CSE3213 Computer Network I

Chapter 3.7 and 3.9 Digital Transmission Fundamentals

Course page: http://www.cse.yorku.ca/course/3213

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Modem and Digital Modulation

Data Encoding

- Digital Data, Digital Signals
 NRZ, Bipolar, Manchester, etc.
- Digital Data, Analog Signals
 ASK, FSK, PSK, etc.
- Analog Data, Digital Signals
 - PCM
- Analog Data, Analog Signals
 - AM, FM, PM



- Bandpass channels pass a range of frequencies around some center frequency f_c
 - Radio channels, telephone & DSL modems
- Digital modulators embed information into waveform with frequencies passed by bandpass channel
- Sinusoid of frequency f_c is centered in middle of bandpass channel
- Modulators embed information into a sinusoid



Map bits into frequency: "1" send frequency $f_c + \delta$; "0" send frequency $f_c - \delta$ Demodulator looks for power around $f_c + \delta$ or $f_c - \delta$



- Map bits into phase of sinusoid:
 - "1" send A cos($2\pi ft$) , i.e. phase is 0
 - "0" send A cos($2\pi ft + \pi$), i.e. phase is π
- Equivalent to multiplying $cos(2\pi ft)$ by +A or -A
 - "1" send A cos($2\pi ft$), i.e. multiply by 1
 - "0" send A $cos(2\pi ft+\pi) = -A cos(2\pi ft)$, i.e. multiply by -1

<u>Modulator & Demodulator</u>

Modulate $cos(2\pi f_c t)$ by multiplying by A_k for T seconds:

 $A_{k} \longrightarrow X \longrightarrow Y_{i}(t) = A_{k} \cos(2\pi f_{c} t)$ $\int_{cos(2\pi f_{c} t)} Transmitted signal$ during *k*th interval

Demodulate (recover A_k) by multiplying by $2\cos(2\pi f_c t)$ for *T* seconds and lowpass filtering (smoothing):

$$Y_{i}(t) = A_{k}\cos(2\pi f_{c}t) \longrightarrow X_{i}(t)$$
Received signal
during *k*th interval
$$X_{i}(t)$$

$$ZA_{k}\cos^{2}(2\pi f_{c}t) = A_{k} \{1 + \cos(2\pi 2f_{c}t)\}$$

Example of Modulation



Example of Demodulation



Fact from modulation theory

lf

Baseband signal *x(t)* with bandwidth *B* Hz

then

Modulated signal $x(t)\cos(2\pi f_c t)$ has bandwidth 2B Hz



Quadrature Amplitude Modulation (QAM)

- QAM uses two-dimensional signaling
 - A_k modulates in-phase cos($2\pi f_c t$)
 - B_k modulates quadrature phase $\cos(2\pi f_c t + \pi/4) = \sin(2\pi f_c t)$
 - Transmit sum of inphase & quadrature phase components



- $Y_i(t)$ and $Y_q(t)$ both occupy the bandpass channel
- QAM sends 2 pulses/Hz

QAM Demodulation



Signal Constellations

- Each pair (A_k, B_k) defines a point in the plane
- Signal constellation set of signaling points





4 possible points per *T* sec. 2 bits / pulse 16 possible points per *T* sec.4 bits / pulse

Other Signal Constellations

Point selected by amplitude & phase

 $A_k \cos(2\pi f_c t) + B_k \sin(2\pi f_c t) = \sqrt{A_k^2 + B_k^2} \cos(2\pi f_c t + \tan^{-1}(B_k/A_k))$



4 possible points per *T* sec.

16 possible points per T sec.

Telephone Modem Standards

Telephone Channel for modulation purposes has W_c = 2400 Hz \rightarrow 2400 pulses per second

Modem Standard V.32bis

- Trellis modulation maps m bits into one of 2^{m+1} constellation points
- 14,400 bps Trellis 128 2400x6
- 9600 bps Trellis 32 2400x4
- 4800 bps QAM 4 2400x2

Modem Standard V.34 adjusts pulse rate to channel

• 2400-33600 bps Trellis 960 2400-3429 pulses/sec

Error Detection

Error Control

- Digital transmission systems introduce errors
- Applications require certain reliability level
 - Data applications require error-free transfer
 - Voice & video applications tolerate some errors
- Error control used when transmission system does not meet application requirement
- Error control ensures a data stream is transmitted to a certain level of accuracy despite errors
- Two basic approaches:
 - Error *detection* & retransmission (ARQ)
 - Forward error *correction* (FEC)

<u>Key Idea</u>

- All transmitted data blocks ("codewords") satisfy a pattern
- If received block doesn't satisfy pattern, it is in error
- Redundancy: Only a subset of all possible blocks can be codewords
- Blindspot: when channel transforms a codeword into another codeword



Single Parity Check

• Append an overall parity check to k information bits

Info Bits: $b_1, b_2, b_3, ..., b_k$

Check Bit: $b_{k+1} = b_1 + b_2 + b_3 + ... + b_k \mod 2$ Codeword: $(b_1, b_2, b_3, ..., b_k, b_{k+1})$

All codewords have even # of 1s

- Receiver checks to see if # of 1s is even
 - All error patterns that change an odd # of bits are detectable
 - All even-numbered patterns are undetectable
- Parity bit used in ASCII code

Example of Single Parity Code

- Information (7 bits): (0, 1, 0, 1, 1, 0, 0)
- Parity Bit: $b_8 = 0 + 1 + 0 + 1 + 1 + 0 = 1$
- Codeword (8 bits): (0, 1, 0, 1, 1, 0, 0, 1)
- If single error in bit 3 : (0, 1, 1, 1, 1, 0, 0, 1)
 - # of 1's =5, odd
 - Error detected
- If errors in bits 3 and 5: (0, 1, 1, 1, 0, 0, 0, 1)
 - # of 1's =4, even
 - Error not detected

Checkbits & Error Detection



How good is the single parity check code?

- Redundancy: Single parity check code adds 1 redundant bit per k information bits: overhead = 1/(k+1)
- Coverage: all error patterns with odd # of errors can be detected
 - An error pattern is a binary (k + 1)-tuple with 1s where errors occur and 0's elsewhere
 - Of 2^{k+1} binary (k+1)-tuples, $\frac{1}{2}$ are odd, so 50% of error patterns can be detected
- Is it possible to detect more errors if we add more check bits?
- Yes, with the right codes

Two-Dimensional Parity Check

- More parity bits to improve coverage
- Arrange information as columns
- Add single parity bit to each column
- Add a final "parity" column
- Used in early error control systems

```
      1
      0
      1
      0
      0

      0
      1
      0
      0
      1
      Last column consists of check bits for each row

      1
      0
      0
      1
      1
      0

      1
      0
      0
      1
      1
```

Bottom row consists of check bit for each column

Error-detecting capability



Arrows indicate failed check bits

Other Error Detection Codes

- Many applications require very low error rate
- Need codes that detect the vast majority of errors
- Single parity check codes do not detect enough errors
- Two-dimensional codes require too many check bits
- The following error detecting codes used in practice:
 - Internet Check Sums
 - CRC Polynomial Codes

Internet Checksum

- Several Internet protocols (e.g. IP, TCP, UDP) use check bits to detect errors in the *IP header* (or in the header and data for TCP/UDP)
- A checksum is calculated for header contents and included in a special field.
- Checksum recalculated at every router, so algorithm selected for ease of implementation in software
- Let header consist of L, 16-bit words,

 $\mathbf{b}_0, \, \mathbf{b}_1, \, \mathbf{b}_2, \, ..., \, \mathbf{b}_{L-1}$

• The algorithm appends a 16-bit checksum $\mathbf{b}_{\mathcal{L}}$

Checksum Calculation

The checksum \mathbf{b}_{L} is calculated as follows:

• Treating each 16-bit word as an integer, find

 $\mathbf{x} = \mathbf{b}_0 + \mathbf{b}_1 + \mathbf{b}_2 + \dots + \mathbf{b}_{L-1} \mod 2^{16} - 1$

• The checksum is then given by:

 $b_{L} = -x$ modulo 2¹⁶-1

Thus, the headers must satisfy the following *pattern*:

 $\mathbf{0} = \mathbf{b}_0 + \mathbf{b}_1 + \mathbf{b}_2 + \dots + \mathbf{b}_{L-1} + \mathbf{b}_L \text{ modulo } 2^{16} - 1$

• The checksum calculation is carried out in software using one's complement arithmetic

Internet Checksum Example

Use Modulo Arithmetic

- Assume 4-bit words
- Use mod 2⁴-1 arithmetic
- <u>b</u>₀=1100 = 12
- <u>b</u>₁=1010 = 10
- $\underline{b}_0 + \underline{b}_1 = 12 + 10 = 7 \mod 15$
- $\underline{b}_2 = -7 = 8 \mod 15$
- Therefore
- <u>b</u>₂=1000

Use Binary Arithmetic

- Note 16 =1 mod15
- So: 10000 = 0001 mod15
- leading bit wraps around

```
b_0 + b_1 = 1100+1010
=10110
=10000+0110
=0001+0110
=0111
=7
Take 1s complement
b_2 = -0111 = 1000
```

Polynomial Codes

- Polynomials instead of vectors for codewords
- Polynomial arithmetic instead of check sums
- Implemented using shift-register circuits
- Also called cyclic redundancy check (CRC) codes
- Most data communications standards use polynomial codes for error detection
- Polynomial codes also basis for powerful error-correction methods

Binary Polynomial Arithmetic

• Binary vectors map to polynomials

$$(i_{k-1}, i_{k-2}, \dots, i_2, i_1, i_0) \rightarrow i_{k-1}x^{k-1} + i_{k-2}x^{k-2} + \dots + i_2x^2 + i_1x + i_0$$

Addition:

$$(x^{7} + x^{6} + 1) + (x^{6} + x^{5}) = x^{7} + x^{6} + x^{6} + x^{5} + 1$$
$$= x^{7} + (1+1)x^{6} + x^{5} + 1$$
$$= x^{7} + x^{5} + 1 \text{ since } 1 + 1 = 0 \text{ mod} 2$$

Multiplication:

$$(x + 1) (x2 + x + 1) = x(x2 + x + 1) + 1(x2 + x + 1)$$
$$= x3 + x2 + x) + (x2 + x + 1)$$
$$= x3 + 1$$

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Binary Polynomial Division

Division with Decimal Numbers



Polynomial Coding

Code has binary generating polynomial of degree n-k

 $g(x) = x^{n-k} + g_{n-k-1}x^{n-k-1} + \dots + g_2x^2 + g_1x + 1$

• k information bits define polynomial of degree k-1

$$i(x) = i_{k-1}x^{k-1} + i_{k-2}x^{k-2} + \dots + i_2x^2 + i_1x + i_0$$

• Find *remainder polynomial* of at most degree n - k - 1

$$g(x) \xrightarrow{q(x)} x^{n-k} i(x) = q(x)g(x) + r(x)$$

$$r(x)$$

Define the codeword polynomial of degree n-1

$$\underbrace{b(x)}_{n \text{ bits}} = \underbrace{x^{n-k}i(x)}_{k \text{ bits}} + \underbrace{r(x)}_{n-k \text{ bits}}$$

Polynomial Encoding: Steps

- 1. Multiply i(x) by x^{n-k}
- 2. Divide $x^{n-k}i(x)$ by g(x) $x^{n-k}i(x) = g(X)q(x) + r(x)$
- 3. Add remainder r(x) to $x^{n-k}i(x)$

 $b(x) = x^{n-k}i(x) + r(x) \leftarrow \text{transmitted codeword}$

Polynomial example: k = 4, n-k = 3

 Generator polynomial: $g(x) = x^3 + x + 1$

 Information: (1,1,0,0) $i(x) = x^3 + x^2$

 Encoding: $x^3i(x) = x^6 + x^5$



Transmitted codeword: $b(x) = x^6 + x^5 + x$ \longrightarrow $\underline{b} = (1,1,0,0,0,1,0)$

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The Pattern in Polynomial Coding

• All codewords satisfy the following **pattern**:

 $b(x) = x^{n-k}i(x) + r(x) = q(x)g(x) + r(x) + r(x) = q(x)g(x)$

- All codewords are a multiple of g(x)!
- Receiver should divide received n-tuple by g(x) and check if remainder is zero
- If remainder is nonzero, then received n-tuple is not a codeword

Undetectable error patterns



- e(x) has 1s in error locations & Os elsewhere
- Receiver divides the received polynomial R(x) by g(x)
- Blindspot: If e(x) is a multiple of g(x), that is, e(x) is a nonzero codeword, then

R(x) = b(x) + e(x) = q(x)g(x) + q'(x)g(x)

- The set of undetectable error polynomials is the set of nonzero code polynomials
- Choose the generator polynomial so that selected error patterns can be detected.

Standard Generator Polynomials

CRC = cyclic redundancy check

- CRC-8: = $x^8 + x^2 + x + 1$
- CRC-16: = $x^{16} + x^{15} + x^2 + 1$ = $(x + 1)(x^{15} + x + 1)$

ATM

Bisync

• CCITT-16:

 $= x^{16} + x^{12} + x^5 + 1$ HDLC, XMODEM, V.41

• CCITT-32: IEEE 802, DoD, V.42

 $= x^{32} + x^{26} + x^{23} + x^{22} + x^{16} + x^{12} + x^{11} + x^{10} + x^8 + x^7 + x^5 + x^4 + x^2 + x + 1$