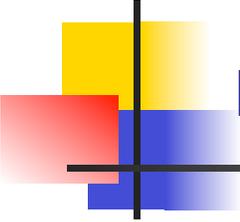
Data view

- **For what is a data view**
 - **Good?**
 - **Bad?**



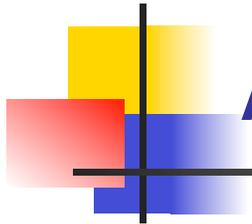
Data view – 2

- **Good for transaction view of systems**
- **Poor for user interface**



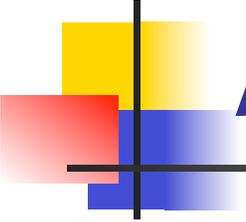
Data and thread relationships

- Threads can sometimes be identified from the data model
 - **1-1, N-1, 1-N and N-N relationships have thread implications**
 - **Need additional data to identify which of many entities is being used**
 - e.g. account numbers
- Read-only data is an indicator of source atomic system functions



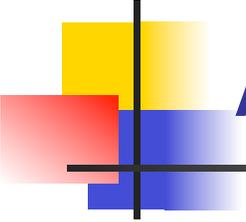
Actions

- **What is the relationship between a system and actions?**



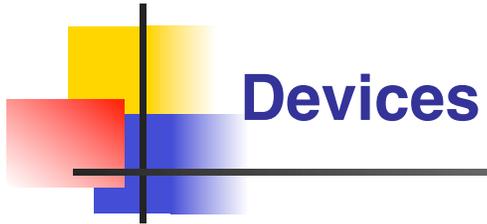
Actions – 2

- Action-centered modeling is a common form for requirements specification
- Actions have input and output
 - **Either data events**
 - **Or port events**
- Synonyms
 - **Transform, data transform, control transform, process, activity, task, method and service**



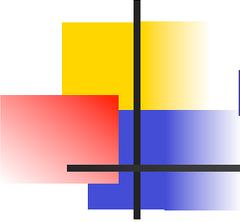
Actions – 3

- Used in functional testing
- They can be refined (decomposed)
 - **Basis of structural testing**



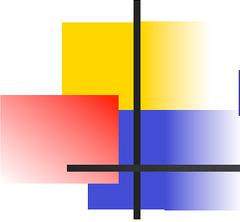
Devices

- **What is the relationship between systems and devices?**



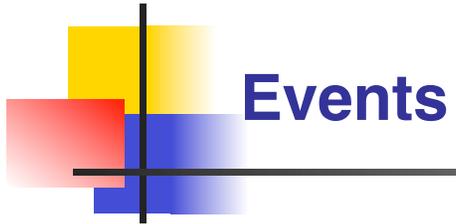
Devices – 2

- A port is a point at which an I/O device is attached to a system
- Physical actions occur on devices and enter / leave system through ports
 - **Physical to logical translation on input**
 - **Logical to physical translation on output**
- Port input and output is handled by devices



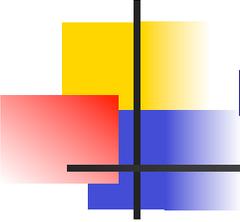
Devices – 3

- System testing can be moved to the logical level
 - **Ports**
 - **No need for devices**
- Thinking about ports helps testers define the input space and output space for functional testing



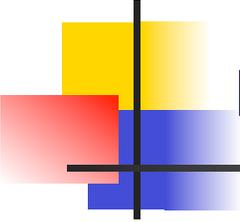
Events

- **What is the relationship between systems and events?**



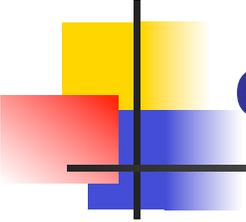
Events – 2

- A system-level input / output that occurs on a port device
- Data-like characteristic
 - **Input / output actions**
 - **Discrete**



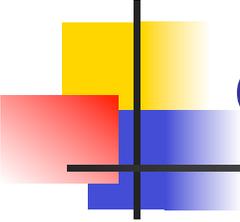
Events – 3

- Action-like characteristic
 - **The physical – logical translation done at ports**
- From the tester's viewpoint think of it as a physical event
 - **Logical event is a part of integration testing**



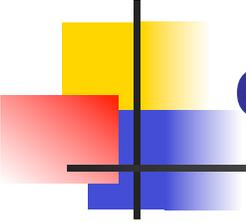
On continuous events

- No such thing
 - **Textbook is incorrect**
- Events have the following properties
 - **Occur instantaneously – No duration**
 - **A person can start eating and stop eating**
 - **No corresponding event eating**
 - **Take place in the real world, external to the system**
 - **Are atomic, indivisible, no substructure**
 - **Events can be common among entities**



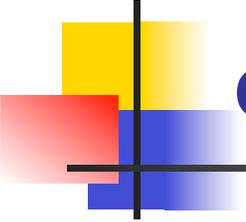
On continuous events – 2

- To handle duration
 - **Need start and end events**
 - **Time-grain markers to measure the duration**
- Events are detected at the system boundary by the arrival of a message
- For testing, events are also the output of a message
 - **The entry of the message to the real world is the event**



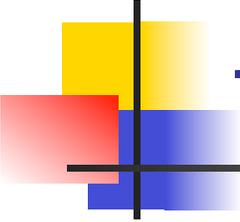
On the temperature event

- Temperature is not an a continuous event
 - **To be continuous a continuous message would have to arrive at the system boundary**
 - **A continuous message is not a meaningful concept**
 - **Messages are discrete**



On the temperature event – 2

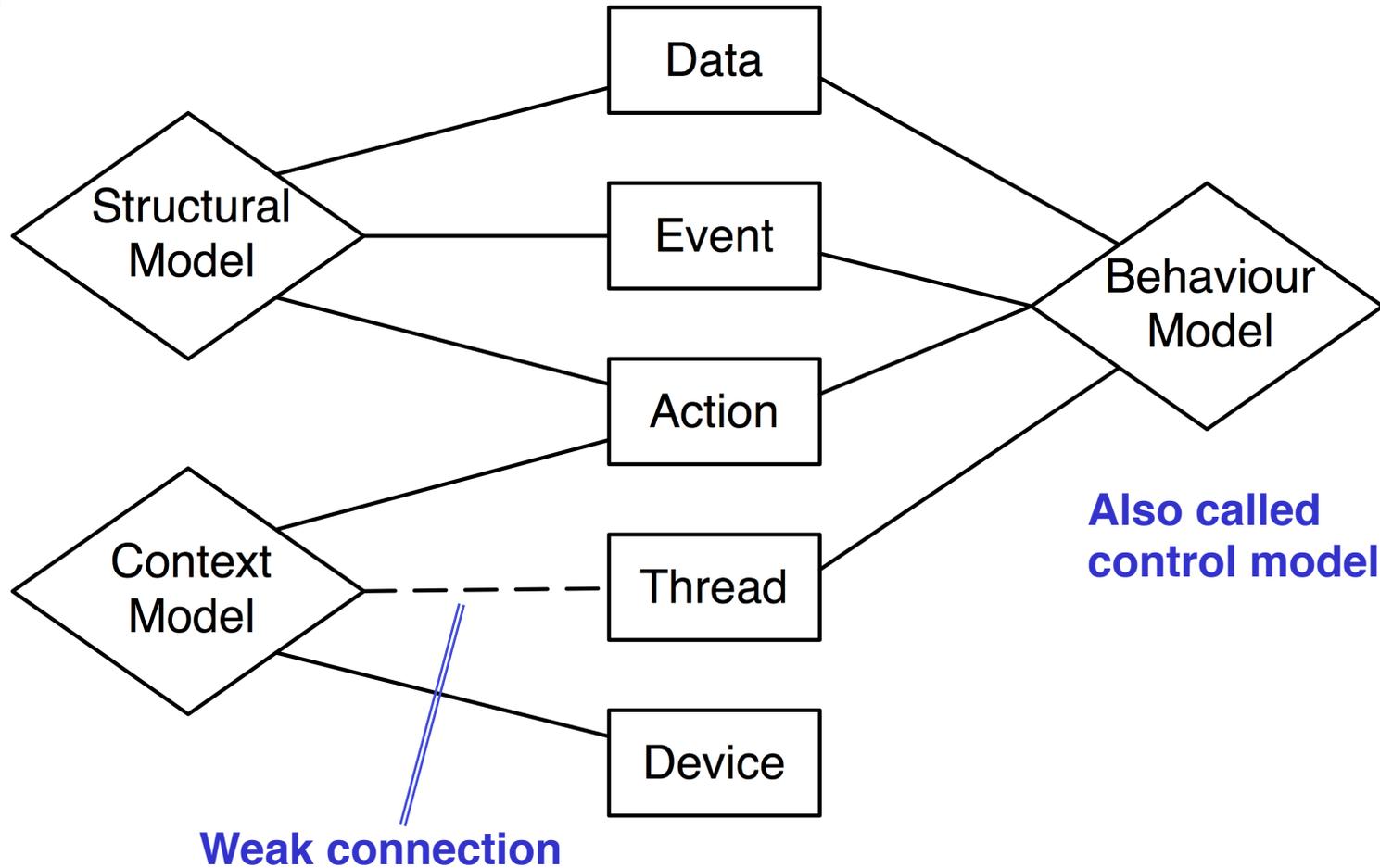
- In practice, thermometers do not send messages to a system, instead a system reads a thermometer
 - **Reading is at the discretion of the receiver not the sender**
 - **Called a statevector connection**
 - **The other option is message sending which is at the option of the sender, receiver can only read after the message is sent**
 - **Called a data stream connection**

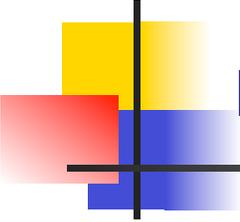


Threads

- Almost never occur in requirements specifications
 - **Testers have to search for them in the interactions among data, actions and events**
 - **Can occur in rapid prototyping with a scenario recorder**
- Behaviour models of systems make it easy to find threads
 - **Problem is they are models – not the system**

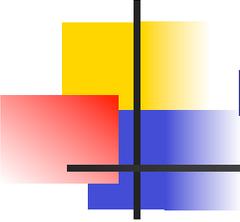
Modeling with basis concepts





Behaviour model

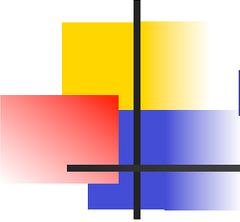
- Need appropriate model
 - **Not too weak to express important behaviours**
 - **Not too strong to obscure interesting behaviours**
- Decision tables
 - **Computational systems**



Behaviour model – 2

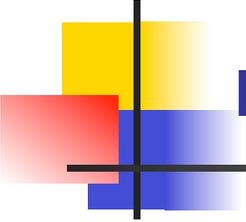
- Finite state machines
 - **Menu driven systems**

- Petri nets
 - **Concurrent systems**
 - **Good for analyzing thread interactions**



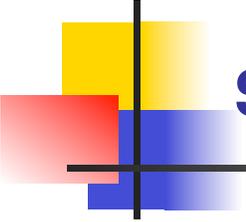
Finding threads in finite state machines

- Construct a machine such that
 - **Transitions are caused by port input events**
 - **Actions on transitions are port output events**
 - **Definition of the machine may be hierarchical, where lower levels are sub-machines – may be used in multiple contexts**



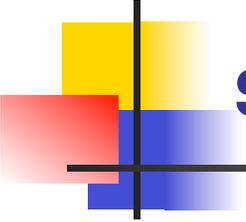
Finding threads in finite state machines – 2

- Test cases follow a path of transitions
 - Take note of the port input and output events along the path
 - Problem is path explosion
 - Have to choose which paths to test



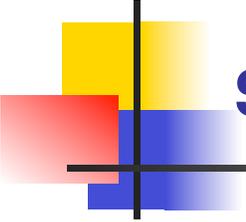
Structural strategy for thread testing

- Bottom-up
 - **The only one**



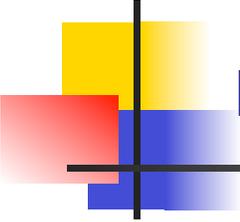
Structural coverage metrics

- **Given a finite state machine with input and output ports, what structural coverage metrics could we use?**



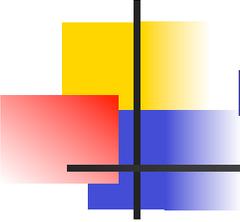
Structural coverage metrics – 2

- Use same coverage metrics as for paths in unit testing
 - **Finite state machine is a graph**
- Node coverage is analogous to statement coverage
 - **The bare minimum**
- Edge (transition) coverage is the better minimum standard
 - **If transitions are in terms of port events, then edge coverage implies port coverage**



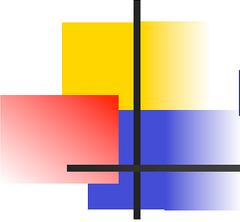
Functional strategies for thread testing

- **What are they?**
 - **Look at slides ST-28 and ST-30 for a hint**



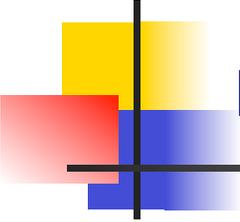
Functional strategies for thread testing – 2

- Event-based
 - **Recall that events are port input and output**
- Port-based
- Data-based



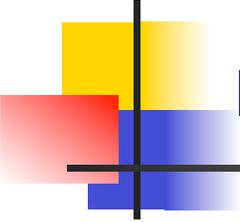
Port input thread coverage metrics

- Five port input thread coverage metrics are useful
 - **PI1: Each port input event occurs**
 - **Inadequate bare minimum**
 - **PI2: Common sequences of port input events occur**
 - **Most common**
 - **Corresponds to intuitive view of testing**
 - **Problem:**
 - What is a common / uncommon sequence?



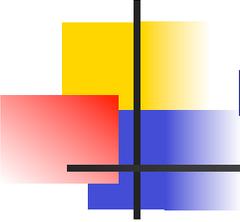
Port input thread coverage metrics – 2

- **PI3: Each port input event occurs in every relevant data context**
 - **Physical input where logical meaning is determined by the context in which they occur**
 - **Example is a button that has different actions depending upon where in a sequence of buttons it is pressed**



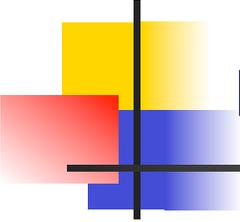
Port input thread coverage metrics – 3

- **PI4: For a given context, all inappropriate input events occur**
 - **Start with a context and try different events**
 - **Often used on an informal basis to try to break the system**
 - **Partially a specification problem**
 - Difference between prescribed and proscribed behaviour
 - Proscribed behaviour is difficult to enumerate



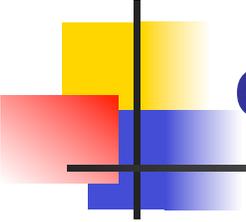
Port input thread coverage metrics – 4

- **PI5: For a given context, all possible input events occur**
 - **Start with a context and try all different events**



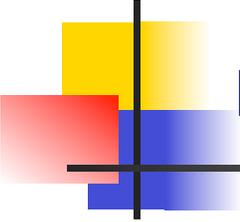
Event-based thread testing

- PI4 & PI5 are effective
 - **How does one know what the expected output is?**
 - **Good feedback for requirements specification**
 - **Good for rapid prototyping**



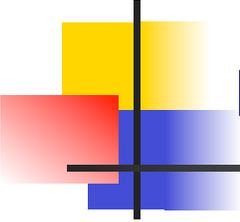
Output port coverage metrics

- Two output port coverage metrics
 - **PO1: Each port output event occurs**
 - **An acceptable minimum**
 - **Effective when there are many error conditions with different messages**
 - **PO2: Each port output event occurs for each cause**
 - **Most difficult faults are those where an output occurs for an unsuspected cause**
 - **Example: Message that daily withdrawal limit reached when cash in ATM is low**



Port-based thread testing

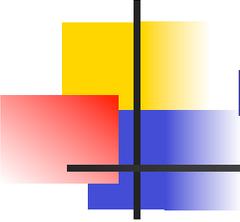
- For each port
 - Try threads that exercise ports with respect to the events in which they can engage
 - Useful when port devices come from outside suppliers
 - The many-to-many relationship between ports and events should be exercised in each direction
 - See E/R diagram
- Complements event-based testing



Event driven systems

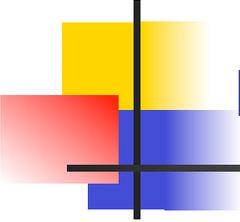
- Event and port based testing is good for event driven systems
- Reactive systems – react to input events, often with output events
 - **Are long running**
 - **Maintain a relationship with the environment**
 - **E/R model is simple and not particularly useful**

Note: payroll example when properly designed is a long running process. It is a sequence of payroll runs, where each run is in the context of previous runs.



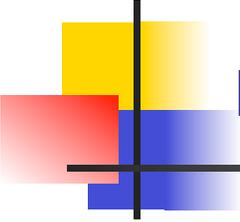
Data-based thread testing

- Good for systems where data is of primary importance
 - **Static**
 - **Transformational**
 - **Support transactions on a database**
 - **E/R model is dominant**



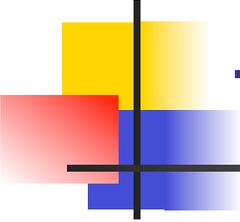
Data-based thread testing – 2

- Data-based coverage metrics – based on E/R model
 - **DM1: Exercise the cardinality of every relationship**
 - 1-1, 1-N, N-1, N-N
 - **DM2: Exercise the participation of every relationship**
 - **Does every specified entity participate**
 - **Can have numerical limits**



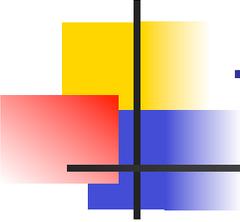
Data-based thread testing – 3

- **DM3: Exercise the functional dependencies among relationships**
 - **Functional dependencies are explicit logical connections**
 - Cannot repair a machine that one does not have



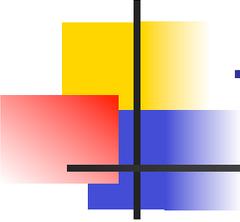
Thread explosion – Pseudo-structural testing

- Use the graph-based metrics as a cross-check on the functional coverage metrics
 - **Analogous to using DD-paths to identify gaps and redundancies of functional testing at the unit level**
- Pseudo occurs because graph is on the control model, which is not the system itself



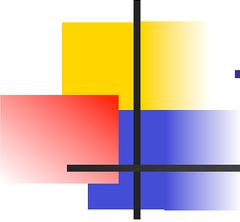
Thread explosion – Pseudo-structural testing – 2

- Weak method if model is poor
 - **used the incorrect model for type of system**
 - **Can be transformational, interactive, concurrent**
 - **Did not design a good model**



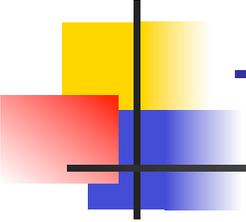
Thread explosion – Pseudo-structural testing – 3

- Decision tables and finite state machines good for atomic system function testing
- Thread-based testing is best done with Petri nets
 - **Devise tests to cover**
 - **Every place**
 - **Every transition**
 - **Every sequence of transitions**



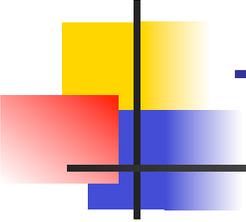
Thread based testing problem

- **What is the big problem of using thread based system testing?**



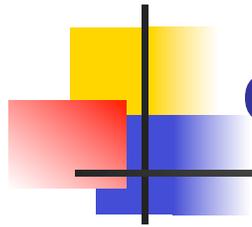
Thread based testing problem – 2

- **What is the big problem of using thread based system testing?**
 - **Thread explosion**
- **How do we deal with thread explosion?**



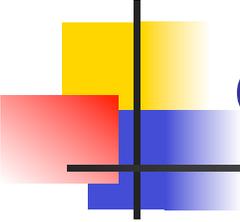
Thread based testing problem – 3

- **What is the big problem of using thread based system testing?**
 - **Thread explosion**
- **How do we deal with thread explosion?**
 - **Operational profiles**



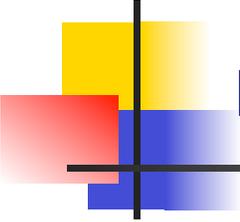
Operational profiles

- **What is an operational profile?**



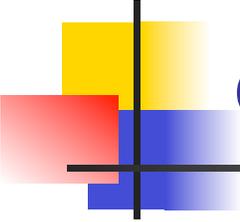
Operational profiles – 2

- Make use of Zipf's law
 - **80% of activities occur in 20% of the activity space**
- Make use of the idea that you want to reveal faults
 - **Testing is to find cases that when a failure occurs the location of a fault is revealed**
- Make use of the fact
 - **Distribution of faults is indirectly related to the reliability of a system**



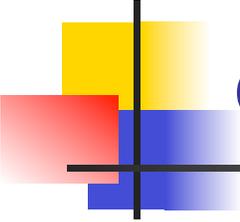
Reliability question

- **What is system reliability?**



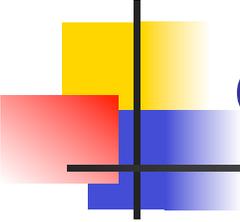
Operational profiles – 3

- Make use of system reliability
 - **System reliability is the probability that no failure occurs within a given time-period**
 - **Faults are on low use threads**
 - **The system is reliable**
 - **Faults are on high use threads**
 - **The system is unreliable**



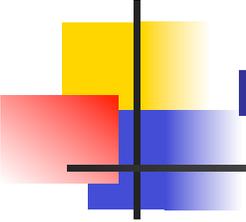
Operational profiles – 4

- When test time is limited maximize probability of finding faults by finding failures in the most frequently used threads



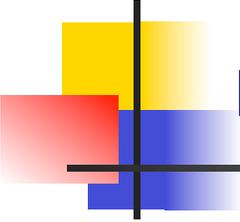
Operational profiles – 5

- Use a decision tree
 - Works well with hierarchy of finite state machines
 - Estimate the probability of each outgoing transition (sum to 1)
 - Can get statistics from customer monitoring / feedback
 - Probabilities in sub-states split the probability of the parent state
 - The probability of a thread is the product of the transitions comprising the thread
 - Test from high to low probability



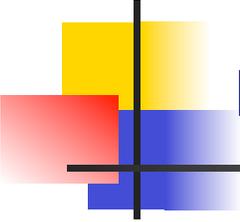
Progressive and regressive testing

- **What are they?**



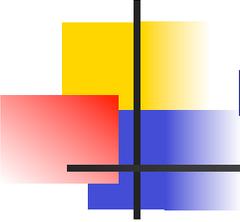
Progressive & regressive testing – 2

- Use of builds makes a need for regression testing
 - **20% of changes to a system create new faults**
 - **Regression testing takes a significant amount of time**
 - **Reduce by looking at difference between progression and regression testing**



Progressive & regressive testing – 3

- Most common regression testing is to run all the tests
- Progressive testing needs to be diagnostic to isolate faults more easily
 - **Use short threads**
- Regressive testing not as concerned with fault isolation
 - **Use long threads**



Progressive & regressive testing – 4

- Together have good coverage
 - **State & transition coverage sparse for progressive tests, dense for regressive tests**
- Different from operational profiles
 - **Good regressive tests have low operational probability**
 - **Good progressive tests have high operational probability**